




This EE-Note provides three different ways to implement a powerful debug system, which keeps the look and feel of C-standard I/O functions. It includes software examples for currently available Blackfin evaluation boards. The three methods are described in the sections:

- [Accessing the UART Directly](#)
- [Replacing the Standard Device](#)
- [Extending I/O Support to New Devices](#)

It is assumed that the audience of this EE-Note is familiar with the C programming language and the I/O features which are implemented in the standard. For details, refer to [1].

 To understand this EE-Note, it is necessary to work with the example code provided in the associated .ZIP file.

## Preparations

All the methods described later will require the Blackfin processor's UART interface to be set up properly. The examples provide target-specific functions to do this. They can be found in the `ADSP-BF5xx-UART.c` and `ADSP-BF60x-UART.c` files, respectively. The functions are used to initialize the Blackfin ports, the UART, and the routines to send out buffer contents over the UART.

The associated header files, named `ADSP-BF5xx-UART.h`, contain information about the UART device number to be used, the DMA channel, and indicate whether autobaud detection is used instead of a hard-coded bitrate.

Another set of required sources is `BfDebugger.c` and `BfDebugger.h`. Their functions are described in the following sections.

## Accessing the UART Directly

Direct access, the first method illustrated in this EE-Note, is based on a set of preprocessor macros and uses the string library (`string.h`) to

generate a formatted string for UART transmission.

The functions can be found in `BfDebugger.c` and `BfDebugger.h` and use the following prototypes:

```
short udprintf(unsigned char UartNum,
               unsigned char DmaChan, const char
               *format, /* args */ ...);

short uprintf(unsigned char UartNum,
              const char *format, /* args */ ...);
```

The look and feel is like `printf`, which takes a variable list of arguments. The argument format contains a set of conversion specifiers, directives, and ordinary characters that are used to control how the data is formatted.

```
udprintf(0,9,"Hello UART%d\n",0);
uprintf(0,"Hello UART%d\n",0);
```

A carriage return and C-style NULL termination is inserted automatically. The first arguments are the UART number and the DMA channel number, respectively.

The function returns the number of characters transmitted, or a negative value if unsuccessful.

## Preprocessor Definitions

To assist the programmer with a flexible support of the `uprintf` functions versus the regular `printf` functions, a set of preprocessor macros helps to switch between different modes. Use only one at the same time:

- `__DEBUG_UART_DMA__` Directs prints to the UART, DMA mode
- `__DEBUG_UART__` Directs prints to the UART, Core mode
- `__DEBUG_FILE__` Directs prints to a file
- `__DEBUG_VDSP__` Directs prints to the VisualDSP++ Output window (console)

The last two definitions are just an additional feature for completeness and use the standard `fprintf()` function.

- `__VERBOSITY__` [int] Level of verbosity (LoV)

This definition allows masking or unmasking certain messages using a level hierarchy. So for example, `__VERBOSITY__` is defined as 2, so any messages using the preprocessor macros in the next section and have `n` set to 1 or 2 (`DEBUG(1, args)` or `DEBUG(2, args)`) are printed while 3 (`DEBUG(3, args)`) or higher are masked by the preprocessor.

## Preprocessor Macros

A set of preprocessor macros adds additional functionality such as evaluation of a desired verbosity level and automatic color output. They insert, according to `ADSP-BF5xx-UART.h`, the correct UART number and DMA channel, respectively.

- `DEBUG(n, *format, /* args */ ...)`  
No color
- `INFO(n, *format, /* args */ ...)`  
Yellow text
- `ERROR(n, *format, /* args */ ...)`  
Red text
- `MSG(n, *format, /* args */ ...)`  
Green text

ANSI escape sequences are used to color the output. A list of available ESC codes can be found in [4].

Finally, the macros `DEBUG_OPEN()` and `DEBUG_CLOSE()`, both of which are required only once in the application, are used to prepare and close all required resources, including the UART setup.

```
DEBUG_OPEN();
DEBUG(1, "Hello UART%d\n", 0);
ERROR(1, "This is an error message\n");
DEBUG_CLOSE();
```

## C/C++ Run-Time I/O Library

This section discusses C/C++ run-time (CRT) I/O library features, which can be used to send debug information from within an application. Additional examples showing how to work with the I/O library can be found in [2] and [3].

### Stdio.h Basics

The `stdio.h` header file defines a set of functions, macros, and data types for performing input and output. The standard functions for generating formatted output are the `printf` family. The `printf` function sends its arguments to `stdout`, which by default, is the VisualDSP++ console output window. The programmer can change the device or file to which `stdout` refers. The `fprintf` function writes to a file-pointer. The associated file is opened / closed on the PC by the `fopen` / `fclose` function.

### File I/O Support

File I/O support is described in detail in [1]. By default, the standard C functionality is achieved through a device called `PrimIO`. It is set up and registered on startup by the CRT and handles the three standard files (`stdin`, `stdout`, and `stderr`) and any other stream to be opened by the user, unless the default device is changed.

## Replacing the Standard Device

This method is radical. Any `printf` call will be formatted as usual by the I/O subsystem but directed to the `_write` function (see `DevEntry` structure, defined in the `device.h` header file), which is associated with your new device. The downside is that you lose the print-to-console functionality. The advantage is that existing source files may remain virtually unchanged. Only a few additions to the project are required.

The documentation describes what changes are required to `devtab.c` and `primiolib.c`. These files are prepared and included in the example projects already.

A modification to `devtab.c` is required if a device should be pre-registered when the CRT is setting up.

If a new device claims the standard streams instead of the `PrimIO` device, `primiolib.c` must be modified.

The `BfDebugger.c` file defines the device with the required function pointers:

```
struct DevEntry UartIODevice
```

The `BfDebugger.h` file provides the preprocessor definitions used to activate the replacing method:

- `__UART_IO_DEVICE__`
- `__PRE_REGISTERING_DEVICE__`

The following definitions determine whether the UART transfer is done by Core or DMA. Use only one at a time:

- `__DEBUG_UART_DMA__`
- `__DEBUG_UART__`

Now any `printf` output is redirected.

## Extending I/O Support to New Devices

The last method is a bit more elegant than the previous one. It uses the possibility to extend I/O support to new devices, too. But now standard functionality is preserved.

The same sources as the previous example are used. Pre-registering of the device is not done.

```
int PrimDevId =
get_default_io_device();
int SecDevId =
add_devtab_entry(&UartIODevice);
set_default_io_device(SecDevId);
pUartIOFile = fopen("uart","w");
if(setvbuf(pUartIOFile,buf,_IOLBF,size
of(buf)) == -1) { return -1; }
```

```
set_default_io_device(PrimDevId);
fprintf(pUartIOFile,"Test\n");
printf("Test\n");
fclose(pUartIOFile);
```

The above example saves the current device ID (`PrimDevId`). Then a new device (`UartIODevice`) is added and marked as default. A `fopen` operation opens a dummy file on the default device. Immediately *afterwards*, a new buffer is required to be associated with the new device. Line buffering is preferred for console output. The previous default device can be restored, and writes can be performed to the new device. A `printf` output will still be seen to the VisualDSP++ Output window.

## SDTIO System Service

The System Services, starting with VisualDSP++ Update 8, provide a similar approach for redirecting a `printf` to UART. The examples can be found in the specific Evaluation Board examples folder:

```
\Services\stdio\char_echo\
```

## UART Direct Access vs. I/O Device

The downside of using an I/O device rather than accessing the UART directly is the DMA mode. Before updating the buffer, any ongoing DMA transfer must be finished first. This is ensured by a function named

```
UartDmaWaitForDmaDone.
```

Since the I/O system that prepares the buffer is called in the very first stage, polling of the `DMA_DONE` status bit must be performed immediately after starting the transfer. Accessing the UART directly allows moving the wait routine right before preparing the buffer to be transmitted.

## Console Application

Figure 1 shows the console output with the Windows program PuTTY. See [5] for download details. This program can be used as an alternative terminal window as HyperTerminal® has been removed from Windows Vista®. The window must be set to at least 91 columns to show the “welcome screen” displayed in the picture.

The Blackfin application features a UART talk-through mode based on interrupts. This means you can type characters in you console application window and get them bounced back and displayed on the screen.

## CrossCore Embedded Studio® Support

The document and especially the attached ZIP file have been updated to support the new members of the Blackfin family, ADSP-BF60x processors. This processor family is only supported by the new IDE, CrossCore Embedded Studio® software. A dual core project running on the ADSP-BF609 ET-KIT Lite® Evaluation Board is included.

## Conclusion

This EE-Note has shown some methods to create debug information and print them without the low-speed Output window (console) output of the VisualDSP++ debugger. The provided examples can be used as is on any Blackfin EZ-KIT Lite evaluation board and easily included in existing projects with similar targets.

## References

- [1] *VisualDSP++ 5.0 C/C++ Compiler and Library Manual for Blackfin Processors*. Rev. 5.2, September 2009. Analog Devices, Inc.
- [2] *VisualDSP++ 5.0 Blackfin examples: Services\File System\VDK\shell\_browser\*. Analog Devices, Inc.
- [3] *VisualDSP++ 5.0 Blackfin examples: LAN\FileServerStdio\*. Analog Devices, Inc.
- [4] *ASCII-Table.com*: <http://ascii-table.com/ansi-escape-sequences.php>
- [5] *PuTTY.org*: <http://www.putty.org>
- [6] *CrossCore® Embedded Studio 1.0.0 C/C++ Compiler and Library Manual for Blackfin Processor*. Rev. 1.0, March 2012. Analog Devices, Inc.

## Document History

Revision	Description
<i>Rev 1 – January 26, 2010 by Andreas Pellkofer</i>	Initial release.
<i>Rev 2 – December 10, 2010 by Andreas Pellkofer</i>	Chapter Console Application updated. Example Code enhanced and extended to new Blackfin Evaluation Boards.
<i>Rev 3 – June 21, 2012 by Andreas Pellkofer</i>	Example Code enhanced and extended to new Blackfin Evaluation Boards. Support for ADSP-BF60x Blackfin Processor family added.