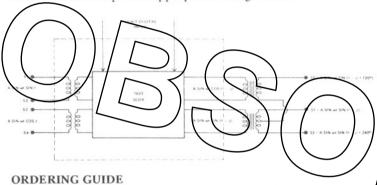
SOLID STATE CONTROL DIFF TRANSMITTER

GENERAL DESCRIPTION

The SCDX Series are solid state control differential transmitters. Their function is analogous to an electromechanical CDX except that the mechanical input of the CDX has been replaced by a binary input angle. The solid state differential transmitter accepts a digital angle input together with either a 3 wire Synchro (or 4 wire resolver) angle input and gives as output synchro or resolver signals representing the difference between the two input angles. Thus the outputs can be described by A sin wt sin $(\theta - \phi)$ and A sin wt cos $(\theta - \phi)$ where θ represents the synchro or resolver input angle, ϕ represents the binary input angle (14 bits) and wt is the synchro excitation frequency.

The outputs from the SCDX resemble in their function the outputs from a conventional resolver but they are not transformer isolated. The outputs are from a pair of operational amplifiers (5.0 volts rms at maximum) which can be fed into a power amplifier and Scott transformer to provide either 3 wire synchro or 4 wire resolver outputs at appropriate voltage levels.



1. Specify the basic model number per the following table. 60Hz versions require separate transformers.

# of Bits	Temp. Range	Freq.	Converter	Transformers	
14	0 to +70°C	400Hz	SCDX162351Z	Integral	
14	-55°C to $+105$ °C	400Hz	SCDX162361Z	Integral	
14	$0 \text{ to } +70^{\circ}\text{C}$	60Hz	SCDX1623507	STM163152Z	
14	-55°C to $+105$ °C	60Hz	SCDX1623607	STM163162Z	

Notes 2 and 3 of SDC series ordering guide apply

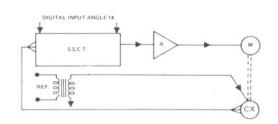
SPECIFICATION SUMMARY (typical @ +25°C

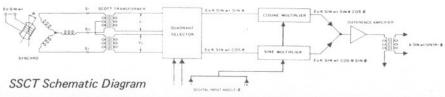
	SCDX1623		
Accuracy ¹ (max error):	±4 arc-minutes		
Input Resolution:	14 bits		
Synchro	See Table I		
Inputs:	Transformer isolated		
Reference:	Not required		
Output	5V rms into 2k ohms min		
Voltages:	(not transformer isolated)		
Output	360°		
Angle Range:	300		
Power	+15V @ 45mA		
Supplies:	-15V @ 45mA		
	+5V @ 20mA		
Power Dissipation:	1.6 Watts		
Size:	3.125" x 2.625" x 0.8"		
Operating	0 to +70°C or		
Temperature:	-55°C to +105°C		
Weight	7 oz.		
NOTES: 1. Accu	racy applies over the operating temp. range plus Tab		
I parameters			

SOLID STATE CONTROL TRANSFORMER

GENERAL DESCRIPTION

This SSCT1621 is a solid state control transformer which performs an identical function to an electromechanical control transformer except that the mechanical input of the latter has been replaced by a digital input. The SSCT1621 accepts a 3 wire synchro input together with a digital angle input and outputs the sine of the difference of the two input angles. The output can be described by A sin wt sin $(\theta - \phi)$ where " ϕ " represents a 14 bit parallel binary input angle, " θ " represents a 3 wire synchro input angle, and "wt" is the synchro excitation frequency.





The scaling of the SSCT1621 is 0.4 volts/degree and the nominal output voltage range is ±5 volts. This implies a span of ±12.5° for full scale output. The SSCT1621 is intended for use as an error generator in follow up servo systems and for this reason the span of the device is more than adequate for all such systems. The A.C. output of the SSCT1621 is transformer isolated.

The SSCT1621 provides an attractive alternative to digital-tosynchro converters in follow up servo applications since the distribution of system power dissipation, and the elimination of balanced output transformers removes constraints associated with D to S converters.

SPECIFICATION SUMA	MARY (typical @ $+25^{\circ}$ C and ± 15 VDC	C unless otherwise noted)	
	SSCT1621		
Accuracy¹ (max) error):	±4 arc-minines		+15V @ 40mA -15V @ 40mA
Input Resolution:	14 bits	Power Dissipation:	No +5V required 1.3 Watts
Synchro Inputs:	See Table I Transformer Isolated	Size:	3.125" x 2.625" x 0.8"
Reference:	Not Required	Operating Temperature:	0 to +70°C or -55°C to +105°C
Output Voltages:	5V rms into 2k ohms min (transformer isolated)	Weight:	7 oz.
Output Angle Range: ORDERING GUIDE	±12.5° del number per the following table.	NOTE: ¹ Accuracy applies Table I paramete	over the operating temp, range plus rs.
# of Bits Temp. R	ange req. converter	Transformers 1Z Integral	
14 -55°C to 14 0 to +70' 14 -55°C to	°C 60Hz SSC \$16218	07 STM163652Z	
Notes 2 and 3 of SDC se	eries ordering guide apply.		
	AN	GLE POSITI	ION INDICATED

GENERAL DESCRIPTION

Model API 1620 gives a digital display of angles measured by synchros and resolvers. It has a full scale range equivalent to 359.99 mechanical degrees. It has an accuracy of 0.01 degrees and uses a converter which has a resolution of 20 arc-seconds.

Two separate input channels are provided which may be alternately switched into the synchro converter. High level or low level synchros or resolvers can be connected to these inputs and the accuracy or the shaft position of two separate devices can be directly compared.

The meter will work with any reference voltage from 3 volts rms to 115 volts rms and from any reference frequency from 45Hz to 1100Hz. A two position "bite" is incorporated which self checks the meter at 45° and 225°. This is manually operated by a front panel switch.

A push button display check exercises the L.E.D. dot matrix readout and indicates "all 8's". The internal power unit requires 17VA 45 to 400Hz. A power line selector allows voltages of either 115VAC or 230VAC to be chosen. A 5 decade binary or BCD output is available. A data hold capability is provided. This allows a display and output data to be frozen.

SPECIFICATIONS (typical (@ +25°C unless otherwise note(1)		
Accuracy	±0.01° ±1 digit		
Angle Range Signal	000.00° to 359.99° continuous		
	rotation		
Temperature Range	0 - 50°C		
Power	115/230VAC selectable		
	17VA. 47Hz - 400Hz		
Input Signal Voltages			
Synchro or Resolver	11.8V/26V/90V		
Frequency	Same as Reference		
Reference			
Voltage	3 volts to 115 volts rms		
Frequency	47Hz to 1100Hz		
Input Impedance			
Reference	200k ohms		
Signals	2 meg ohms		
Phase Relative to Reference	20°		
Display	5 digit, dot matrix LED		
Data Outputs			
Angle	5 decades BCD (Binary optional)		
	continuously available		
Inhibit	"1" track "0" hold		
Converter Busy	"0" = Data stable		
	"1" = converter busy		
Display Enable	"0" = Update (follows) "1" = Hold		