

## Sensing Low-g Acceleration Using the **ADXL345** Digital Accelerometer Connected to the **ADuC7024** Precision Analog Microcontroller

### CIRCUIT FUNCTION AND BENEFITS

The **ADXL345** is a small, thin, low power, 3-axis accelerometer with high resolution (13-bit) measurement up to  $\pm 16\text{ g}$ . Digital output data is formatted as 16-bit twos complement and is accessible through either a serial peripheral interface (SPI), 3-wire or 4-wire, or an I<sup>2</sup>C digital interface.

The **ADXL345** is well suited for mobile device applications. The **ADXL345** measures the static acceleration of gravity in tilt sensing applications, as well as dynamic acceleration resulting from motion or shock. The high resolution of the **ADXL345** (4 mg/LSB) enables measurement of inclination changes of about 0.25°. Using a digital output accelerometer such as the **ADXL345** eliminates the need for analog-to-digital conversion, reducing system cost and real estate. Additionally, the **ADXL345** includes a variety of built in features. Activity detection or inactivity

detection, tap detection or double tap detection, and free fall detection are all done internally with no need for the host processor to perform any calculations. A built in, 32-stage first in, first out (FIFO) memory buffer reduces the burden on the host processor, allowing algorithm simplification and power savings. Additional system level power savings can be implemented using the built in activity or inactivity detection and by using the **ADXL345** as a motion switch to turn the whole system off when no activity is felt and on when activity is sensed again.

The **ADXL345** communicates via an I<sup>2</sup>C interface or an SPI interface. The circuits described in this application note demonstrate how to implement communication via these protocols.

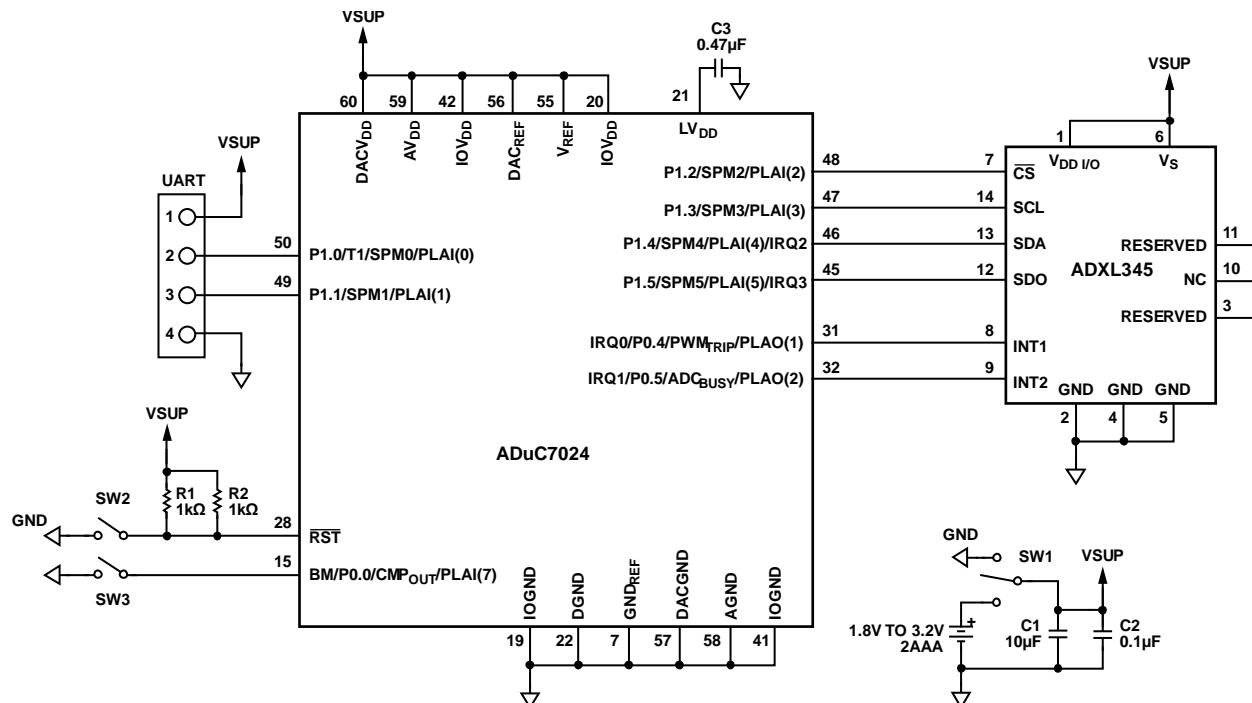


Figure 1. **ADXL345** and **ADuC7024** in 4-Wire SPI Configuration (Simplified Schematic: Decoupling and All Connections Not Shown)

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## REVISION HISTORY

### 10/2018—Rev. 0 to Rev. A

Document Title Changed from CN0133 to AN-1588...Universal Changes to Figure 1 .....	1
Moved Revision History Section .....	2
Changes to Figure 3 and Common Variations Section .....	3
Deleted Data Sheets and Evaluation Boards Section .....	3
Deleted Learn More Section .....	4
Changes to Figure 4.....	4
Added Figure 5; Renumbered Sequentially .....	4

### 10/2009—Revision 0: Initial Version

## CIRCUIT DESCRIPTION

This circuit uses an [ADuC7024](#) precision analog microcontroller in conjunction with the [ADXL345](#) digital accelerometer. Both are I<sup>2</sup>C ready and SPI ready. Figure 1 shows the [ADXL345](#) and [ADuC7024](#) in an SPI configuration, and Figure 3 shows the same devices in an I<sup>2</sup>C configuration. The CS pin (Pin 7 on the [ADXL345](#)) is used to select the desired interface. I<sup>2</sup>C mode is enabled if the CS pin is tied high to V<sub>DD,I/O</sub> (Pin 1 on the [ADXL345](#)). In SPI mode, CS is toggled to signify the beginning and end of each transmission. Pulling CS high indicates that no SPI transmission is occurring or that an I<sup>2</sup>C transmission may occur.

Both schematics are simplified but required connections (for example, supplies and ground connections) are shown. In these schematics, the **ADuC7024** is programmed via a universal asynchronous receiver-transmitter (UART) that connects to Pin 49 and Pin 50 of the **ADuC7024**. SW2 and SW3 are reset and download buttons, respectively, for programming the microcontroller. SW1 is an on or off power switch.

## COMMON VARIATIONS

Figure 1 shows the ADXL345 in a 4-wire SPI configuration, and Figure 2 shows that the ADXL345 can also communicate via a 3-wire SPI.

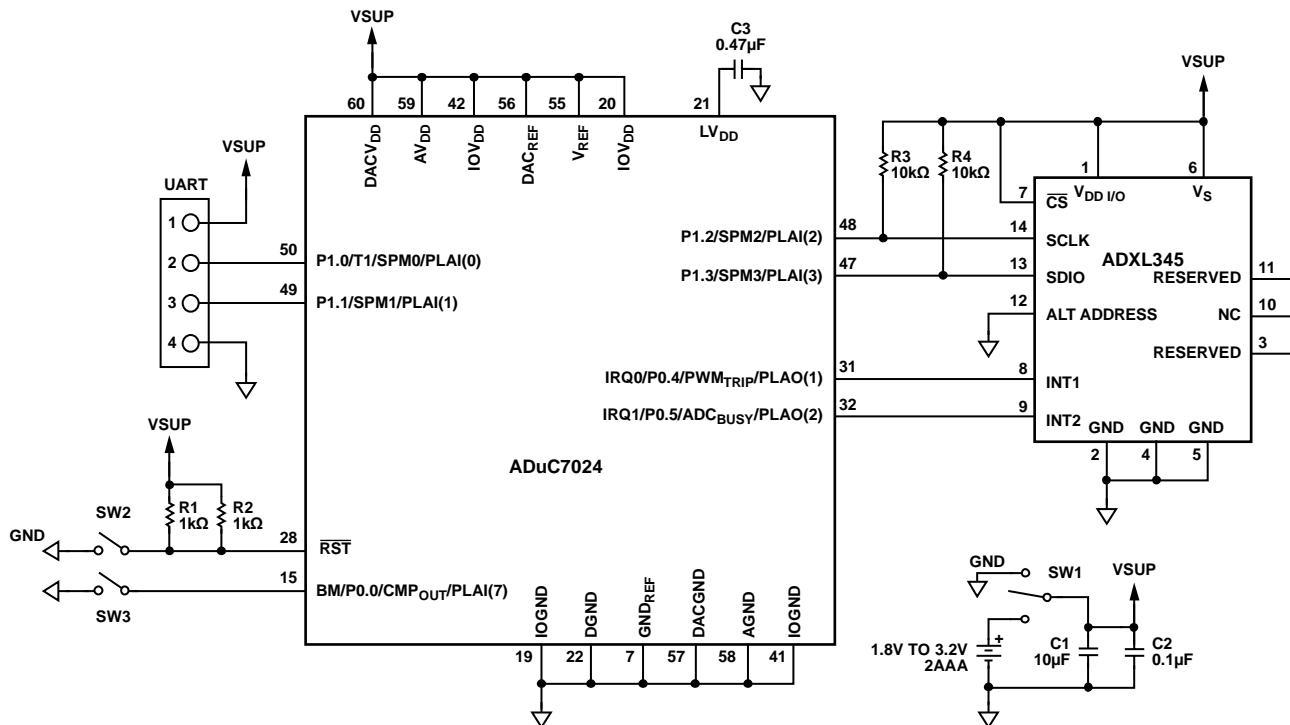
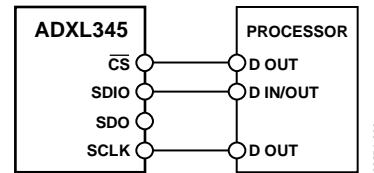


Figure 3. *ADXL345* and *ADuC7024* in I<sup>2</sup>C Configuration (Simplified Schematic: Decoupling and All Connections Not Shown)



*Figure 2. 3-Wire SPI Connection Diagram*

The circuit described in Figure 1 and Figure 3 use the ADuC7024 microcontroller. The same configuration can be applied with any SPI capable or I<sup>C</sup> capable microcontroller, as outlined in Figure 4 and Figure 5. The standard I<sup>C</sup> connection and SPI connection are used. Pin functions for the two protocols are listed in Table 1.

For information on **ADXL345** operation and register functions, refer to the **ADXL345** data sheet.

For information on programming the [ADuC7024](#), see the [ADuC7024](#) data sheet.

Table 1. ADXL345 Pin Functionality in SPI and I<sup>2</sup>C Communication Modes

Pin Number	Pin Name	Functionality	
		I <sup>2</sup> C	SPI
7	CS	Connect to V <sub>DD</sub> I/O for I <sup>2</sup> C	Chip select
12	SDO/ALT ADDRESS	Alternate address select	Serial data output
13	SDA/SDI/SDIO	Serial data	Serial data input (SPI 4-wire)/serial data input and output (SPI 2-wire)
14	SCL/SCLK	Serial communications clock	Serial communications clock

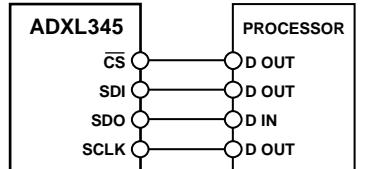
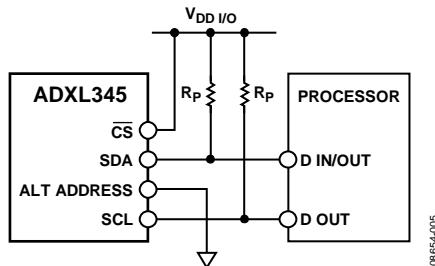


Figure 4. SPI Compatible Connection Diagram

Figure 5. I<sup>2</sup>C Compatible Connection Diagram

I<sup>2</sup>C refers to a communications protocol originally developed by Philips Semiconductors (now NXP Semiconductors).