# Programmable AC Power Source

APS-7000 Series

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**PROGRAMMING MANUAL**

**GWINSTEK**

# Table of Contents

# SAFETY INSTRUCTIONS

This chapter contains important safety instructions that you must follow during operation and storage. Read the following before any operation to insure your safety and to keep the instrument in the best possible condition.

## Safety Symbols

These safety symbols may appear in this manual or on the instrument.

| | |
|---|---|
| ⚠ WARNING | Warning: Identifies conditions or practices that could result in injury or loss of life. |
| ⚠ CAUTION | Caution: Identifies conditions or practices that could result in damage to the APS-7000 or to other properties. |
| ⚡ | DANGER High Voltage |
| ⚠ | Attention Refer to the Manual |
| ⏚ | Protective Conductor Terminal |
| ⏚ | Earth (ground) Terminal |

Do not dispose electronic equipment as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased.

## Safety Guidelines

General Guideline

⚠ CAUTION

- Do not place any heavy object on the APS-7000.
- Avoid severe impact or rough handling that leads to damaging the APS-7000.
- Do not discharge static electricity to the APS-7000.
- Use only mating connectors, not bare wires, for the terminals.
- Do not block the cooling fan opening.
- Do not disassemble the APS-7000 unless you are qualified.

(Measurement categories) EN 61010-1:2010 specifies the measurement categories and their requirements as follows. The APS-7000 doesn't fall under category II, III or IV.

- Measurement category IV is for measurement performed at the source of low-voltage installation.
- Measurement category III is for measurement performed in the building installation.
- Measurement category II is for measurement performed on the circuits directly connected to the low voltage installation.
- 0 is for measurements performed on circuits not directly connected to Mains.

Power Supply

⚠ WARNING

- AC Input voltage range:
  115/230 Vac ± 15% (APS-7050, APS-7100)
  230 Vac ± 15% (APS-7200, APS-7300)
- Frequency: 50/60Hz
- To avoid electrical shock connect the protective grounding conductor of the AC power cord to an earth ground.

| | |
|---|---|
| Cleaning the APS-7000 | • Disconnect the power cord before cleaning. |
| | • Use a soft cloth dampened in a solution of mild detergent and water. Do not spray any liquid. |
| | • Do not use chemicals containing harsh material such as benzene, toluene, xylene, and acetone. |

Operation Environment

- Location: Indoor, no direct sunlight, dust free, almost non-conductive pollution (Note below)
- Relative Humidity: 20%~ 80%
- Altitude: < 2000m
- Temperature: 0°C to 40°C

(Pollution Degree) EN 61010-1:2010 specifies the pollution degrees and their requirements as follows. The APS-7000 falls under degree 2.

Pollution refers to "addition of foreign matter, solid, liquid, or gaseous (ionized gases), that may produce a reduction of dielectric strength or surface resistivity".

- Pollution degree 1: No pollution or only dry, non-conductive pollution occurs. The pollution has no influence.
- Pollution degree 2: Normally only non-conductive pollution occurs. Occasionally, however, a temporary conductivity caused by condensation must be expected.
- Pollution degree 3: Conductive pollution occurs, or dry, non-conductive pollution occurs which becomes conductive due to condensation which is expected. In such conditions, equipment is normally protected against exposure to direct sunlight, precipitation, and full wind pressure, but neither temperature nor humidity is controlled.

Storage environment

- Location: Indoor
- Temperature: -10°C to 70°C
- Relative Humidity: ≤80%, no condensation

Disposal

Do not dispose this instrument as unsorted municipal waste. Please use a separate collection facility or contact the supplier from which this instrument was purchased. Please make sure discarded electrical waste is properly recycled to reduce environmental impact.

## Power cord for the United Kingdom

When using the instrument in the United Kingdom, make sure the power cord meets the following safety instructions.

NOTE: This lead/appliance must only be wired by competent persons

⚠️ WARNING: THIS APPLIANCE MUST BE EARTHED

IMPORTANT: The wires in this lead are coloured in accordance with the following code:

Green/ Yellow:    Earth
Blue:             Neutral
Brown:            Live (Phase)

As the colours of the wires in main leads may not correspond with the coloured marking identified in your plug/appliance, proceed as follows:

The wire which is coloured Green & Yellow must be connected to the Earth terminal marked with either the letter E, the earth symbol ⏚ or coloured Green/Green & Yellow.

The wire which is coloured Blue must be connected to the terminal which is marked with the letter N or coloured Blue or Black.

The wire which is coloured Brown must be connected to the terminal marked with the letter L or P or coloured Brown or Red.

If in doubt, consult the instructions provided with the equipment or contact the supplier.

This cable/appliance should be protected by a suitably rated and approved HBC mains fuse: refer to the rating information on the equipment and/or user instructions for details. As a guide, a cable of 0.75mm$^2$ should be protected by a 3A or 5A fuse. Larger conductors would normally require 13A types, depending on the connection method used.

Any exposed wiring from a cable, plug or connection that is engaged in a live socket is extremely hazardous. If a cable or plug is deemed hazardous, turn off the mains power and remove the cable, any fuses and fuse assemblies. All hazardous wiring must be immediately destroyed and replaced in accordance to the above standard.

# GETTING STARTED

This chapter describes the power source in a nutshell, including its main features and front / rear panel introduction.

# APS-7000 Series Overview

## Series lineup

The APS-7000 series consists of 4 models, the APS-7050, APS-7100, APS-7200 and APS-7300, differing only in capacity. Note that throughout the user manual, the term "APS-7000" refers to any of the models, unless stated otherwise.

| Model name | Max. Output Current | Power Rating | Output  Voltage |
|------------|---------------------|--------------|-----------------|
| APS-7050   | 4.2A/2.1A           | 500VA        | 0~310.0 Vrms    |
| APS-7100   | 8.4A/4.2A           | 1000VA       | 0~310.0 Vrms    |
| APS-7200   | 16.8A/8.4A          | 2000VA       | 0~310.0 Vrms    |
| APS-7300   | 25.2A/16.8A         | 3000VA       | 0~310.0 Vrms    |

## Main Features

Performance
- Low output ripple and noise
- Excellent and feature-rich measurement capacity
- Standard maximum output voltage is 310Vrms
- Maximum output voltage and frequency of 600Vrms(APS-003 Option)/999.9Hz(APS-004 Option)

| Features | • OVP, OPP and OTP protection |
|---|---|
| | • Variable voltage, frequency and current limiter |
| | • Sequence and simulation function |
| | • Large 4.3 inch panel |
| | • Globally adjustable power inlet not restricted by the power supply environment |
| | • USB interface is equipped as standard with the ability to save and recall files. |
| | • Only 88mm (2U) case height (APS-7050 and APS-7100 models only). |

| Interface | Standard: |
|---|---|
| | • Ethernet port |
| | • USB host |
| | • USB CDC (APS-7200 and APS-7300 models only) |
| | Optional: |
| | • GPIB |
| | • RS-232 / USB CDC (APS-7050 and APS-7100 models only) |
| | • RS-232 (APS-7200 and APS-7300 models only) |

## Accessories

| Standard Accessories | Part number | Description |
|---|---|---|
| | CD ROM | User manual, programming manual |
| | 82GW1SAFE0M*1 | Safety guide |
| | Region dependent | Type I Power cord (APS-7050) |

| | | |
|---|---|---|
| | Region dependent | Type II Power cord (APS-7100) |
| | Region dependent | Type III Power cord (APS-7200, APS-7300) |
| | 62PS-7K0SC701 x1 5302-01613001 x1 | Mains terminal cover set (APS-7050) |
| | 62PS-7K0SC401 x1 5302-01613001 x2 | Mains terminal cover set (APS-7100) |
| | GTL-123 | Test leads: 1x red, 1x black |
| Optional Capacity | Part number | Description |
| | APS-003 | Output Voltage Capacity: 0 ~ 600Vrms |
| | APS-004 | Output Frequency Capacity: 45 ~ 999.9Hz |
| Optional Accessories | Part number | Description |
| | GRA-423 | APS-7050 and APS-7100 rack mount kit |
| | GRA-429 | APS-7200 rack mount kit |
| | GRA-430 | APS-7300 rack mount kit |
| | APS-001 | GPIB interface card |
| | APS-002 | RS-232 / USB CDC interface card (APS-7050 and APS-7100 only) |
| | APS-007 | RS-232 interface card (APS-7200 and APS-7300 only) |
| | GPW-004 | Power Cord 8mm$^2$/3C, 3m Max Length, 105°C, RNYBS8-6*3P, RNYB8-8*3P |
| Download | Name | Description |
| | gw_aps.inf | USB driver |

# Appearance

## Front Panel

APS-7050, APS-7100

Power switch | Front voltage output socket | Display mode key | Menu, Test, Preset keys | Arrow keys, Scroll wheel



LCD display

Function keys | Keypad | Output key

USB A port | Voltage, Frequency, Current setting and limit | Range, Shift, Cancel, Enter, Lock keys

APS-7200                                          APS-7300



Caster                                            Caster
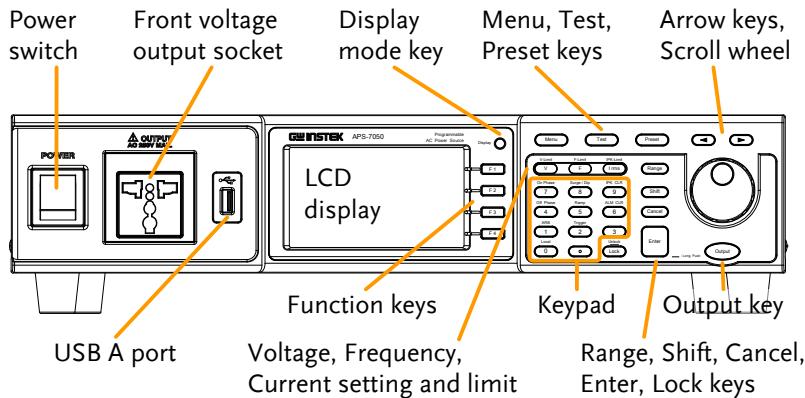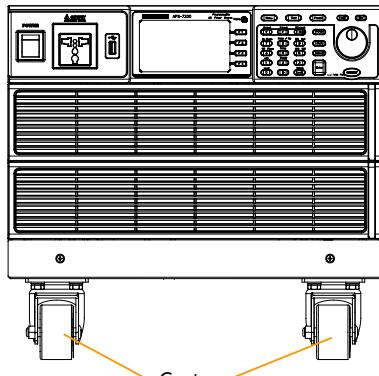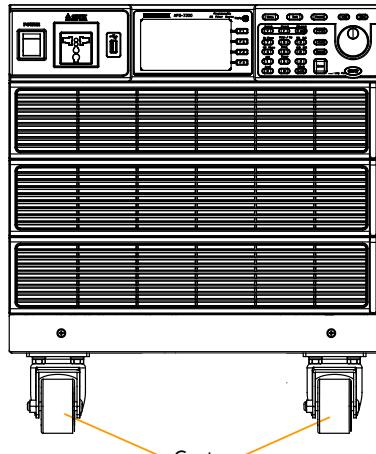
| Item | | Description |
|------|--|-------------|
| Power Switch | POWER | Turns on the mains power. |
| Front Voltage Output Socket | Neutral — Line GND △ OUTPUT AC 250V MAX. | Output voltage terminal using a regional universal plug. There is a Euro and a Universal regional plug. |
| | ⚠ CAUTION | Maximum allowable output voltage and current are 250Vrms and 10Arms. For voltages exceeding 250Vrms or current over 10Arms, please use the rear output terminal. |
| USB A Port | ⟵⟶ | The USB port is used for data transfers and upgrading software. |
| LCD Screen | | Displays the measured values or menu system. |
| Display Mode Select Key | Display ◯ | Selects between Standard mode and Simple mode. |
| Function Keys | F 1 | Assigned to the functions displayed on the right-hand side of the screen. |
| Menu Key | Menu | Enters the Main menu or goes back to one of the display modes. |

| Test Key | Test | Puts the instrument into the Sequence, Simulation and Program Control mode. |
|---|---|---|
| Preset Key | Preset | Puts the instrument into Preset mode. |
| Arrow Keys | ◁  ▷ | The arrow keys are used to select the digit power of a value that is being edited. |
| V | V-Limit / V | Used for setting the output voltage. |
| V-Limit | (Shift + V) | Used for setting the output voltage limit value. |
| F | F-Limit / F | Used for setting the output frequency. |
| F-Limit | (Shift + F) | Used for setting the output frequency limit value. |
| I rms | IPK-Limit / I rms | Used for setting the maximum output current. |
| IPK-Limit | (Shift + I rms) | Used to set the peak output current limit value. |
| Range Key | Range | Switches between the 155V, 310V and 600V ranges (the 600V range is an option). |
| Scroll Wheel | | Used to navigate menu items or for incrementing/decrementing values one step at a time. |
| Lock Key | Unlock / Lock | Locks the number pad to prevent accidentally changing panel settings. |
| Unlock Key | (Long press) | Disables the key lock. |
| Enter Key | Enter | Confirms selections / settings |

| | | |
|---|---|---|
| Cancel Key | ( Cancel ) | Clears entries that are made in the number entry dialog when a value is edited using the arrow keys or the scroll wheel. |
| | | The Cancel key can also be used to cancel function setting menus or dialogs. |
| Shift Key | ( Shift ) | Turns on the shift state, which enables shortcut operations. |
| Output Key | ( Output ) | Turns the output on or off. |
| Number Pad | | Used to enter values. |
| Local Mode | (Shift + 0) | Switches operation back to local mode from remote mode. |
| ARB Mode | (Shift + 1) | Sets the ARB function. |
| Trigger Mode | (Shift + 2) | Sets the JI port trigger behavior on the rear panel. |
| Off Phase | (Shift + 4) | Sets the off phase for the output voltage. |
| RAMP | (Shift + 5) | Quick settings for Ramp control. |
| ALM CLR | (Shift + 6) | Clears alarms. |
| On Phase | (Shift + 7) | Sets the on phase for the output voltage. |
| Surge/Dip | (Shift + 8) | Quick settings for Surge/Dip control. |
| IPK CLR | (Shift + 9) | Clears peak current hold. |

## Rear Panel

GPIB

Fan          Line voltage input          RS-232/
                                         USB Device

Opt. int. port

Sync

APS-7050

Signal Output          Rear panel voltage
                       output terminal

Remote control          Ethernet port

APS-7100                          Line voltage input

Ethernet port

Remote control                    USB port                    GPIB

Signal Output                                                   RS-232



Sync                                                            Optional
                                                               interface
                                                               port

                                                               Fan

Rear panel voltage                Circuit
output and                        breaker
sensing terminals                 (current)

APS-7200                          Line voltage input

Ethernet port

Remote control

USB port

Signal Output

GPIB

RS-232

Sync

Optional interface port

Fan

Rear panel voltage output and sensing terminals

Circuit breaker (current)

APS-7300

Line voltage input

| | | |
|---|---|---|
| Line Voltage Input | APS-7050 | Voltage Input: 115/230±15% VAC; Line frequency: 50Hz/60 Hz (Automatically switchable) |
| | APS-7100 | Voltage Input: 115/230±15% VAC ; Line frequency: 50Hz/60 Hz (Automatically switchable) |
| | APS-7200 & 7300 | Voltage Input: 230±15% VAC ; Line frequency: 50Hz/60 Hz |
| Rear Voltage Output Socket | Output voltage terminal. | |
| | APS-7050      APS-7100      APS-7200 & 7300 | |
| Sync Output Socket | SYNC | BNC socket. This socket will output a signal of approximately 10V when the output is on. |
| Signal Output | Signal output  APS-7050 APS-7100  APS-7200 APS-7300 | Connector for monitoring PASS, FAIL and PROCESSING output signals when using the Program mode. |
| Remote Control | Trigger In  Out On / Off  Trigger Out  COM  APS-7050 and APS-7100  Out On / Off  Trigger In  COM  Trigger Out  APS-7200 and APS-7300 | Connector for controlling the TRIGGER IN, TRIGGER OUT and OUT ON/OFF states. |

| Ethernet Port |  | The Ethernet port is used for remote control and digital monitoring from a PC. |
| Optional Interface Slot | | Optional GPIB communication, RS-232/USB B communication and RS-232 communication. |
| Circuit breaker (APS-7200, APS-7300 only) |  | Main power circuit (current) breaker<br>Rating : 40A (APS-7200)<br>　　　　　63A (APS-7300)<br>Note: Check the status of the power breaker before power-on the APS-7200 or APS-7300. |
| FAN | | Temperature controlled fan. |
| Remote sense (APS-7200, APS-7300 only) |  | Compensation of the load wire drop. |
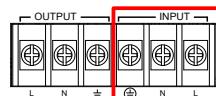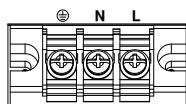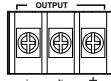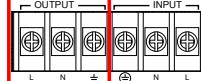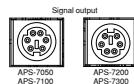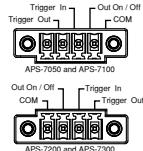
# REMOTE CONTROL

This chapter describes basic configuration of
IEEE488.2 based remote control.

# Interface Configuration

## USB Remote Interface – Optional (APS-7050 and APS-7100 only)

| USB configuration | PC side connector | Type A, host |
| --- | --- | --- |
| | APS-7000 side connector | Rear panel Type B, slave |
| | Speed | 1.1/2.0 (full speed/auto speed) |
| | USB Class | CDC (communications device class) |

⚠ Note
The RS-232/USB interface card (APS-002) must first be installed before the USB interface can be used for remote control. Please see the user manual for installation details.

Steps
1. Connect the Type A-Type B USB cable from the PC to the rear panel USB B port.

2. Press the *Menu* key. The Menu setting will appear on the display.

   Menu

3. Use the scroll wheel to go to item 6, *Rear USB* and press *Enter*.

4. Go to the *Speed* setting and set the USB speed.

   | Speed | Full, Auto |
   | --- | --- |

5. If the connection is successful *Connection Status* will change from Offline to Online.

Connection status



Speed settings
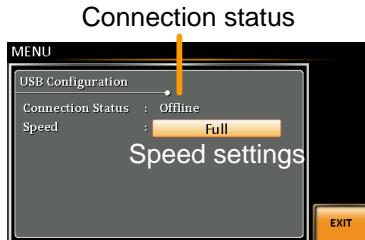
| Exit | 6. Press *Exit[F4]* to exit from the rear panel USB settings. | |
|------|------|------|

## RS-232 Remote Interface - Optional

The APS-002 RS-232/USB or APS-007 RS-232 interface card must be installed to remotely control the APS-7000 via the serial port.

| RS-232 configuration | Connector | BD-9, male |
|------|------|------|
| | Parameters | Baud rate, data bits, parity, stop bits. |

| Pin Assignment | 1 2 3 4 5 <br> 6 7 8 9 | 2: RxD (Receive data) <br> 3: TxD (Transmit data) <br> 5: GND <br> 4, 6 ~ 9: No connection |
|------|------|------|

| Pin Connection | Use a Null Modem connection (RS-232C cable) as shown in the diagram below. |
|------|------|
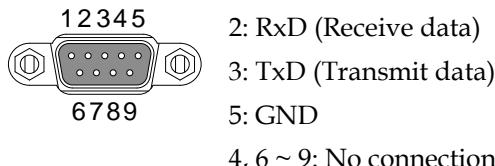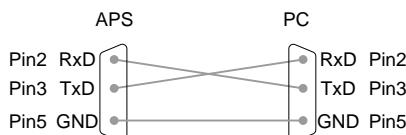
⚠ Note | The RS-232/USB (APS-002) or RS-232 (APS-007) must first be installed before the RS-232 interface can be used for remote control. Please see the user manual for installation details.

Steps

1. Connect the RS-232C cable from the PC to the rear panel RS-232 port.
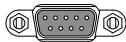
2. Press the *Menu* key. The Menu setting will appear on the display.

> Menu

3. Use the scroll wheel to go to item 7, *Serial Port* and press *Enter*.

4. Go to the *Function Active* setting and turn the serial port connection on.

| Function Active | ON, OFF |
|---|---|

5. Set the remaining serial port settings.

| Baud rate | 1200, 2400, 4800, 9600(default), 19200, 38400, 57600, 115200, |
|---|---|
| Data bits | 7, 8(default) |
| Parity | None(default), odd, even |
| Stop bits | 1(default),2 |

Serial port configuration
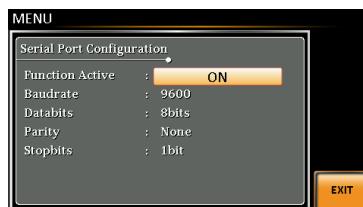
Exit

6. Press *Exit[F4]* to exit from the serial port settings.

`EXIT`

## RS-232/USB Remote Control Function Check

Functionality check

Invoke a terminal application such as Realterm.

For both USB and RS-232, set the COM port, baud rate, stop bit, data bit and parity accordingly. The RS-232 settings are configured on the APS-7000. The UART settings for the USB connection can be seen in the Windows Device Manager.

To check the COM settings in Windows, see the Device Manager. For example, in WinXP go to the  Control panel → System → Hardware tab.

⚠ Note

If you are not familiar with using a terminal application to send/receive remote commands from the serial port or via a USB connection, please page 26 for more information.

Run this query command via the terminal after the instrument has been configured for RS-232/USB remote control (page 23, 22).

*IDN?

This should return the Manufacturer, Model number, Serial number, and Software version in the following format.

GWINSTEK,APS-7050, GEXXXXXXX, XX.XX.XXXXXXXX

Manufacturer: GWINSTEK
Model number : APS-7050

Serial number : GEXXXXXXX
Software version : XX.XX.XXXXXXXX

## Using Realterm to Establish a Remote Connection

Background       Realterm is a terminal program that can be
                 used to communicate with a device attached to
                 the serial port of a PC or via an emulated serial
                 port via USB.

                 The following instructions apply to version
                 2.0.0.70. Even though Realterm is used as an
                 example to establish a remote connection, any
                 terminal program can be used that has similar
                 functionality.

⚠ Note           Realterm can be downloaded on Sourceforge.net
                 free of charge.

                 For more information please see
                 http://realterm.sourceforge.net/

Operation    1.  Download Realterm and install according to the
                 instructions on the Realterm website.

             2.  Connect the APS-7000 via USB (page 23) or via
                 RS-232 (page 22).

             3.  If using RS-232, make note of the configured
                 baud rate, stop bits and parity.

             4.  Go to the Windows device manager and find
                 the COM port number for the connection.
                 For example, go to the Start menu > Control
                 Panel > Device Manager.

                 Double click the *Ports* icon to reveal the
                 connected serial port devices and the COM port

for the each connected device.

If using USB, the baud rate, stop bit and parity settings can be viewed by right-clicking the connected device and selecting the *Properties* option.
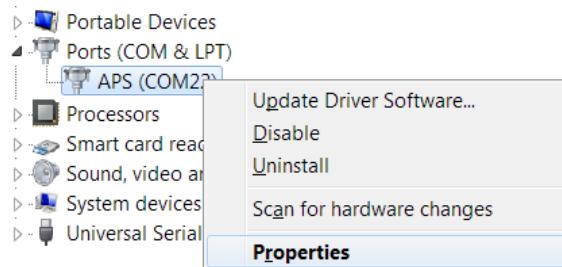


5. Start Realterm on the PC as an administrator. Click:
   Start menu>All Programs>RealTerm>realterm

   Tip: to run as an administrator, you can right click the Realterm icon in the Windows Start menu and select the *Run as Administrator* option.

6. After Realterm has started, click on the *Port* tab.

   Enter the *Baud\**, *Parity*, *Data bits*, *Stop bits* and *Port* number configuration for the connection.

   The *Hardware Flow Control*, *Software Flow Control* options can be left at the default settings.

   Press *Open* to connect to the APS-7000.
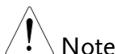
⚠️ Note          \*The baud must be set to 115200 when using USB to control the APS with RealTerm.
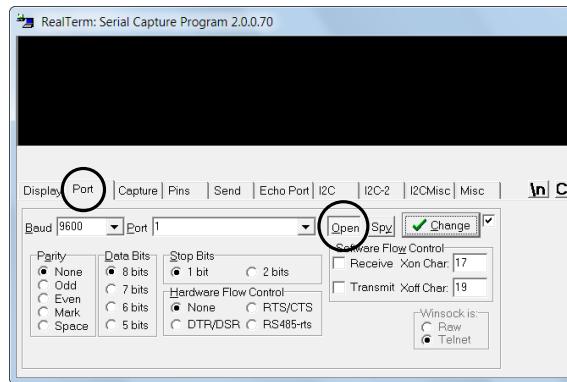
7.  Click on the *Send* tab.

    In the *EOL* configuration, check on the *+LF*
    check boxes.

    Enter the query:
    *\*idn?*

    Click on *Send ASCII*.
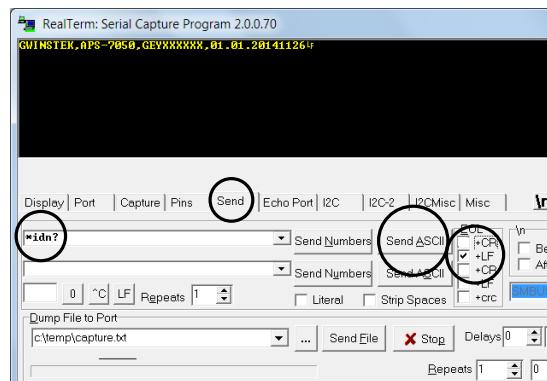
8. The terminal display will return the following:

   *GWINSTEK,APS-7050, GEXXXXXXX,*
   *XX.XX.XXXXXXXX*

   (manufacturer, model, serial number, software
   version)

9. If Realterm fails to connect to the APS-7000,
   please check all the cables and settings and try
   again.

## Configure GPIB Interface - Optional

To use GPIB, the optional APS-001 GPIB interface card must first be
installed.

| | |
|---|---|
| ⚠ Note | The GPIB interface card (APS-001) must first be installed before the GPIB interface can be used for remote control. Please see the user manual for installation details. |

| | |
|---|---|
| GPIB Configuration | 1. Connect a GPIB cable from the PC to the GPIB on the interface card. |
| | 2. Press the *Menu* key. The Menu setting will appear on the display. |
| | 3. Use the scroll wheel to go to item 8, *GPIB* and press *Enter*. |
| | 4. If the GPIB card is installed successfully, the *Card Status* will show *Plugged in*. |
| | 5. Go to the *Function Active* setting and turn the GPIB port on. |

| Function Active | ON, OFF |
|---|---|
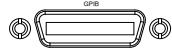
6. Set the GPIB address.

| GPIB Address | 0 ~ 30 |
|---|---|

GPIB port configuration
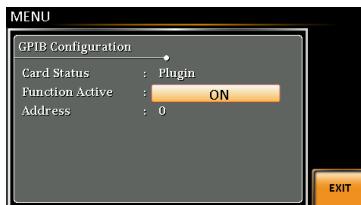


Exit

7. Press *Exit[F4]* to exit from the serial port settings.



GPIB constraints
- Maximum 15 devices altogether, 20m cable length, 2m between each device
- Unique address assigned to each device
- At least 2/3 of the devices turned On
- No loop or parallel connection

## GPIB Function Check

Functionality check

Please use the National Instruments Measurement & Automation Controller software to confirm GPIB/LAN functionality.

See the National Instrument website, http://www.ni.com for details.

Operation

1. Start the NI Measurement and Automation Explorer (MAX) program. Using Windows, press:

*Start>All Programs>NI MAX*
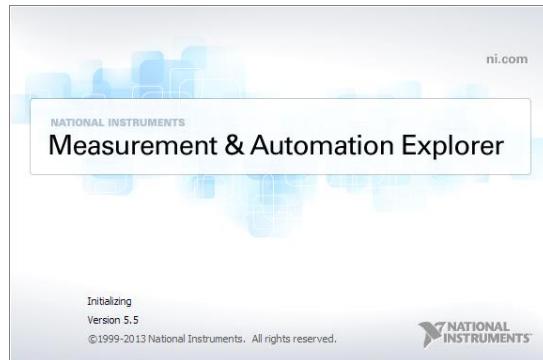


2. From the Configuration panel access;

   My System>Devices and Interfaces>GPIB0

3. Press the *Scan for Instruments* button.

4. In the *Connected Instruments* panel the APS-7000 should be detected as *Instrument 0* with the address the same as that configured on the APS-7000.

5. Double click the *Instrument 0* icon.
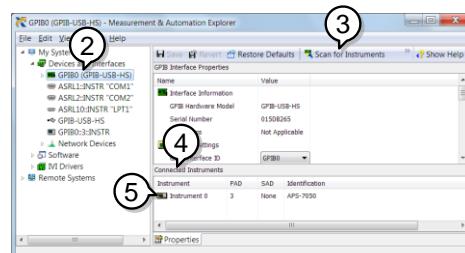


6. Click on *Visa Properties*.

7. Click on *Open Visa Test Panel*.
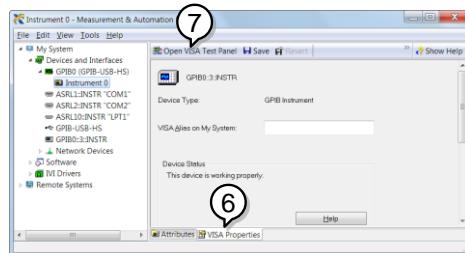
8.  Click on the *Input/Output* icon.

9.  Under the Basic I/O tab, ensure *\*IDN?* is written in the *Select or Enter Command* text box.

10. Click on the *Query* button to send the *\*IDN?* query to the instrument.

11. The instrument identification string will be returned to the buffer area:

    *GWINSTEK,APS-7050, GEXXXXXXX, XX.XX.XXXXXXXX*

    (manufacturer, model, serial number, software version)
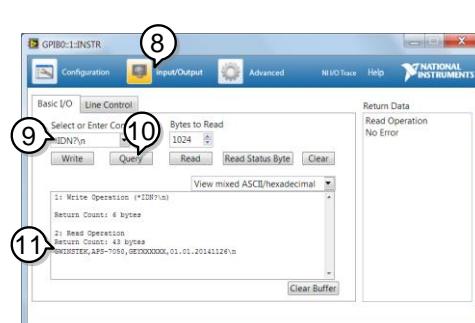


12. The function check is complete.

## Configure Ethernet Connection

The Ethernet interface can be configured for a number of different applications. Ethernet can be configured for basic remote control or monitoring using a web server or it can be configured as a socket server.

The APS-7000 supports both DHCP connections so the instrument can be automatically connected to an existing network or alternatively, network settings can be manually configured.

| Ethernet Parameters | MAC Address (display only) | DHCP |
|---|---|---|
| | IP Address | Subnet Mask |
| | Gateway | DNS Address |
| | DNS Server | Socket port fixed at 2268 |

| | |
|---|---|
| Ethernet Configuration | 1. Connect a LAN cable from the PC to the Ethernet port on the rear panel. |

2. Press the *Menu* key. The Menu setting will appear on the display.

[ Menu ]

3. Use the scroll wheel to go to item 5, *LAN* and press *Enter*.

4. If the LAN cable is installed correctly a connection is active, the *Connection Status* will show *Online*.

5. To automatically have the network assign an IP address, set DHCP to ON. Otherwise set DHCP to OFF to manually set the Ethernet settings.

| DHCP | ON, OFF |
|---|---|

6. If DHCP was set to OFF, configure the remaining LAN parameters.

| IP Address |
| --- |
| Subnet Mask |
| Gateway |
| DNS Server |

LAN configuration



Exit      7. Press *Exit[F4]* to exit from the LAN settings.

## Web Server Remote Control Function Check

Functionality
check

Enter the IP address of the power supply (for example: http:// XXX.XXX.XXX.XXX) in a web browser after the instrument has been configured for LAN(page 33).

The web interface allows you to:
- View the system and information and the network configuration.
- View the analog control pinout.
- View the dimensions of the unit.
- View the operating area

Example:

## Socket Server Function Check

| | |
|---|---|
| Background | To test the socket server functionality, National Instruments Measurement and Automation Explorer can be used. This program is available on the NI website, www.ni.com., via a search for the VISA Run-time Engine page, or "downloads" at the following URL, http://www.ni.com/visa/ |

| | |
|---|---|
| Requirements | Operating System: Windows XP, 7, 8, 8.1 |

| | |
|---|---|
| Functionality check | 1. Start the NI Measurement and Automation Explorer (MAX) program. Using Windows, press: |

*Start>All Programs>NI MAX*
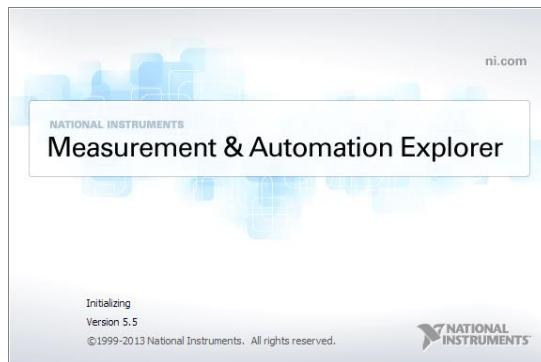


2. From the Configuration panel access;

*My System>Devices and Interfaces>Network Devices*

3. Press *Add New Network Device>Visa TCP/IP Resource…*
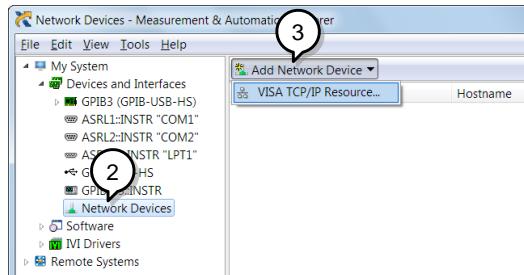
4. Select *Manual Entry of Raw Socket* from the popup window.
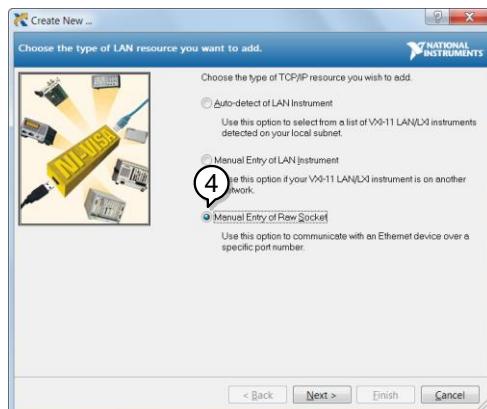


5. Enter the IP address and the port number of the APS-7000. The port number is fixed at 2268.

6. Double click the Validate button and press *Next*.
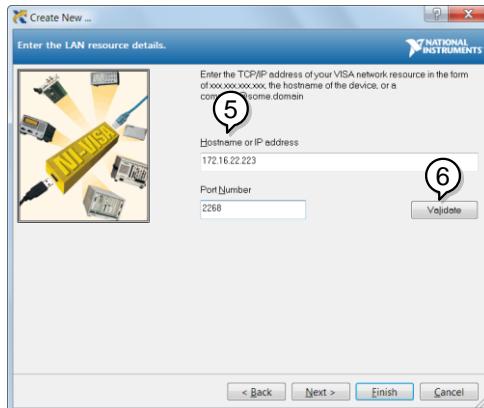
7.  Next configure the Alias (name) of the APS-7000 connection. In this example the Alias is: APS

8.  Click finish.
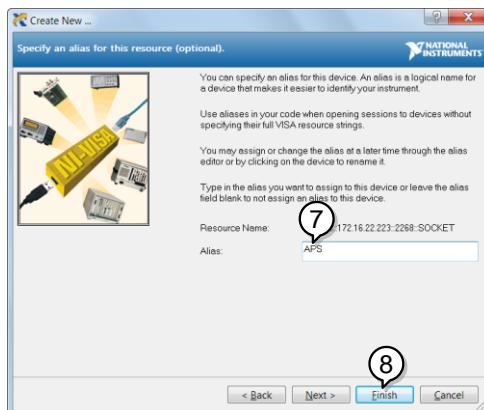


9.  The IP address of the power supply will now appear under Network Devices in the configuration panel. Select this icon now.

10. Press *Open VISA Test Panel.*
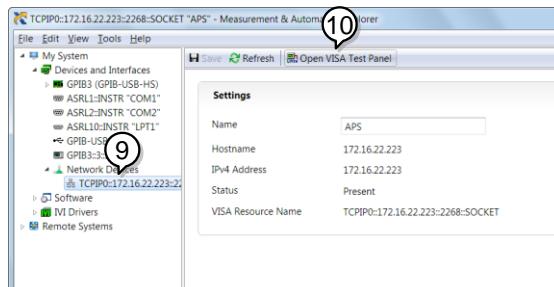
11. Click the *Configuration* Icon. Under the *IO Settings* tab check *Enable Termination Character*. The termination character should be set as *Line Feed - \ n*.
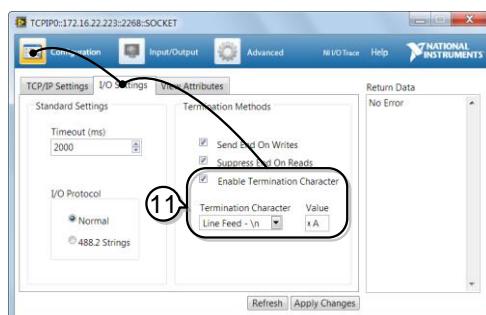


12. Click the *Input/Output* icon. Under the *Basic I/O* tab, make sure *\*IDN? \ n* is entered in the *Select or Enter Command* drop box.

13. Click Query.

    The APS-7000 will return the machine identification string into the buffer area: *GWINSTEK,APS-7050, GEXXXXXXX, XX.XX.XXXXXXXX*
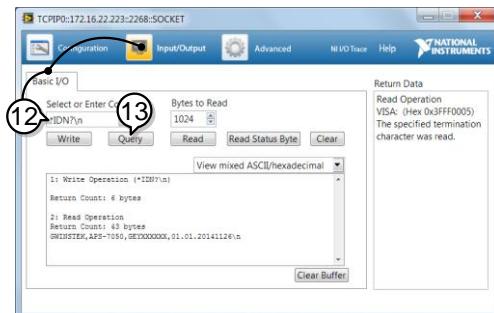
# Command Syntax

| Compatible Standard | IEEE488.2 | Partial compatibility |
|---|---|---|
| | SCPI, 1999 | Partial compatibility |

Command Structure

SCPI commands follow a tree-like structure, organized into nodes. Each level of the command tree is a node. Each keyword in a SCPI command represents each node in the command tree. Each keyword (node) of a SCPI command is separated by a colon (:).

For example, the diagram below shows an SCPI sub-structure and a command example.

```
          MEASure        MEASure:SCALar:FREQuency?
             |
          SCALar
             |
FREQuency  CURRent  VOLTage
             |         |
            RMS       RMS
```
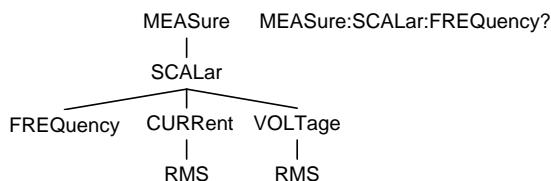
Command types

There are a number of different instrument commands and queries. A command sends instructions or data to the unit and a query receives data or status information from the unit.

Command types

| Simple | A single command with/without a parameter |
|---|---|
| Example | *IDN? |

| | | |
|---|---|---|
| Query | A query is a simple or compound command followed by a question mark (?). A parameter (data) is returned. | |
| Example | meas:curr? | |

| | | |
|---|---|---|
| Compound | Two or more commands on the same command line. Compound commands are separated with either a semi-colon (;) or a semi-colon and a colon (;:). | |
| | A semi-colon is used to join two related commands, with the caveat that the last command must begin at the last node of the first command. | |
| Example | meas:volt?;curr? | |
| | A semi-colon and colon are used to combine two commands from different nodes. | |
| Example | meas:volt?;:sour:volt? | |

| | |
|---|---|
| ⚠ Note (Further explanation) | A semi-colon(;) is used to connect two commands. A colon(:) at the start of a command indicates that the command starts from the root node. The first command can ignore that first colon. Any commands after the first command (for compound commands) that do not begin with a colon, must begin at the last node of the first command. |

Command Forms

Commands and queries have two different forms, long and short. The command syntax is written with the short form of the command in capitals and the remainder (long form) in lower case.

The commands can be written in capitals or lower-case, just so long as the short or long forms are complete. An incomplete command will not be recognized.

Below are examples of correctly written commands.

| | |
|---|---|
| Long form | :STATus:PRESet<br>:STATUS:PRESET<br>:status:preset |
| Short form | STAT:PRES<br>stat:pres |

Square Brackets

Commands that contain square brackets indicate that the contents are optional. The function of the command is the same with or without the square bracketed items, as shown below.

For example the query ":OUTPut[:STATe]?" has two valid forms, ":OUTPut:STATe?" and ":OUTPut?".

Command Format

HEADER P1,P2

1. Command header
2. Space
3. Parameter 1
4. Comma (no space before/after comma)
5. Parameter 2

| Parameters | Type | Description | Example |
|---|---|---|---|
| | <Boolean> | Boolean logic | 0, 1 |
| | <NR1> | integers | 0, 1, 2, 3 |
| | <NR2> | decimal numbers | 0.1, 3.14, 8.5 |
| | <NR3> | floating point | 4.5e-1, 8.25e+1 |
| | <NRf> | any of NR1, 2, 3 | 1, 1.5, 4.5e-1 |
| | <block data> | Definitive length arbitrary block data. A single decimal digit followed by data. The decimal digit specifies how many 8-bit data bytes follow. | |

| Message Terminator | LF | Line feed code | |
|---|---|---|---|

# Command List

## Abort Command

## :ABORt                                          ⟮ Set ⟯⟶

| Description | The ABORt command will cancel any triggered actions. |
|---|---|
| Syntax | :ABORt |

## IEEE 488.2 Common Commands

## *CLS                                          ⟮ Set ⟯⟶

| Description | The *CLS command clears all the event registers, including the status byte, event status and error queue. |
|---|---|
| Syntax | *CLS |

## *ESE

Set →
→ Query
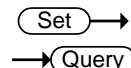
| Description | Sets or queries the Standard Event Status Enable register. | |
|---|---|---|
| Syntax | *ESE <NR1> | |
| Query Syntax | *ESE? | |
| Parameter | <NR1> | 0~255 |
| Return parameter | <NR1> | Returns the bit sum of the Standard Event Status Enable register. |

## *ESR

→ Query

| Description | Queries the Standard Event Status (Event) register. The Event Status register is cleared after it is read. | |
|---|---|---|
| Query Syntax | *ESR? | |
| Return parameter | <NR1> | Returns the bit sum of the Standard Event Status (Event) register and clears the register. |

## *IDN

→ Query

| Description | Queries the manufacturer, model name, serial number, and firmware version of the APS. | |
|---|---|---|
| Query Syntax | *IDN? | |
| Return parameter | <string> | Returns the instrument identification as a string in the following format: GWINSTEK,APS-7050,GEYXXXXXX,T1.01.20141009 Manufacturer: GW-INSTEK Model number : APS-7050 Serial number : GEYXXXXXX Firmware version : T01.01.2014109 |

## *OPC

Set →
→ Query
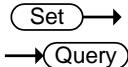
| | |
|---|---|
| Description | The *OPC command sets the OPC bit (bit0) of the Standard Event Status Register when all current commands have been processed. |
| | The *OPC? Query returns 1 when all the outstanding commands have completed. |
| Syntax | *OPC |
| Query Syntax | *OPC? |
| Return parameter | 1    Returns 1 when all the outstanding commands have completed. |

## *RCL

Set →

| | |
|---|---|
| Description | Recalls the contents stored in memory slot M0 ~ M9. These memory slots are mapped to the preset settings. |
| Syntax | *RCL {<NR1>\|MAX\|MIN} |
| Parameter | <NR1>   0 ~ 9 (as memory M0 ~ M9) |
| | MIN   Recalls the M0 memory contents. |
| | MAX   Recalls the M9 memory contents. |

## *RST

Set →

| | |
|---|---|
| Description | Performs a device reset. Configures the unit to a known configuration (default settings). This known configuration is independent of the usage history. |
| Syntax | *RST |

## *SAV                                                    Set ⟶

| | |
|---|---|
| Description | Saves the settings into memory slot M0 ~ M9. These memory slots are mapped to the preset settings. |
| Syntax | *SAV {<NR1>\|MIN\|MAX} |
| Return parameter | <NR1>    0 ~ 9 (as memory M0 ~ M9) |

## *SRE

Set ⟶
⟶ Query

| | |
|---|---|
| Description | Sets or queries the Service Request Enable register. The Service Request Enable register determines which registers of the Status Byte register are able to generate service requests. |
| Syntax | *SRE <NR1> |
| Query Syntax | *SRE? |
| Parameter | <NR1>    0~255 |
| Return parameter | <NR1>    Returns the bit sum of the Service Request Enable register. |

## *STB                                                    ⟶ Query

| | |
|---|---|
| Description | Queries the bit sum of the Status Byte register with MSS (Master summary Status) replacing the RQS bit (bit 6). |
| Query Syntax | *STB? |
| Return parameter | <NR1>    Returns the bit sum of the Status Byte register with the MSS bit (bit 6). |

## *TST                                                    ⟶ Query

| | |
|---|---|
| Description | Executes a self test. |
| Query Syntax | *TST? |

| Return parameter | 0 | Returns "0" if there are no errors. |
| --- | --- | --- |
| | <NR1> | Returns an error code <NR1> if there is an error. |

## *WAI                                    ⟨ Set ⟩⟶

| Description | Prevents any other commands or queries from being executed until all outstanding commands have completed. |
| --- | --- |
| Syntax | *WAI |

## *TRG                                    ⟨ Set ⟩⟶

| Description | The *TRG command is able to generate a "get" (Group Execute Trigger). If the unit cannot accept a trigger at the time of the command, an error message is generated (-211, "Trigger ignored"). |
| --- | --- |
| Syntax | *TRG |

## Data/Trace Commands

| ⚠ Note | The DATA and the TRACe node for the following commands are functionally equivalent. |
|---|---|

## :DATA|TRACe:SEQuence:CLEar ⟨ Set ⟩⟶

| Description | Clears the sequence data for the selected save memory (Seq0 ~ Seq9). |
|---|---|
| Syntax | :DATA|TRACe:SEQuence:CLEar {<NR1>|MINimum|MAXimum} |
| Parameter | <NR1>    0~9 <br> MIN    0 <br> MAX    9 |
| Example | :DATA:SEQ:CLE 1 <br><br> Clears the sequence data from Seq1. |

## :DATA|TRACe:SEQuence:RECall ⟨ Set ⟩⟶

| Description | Loads the sequence data. This command is the equivalent to recalling a sequence memory in the Sequence mode. |
|---|---|
| Syntax | :DATA|TRACe:SEQuence:RECall {<NR1>|MINimum|MAXimum} |
| Parameter | <NR1>    0~9 (Seq0 ~ Seq9). <br> MIN    0 <br> MAX    9 |

| Example | :DATA:SEQ:REC 1 |
|---|---|
| | Loads the data from Seq1. |

## :DATA|TRACe:SEQuence:STORe            ⟨ Set ⟩→

| Description | Saves the sequence data. This command is the equivalent to saving a sequence memory in Sequence mode. |
|---|---|
| Syntax | :DATA|TRACe:SEQuence:STORe {<NR1>|MINimum|MAXimum} |
| Parameter | <NR1>     0~9 (Seq0 ~ Seq9). |
| | MIN       0 |
| | MAX       9 |
| Example | :DATA:SEQ:STOR 1 |
| | Saves the data from Seq1. |

## :DATA|TRACe:SIMulation:CLEar            ⟨ Set ⟩→

| Description | Clears the simulation data for the selected save memory (SIM0 ~ SIM9). |
|---|---|
| Syntax | :DATA|TRACe:SIMulation:CLEar {<NR1>|MINimum|MAXimum} |
| Parameter | <NR1>     0~9 |
| | MIN       0 |
| | MAX       9 |
| Example | :DATA:SIM:CLE 1 |
| | Clears the simulation data from SIM1. |

## :DATA|TRACe:SIMulation:RECall            ⟨ Set ⟩→

| Description | Loads the simulation data. This command is the equivalent to recalling a simulation memory in the Simulation mode (SIM0~SIM9). |
|---|---|
| Syntax | :DATA|TRACe:SIMulation:RECall {<NR1>|MINimum|MAXimum} |

| Parameter | <NR1> | 0~9 (SIM0 ~ SIM9). |
|-----------|-------|---------------------|
|           | MIN   | 0 |
|           | MAX   | 9 |

| Example | :DATA:SIM:REC 1 |
|---------|------------------|
|         | Loads the data from SIM1. |

## :DATA|TRACe:SIMulation:STORe        $\boxed{\text{Set}}\longrightarrow$

| Description | Saves the simulation data. This command is the equivalent saving a simulation memory in Simulation mode (SIM0 ~ SIM9). |
|-------------|----------------|

| Syntax | :DATA|TRACe:SIMulation:STORe {<NR1>|MINimum|MAXimum} |
|--------|-------------|

| Parameter | <NR1> | 0~9 (SIM0 ~ SIM9). |
|-----------|-------|---------------------|
|           | MIN   | 0 |
|           | MAX   | 9 |

| Example | :DATA:SIM:STOR 1 |
|---------|-------------------|
|         | Saves the data from SIM1. |

## Initiate Commands

## :INITiate[:IMMediate]:NAME                    ⬚Set ⟶

| | | |
|---|---|---|
| Description | The INITiate command starts the TRANsient, OUTPut, MEMory or SDIP (surge/dip) trigger. | |
| Syntax | :INITiate[:IMMediate]:NAME {TRANsient\|OUTPut\|MEMory\|SDIP} | |
| Parameter | TRANsient | Starts the TRANsient trigger. |
| | OUTPut | Starts the OUTput trigger. |
| | MEMory | Starts the MEMory trigger. |
| | SDIP | Starts the (SDIP) Surge/Dip trigger. |
| Example | :INIT:NAME TRAN | |
| | Starts the transient trigger. | |

## :INITiate[:IMMediate][:TRANsient]             ⬚Set ⟶

| | |
|---|---|
| Description | This command controls the enabling of output triggers. When a trigger is enabled, a trigger causes the specified action to occur. If the trigger system is not enabled, all triggers are ignored. |
| Syntax | :INITiate[:IMMediate][:TRANsient] |
| Example | :INIT |

## Measure Commands

## :MEASure[:SCALar]:CURRent:CFACtor    → (Query)

| | |
|---|---|
| Description | Returns the output current crest factor. |
| Query syntax | :MEASure[:SCALar]:CURRent:CFACtor? |
| Return parameter | <NR2>       Returns the crest factor. |

## :MEASure[:SCALar]:CURRent:HIGH    → (Query)

| | |
|---|---|
| Description | Returns the output current maximum peak value (Ipk). |
| Note: | Current maximum peak value is defined as the highest peak value in the complete period. |
| Syntax | :MEASure[:SCALar]:CURRent:HIGH? |
| Return parameter | <NR2>       Returns the current in amps. |

## :MEASure[:SCALar]:CURRent:PEAK:CLEar    (Set)→

| | |
|---|---|
| Description | Clears the current peak-hold value. |
| Syntax | :MEASure[:SCALar]:CURRent:PEAK:CLEar |

## :MEASure[:SCALar]:CURRent:PEAK:HOLD  → Query

| | |
|---|---|
| Description | Returns the current peak hold value in amps (Ipk). |
| Syntax | :MEASure[:SCALar]:CURRent:PEAK:HOLD? |
| Return | <NR2>  Returns the peak hold value in amps. |

## :MEASure[:SCALar]:CURRent[:RMS]  → Query

| | |
|---|---|
| Description | Returns the output current (Irms). |
| Syntax | :MEASure[:SCALar]:CURRent[:RMS]? |
| Return | <NR2>  Returns the Irms. |

## :MEASure[:SCALar]:CURRent:RANGe  Set → → Query

| | | |
|---|---|---|
| Description | Sets or queries the current range. | |
| Syntax | :MEASure[:SCALar]:CURRent:RANGe? | |
| Query Syntax | {AUTO|R0A28|R1A40|R14A0|R70A0| R140A} | |
| Parameter/ | AUTO | Auto range. |
| Return parameter | R0A28 | 0.28A range (APS-7050, APS-7100 only) |
| | R1A40 | 1.4A range (APS-7050, APS-7100 only) |
| | R14A0 | 14A range |
| | R70A0 | 70A range (APS-7050, APS-7100 only) |
| | R140A | 140A range (APS-7200, APS-7300 only) |
| Example | :MEAS:SCAL:CURR:RANG AUTO | |
| | Sets the current range to Auto range. | |

## :MEASure[:SCALar]:FREQuency  → Query

| | |
|---|---|
| Description | Returns the SYNC signal source frequency in Hz. |
| Syntax | :MEASure[:SCALar]:FREQuency? |
| Return | <NR2>  Returns the SYNC frequency in Hz. (500Hz or 999.9Hz(with option)) |

## :MEASure[:SCALar]:POWer[:AC]:APParent    →(Query)

| Description | Returns the apparent power (VA). | |
|---|---|---|
| Syntax | :MEASure[:SCALar]:POWer[:AC]:APParent? | |
| Return | <NR2> | Returns the apparent power in VA. |

## :MEASure[:SCALar]:POWer[:AC]:PFACtor    →(Query)

| Description | Returns the power factor. | |
|---|---|---|
| Syntax | :MEASure[:SCALar]:POWer[:AC]:PFACtor? | |
| Return | <NR2> | Returns the power factor. |

## :MEASure[:SCALar]:POWer[:AC]:REACtive    →(Query)

| Description | Returns the reactive power (VAR). | |
|---|---|---|
| Syntax | :MEASure[:SCALar]:POWer[:AC]:REACtive? | |
| Return | <NR2> | Returns the reactive power in VAR. |

## :MEASure[:SCALar]:POWer[:AC][:REAL]    →(Query)

| Description | Returns the active power in Watts. | |
|---|---|---|
| Syntax | :MEASure[:SCALar]:POWer[:AC][:REAL]? | |
| Return | <NR2> | Returns the power in W. |

## :MEASure[:SCALar]:VOLTage[:RMS]    →(Query)

| Description | Returns the voltage (Vrms). | |
|---|---|---|
| Syntax | :MEASure[:SCALar]:VOLTage[:RMS]? | |
| Return | <NR2> | Returns the voltage in Vrms. |

## Memory Commands

### :MEMory:SAV                                      ⸢ Set ⸣ ⟶

| | |
|---|---|
| Description | Saves the settings into memory slot M0 ~ M9. These memory slots are mapped to the preset settings. Equivalent to the *SAV command. |
| Syntax | :MEMory:SAV {<NR1>\|MINimum\|MAXimum} |
| Parameter | <NR1>    0~9<br>MINimum  0<br>MAXimum  9 |
| Example | :MEMory:SAV 1 |
| | Save the settings to M1. |

### :MEMory:RCL                                      ⸢ Set ⸣ ⟶

| | |
|---|---|
| Description | Recalls the settings from memory slot M0~M9. These memory slots are mapped to the preset settings. Equivalent to the *RCL command. |
| Syntax | :MEMory:RCL {<NR1>\|MINimum\|MAXimum} |
| Parameter | <NR1>    0~9<br>MINimum  0<br>MAXimum  9 |
| Example | :MEMory:RCL |
| | Recall the settings to M1. |

Set →

:MEMory:TRIGgered                          → Query
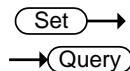
| Description | Recalls the selected memory (M0 ~ M9) when receiving an input trigger. These memory slots are mapped to the preset settings. |
|---|---|
| Syntax | :MEMory:TRIGgered {<NR1>\|MINimum\|MAXimum} |
| Query Syntax | :MEMory:TRIGgered? |

| Parameter/ Return parameter | <NR1> | 0 ~ 9 |
|---|---|---|
| | MIN | 0 |
| | MAX | 9 |

| Example | :MEMory:TRIGgered 1 |
|---|---|
| | Recalls M1 when an input trigger is received. |

## Output Commands

### :OUTPut:PON

<div align="right">

Set ⟶
⟶ Query

</div>
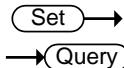
| | |
|---|---|
| Description | Sets the output state at power-on. |
| Syntax | :OUTPut:PON {<bool>|OFF|ON} |
| Return Syntax | :OUTPut:PON? |

| Parameter | OFF \| 0 | Disabled |
|---|---|---|
| | ON \| 1 | Enabled |
| Return parameter | <bool> | Returns the power-on state. |

### :OUTPut:PROTection:CLEar

<div align="right">

Set ⟶

</div>

| | |
|---|---|
| Description | Clears the protection circuits (OCP, OTP). |
| Syntax | :OUTPut:PROTection:CLEar |

### :OUTPut[:STATe]

<div align="right">

Set ⟶
⟶ Query

</div>

| | |
|---|---|
| Description | Sets or queries the output state of power source. |
| Syntax | :OUTPut[:STATe] {<bool>|OFF|ON} |
| Query Syntax | :OUTPut[:STATe]? |

| Parameter | OFF \| 0 | Turns the output off. |
|---|---|---|
| | ON \| 1 | Turns the output on. |
| Return parameter | <bool> | Returns output status of the instrument. |

| :OUTPut[:STATe]:TRIGgered | Set → |
| | → Query |

| Description | Turns the output on/off when a trigger has been generated. |
|---|---|
| Syntax | :OUTPut[:STATe]:TRIGgered {<bool>|OFF|ON} |
| Query Syntax | :OUTPut[:STATe]:TRIGgered? |
| Parameter/ Return parameter | OFF \| 0   Turns the output off when a trigger is generated. <br> ON \| 1   Turns the output on when a trigger is generated. |
| Example | The following example shows how to configure and trigger the output trigger: <br><br> :SYSTem:CONFigure:TRIGger:INPut:SOURce NONE <br> :TRIGger:OUTPut:SOURce BUS (*TRG) <br><br> After you receive a trigger from the trigger source, you can then turn the output ON/OFF: <br> :OUTPut[:STATe]:TRIGgered <bool>\|OFF\|ON <br> :INITiate[:IMMediate]:NAME OUTPut <br> Lastly send a *TRG or trigger input. |
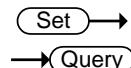
## Status Commands

For an overview of all the status registers, their associated register contents and the system diagram, please see the status overview on page 123

## :STATus:OPERation:CONDition  ➔ Query

| | |
|---|---|
| Description | Queries the Operation Status register. This query will not clear the register. |
| Syntax | :STATus:OPERation:CONDition? |
| Return | <NR1> Returns the bit sum of the Operation Condition register. (0~32767) |
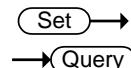
## :STATus:OPERation:ENABle

Set ⟶
⟶ Query

| Description | Sets or queries the bit sum of the Operation Status Enable register. |
|---|---|
| Syntax | :STATus:OPERation:ENABle \<NR1\> |
| Query Syntax | :STATus:OPERation:ENABle? |
| Parameter | \<NR1\> | 0~32767 |
| Return parameter | \<NR1\> | 0~32767 |

## :STATus:OPERation[:EVENt]

⟶ Query

| Description | Queries the Operation Status Event register and clears the contents of the register. |
|---|---|
| Syntax | :STATus:OPERation[:EVENt]? |
| Return | \<NR1\> | Returns the bit sum of the Operation Status Event register. |

## :STATus:OPERation:NTRansition
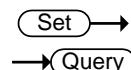
Set ⟶
⟶ Query

| Description | Sets or queries the bit sum of the negative transition filter of the Operation Status register. |
|---|---|
| Syntax | :STATus:OPERation:NTRansition \<NR1\> |
| Query Syntax | :STATus:OPERation:NTRansition? |
| Parameter | \<NR1\> | 0~32767 |
| Return parameter | \<NR1\> | 0~32767 |
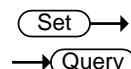
## :STATus:OPERation:PTRansition

Set ⟶
⟶ Query

| Description | Sets or queries the bit sum of the positive transition filter of the Operation Status register. |
|---|---|
| Syntax | :STATus:OPERation:PTRansition \<NR1\> |
|  | :STATus:OPERation:PTRansition? |
| Parameter | \<NR1\> | 0~32767 |
| Return parameter | \<NR1\> | 0~32767 |

## :STATus:QUEStionable[:EVENt]      →( Query )

| | |
|---|---|
| Description | Queries the bit sum of the Questionable Status Event register. This query will also clear the contents of the register. |
| Query Syntax | :STATus:QUEStionable[:EVENt]? |
| Return parameter | <NR1>    0~32767 |

## :STATus:QUEStionable:CONDition      →( Query )

| | |
|---|---|
| Description | Queries the status (bit sum) of the Questionable Status register. This query will not clear the register. |
| Query Syntax | :STATus:QUEStionable:CONDition? |
| Return parameter | <NR1>    0~32767 |

## :STATus:QUEStionable:ENABle      ( Set )→
                                   →( Query )

| | |
|---|---|
| Description | Sets or queries the bit sum of the Questionable Status Enable register. |
| Syntax | :STATus:QUEStionable:ENABle <NR1> |
| Query Syntax | :STATus:QUEStionable:ENABle? |
| Parameter | <NR1>    0~32767 |
| Return parameter | <NR1>    0~32767 |
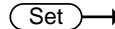
## :STATus:QUEStionable:NTRansition      ( Set )→
                                        →( Query )

| | |
|---|---|
| Description | Sets or queries the bit sum of the negative transition filter of the Questionable Status register. |
| Syntax | :STATus:QUEStionable:NTRansition <NR1> |
| Query Syntax | :STATus:QUEStionable:NTRansition? |

| Parameter | \<NR1\> | 0~32767 |
|-----------|---------|---------|
| Return parameter | \<NR1\> | 0~32767 |
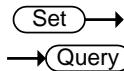
## :STATus:QUEStionable:PTRansition

Set →
→ Query

| Description | Sets or queries the bit sum of the positive transition filter of the Questionable Status register. |
|-------------|------------------------------------------------------|
| Syntax | :STATus:QUEStionable:PTRansition \<NR1\> |
| Return Syntax | :STATus:QUEStionable:PTRansition? |
| Parameter | \<NR1\> | 0~32767 |
| Return parameter | \<NR1\> | 0~32767 |

## :STATus:PRESet

Set →

| Description | This command resets the ENABle register, the PTRansistion filter and NTRansistion filter on the Operation Status, Questionable Status and Warning Status Registers. The registers/filters will be reset to a default value. |
|-------------|------------------------------------------------------|

| Default Register/Filter Values | Setting |
|--------------------------------|---------|
| QUEStionable Status Enable | 0x0000 |
| QUEStionable Status Positive Transition | 0x7FFF |
| QUEStionable Status Negative Transition | 0x0000 |
| Operation Status Enable | 0x0000 |
| Operation Status Positive Transition | 0x7FFF |
| Operation Status Negative Transition | 0x0000 |
| WARNing Status Enable | 0x0000 |
| WARNing Status Positive Transition | 0x7FFF |
| WARNing Status Negative Transition | 0x0000 |

Summary: The Questionable Status Enable registers, the Operation Status Enable registers and Warning Status registers are both reset to 0.

The Questionable Status, Operation Status and Warning Positive Transition filters are all set high (0x7FFF) and the Negative Transition filters are all set low (0x0000).  I.e., only positive transitions will be recognized for the Questionable Status, Operation Status and Warning Status registers.

| Syntax | :STATus:PRESet |
|---|---|

## :STATus:WARNing:CONDition      ➔ Query

| Description | Queries the Warning Status register. This query will not clear the register. |
|---|---|
| Syntax | :STATus:WARNing:CONDition? |
| Return | <NR1> | Returns the bit sum of the Warning Condition register. (0~32767) |

## :STATus:WARNing:ENABle      Set ➔    ➔ Query

| Description | Sets or queries the bit sum of the Warning Status Enable register. |
|---|---|
| Syntax | :STATus:WARNing:ENABle <NR1> |
| Query Syntax | :STATus:WARNing:ENABle? |
| Parameter | <NR1> | 0~32767 |
| Return parameter | <NR1> | 0~32767 |

## :STATus:WARNing[:EVENt] → Query

| | |
|---|---|
| Description | Queries the Warning Status Event register and clears the contents of the register. |
| Syntax | :STATus:WARNing[:EVENt]? |
| Return | <NR1> Returns the bit sum of the Warning Status Event register. |
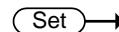
Set →
## :STATus:WARNing:NTRansition → Query

| | |
|---|---|
| Description | Sets or queries the bit sum of the negative transition filter of the Warning Status register. |
| Syntax | :STATus:WARNing:NTRansition <NR1> |
| Query Syntax | :STATus:WARNing:NTRansition? |
| Parameter | <NR1> 0~32767 |
| Return parameter | <NR1> 0~32767 |

Set →
## :STATus:WARNing:PTRansition → Query

| | |
|---|---|
| Description | Sets or queries the bit sum of the positive transition filter of the Warning Status register. |
| Syntax | :STATus:WARNing:PTRansition <NR1> |
| | :STATus:WARNing:PTRansition? |
| Parameter | <NR1> 0~32767 |
| Return parameter | <NR1> 0~32767 |

## System Function Command

Set ⟶
⟶ Query

## :SYSTem:BEEPer:STATe

| Description | Sets or queries the buzzer state on/off. |
|---|---|
| Syntax | :SYSTem:BEEPer:STATe {<bool>|OFF|ON} |
| Query Syntax | :SYSTem:BEEPer:STATe? |
| Parameter | OFF \| 0   Turns the buzzer off. <br> ON \| 1   Turns the buzzer on. |
| Return parameter | <bool>   Returns the buzzer status. |

## :SYSTem:COMMunicate:GPIB[:SELF] :ADDRess

Set ⟶
⟶ Query
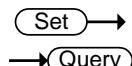
| Description | Sets or queries the GPIB address. |
|---|---|
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:GPIB[:SELF]:ADDRess <NR1> |
| Query Syntax | :SYSTem:COMMunicate:GPIB[:SELF]:ADDRess? |
| Parameter/Return | <NR1>   0~30 |
| Example | SYST:COMM:GPIB:ADDR 15 <br> Sets the GPIB address to 15. |

Set ⟶
⟶ Query

## :SYSTem:COMMunicate:LAN:DHCP
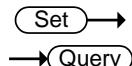
| Description | Turns DHCP on/off. Queries the DHCP status. |
|---|---|

| Note: | The setting will only be valid after the power has been cycled. |
|---|---|
| Syntax | :SYSTem:COMMunicate:LAN:DHCP {<bool>\|OFF\|ON} |
| Query Syntax | :SYSTem:COMMunicate:LAN:DHCP? |
| Parameter | OFF \| 0   DHCP off |
| | ON \| 1   DHCP on |
| Return parameter | <bool>   Returns the DHCP status. |

Set  →
:SYSTem:COMMunicate:LAN:DNS      → Query
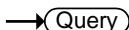
| Description | Sets or queries the DNS address. |
|---|---|
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:LAN:DNS <string> |
| Query Syntax | :SYSTem:COMMunicate:LAN:DNS? |
| Parameter/Return | <string>   DNS in string format ("mask") Applicable ASCII characters: 20H to 7EH |
| Example | SYST:COMM:LAN:DNS "172.16.1.252" Sets the DNS to 172.16.1.252. |

Set  →
:SYSTem:COMMunicate:LAN:GATEway      → Query
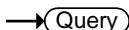
| Description | Sets or queries the Gateway address. |
|---|---|
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:LAN:GATEway <string> |
| Query Syntax | :SYSTem:COMMunicate:LAN:GATEway? |
| Parameter/Return | <string>   Gateway address in string format ("address") Applicable ASCII characters: 20H to 7EH |
| Example | SYST:COMM:LAN:GATE "172.16.0.254" Sets the LAN gateway to 172.16.0.254. |

Set  →
:SYSTem:COMMunicate:LAN:IPADdress      → Query
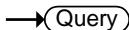
| | |
|---|---|
| Description | Sets or queries LAN IP address. |
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:LAN:IPADdress <string> |
| Query Syntax | :SYSTem:COMMunicate:LAN:IPADdress? |
| Parameter/Return | <string>   LAN IP address in string format ( "address")<br>Applicable ASCII characters: 20H to 7EH |
| Example | SYST:COMM:LAN:IPAD "172.16.5.111"<br>Sets the IP address to 172.16.5.111. |

## :SYSTem:COMMunicate:LAN:MAC      � Query

| | |
|---|---|
| Description | Returns the unit MAC address as a string. The MAC address cannot be changed. |
| Query Syntax | :SYSTem:COMMunicate:LAN:MAC? |
| Return parameter | <string>   Returns the MAC address in the following format "FF-FF-FF-FF-FF-FF" |
| Example | SYST:COMM:LAN:MAC?<br>02-80-AD-20-31-B1<br>Returns the MAC address. |

Set ➜
## :SYSTem:COMMunicate:LAN:SMASk    ➜ Query

| | |
|---|---|
| Description | Sets or queries the LAN subnet mask. |
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:LAN:SMASk <string> |
| Query Syntax | :SYSTem:COMMunicate:LAN:SMASk? |
| Parameter/Return | <string>   Subnet mask in string format ( "mask")<br>Applicable ASCII characters: 20H to 7EH |
| Example | SYST:COMM:LAN:SMASk "255.255.0.0"<br>Sets the LAN mask to 255.255.0.0. |

Set ➜
## :SYSTem:COMMunicate:RLSTate    ➜ Query
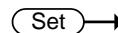
| Description | Enables or disables local/remote state of the instrument. |
|---|---|
| Syntax | :SYSTem:COMMunicate:RLSTate {LOCal|REMote|RWLock} |
| Query Syntax | :SYSTem:COMMunicate:RLSTate? |

| Parameter/Return parameter | LOCal | All keys are valid. This instrument is controlled by the front panel controls. |
|---|---|---|
| | REMote | All keys are invalid, except for the [local] key and the ability to turn the output off. |
| | RWLock | All keys are invalid. The instrument can only be controlled remotely. |

| Example | :SYST:COMM:RLST LOCAL <br> Sets the operating mode to local. |
|---|---|

## :SYSTem:COMMunicate:SERial[:RECeive] :TRANsmit:BAUD    ⬤Set⟶   ⟶⬤Query

| Description | Sets or queries the UART baud rate. |
|---|---|
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit :BAUD <NR1> |
| Query Syntax | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit :BAUD? |
| Parameter/Return | <NR1> | 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200 |
| Example | SYST:COMM:SER:TRAN:BAUD? <br> >2400 <br> Returns the baud rate settings. |

## :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit:BITS

Set →
→ Query

| | |
|---|---|
| Description | Sets or queries the UART number of data bits. |
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit:BITS <NR1> |
| Query Syntax | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit:BITS? |

| Parameter | 0 | 7 bits |
|---|---|---|
| | 1 | 8 bits |

| Return parameter | +0 | 7 bits |
|---|---|---|
| | +1 | 8 bits |

| Example | SYST:COMM:SER:TRAN:BITS? |
|---|---|
| | >+1 |
| | Indicates that 8 data bits are used for the UART connection. |

## :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit:PARity

Set →
→ Query

| | |
|---|---|
| Description | Sets or queries the parity of the UART connection. |
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax<br>Query Syntax | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit:PARity {NONE|ODD|EVEN} |
| | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit:PARity? |

| Parameter | NONE | No parity |
|---|---|---|
| | ODD | Odd parity |
| | EVEN | Even parity |

| Return parameter | +0 | No parity |
|---|---|---|
| | +1 | Odd parity |
| | +2 | Even parity |

| Example | SYST:COMM:SER:TRAN:PARity? |
|---|---|
| | >+0 |
| | Indicates that no parity is used for the UART connection. |

## :SYSTem:COMMunicate:SERial[:RECeive] :TRANsmit:SBITs

(Set) →
→ (Query)

| Description | Sets or queries the number of stop bits used for the UART connection. |
|---|---|
| Note: | The setting will only be valid after the power has been cycled. |
| Syntax | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit :SBITs <NR1> |
| Query Syntax | :SYSTem:COMMunicate:SERial[:RECeive]:TRANsmit :SBITs? |
| Parameter | 0   1 stop bit |
| | 1   2 stop bits |
| Return parameter | +0  1 stop bit |
| | +1  2 stop bits |
| Example | SYST:COMM:SER:TRAN:SBITs? |
| | >+1 |
| | Indicates that one stop bit is used for the UART connection. |

## :SYSTem:COMMunicate:TCPip:CONTrol

→ (Query)

| Description | Queries the socket port number. |
|---|---|
| Query Syntax | :SYSTem:COMMunicate:TCPip:CONTrol? |
| Return parameter | <NR1>  0000 ~ 9999 |
| Example | SYST:COMM:TCP:CONT? |
| | >2268 |
| | Returns the socket port number. |

## :SYSTem:COMMunicate:USB:FRONt:STATe

→ (Query)

| Description | Queries the front panel USB-A port state. |
|---|---|

| Query Syntax | :SYSTem:COMMunicate:USB:FRONt:STATe? | |
|---|---|---|
| Return parameter | +0 | <NR1>Absent |
| | +1 | <NR1>Mass Storage |

Set →

## :SYSTem:COMMunicate:USB:REAR:MODE → Query

| Description | Sets or queries the speed of the rear panel USB B port. This setting is applied only after the unit is reset. | |
|---|---|---|
| Syntax | :SYSTem:COMMunicate:USB:REAR:MODE {<NR1>\|AUTO\|FULL} | |
| Query Syntax | :SYSTem:COMMunicate:USB:REAR:MODE? | |
| Parameter | 0 \| AUTO | AUTO |
| | 1 \| FULL | FULL |
| Return parameter | <NR1> | |
| | +0 | AUTO |
| | +1 | FULL |

## :SYSTem:COMMunicate:USB:REAR:STATe → Query

| Description | Queries the rear panel USB-B port state. | |
|---|---|---|
| Query Syntax | :SYSTem:COMMunicate:USB:REAR:STATe? | |
| Return parameter | +0 | <NR1>Absent |
| | +1 | <NR1>Connected to the PC |

Set →

## :SYSTem:CONFigure:RAMP[:MODE] → Query

| Description | Sets or queries the ramp mode for the power supply or disables the ramp mode. | |
|---|---|---|
| Syntax | :SYSTem:CONFigure:RAMP[:MODE] {<NR1>\|DISable\|TIME\|VOLTage} | |
| Query Syntax | :SYSTem:CONFigure:RAMP[:MODE]? | |
| Parameter | 0 \| DISable | Disables ramp mode. |
| | 1 \| TIME | Time mode |
| | 2 \| VOLTage | Voltage mode |

| Return parameter | <NR1> | |
|---|---|---|
| | +0 | Ramp mode is disabled. |
| | +1 | Time mode |
| | +2 | Voltage mode |

⊂ Set ⊃ →

## :SYSTem:CONFigure:RAMP:VOLTage → Query

| Description | Sets or queries the ramp Vup and Vdn parameters. |
|---|---|
| Syntax | :SYSTem:CONFigure:RAMP:VOLTage[:LEVel][:AMPLitude] {<NR2>|MINimum|MAXimum,<NR2>|MINimum|MAXimum} |
| Query Syntax | :SYSTem:CONFigure:RAMP:VOLTage[:LEVel][:AMPLitude]? [MINimum|MAXimum] |

| Parameter | <NR2> | Vup (Vrms). |
|---|---|---|
| | MINimum | Minimum Vup. |
| | MAXimum | Maximum Vdn. |
| | <NR2> | Vdn (Vrms). |
| | MINimum | Minimum Vup. |
| | MAXimum | Maximum Vdn. |
| Return parameter | <NR2>,<NR2> | Returns the Vup,Vdn voltage levels. |
| Example | :SYST:CONF:RAMP:VOLT? | |
| | >+0.2000,+0.3000 | |
| | Returns the Vup,Vdn values. | |

⊂ Set ⊃ →

## :SYSTem:CONFigure:RAMP:TIME → Query

| Description | Sets or queries the ramp Tup and Tdn parameters. |
|---|---|
| Syntax | :SYSTem:CONFigure:RAMP:TIME {<NR2>|MINimum|MAXimum,<NR2>|MINimum|MAXimum} |
| Query Syntax | :SYSTem:CONFigure:RAMP:TIME? [MINimum|MAXimum] |

| Parameter | <NR2> | Tup in milliseconds |
| --- | --- | --- |
| | MINimum | Minimum Tup |
| | MAXimum | Maximum Tup |
| | <NR2> | Tdn in milliseconds |
| | MINimum | Minimum Tdn |
| | MAXimum | Maximum Tdn |
| Return parameter | <NR2>,<NR2> | Returns the Tup,Tdn time. |
| Example | :SYST:CONF:RAMP:TIME? | |
| | >+3.0000,+4.0000 | |
| | Returns the Tup,Tdn values. | |

Set →

## :SYSTem:CONFigure[:MODE]                    → Query

| Description | Sets or queries the test mode for the power supply. |
| --- | --- |
| Syntax | :SYSTem:CONFigure[:MODE] {<NR1>\|CONTinuous\|SEQuence\|SIMulation\|PROGram} |
| Query Syntax | :SYSTem:CONFigure[:MODE]? |

| Parameter | 0 \| CONTinuous | Continuous mode (normal operating mode) |
| --- | --- | --- |
| | 1 \| SEQuence | Sequence mode |
| | 2 \| SIMulation | Simulation mode |
| | 3 \| PROGram | Program mode |
| Return parameter | <NR1> | |
| | CONT | Continuous mode (normal operating mode) |
| | SEQ | Sequence mode |
| | SIM | Simulation mode |
| | PROG | Program mode |

## :SYSTem:CONFigure:PHASe                    → Query

| Description | Queries the phase of the system. |
| --- | --- |
| Query Syntax | :SYSTem:CONFigure:PHASe? |
| Return parameter | +0 | <NR1>Single phase |

Set →

:SYSTem:CONFigure:SDIP[:MODE]          → Query

| Description | Sets or queries the surge/dip mode for the power supply or disables the surge/dip mode. | |
|---|---|---|
| Syntax | :SYSTem:CONFigure:SDIP[:MODE] {<NR1>|DISable|MANual|AUTO } | |
| Query Syntax | :SYSTem:CONFigure:SDIP[:MODE]? | |
| Parameter | 0 | DISable | Disables surge/dip mode. |
| | 1 | MANual | Sets the surge/dip mode to manual. |
| | 2 | AUTO | Sets the surge/dip mode to auto. |
| Return parameter | <NR1> | |
| | +0 | Surge/dip mode off. |
| | +1 | Manual mode. |
| | +2 | Auto mode. |

Set →

:SYSTem:CONFigure:SDIP:SITE          → Query

| Description | Sets or queries the surge/dip site (equivalent to the T1 time setting using the panel controls). | |
|---|---|---|
| Syntax | :SYSTem:CONFigure:SDIP:SITE {<NR2>|MINimum|MAXimum} | |
| Query Syntax | :SYSTem:CONFigure:SDIP:SITE? [MINimum|MAXimum] | |
| Parameter | <NR2> | Site number: 0 ~99ms(manual SDIP mode) 0 ~22ms(auto SDIP mode) |
| | MINimum | Minimum site 0 |
| | MAXimum | Maximum site 99(manual)/22(auto) |
| Return parameter | <NR1> | Returns the site in msecs (+NR1). |

Set →

:SYSTem:CONFigure:SDIP:VOLTage          → Query

| Description | Sets or queries the surge/dip voltage level. |
|---|---|
| Syntax | :SYSTem:CONFigure:SDIP:VOLTage[:LEVel][:AMPLitude] {<NR2>|MINimum|MAXimum} |

| Query Syntax | :SYSTem:CONFigure:SDIP:VOLTage[:LEVel][:AMPLitude]? [MINimum\|MAXimum] | |
|---|---|---|
| Parameter | <NR2> | ACV level from 0V. |
| | MINimum | Minimum voltage (0V) |
| | MAXimum | Maximum voltage (set voltage range) |
| Return parameter | <NR1> | Returns the surge/dip voltage (+NR1). |

## :SYSTem:CONFigure:SDIP:WIDTh

Set →
→ Query
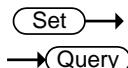
| Description | Sets or queries the width of the surge/dip site. |
|---|---|
| Syntax | :SYSTem:CONFigure:SDIP:WIDTh {<NR2>\|MINimum\|MAXimum} |
| Query Syntax | :SYSTem:CONFigure:SDIP:WIDTh? [MINimum\|MAXimum] |

| Parameter | <NR2> | Width in milliseconds |
|---|---|---|
| | MINimum | Minimum width |
| | MAXimum | Maximum width |
| Return parameter | <NR2> | Returns the width in ms. |

## :SYSTem:CONFigure:TRIGger:INPut :SOURce

Set →
→ Query
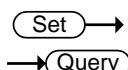
| Description | Configures the source for the trigger input. Equivalent to the Input Pin>Action settings when Shift + 2[Trigger] is pressed using the front panel controls. |
|---|---|
| Syntax | :SYSTem:CONFigure:TRIGger:INPut:SOURce {<NR1>\|NONE\|OUTPut\|SETTing\|PRESet\|SDIP} |
| Query Syntax | :SYSTem:CONFigure:TRIGger:INPut:SOURce? |

| Parameter | 0 \| NONE | No source is assigned. |
|---|---|---|
| | 1 \| OUTPut | Turning the output on will generate a trigger. |
| | 2 \| SETTing | Changing a setting will generate a trigger. |
| | 3 \| PRESet | Loading a preset will generate a trigger. |
| | 4 \| SDIP | Surge/ dip will generate a trigger. |
| Return parameter | +0 | No source is assigned. |

| | +1 | Turning the output on will generate a trigger. |
| | +2 | Changing a setting will generate a trigger. |
| | +3 | Loading a preset will generate a trigger. |

| Example | :SYST:CONF:TRIG:INP:SOUR? |
| | >0 |
| | No trigger source is assigned. |

## :SYSTem:CONFigure:TRIGger:INPut :WIDTh

(Set) ⟶
⟶(Query)

| Description | Sets or queries the type of trigger input. The trigger input can be set as a user-defined pulse width or as a trigger level. |
| Syntax | :SYSTem:CONFigure:TRIGger:INPut:WIDTh {<NR2>|MINimum|MAXimum} |
| Query Syntax | :SYSTem:CONFigure:TRIGger:INPut:WIDTh? [MINimum|MAXimum] |
| Parameter | <NR2> | 0, 1ms ~ 60ms. 0 = trigger controlled by trigger level, not pulse width. |
| | MINimum | 0 |
| | MAXimum | 60ms |
| Return parameter | <NR2> | Returns the input width. |
| Example | :SYST:CONF:TRIG:INP:WIDT 0.005 |
| | Sets the input width to 5ms. |

## :SYSTem:CONFigure:TRIGger:OUTPut :WIDTh

(Set) ⟶
⟶(Query)

| Description | Sets or queries the type of trigger output. The trigger output can be set as a user-defined pulse width or as a trigger output level. |
| Syntax | :SYSTem:CONFigure:TRIGger:OUTPut:WIDTh {<NR2>|MINimum|MAXimum} |
| Query Syntax | :SYSTem:CONFigure:TRIGger:OUTPut:WIDTh? [MINimum|MAXimum] |

| Parameter | <NR2> | 0, 1ms ~ 60ms. 0 = trigger output is set to output level, not pulse width. |
|---|---|---|
| | MINimum | 0 = trigger level |
| | MAXimum | 60ms |
| Return parameter | <NR2> | Returns the output width. |

| Example | :SYST:CONF:TRIG:OUT:WIDT 0.005 |
|---|---|
| | Sets the input width to 5ms. |

## :SYSTem:CONFigure:TRIGger:OUTPut :SOURce

Set →
→ Query

| Description | Configures the source for the trigger output. Equivalent to the Output Pin>Source settings when Shift + 2[Trigger] is pressed using the front panel controls. |
|---|---|
| Syntax | :SYSTem:CONFigure:TRIGger:OUTPut:SOURce {<NR1>|NONE|OUTPut|SETTing|PRESet|ALL} |
| Query Syntax | :SYSTem:CONFigure:TRIGger:OUTPut:SOURce? |

| Parameter | 0 \| NONE | No source is assigned. |
|---|---|---|
| | 1 \| OUTPut | Turning the output on will generate a trigger. |
| | 2 \| SETTing | Changing a setting will generate a trigger. |
| | 3 \| PRESet | Loading a preset will generate a trigger. |
| | 4 \| ALL | The output source is any of the above actions. |
| Return parameter | +0 | No source is assigned. |
| | +1 | Turning the output on will generate a trigger. |
| | +2 | Changing a setting will generate a trigger. |
| | +3 | Loading a preset will generate a trigger. |
| | +4 | The output source is any of the above actions. |

| Example | :SYST:CONF:TRIG:OUTP:SOUR? |
|---|---|
| | >0 |
| | No trigger source is assigned. |

## :SYSTem:CONFigure:TRIGger:OUTPut :LEVel

Set ⟶
⟶ Query

| | |
|---|---|
| Description | Sets or queries the trigger output level when the trigger output width is set to 0. See the :SYSTem:CONFigure:TRIGger:OUTPut:WIDTh command. |
| Syntax | :SYSTem:CONFigure:TRIGger:OUTPut:LEVel {<NR1>\|LOW\|HIGH} |
| Query Syntax | :SYSTem:CONFigure:TRIGger:OUTPut:LEVel? |
| Parameter/ Return parameter | <NR1>   0 = Low, 1 = High<br>LOW   Low level<br>HIGH   High level |
| Example | :SYSTem:CONFigure:TRIGger:OUTPut:LEVel HIGH<br>Sets the trigger level to high. |

## :SYSTem:ERRor

⟶ Query

| | |
|---|---|
| Description | Queries the error queue. The last error message is returned. A maximum of 32 errors are stored in the error queue. |
| Query Syntax | :SYSTem:ERRor? |
| Return parameter | <string>   Returns an error code followed by an error message as a single string. |
| Example | SYSTem:ERRor?<br>-100, "Command error" |

## :SYSTem:ERRor:ENABle

Set ⟶

| | |
|---|---|
| Description | Clears the Error Queue and enables all error messages to be placed in the System Error Queue. |
| Syntax | :SYSTem:ERRor:ENABle |

Set →
:SYSTem:KLOCk                    → Query
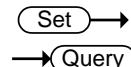
| Description | Enables or disables the front panel key lock. |
|---|---|
| Syntax | :SYSTem:KLOCk {<bool>|OFF|ON} |
| Query Syntax | :SYSTem:KLOCk? |
| Parameter | OFF \| 0   Panel keys unlocked |
| | ON \| 1    Panel keys locked |
| Return parameter | <bool>   Returns the key lock status. |

Set →
:SYSTem:LANGuage:EMULation      → Query
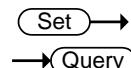
| Description | Sets the SCPI remote control emulation mode. |
|---|---|
| Syntax | :SYSTem:LANGuage:EMULation <string> |
| Query Syntax | :SYSTem:LANGuage:EMULation? |
| Parameter/ Return parameter | <string>   The string parameter determines the which remote control mode. |
| | "NONE"   No emulation is used. The SCPI mode continues to use the GW Instek SCPI remote control mode. |
| | "EXTECH"   Sets the emulation mode to EXTECH SCPI remote control mode. |
| | "N/A"   Sets the emulation mode to ALL POWER mode (not an SCPI control mode). |
| | Note: The string parameter must be enclosed in double brackets. |

:SYSTem:REBoot                    Set →

| Description | Reboots the APS system. |
|---|---|
| Syntax | :SYSTem:REBoot |

## :SYSTem:WRELease                          Set →

| | |
|---|---|
| Description | Clears the protection circuits (OCP, OTP). This command is functionally the same as the :OUTPut:PROTection:CLEar command (page 65). |
| Syntax | :SYSTem:WRELease |

## :SYSTem:IPKHold:TIME                    Set → / → Query

| | | |
|---|---|---|
| Description | Sets or queries the Ipeak hold time for peak current measurement when output on. | |
| Syntax | :SYSTem:IPKhold:TIME {<NR1>} | |
| Query Syntax | :SYSTem:IPKhold:TIME? | |
| Parameter | <NR1> | 1~60,000 |
| Example | :SYSTem:IPKHold:TIME 10 Sets the Ipeak hold time 10ms to measure when output on. | |

## :SYSTem:HOLD:STATe                     Set → / → Query

| | | |
|---|---|---|
| Description | Sets or queries the freeze hold state on/off. | |
| Syntax Query Syntax | :SYSTem:HOLD:STATe {<bool>|OFF|ON} :SYSTem:HOLD:STATe? | |
| Parameter | OFF \| 0 | Turns the freeze hold off. |
| | ON \| 1 | Turns the freeze hold on. |
| Return parameter | <bool> | Returns the freeze hold status. |

## Trigger Commands

The triggering commands are divided into trigger input and trigger output commands. The trigger input commands are further divided into Bus, Immediate and External commands. To use the trigger subsystem a trigger source must be selected, the triggering system must then be initiated (immediate trigger only), and finally triggered, either manually or by a system trigger.

The trigger sources range from loading a memory setting, turning on the output or one of the transient trigger sources.

The flow chart below shows the basic steps for using the trigger system.

| | |
|---|---|
| Select Trigger Mode | Configure to manual or auto trigger mode:<br>:SYSTem:CONFigure:TRIGger:INPut:MODE MANual |
| Select Trigger Action | Action for output trigger:<br>OUTPut[:STATe]:TRIGgered {<bool>\|OFF\|ON}<br>Action for memory trigger:<br>:MEMory:TRIGgered <NR1>(M0~M9)<br>Action for transient trigger:<br>[:SOURce]:FREQuency:TRIGgered {<NR2>(HZ)<br>[:SOURce]:VOLTage[:LEVel]:TRIGgered[:AMPLitude] {<NR2>(V) |
| Select Trigger Sources | Applicable commands to select trigger source:<br>:TRIGger:OUTPut:SOURce BUS\|IMMediate\|EXTernal<br>:TRIGger:MEMory:SOURce BUS\|IMMediate\|EXTernal<br>:TRIGger[:TRANsient]:SOURce BUS\|IMMediate\|EXTernal |
| Trigger Idle State | Applicable commands to initiate selected [immediate] trigger:<br>:INITiate[:IMMediate]:NAME TRANsient\|OUTPut\|MEMory<br>:INITiate[:IMMediate][:TRANsient] |
| Trigger Initiated State | Applicable commands to begin triggering when the trigger source is set to immediate:<br>:TRIGger:OUTPut[:IMMediate]<br>:TRIGger:MEMory[:IMMediate]<br>:TRIGger[:TRANsient][:IMMediate]<br><br>Applicable actions to begin triggering when source is set to EXT:<br>Receive high signal from Trigger Input pin (J1 connector).<br><br>Applicable action to begin triggering when source is set to BUS:<br>*TRG |
| Measurement or action initiated | |

Trigger Examples

The follow 3 examples show the steps necessary to use the output, transient or memory trigger system:

Output Trigger Example:

    :SYSTem:CONFigure:TRIGger:INPut:MODE MANual

    :TRIGger:OUTPut:SOURce BUS

    :OUTPut:STATe:TRIGgered <bool>|OFF|ON

    :INITiate:IMMediate:NAME OUTPut

    *TRG

Transient Trigger Example:

    :SYSTem:CONFigure:TRIGger:INPut:MODE MANual

    :SOURce:FREQuency:TRIGgered 60

    :SOURce:VOLTage:LEVel:TRIGgered:AMPLitude 100

    :TRIGger:TRANsient:SOURce BUS

    :INITiate:IMMediate:NAME TRANsient

    *TRG

Memory Trigger Example:

    :SYSTem:CONFigure:TRIGger:INPut:MODE MANual

    :MEMory:TRIGgered 1

    :TRIGger:MEMory:SOURce BUS

    :INITiate:IMMediate:NAME MEMory

    *TRG

## :TRIGger:OUTPut:SOURce

Set →
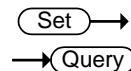
→ Query

| | |
|---|---|
| Description | Sets or queries the trigger source of the output trigger. |
| Syntax | :TRIGger:OUTPut:SOURce {BUS|IMMediate|EXTernal} |
| Query Syntax | :TRIGger:OUTPut:SOURce? |
| Parameter/ Return parameter | BUS — Output trigger is generated by the bus. IMMediate — Output trigger is immediately generated. EXTernal — The output trigger is generated when an external signal triggers it. |
| Example | :TRIGger:OUTPut:SOURce? EXT Sets the output trigger source to EXT. |

## :TRIGger:OUTPut[:IMMediate]

Set →

| | |
|---|---|
| Description | Generates an immediate trigger for the output trigger system. |
| Syntax | :TRIGger:OUTPut[:IMMediate] |
| Example | :TRIG:OUTP |

Set →
→ Query

## :TRIGger:MEMory:SOURce

| Description | Sets or queries the source of the memory trigger. |
|---|---|
| Syntax | :TRIGger:MEMory:SOURce {BUS\|IMMediate\|EXTernal} |
| Query Syntax | :TRIGger:MEMory:SOURce? |
| Parameter/ Return parameter | BUS — Memory trigger is generated by the bus. IMMediate — Memory trigger is immediately generated. EXTernal — The memory trigger is generated when an external signal triggers it. |
| Example | :TRIGger:MEMory:SOURce? EXT Sets the memory trigger source to EXT. |

## :TRIGger:MEMory[:IMMediate]

Set →

| Description | Generates an immediate trigger for the memory trigger system. |
|---|---|
| Syntax | :TRIGger:MEMory[:IMMediate] |
| Example | :TRIG:MEM |

Set →
→ Query

## :TRIGger:SDIP:SOURce

| Description | Sets or queries the surge/dip source. |
|---|---|
| Syntax | :TRIGger:SDIP:SOURce {BUS\|IMMediate\|EXTernal} |
| Query Syntax | :TRIGger:SDIP:SOURce? |
| Parameter/ Return parameter | BUS — Sets the source to BUS. IMMediate — Sets the source to IMMediate. EXTernal — Sets the source to EXTernal. |
| Example | :TRIG:SDIP:SOUR? EXT Sets the surge/dip source to EXT. |

## :TRIGger:SDIP[:IMMediate]    ⟨ Set ⟩⟶

| | |
|---|---|
| Description | Generates an immediate trigger for the surge/dip trigger system. |
| Syntax | :TRIGger:SDIP[:IMMediate] |
| Example | :TRIG:SDIP |

## :TRIGger:SEQuence:SELected:EXECute    ⟨ Set ⟩⟶

| | | |
|---|---|---|
| Description | Sets the control parameters of the selected step for the sequence mode. This command can only be executed when the sequence mode is turned on. | |
| Syntax | :TRIGger:SEQuence:SELected:EXECute {<NR1>|STOP|STARt|HOLD|BRAN1|BRAN2} | |
| Parameter | <NR1> | Step number <NR1>. |
| | STOP | Stop the step |
| | STARt | Start the step |
| | HOLD | Hold the step (2) and wait for the user to continue. |
| | BRAN1 | Branch 1 |
| | BRAN2 | Branch 2 |
| Example | :TRIG:SEQ:SEL:EXEC STOP | |
| | Stop the sequence. | |

## :TRIGger:SIMulation:SELected:EXECute    ⟨ Set ⟩⟶

| | | |
|---|---|---|
| Description | Sets the control parameters for the selected step for the simulation mode. This command can only be executed when the simulation mode is turned on. | |
| Syntax | :TRIGger:SIMulation:SELected:EXECute {<NR1>|STOP|STARt|HOLD} | |
| Parameter | <NR1> | Go to the step <NR1>. |
| | STOP | Stop the step (0) |
| | STARt | Start the step (1) |

| HOLD | Hold the step (2) and wait for the user to continue. |
|---|---|

| Example | :TRIG:SIM:SEL:EXEC STOP |
|---|---|
| | Stop the simulation. |

## :TRIGger[:TRANsient]:SOURce

<span style="float:right">Set →</span>
<span style="float:right">→ Query</span>
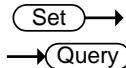
| Description | Sets or queries the source of the transient trigger. |
|---|---|
| Syntax | :TRIGger[:TRANsient]:SOURce {BUS\|IMMediate\|EXTernal} |
| Query Syntax | :TRIGger[:TRANsient]:SOURce? |
| Parameter/ Return parameter | BUS | Transient trigger is generated by the bus. |
| | IMMediate | Transient trigger is immediately generated. |
| | EXTernal | The transient trigger is generated when an external signal triggers it. |
| Example | :TRIG:SOUR? |
| | EXT |
| | Sets the transient trigger source to EXT. |

## :TRIGger[:TRANsient][:IMMediate]

<span style="float:right">Set →</span>

| Description | Generates an immediate trigger for the transient trigger system. |
|---|---|
| Syntax | :TRIGger[:TRANsient][:IMMediate] |
| Example | :TRIG |

## Source Commands

## [:SOURce]:CURRent:LIMit:PEAK:HIGH

Set →
→ Query

| Description | Sets or queries the Ipk-Limit parameter for the continuous operation mode. |
|---|---|
| Syntax | [:SOURce]:CURRent:LIMit:PEAK:HIGH {<NR2>\|MINimum\|MAXimum} |

| Query Syntax | [:SOURce]:CURRent:LIMit:PEAK:HIGH?<br>[MINimum\|MAXimum] | |
|---|---|---|
| Parameter | <NR2><br>MINimum<br>MAXimum | Ipk-Limit in Arms.<br>Minimum  settable peak current limit<br>Maximum settable peak current limit |
| Return parameter | <NR2> | Returns the Ipk-Limit value |
| Example | CURR:LIM:PEAK:HIGH?<br><br>16.80<br><br>Returns the peak current limit as 16.8Arms. | |

## [:SOURce]:CURRent:LIMit:PEAK:TIME

Set →
→ Query
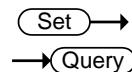
| Description | Sets or queries Ipk-Limit delay time by turn off. | |
|---|---|---|
| Syntax | [:SOURce]:CURRent:LIMit:PEAK:TIME<br>{<NR2>\|MINimum\|MAXimum} | |
| Query Syntax | [:SOURce]:CURRent:LIMit:PEAK:TIME?<br>{MINimum\|MAXimum} | |
| Parameter | <NR2><br>MINimum<br>MAXimum | 0~10 Ipk-Limint delay time in Second<br>Minimum Ipk-Limint delay time<br>Maximum Ipk-Limint delay time |
| Return parameter | <NR2> | Return the Ipk-Limint delay time value |
| Example | :CURR:LIM:PEAK:TIME?<br><br>0<br><br>Returns Ipk-Limint delay off time as 0Sec. | |

## [:SOURce]:CURRent:LIMit:RMS [:AMPLitude]

Set →
→ Query

| Description | Sets or queries the Irms parameter for the<br>continuous operation mode. | |
|---|---|---|
| Syntax | [:SOURce]:CURRent:LIMit:RMS[:AMPLitude]<br>{<NR2>\|MINimum\|MAXimum} | |
| Query Syntax | [:SOURce]:CURRent:LIMit:RMS[:AMPLitude]?<br>[MINimum\|MAXimum] | |
| Parameter | <NR2> | Irms in A. |

| | MINimum | Minimum settable current |
|---|---|---|
| | MAXimum | Maximum settable current |
| Return parameter | <NR2> | Returns the Irms. |

| Example | CURR:LIM:RMS? |
|---|---|
| | 4.20 |
| | Returns the Irms setting. |

## [:SOURce]:CURRent:LIMit:RMS:TIME

Set ⟶
⟶ Query

| Description | Sets or queries IRMS delay time by turn off. |
|---|---|
| Syntax | [:SOURce]:CURRent:LIMit:RMS:TIME {<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:CURRent:LIMit:RMS:TIME? {MINimum\|MAXimum} |
| Parameter | <NR2> | 0~10 IRMS delay time in Second |
| | MINimum | Minimum IRMS delay time |
| | MAXimum | Maximum IRMS delay time |
| Return parameter | <NR2> | Return the IRMS delay time value |

| Example | :CURR:LIM:RMS:TIME? |
|---|---|
| | 0 |
| | Returns IRMS delay off time as 0Sec. |

## [:SOURce]:FREQuency:LIMit:HIGH

Set ⟶
⟶ Query
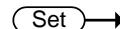
| Description | Sets or queries the frequency upper limit range. |
|---|---|
| Syntax | [:SOURce]:FREQuency:LIMit:HIGH {<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:FREQuency:LIMit:HIGH? [INimum\|MAXimum] |
| Parameter | <NR2> | Frequency in Hz. |
| | MINimum | Minimum settable frequency |
| | MAXimum | Maximum settable frequency |
| Return parameter | <NR2> | Returns the frequency limit |

| | |
|---|---|
| Example | FREQ:LIM:HIGH? |
| | >60.50 |
| | Returns the frequency limit. |

## [:SOURce]:FREQuency:TRIGgered

Set →
→ Query
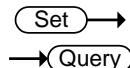
| | | |
|---|---|---|
| Description | Sets or queries the frequency when triggered. | |
| Syntax | [:SOURce]:FREQuency:TRIGgered {<NR2>(HZ)\|MINimum\|MAXimum} | |
| Query Syntax | [:SOURce]:FREQuency:TRIGgered? [MINimum\|MAXimum] | |
| Parameter | <NR2> | Frequency in Hz. |
| | MINimum | Minimum settable frequency |
| | MAXimum | Maximum settable frequency |
| Return parameter | <NR2> | Returns the frequency |
| Example | :FREQ:TRIG? | |
| | >60.50 | |
| | Returns the frequency setting. | |

## [:SOURce]:FREQuency[:IMMediate]

Set →
→ Query
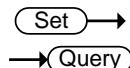
| | | |
|---|---|---|
| Description | Sets or queries the frequency for the immediate trigger. | |
| Syntax | [:SOURce]:FREQuency[:IMMediate] {<NR2>(HZ)\|MINimum\|MAXimum} | |
| Query Syntax | [:SOURce]:FREQuency[:IMMediate]? [MINimum\|MAXimum] | |
| Parameter/Return parameter | <NR2> | Frequency setting in Hz. |
| | MINimum | Minimum frequency |
| | MAXimum | Maximum frequency |
| Example | :FREQ | |
| | 60.00 | |
| | Sets the frequency of 60Hz. | |

Set ⟶

[:SOURce]:FUNCtion:CSINe:CFACtor          ⟶ Query

| Description | Sets or queries the crest factor setting for the waveform. |
|---|---|
| Note: | The :SOURce:FUNCtion:CSINe:TYPE command must first be used to set the save slot number (CLP1\|2\|3) and CFACtor as the waveform type before this command is executed. |
| Syntax | [:SOURce]:FUNCtion:CSINe:CFACtor {CLP1\|CLP2\|CLP3,<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:FUNCtion:CSINe:CFACtor? {CLP1\|CLP2\|CLP3[,MINimum\|MAXimum]} |

| Parameter/Return parameter | <NR2> | Crest factor |
|---|---|---|
| | CLP1 | Save slot 1 |
| | CLP2 | Save slot 2 |
| | CLP3 | Save slot 3 |
| | MIN | 1.4 |
| | MAX | 10.0 |

| Example | :FUNC:CSIN:CFAC CLP1,2.0 |
|---|---|
| | Sets the crest factor to 2.0. |

Set ⟶

[:SOURce]:FUNCtion:CSINe:CLIP          ⟶ Query

| Description | Sets or queries the CLIP waveform settings. |
|---|---|
| Note: | The :SOURce:FUNCtion:CSINe:TYPE command must first be used to set the save slot number (CLP1\|2\|3) and CLIP as the waveform type before this command is executed. |
| Syntax | [:SOURce]:FUNCtion:CSINe:CLIP {CLP1\|CLP2\|CLP3,<NR2>\|MINimum\|MAXimum, <NR1>\|RATio\|KEEP} |
| Query Syntax | [:SOURce]:FUNCtion:CSINe:CLIP? {CLP1\|CLP2\|CLP3[,MINimum\|MAXimum]} |

| Parameter/Return parameter | CLP1 | Save slot 1 |
|---|---|---|
| | CLP2 | Save slot 2 |

| | |
|---|---|
| CLP3 | Save slot 3 |
| <NR2> | Clip range. 0.5 ~ 0.99 |
| MIN | 0.5 |
| MAX | 0.99 |
| <NR1> | 0 = Ratio, 1 = Keep |
| RATio | Sets the VRMS of the clipped sine wave as the clip range ratio. I.e., if the clip range = 0.5 then the VRMS will be halved. |
| KEEP | Keeps the VRMS value of the clipped sine wave the same as the setting value. |

| Example | :FUNC:CSIN:CLIP CLP1,0.5,KEEP |
|---|---|
| | Sets the clip range to 0.5. |

## [:SOURce]:FUNCtion:CSINe:SDIP

Set →
→ Query
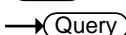
| Description | Sets or queries the surge\|dip waveform type, site and voltage level. |
|---|---|
| Note: | The :SOURce:FUNCtion:CSINe:TYPE command must first be used to set the save slot number (CLP1\|2\|3) and SDIP as the waveform type before this command can be executed. |
| Syntax | [:SOURce]:FUNCtion:CSINe:SDIP {CLP1\|CLP2\|CLP3,<NR1>\|SQUare\|SINE,<NR2>\|MINimum\|MAXimum,<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:FUNCtion:CSINe:SDIP? {CLP1\|CLP2\|CLP3[,MINimum\|MAXimum]} |
| Parameter/Return parameter | CLP1 | Save slot 1 |
| | CLP2 | Save slot 2 |
| | CLP3 | Save slot 3 |
| | <NR1>\|SQUare\|SINE | 0 \| Square, 1\| Sine (Site waveform shape) |
| | <NR2> | 0 ~100%. ACV. |
| | MINimum | 0 (0%) |
| | MAXimum | 100 (100%) |
| | <NR2> | 0 ~100%. Site |
| | MINimum | 0 (0%) |
| | MAXimum | 100 (100%) |

| Example | :FUNC:CSIN:SDIP CLP1, SQU,50,50 |
|---|---|
| | Sets the surge/dip arbitrary waveform parameters as site=square, ACV=50%, site=50%. |

## [:SOURce]:FUNCtion:CSINe:STAircase

Set →
→ Query
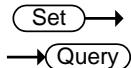
| Description | Sets or queries the staircase waveform type and the number of "steps" in the waveform. |
|---|---|
| Note: | The :SOURce:FUNCtion:CSINe:TYPE command must first be used to set the save slot number (CLP1\|2\|3) and the waveform type (STAircase) before this command can be executed. |
| Syntax | [:SOURce]:FUNCtion:CSINe:STAircase {CLP1\|CLP2\|CLP3,<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:FUNCtion:CSINe:STAircase? {CLP1\|CLP2\|CLP3[,MINimum\|MAXimum]} |

| Parameter/Return parameter | | |
|---|---|---|
| | CLP1 | Save slot 1 |
| | CLP2 | Save slot 2 |
| | CLP3 | Save slot 3 |
| | <NR2> | 1 ~100 steps |
| | MINimum | 1 step |
| | MAXimum | 100 steps |

| Example | :FUNC:CSIN:STA CLP1,50 |
|---|---|
| | Sets the staircase arbitrary waveform at memory CLP1 to have 50 steps. |

## [:SOURce]:FUNCtion:CSINe:TYPE

Set →
→ Query
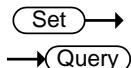
| Description | Sets the selected save slot to a type of arbitrary waveform or queries its state. |
|---|---|
| Note: | This command must be used before one of the [:SOURce]:FUNCtion:CSINe:CFACtor, [:SOURce]:FUNCtion:CSINe:CLIP, [:SOURce]:FUNCtion:CSINe:SDIP or [:SOURce]:FUNCtion:CSINe:STAircase commands are used. |

| Syntax | [:SOURce]:FUNCtion:CSINe:TYPE {CLP1|CLP2|CLP3,CFACtor|CLIP|SDIP|STAircase|TRIangle} |
|---|---|
| Query Syntax | [:SOURce]:FUNCtion:CSINe:TYPE? {CLP1|CLP2|CLP3} |

| Parameter/Return parameter | CLP1 | Save slot 1 |
|---|---|---|
| | CLP2 | Save slot 2 |
| | CLP3 | Save slot 3 |
| | CFACtor | Set the type as a crest factor waveform. |
| | CLIP | Set the type as a clipped sine waveform. |
| | SDIP | Set the type as a surge/dip waveform. |
| | STAircase | Set the type as a staircase waveform. |
| | Triangle | Set the type as a triangle waveform. |

| Example | :FUNC:CSIN:TYPE CLP1,CFACtor |
|---|---|
| | Sets the arbitrary waveform type as a crest factor waveform. |

## [:SOURce]:FUNCtion[:SHAPe][:IMMediate]　→ Set →　→ Query

| Description | Loads the selected arbitrary waveform into the power supply. The selected waveform will be output when the output is turned on. |
|---|---|
| Note: | If the CLP1|2|3 arbitrary waveforms are to be used, they must first be setup before they can be output. Use the [:SOURce]:FUNCtion:CSINe:TYPE command to set the CLP1|2|3 save slots. |
| Syntax | [:SOURce]:FUNCtion[:SHAPe][:IMMediate] {SIN|ARB1|ARB2|ARB3|ARB4|ARB5|ARB6|ARB7|ARB8|ARB9|ARB10|ARB11|ARB12|ARB13|ARB14|ARB15|ARB16|ARB17|ARB18|ARB19|ARB20|ARB21|ARB22|CLP1|CLP2|CLP3} |
| Query Syntax | [:SOURce]:FUNCtion[:SHAPe][:IMMediate]? |

| Parameter/Return parameter | SIN | Sine waveform |
|---|---|---|
| | ARB1 ~ ARB22 | Preset ARB waveforms, number 1 ~ 22. See the user manual for details. |
| | CLP1 | Save slot 1 |
| | CLP2 | Save slot 2 |
| | CLP3 | Save slot 3 |

| Example | :FUNCtion CLP1 |
|---|---|
| | Loads the ARB waveform stored in CLP1. |

Set →

## [:SOURce]:PHASe:STARt[:IMMediate]     → Query

| Description | Sets or queries the start phase. |
|---|---|
| Syntax | [:SOURce]:PHASe:STARt[:IMMediate] {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:PHASe:STARt[:IMMediate]? [MINimum|MAXimum] |

| Parameter/Return parameter | <NR2> | Start phase. |
|---|---|---|
| | MINimum | 0º |
| | MAXimum | 359 º |

| Example | :PHAS:STAR 0 |
|---|---|
| | Sets the starting phase to 0. |

Set →

## [:SOURce]:PHASe:STOP[:IMMediate]     → Query

| Description | Sets or queries the off phase of the waveform. |
|---|---|
| Note: | Sets the off phase of the waveform after the output has been turned off. |
| Syntax | [:SOURce]:PHASe:STOP[:IMMediate] {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:PHASe:STOP[:IMMediate]? [MINimum|MAXimum] |

| Parameter/Return parameter | <NR2> | Stop phase. |
|---|---|---|
| | MINimum | 0 º |
| | MAXimum | 359 º |

| Example | :PHAS:STOP 0 |
|---|---|
| | Sets the stop phase to 0. |

## [:SOURce]:READ     → Query

| Description | Returns the measurement readouts. |
|---|---|

| Query Syntax | [:SOURce]:READ? | |
|---|---|---|
| Return parameter | <voltage>,<current>, <frequency>,<power>, <SVA>,<ipeak> | Returns each measurement readout as <NR3>. |

| Example | :READ? |
|---|---|
| | >+111.9700,+0.0000,+59.9990,+0.0000,+0.0000, +0.0000 |

## [:SOURce]:SEQuence:CPARameter     ⟨Set⟩ ⟶

| Description | Sets the common parameters for the Sequence mode. Please see the user manual for a full description of each parameter. |
|---|---|

| Syntax | [:SOURce]:SEQuence:CPARameter {<NR2>,<NR2>,<bool>|OFF|ON,<NR2>,<bool>|OFF| ON,<NR1>|CONTinue|END|HOLD,<NR1>,<bool>|OF F|ON,<NR1>,<bool>|OFF|ON,<NR1>,<bool>|OFF|O N,<NR1>,<bool>|OFF|ON,<bool>|OFF|ON} |
|---|---|

| Query Syntax | [:SOURce]:SEQuence:CPARameter? |
|---|---|

| Parameter | <NR2> | Step Time |
|---|---|---|
| | <NR2> | On phase |
| | <bool>|OFF|ON | On phase on(1)/off(0) |
| | <NR2> | Off phase |
| | <bool>|OFF|ON | Off phase on/off |
| | <NR1>|CONTinue| END|HOLD | Term settings: Continue(1)/End(2)/Hold(3) |
| | <NR1> | Jump step number (0 ~ 255) |
| | <bool>|OFF|ON | Jump on(1)/off(0) |
| | <NR1> | Jump Cnt (0~ 255) |
| | <bool>|OFF|ON | Code (External trigger output): ON=1/OFF=0 |
| | <NR1> | Branch1 (0 ~ 255) |
| | <bool>|OFF|ON | Branch1 on(1)/off(0) |
| | <NR1> | Branch2 (0 ~ 255) |
| | <bool>|OFF|ON | Branch2 on(1)/off(0) |
| | <bool>|OFF|ON | Trig Out. HI=1/LO=0 |

| Return parameter | <NR2>,<NR2>,<bool>,<NR2>,<bool>,<NR1>,<NR1>, <bool>,<NR1>,<bool>,<NR1>,<bool>,<NR1>,<bool>, <bool> |
|---|---|
| | Returns the common parameters in the following order: Step time, on phase, on phase on/off, off phase, off phase on/off, term settings, jump step number, jump on/off, jump count, code on/off, branch1, branch1 on/off, branch2, branch2 on/off, trig out on/off. |
| Example1 | :SEQ:CPAR 1,0,10,1,HOLD,10,1,0,1,0,0,0,0,1 |
| Example2 | :SEQ:CPAR?<br>>+0.1000,+0,+0,+0,+0,CONT,+1,+1,+1,+0,+0,+0,+0,+0,<br>+0 |

## [:SOURce]:SEQuence:CSTep  ➔ Query

| Description | Returns the currently running step number. |
|---|---|
| Query Syntax | [:SOURce]:SEQuence:CSTep? |
| Return parameter | <NR1>          Current step number |
| Example | :SEQ:CSTep?<br><br>>1 |

Set ➔

## [:SOURce]:SEQuence:SPARameter  ➔ Query

| Description | Sets or queries the parameters for a specified step. |
|---|---|
| Syntax | [:SOURce]:SEQuence:SPARameter {<NR2>,<NR1>|CONSt|KEEP|SWEep,<NR2>,<NR1>|CONSt|KEEP|SWEep,<NR2>,<NR1>|CONSt|KEEP|SWEep,SIN,<NR1>} |
| Query Syntax | [:SOURce]:SEQuence:SPARameter? |
| Parameter | <NR2>                ACV setting |
| | <NR1>\|CONSt\|KEEP\|SWEep   ACV mode: Constant(1) \| Keep(2) \| Sweep(3) |
| | <NR2>                DCV. Not applicable. This parameter will be ignored. |
| | <NR1>\|CONSt\|KEEP\|SWEep   DCV mode: Constant(1) \| Keep(2) \| Sweep(3) |
| | <NR2>                Frequency |

| | <NR1>\|CONSt\|<br>KEEP\|SWEep | Frequency mode: Constant(1) \|<br>Keep(2) \| Sweep(3) |
|---|---|---|
| | SIN | Fixed as sine. |
| | <NR1> | Phase angle. Fixed to 0. |
| Return parameter | <NR2>,<NR1>\|CONSt\|KEEP\|SWEep,<NR2>,<NR1>\|<br>CONSt\|KEEP\|SWEep,<NR2>,<NR1>\|CONSt\|KEEP\|S<br>WEep,SIN,<NR1> | |
| | Returns the step parameters in the following order:<br>ACV, ACV mode, DCV, DCV mode, frequency,<br>frequency mode, SIN, phase. | |
| Example | :SEQ:SPAR? | |
| | >+101.0000,KEEP,+0.0000,CONST,+50.0000,CONST,S<br>IN,0 | |

### [:SOURce]:SEQuence:STEP

Set ⟶
⟶ Query
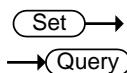
| Description | Sets or queries the current step number. |
|---|---|
| Syntax | [:SOURce]:SEQuence:STEP<br>{<NR1>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:SEQuence:STEP? [MINimum\|MAXimum] |

| Parameter/Return<br>parameter | <NR1> | Step number |
|---|---|---|
| | MINimum | Minimum step number |
| | MAXimum | Maximum step number |

| Example | :SEQ:STEP 1 |
|---|---|
| | Sets the step number to 1. |

### [:SOURce]:SIMulation:ABNormal:CODE

Set ⟶
⟶ Query
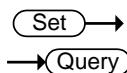
| Description | Sets the external trigger output for the abnormal<br>step parameter. This option is only applicable<br>when in the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:CODE<br>{<NR1>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:CODE?<br>[MINimum\|MAXimum] |

| Parameter | <NR1> | External trigger output, HI=1, LO=0. |
|---|---|---|
| | MINimum | LO, 0 |
| | MAXimum | HI, 1 |
| Return parameter | +0 | LO |
| | +1 | HI |
| Example | SIM:ABN:CODE 1 | |

## [:SOURce]:SIMulation:ABNormal :FREQuency

Set →
→ Query

| Description | Sets or queries the frequency of the abnormal step of the simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:FREQuency {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:FREQuency? [MINimum|MAXimum] |

| Parameter/Return parameter | <NR2> | Frequency of abnormal step |
|---|---|---|
| | MINimum | Minimum frequency |
| | MAXimum | Maximum frequency |
| Example | :SIM:ABN:FREQ 55 | |

Sets the frequency to 55Hz.

## [:SOURce]:SIMulation:ABNormal:PHASe :STARt:ENABle
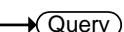
Set →
→ Query

| Description | Enables/Disables the ON Phs parameter of the abnormal step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STARt :ENABle {<bool>|OFF|ON} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STARt :ENABle? |

| Parameter/Return parameter | OFF \| 0 | Disabled |
|---|---|---|
| | ON \| 1 | Enabled |
| Example | :SIM:ABN:PHAS:STAR:ENAB 1 | |

Enable the ON Phs.

[:SOURce]:SIMulation:ABNormal:PHASe        Set →
:STARt[:IMMediate]                         → Query

| Description | Sets or queries the ON Phs parameter of the abnormal step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STARt [:IMMediate] {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STARt [:IMMediate]? [MINimum|MAXimum] |
| Parameter/Return parameter | <NR2>     ON Phs (start phase)<br>MINimum    0<br>MAXimum    359 |
| Example | :SIM:ABN:PHAS:STAR 0<br>Sets ON Phs to 0. |

[:SOURce]:SIMulation:ABNormal:PHASe        Set →
:STOP:ENABle                               → Query

| Description | Enables/Disables the OFF Phs parameter of the abnormal step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STOP :ENABle {<bool>|OFF|ON} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STOP :ENABle? |
| Parameter/Return parameter | OFF \| 0    Disabled<br>ON \| 1     Enabled |
| Example | :SIM:ABN:PHAS:STOP:ENAB 1<br>Enable the OFF Phs. |

[:SOURce]:SIMulation:ABNormal:PHASe        Set →
:STOP[:IMMediate]                          → Query

| Description | Sets or queries the OFF Phs parameter of the abnormal step for the Simulation mode. |
|---|---|

| Note: | Sets the off phase of the waveform after the output has been turned off. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STOP [:IMMediate] {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:PHASe:STOP [:IMMediate]? [MINimum|MAXimum] |
| Parameter/Return parameter | <NR2>      OFF Phs (Stop phase)<br>MINimum   0<br>MAXimum   359 |
| Example | :SIM:ABN:PHAS:STOP 0 |
| | Sets OFF Phs to 0. |

## [:SOURce]:SIMulation:ABNormal:TIME
Set →
→ Query

| Description | Sets or queries the Time parameter of the abnormal step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:TIME {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:TIME? [MINimum|MAXimum] |
| Parameter/Return parameter | <NR2>      Time of the abnormal step in seconds<br>MINimum   0<br>MAXimum   99.99s |
| Example | :SIM:ABN:TIME 1 |
| | Sets the abnormal step time to 1 second. |

## [:SOURce]:SIMulation:ABNormal:VOLTage
Set →
→ Query

| Description | Sets or queries the Vset parameter of the abnormal step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:ABNormal:VOLTage {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:ABNormal:VOLTage? [MINimum|MAXimum] |

| Parameter/Return parameter | <NR2> | Voltage of the abnormal step. |
| | MINimum | Minimum settable voltage |
| | MAXimum | Maximum settable voltage |

| Example | :SIM:ABN:VOLT MAX |
| | Sets the abnormal step voltage to the maximum. |

## [:SOURce]:SIMulation:CSTep                    → Query

| Description | Returns the currently running step. |

| Query Syntax | [:SOURce]:SIMulation:CSTep? |
| Return parameter | <NR1> | Current step |
| | | +0 = Initial step |
| | | +1 = Normal1 step |
| | | +2 = Transition1 step |
| | | +3 = Abnormal step |
| | | +4 = Transition2 step |
| | | +5 = Normal2 step |

| Example | :SIM:CSTep? |
| | >+1 |

## [:SOURce]:SIMulation:INITial:CODE

Set →
→ Query

| Description | Sets the external trigger output for the initial step parameter. This option is only applicable when in the Simulation mode. |

| Syntax | [:SOURce]:SIMulation:INITial:CODE {<NR1>|MINimum|MAXimum} |

| Query Syntax | [:SOURce]:SIMulation:INITial:CODE? [MINimum|MAXimum] |

| Parameter/Return parameter | <NR1> | HI=1, LO=0. |
| | MINimum | LO, 0 |
| | MAXimum | HI, 1 |

| Example | SIM:INIT:CODE 1 |

Set →
## [:SOURce]:SIMulation:INITial:FREQuency → Query

| | |
|---|---|
| Description | Sets or queries the frequency of the initial step of the simulation mode. |
| Syntax | [:SOURce]:SIMulation:INITial:FREQuency {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:INITial:FREQuency? [MINimum|MAXimum] |
| Parameter/Return parameter | <NR2>    Frequency of initial step<br>MINimum   Minimum frequency<br>MAXimum   Maximum frequency |
| Example | :SIM:INIT:FREQ 60<br>Sets the frequency to 60Hz. |

## [:SOURce]:SIMulation:INITial:PHASe:STARt :ENABle
Set →
→ Query

| | |
|---|---|
| Description | Enables/Disables the ON Phs parameter of the initial step for the Simulation mode. |
| Syntax | [:SOURce]:SIMulation:INITial:PHASe:STARt:ENABle {<bool>|OFF|ON} |
| Query Syntax | [:SOURce]:SIMulation:INITial:PHASe:STARt:ENABle? |
| Parameter/Return parameter | OFF \| 0    Disabled<br>ON \| 1    Enabled |
| Example | :SIM:INIT:PHAS:STAR:ENAB 1<br>Enable the ON Phs. |

## [:SOURce]:SIMulation:INITial:PHASe:STARt [:IMMediate]
Set →
→ Query

| | |
|---|---|
| Description | Sets or queries the ON Phs parameter of the initial step for the Simulation mode. |

| Syntax | [:SOURce]:SIMulation:INITial:PHASe:STARt [:IMMediate] {<NR2>\|MINimum\|MAXimum} |
|---|---|
| Query Syntax | [:SOURce]:SIMulation:INITial:PHASe:STARt [:IMMediate]? [MINimum\|MAXimum] |

| Parameter/Return parameter | <NR2> | ON Phs (start phase) |
|---|---|---|
| | MINimum | 0 |
| | MAXimum | 359 |

| Example | :SIM:INIT:PHAS:STAR 0 |
|---|---|
| | Sets ON Phs to 0. |

## [:SOURce]:SIMulation:INITial:PHASe:STOP :ENABle　　Set →　→ Query

| Description | Enables/Disables the OFF Phs parameter of the initial step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:INITial:PHASe:STOP:ENABle {<bool>\|OFF\|ON} |
| Query Syntax | [:SOURce]:SIMulation:INITial:PHASe:STOP:ENABle? |

| Parameter/Return parameter | OFF \| 0 | Disabled |
|---|---|---|
| | ON \| 1 | Enabled |

| Example | :SIM:INIT:PHAS:STOP:ENAB 1 |
|---|---|
| | Enable the OFF Phs. |

## [:SOURce]:SIMulation:INITial:PHASe:STOP [:IMMediate]　　Set →　→ Query

| Description | Sets or queries the OFF Phs parameter of the abnormal step for the Simulation mode. |
|---|---|
| Note: | Sets the off phase of the waveform after the output has been turned off. |
| Syntax | [:SOURce]:SIMulation:INITial:PHASe:STOP [:IMMediate] {<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:INITial:PHASe:STOP [:IMMediate]? [MINimum\|MAXimum] |

| Parameter/Return parameter | <NR2> | OFF Phs (Stop phase) |
| | MINimum | 0 |
| | MAXimum | 359 |

| Example | :SIM:INIT:PHAS:STOP 0 |
| | Sets OFF Phs to 0. |
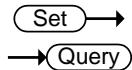
## [:SOURce]:SIMulation:INITial:VOLTage

(Set) →
→ (Query)

| Description | Sets or queries the Vset parameter of the abnormal step for the Simulation mode. |
| --- | --- |
| Syntax | [:SOURce]:SIMulation:INITial:VOLTage {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:INITial:VOLTage? [MINimum|MAXimum] |
| Parameter/Return parameter | <NR2> | Voltage of the initial step. |
| | MINimum | Minimum settable voltage |
| | MAXimum | Maximum settable voltage |
| Example | :SIM:INIT:VOLT MAX |
| | Sets the initial step voltage to the maximum. |

## [:SOURce]:SIMulation:NORMal<1|2>:CODE

(Set) →
→ (Query)
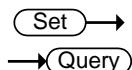
| Description | Sets the external trigger output for the normal 1 or normal 2 step parameter. This option is only applicable when in the Simulation mode. |
| --- | --- |
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:CODE {<NR1>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:CODE? [MINimum|MAXimum] |
| Parameter/Return parameter | <NR1> | HI=1, LO=0 |
| | MINimum | LO, 0 |
| | MAXimum | HI, 1 |
| Example | SIM:NORM1:CODE 1 |

## [:SOURce]:SIMulation:NORMal<1|2>:FREQuency

Set →
→ Query
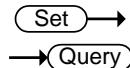
| Description | Sets or queries the frequency of the normal1 or normal2 step of the simulation mode. | |
|---|---|---|
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:FREQuency {<NR2>|MINimum|MAXimum} | |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:FREQuency? [MINimum|MAXimum] | |
| Parameter/Return parameter | <1|2> | Normal 1 or Normal 2 |
| | <NR2> | Frequency of abnormal step |
| | MINimum | Minimum frequency |
| | MAXimum | Maximum frequency |
| Example | :SIM:NORM1:FREQ 60 | |
| | Sets the frequency to 60Hz. | |
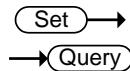
## [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STARt:ENABle

Set →
→ Query

| Description | Enables/Disables the ON Phs parameter of the normal1 or normal2 step for the Simulation mode. | |
|---|---|---|
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STARt:ENABle {<bool>|OFF|ON} | |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STARt:ENABle? | |
| Parameter/Return parameter | <1|2> | Normal 1 or Normal 2 |
| | OFF | 0 | Disabled |
| | ON | 1 | Enabled |
| Example | :SIM:NORM1:PHAS:STAR:ENAB 1 | |
| | Enable the ON Phs. | |

## [:SOURce]:SIMulation:NORMal<1|2> :PHASe:STARt[:IMMediate]

(Set) →

→ (Query)

| | |
|---|---|
| Description | Sets or queries the ON Phs parameter of the normal1 or normal2 step for the Simulation mode. |
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STARt[:IMMediate] {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STARt[:IMMediate]? [MINimum|MAXimum] |
| Parameter/Return parameter | <1|2>    Normal 1 or Normal 2<br><NR2>    ON Phs (start phase)<br>MINimum    0<br>MAXimum    359 |
| Example | :SIM:NORM1:PHAS:STAR 0<br>Sets ON Phs to 0. |

## [:SOURce]:SIMulation:NORMal<1|2> :PHASe:STOP:ENABle

(Set) →

→ (Query)

| | |
|---|---|
| Description | Enables/Disables the OFF Phs parameter of the normal1 or normal2 step for the Simulation mode. |
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STOP:ENABle {<bool>|OFF|ON} |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STOP:ENABle? |
| Parameter/Return parameter | <1|2>    Normal 1 or Normal 2<br>OFF \| 0    Disabled<br>ON \| 1    Enabled |
| Example | :SIM:NORM1:PHAS:STOP:ENAB 1<br>Enable the OFF Phs. |

## [:SOURce]:SIMulation:NORMal<1|2> :PHASe:STOP[:IMMediate]

Set →
→ Query

| Description | Sets or queries the OFF Phs parameter of the normal1 or normal2 step for the Simulation mode. |
|---|---|
| Note: | Sets the off phase of the waveform after the output has been turned off. |
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STOP[:IMMediate] {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:PHASe:STOP[:IMMediate]? [MINimum|MAXimum] |
| Parameter/Return parameter | <1\|2>        Normal 1 or Normal 2<br><NR2>      OFF Phs (Stop phase)<br>MINimum    0<br>MAXimum   359 |
| Example | :SIM:NORM1:PHAS:STOP 0 |
| | Sets OFF Phs to 0. |

Set →
## [:SOURce]:SIMulation:NORMal<1|2>:TIME → Query

| Description | Sets or queries the Time parameter of the normal1 or normal2 step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:TIME {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:TIME? [MINimum|MAXimum] |
| Parameter/Return parameter | <1\|2>        Normal 1 or Normal 2<br><NR2>      Time of the step in seconds<br>MINimum    0<br>MAXimum   99.99s |
| Example | :SIM:NORM1:TIME 1 |
| | Sets the step time to 1 second. |

## [:SOURce]:SIMulation:NORMal<1|2> :VOLTage

Set →
→ Query

| Description | Sets or queries the Vset parameter of the normal1 or normal2 step for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:NORMal<1|2>:VOLTage {<NR2>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:NORMal<1|2>:VOLTage? [MINimum|MAXimum] |
| Parameter/Return parameter | <1|2> Normal 1 or Normal 2 <br> <NR2> Voltage of the abnormal step. <br> MINimum Minimum settable voltage <br> MAXimum Maximum settable voltage |
| Example | :SIM:NORM1:VOLT MAX |
| | Sets the normal1step voltage to the maximum. |

## [:SOURce]:SIMulation:REPeat:COUNt

Set →
→ Query

| Description | Sets or queries the repeat count for the Simulation mode. |
|---|---|
| Syntax | [:SOURce]:SIMulation:REPeat:COUNt {<NR1>|MINimum|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:REPeat:COUNt? |
| Parameter/Return parameter | <NR1> 0 ~ 255 (0 = infinite loop) <br> MINimum <br> MAXimum |
| Example | :SIM:REP:COUN 1 |
| | Sets the repeat count to 1. |

## [:SOURce]:SIMulation:REPeat:ENABle

Set →
→ Query

| Description | Turns the repeat function on or off for the Simulation mode. |
|---|---|

| | |
|---|---|
| Syntax | [:SOURce]:SIMulation:REPeat:ENABle {<bool>\|OFF\|ON} |
| Query Syntax | [:SOURce]:SIMulation:REPeat:ENABle? |
| Parameter/Return parameter | OFF \| 0      Disabled<br>ON \| 1       Enabled |
| Example | :SIM:REP:ENAB 1 |
| | Enables the repeat function. |

## [:SOURce]:SIMulation:TRANsition<1\|2>:TIME

Set →
→ Query
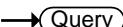
| | |
|---|---|
| Description | Sets or queries the Time parameter of the transition step for the Simulation mode. |
| Syntax | [:SOURce]:SIMulation:TRANsition<1\|2>:TIME {<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:SIMulation:TRANsition<1\|2>:TIME? [MINimum\|MAXimum] |
| Parameter/Return parameter | <NR2>      Time of the step in seconds<br>MINimum    0<br>MAXimum   99.99s |
| Example | :SIM:TRAN1:TIME 1 |
| | Sets the step time to 1 second. |

## [:SOURce]:VOLTage:LIMit:RMS

Set →
→ Query

| | |
|---|---|
| Description | Sets or queries the voltage limit for the continuous operation mode. |
| Syntax | [:SOURce]:VOLTage:LIMit:RMS {<NR2>\|MINimum\|MAXimum} |
| Query Syntax | [:SOURce]:VOLTage:LIMit:RMS? [MINimum\|MAXimum] |
| Parameter | <NR2>        Vrms.<br>MINimum    Minimum voltage limit<br>MAXimum   Maximum voltage limit |
| Return parameter | <NR2>        Returns the voltage limit. |

| Example | VOLT:LIM:RMS? |
| --- | --- |
| | 600.00 |
| | Returns the Vrms limit. |

## [:SOURce]:VOLTage:RANGe

<div align="right">Set →<br>→ Query</div>
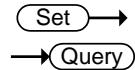
| Description | Sets or queries the voltage range for the continuous operation mode. | |
| --- | --- | --- |
| Syntax | [:SOURce]:VOLTage:RANGe {<NR1>\|R155\|R310\|R600\|AUTO} | |
| Query Syntax | [:SOURce]:VOLTage:RANGe? [MINimum\|MAXimum] | |
| Parameter | <NR1> | Voltage range (155, 310, 600). |
| | R155 | 155 V range |
| | R310 | 310 V range |
| | R600 | 600V range |
| | AUTO | Auto range |
| | MINimum | 155V range |
| | MAXimum | 600V range |
| Return parameter | <NR1> | Returns the voltage range (155, 310, 600). |
| Example | VOLT:RANG R155 | |
| | Sets the voltage range to 155V. | |

## [:SOURce]:VOLTage[:LEVel]:TRIGgered [:AMPLitude]

<div align="right">Set →<br>→ Query</div>
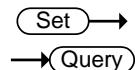
| Description | Sets or queries the RMS voltage for the continuous operation mode (normal operation mode). | |
| --- | --- | --- |
| Syntax | [:SOURce]:VOLTage[:LEVel]:TRIGgered[:AMPLitude] {<NR2>(V)\|MINimum\|MAXimum} | |
| Query Syntax | [:SOURce]:VOLTage[:LEVel]:TRIGgered[:AMPLitude]? [MINimum\|MAXimum] | |
| Parameter/Return parameter | <NR2> | Vrms. |
| | MINimum | Minimum voltage |
| | MAXimum | Maximum voltage |

Example : VOLTage:TRIGgered

150.0

Sets the voltage to 150.0 ACV when triggered.

## [:SOURce]:VOLTage[:LEVel][:IMMediate] [:AMPLitude]
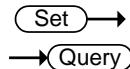
Set →

→ Query

| Description | Sets or queries the RMS voltage for the continuous operation mode. | |
|---|---|---|
| Syntax | [:SOURce]:VOLTage[:LEVel][:IMMediate][:AMPLitude] {<NR2>(V)|MINimum|MAXimum} | |
| Query Syntax | [:SOURce]:VOLTage[:LEVel][:IMMediate][:AMPLitude]? [MINimum|MAXimum] | |
| Parameter/Return parameter | <NR2> | Vrms. |
| | MINimum | Minimum voltage |
| | MAXimum | Maximum voltage |
| Example | :VOLT | |
| | 150.0 | |
| | Sets the voltage to 150.0 ACV. | |

## Remote Sense Command (APS-7200, 7300 only)

Set →
:RSENse:[STATe]                              → Query
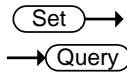
| Description | Sets or queries the state of remote sense. | |
|---|---|---|
| Syntax | :RSENse[:STATE]{<bool>|OFF|ON} | |
| Query Syntax | :RSENse[:STATE]? | |
| Parameter | OFF|0 | Turns the output off. |
| | ON|1 | Turns the output on. |
| Return parameter | <bool> | Returns status of the instrument. |

## Display Command

## :DISPlay[:WINDow]:DESign:MODE     ⟨ Set ⟩⟶

| Description | Sets two display mode. | |
|---|---|---|
| Syntax | :DISPlay[:WINDow]:DESign:MODE{NORMal|SIMPle} | |
| Parameter | MORMal | Configure setup and Measurement. |
| | SIMPle | All measurement times. |
| Example | :DISP:DES:MODE NORM | |
| | Sets standard normal display. | |

## :DISPlay[:WINDow]:MEASure:SOURce<1|3>   ⟨ Set ⟩⟶

| Description | Sets standard normal display to measurement items. | |
|---|---|---|
| Syntax | :DISPlay[:WINDow]:MEASure:SOURce<1|3> {VOLTage|RMS|RPOWer|SPOWer|IPK|IPKH |FREQuency|PFACtor|CFACtor} | |
| Parameter | VOLTage | Measurement voltage. (Only source1, source2, source3) |
| | RMS | Measurement RMS. (Only source1, source2, source3) |
| | RPOWer | Measurement real power. (Only source1, source2, source3) |
| | SPOWer | Measurement apparent power. (Only source1) |
| | IPK | Measurement Ipeak. (Only source2) |
| | IPKH | Measurement Ipeak hold.(Only source2) |
| | FREQuency | Measurement frequency. (Only source3) |
| | PFACtor | Measurement power factor. (Only source3) |
| | CFACtor | Measurement current crest factor. (Only source3) |

Example          :DISP:MEAS:SOURC1 RMS

Sets measurement source 1 RMS display.

# Status Register Overview

To program the APS power supply effectively, the Status registers need to be understood. This chapter explains in detail how the Status registers are used and how to configure them.

## Introduction to the Status Registers

Overview

The status registers are used to determine the status of the power supply. The status registers maintain the status of the protection conditions, operation conditions and instrument errors.

The APS Series have a number of register groups:

- Questionable Status Register Group
- Standard Event Status Register Group
- Operation Status Register Group
- Warning Status Register Group
- Status Byte Register
- Service Request Enable Register
- Service Request Generation
- Error Queue
- Output Buffer

The diagram below shows the structure of the Status registers.

## The Status Registers

**Questionable Status Register**

| | Condition | PTR/NTR | Event | | Enable |
|---|---|---|---|---|---|
| OC (Over Current) | 0 | 0 | 0 | | 0 |
| PU (Device error has occurred) | 1 | 1 | 1 | | 1 |
| | 2 | 2 | 2 | | 2 |
| OT (Over Temperature) | 3 | 3 | 3 | | 3 |
| | 4 | 4 | 4 | | 4 |
| | 5 | 5 | 5 | | 5 |
| | 6 | 6 | 6 | | 6 |
| | 7 | 7 | 7 | | 7 |
| CAL(Calibration data is invalid) | 8 | 8 | 8 | | 8 |
| OP (Over Power) | 9 | 9 | 9 | | 9 |
| | 10 | 10 | 10 | | 10 |
| | 11 | 11 | 11 | | 11 |
| | 12 | 12 | 12 | | 12 |
| | 13 | 13 | 13 | | 13 |
| | 14 | 14 | 14 | | 14 |
| Always 0 | 15 | 15 | 15 | | 15 |

**Operation Status Register**

| | Condition | PTR/NTR | Event | | Enable |
|---|---|---|---|---|---|
| | 0 | 0 | 0 | | 0 |
| Busy status | 1 | 1 | 1 | | 1 |
| | 2 | 2 | 2 | | 2 |
| | 3 | 3 | 3 | | 3 |
| | 4 | 4 | 4 | | 4 |
| | 5 | 5 | 5 | | 5 |
| | 6 | 6 | 6 | | 6 |
| | 7 | 7 | 7 | | 7 |
| LOCK status (SYNC status) | 8 | 8 | 8 | | 8 |
| | 9 | 9 | 9 | | 9 |
| | 10 | 10 | 10 | | 10 |
| | 11 | 11 | 11 | | 11 |
| Sequence is in the Hold status | 12 | 12 | 12 | | 12 |
| | 13 | 13 | 13 | | 13 |
| Sequence or Simulation is in the Run status | 14 | 14 | 14 | | 14 |
| Always 0 | 15 | 15 | 15 | | 15 |

**Warning Status Register**

| | Condition | PTR/NTR | Event | | Enable |
|---|---|---|---|---|---|
| | 0 | 0 | 0 | | 0 |
| Output overcurrent (RMS) | 1 | 1 | 1 | | 1 |
| | 2 | 2 | 2 | | 2 |
| Output overcurrent (Peak) | 3 | 3 | 3 | | 3 |
| | 4 | 4 | 4 | | 4 |
| | 5 | 5 | 5 | | 5 |
| OT (Over Temperature) | 6 | 6 | 6 | | 6 |
| | 7 | 7 | 7 | | 7 |
| | 8 | 8 | 8 | | 8 |
| | 9 | 9 | 9 | | 9 |
| Output OFF after RMS current limiter is activated | 10 | 10 | 10 | | 10 |
| Output OFF after peak current limiter is activated | 11 | 11 | 11 | | 11 |
| | 12 | 12 | 12 | | 12 |
| RMS current limiter is operating | 13 | 13 | 13 | | 13 |
| | 14 | 14 | 14 | | 14 |
| Always 0 | 15 | 15 | 15 | | 15 |

**Standard Event Status Register**

| | Event | | Enable |
|---|---|---|---|
| OPC (Operation Complete) | 0 | | 0 |
| RQC (Request Control) | 1 | | 1 |
| QUE (Query Error) | 2 | | 2 |
| DDE (Device Dependent Error) | 3 | | 3 |
| EXE (Execution Error) | 4 | | 4 |
| CME (Command Error) | 5 | | 5 |
| URQ (User Request) | 6 | | 6 |
| PON (Power ON) | 7 | | 7 |

Output Buffer

Error Queue

**Status Byte Register**

| | |
|---|---|
| | 0 |
| WAR | 1 |
| ERR | 2 |
| QUES | 3 |
| MAV | 4 |
| ESB | 5 |
| RQS | 6 |
| OPER | 7 |

MSS

**Service Request Enable Register**

| |
|---|
| 0 |
| 1 |
| 2 |
| 3 |
| 4 |
| 5 |
| 6 |
| 7 |

Service Request Generation

# Questionable Status Register Group

Overview        The Questionable Status Register Group indicates if any protection modes or limits have been tripped.
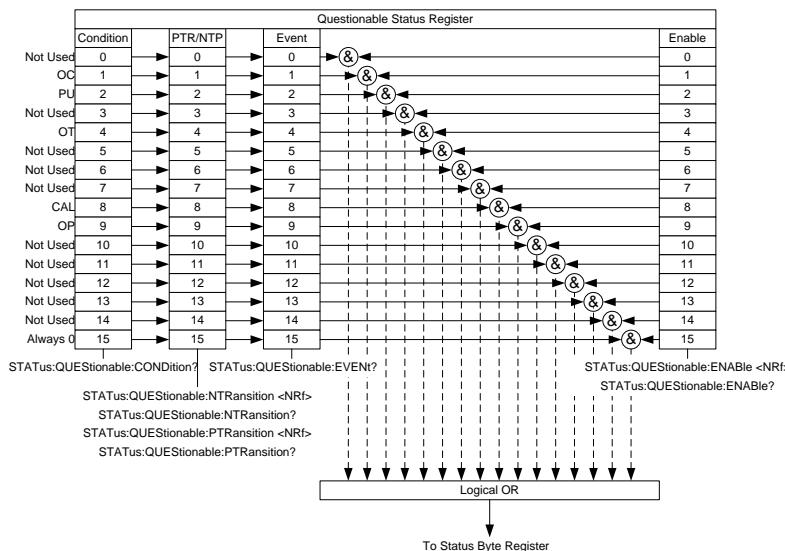


Bit Summary

| Event | Bit # | Bit Weight |
|---|---|---|
| Not Used | 0 | 1 |
| OC (Over-Current) | 1 | 2 |
| Over current protection has been tripped | | |
| PUL (Device error has occurred) | 2 | 4 |
| AC power switch is off | | |
| OT (Over Temperature) | 4 | 16 |
| Over temperature protection has been tripped | | |

| | | |
|---|---|---|
| CAL (Calibration data is invalid) | 8 | 256 |
| OP (Over-Power) | 9 | 512 |
| Over power protection has been tripped | | |
| Always 0 | 15 | 32768 |

| | |
|---|---|
| Condition Register | The Questionable Status Condition Register indicates the status of the power supply. If a bit is set in the Condition register, it indicates that the event is true. Reading the condition register does not change the state of the condition register. |
| PTR/NTR Filters | The PTR/NTR (Positive/Negative transition) register determines the type of transition conditions that will set the corresponding bit in the Event Registers. Use the Positive transition filter to view events that change from false to positive, and use the negative transition filter to view events that change from positive to negative. |

| Positive Transition | 0→1 |
|---|---|
| Negative Transition | 1→0 |

| | |
|---|---|
| Event Register | The PTR/NTR Register will dictate the type of transition conditions will set the corresponding bits in the Event Register. If the Event Register is read, it will be cleared to 0. |
| Enable Register | The Enable register determines which Events in the Event Register will be used to set the QUES bit in the Status Byte Register. |

## Operation Status Register Group

Overview                    The Operation Status Register Group indicates
                            the operating status of the power supply.
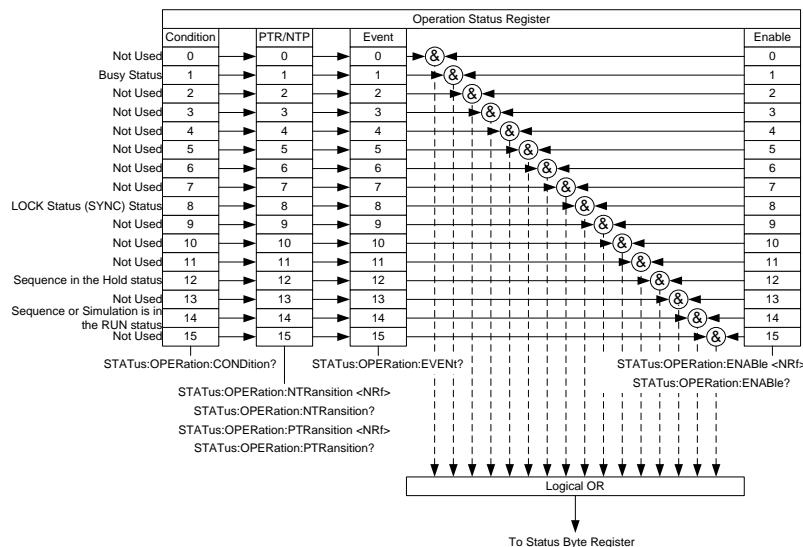


Bit Summary

| Event | Bit # | Bit Weight |
|---|---|---|
| Busy Status | 1 | 2 |
| LOCK status (SYNC) status | 8 | 256 |
| Sequence is in the Hold status | 12 | 4096 |
| Sequence or Simulation is in the RUN status | 14 | 16384 |

| | |
|---|---|
| Condition Register | The Operation Status Condition Register indicates the operating status of the power supply. If a bit is set in the Condition register, it indicates that the event is true. Reading the condition register does not change the state of the condition register. |
| PTR/NTR Filters | The PTR/NTR (Positive/Negative transition) register determines the type of transition conditions that will set the corresponding bit in the Event Registers. Use the Positive transition filter to view events that change from false to positive, and use the negative transition filter to view events that change from positive to negative. |

| | |
|---|---|
| Positive Transition | 0→1 |
| Negative Transition | 1→0 |

| | |
|---|---|
| Event Register | The PTR/NTR Register will dictate the type of transition conditions will set the corresponding bits in the Event Register. If the Event Register is read, it will be cleared to 0. |
| Enable Register | The Enable register determines which registered Events in the Event Register will be used to set the OPER bit in the Status Byte Register. |

## Warning Status Register Group

Overview

The Warning Status Register Group is a secondary protection status register for the supply output.
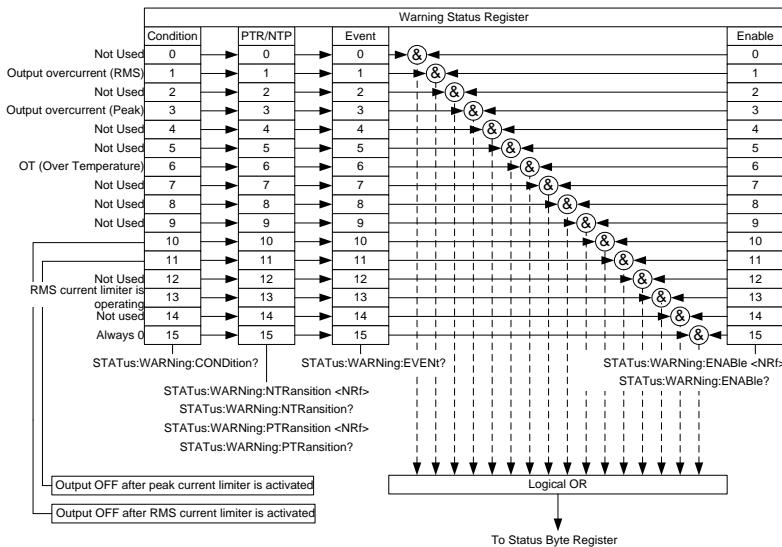


Bit Summary

| Event | Bit # | Bit Weight |
|---|---|---|
| Output overcurrent (RMS) | 1 | 2 |
| Output RMS overcurrent has been tripped. | | |
| Output over-current (Peak) | 3 | 8 |
| Output peak over-current has been tripped. | | |
| OT (Over Temperature) | 6 | 64 |
| Output OFF after peak current limiter is activated | 10 | 1024 |

| | | | |
|---|---|---|---|
| Output OFF after RMS current limiter is activated | 11 | 2048 |
| RMS current limiter is operating | 13 | 8192 |
| Always 0 | 15 | 32768 |

| | |
|---|---|
| Condition Register | The Warning Status Condition Register indicates the warning status of the power supply. If a bit is set in the Condition register, it indicates that the event is true. Reading the condition register does not change the state of the condition register. |
| PTR/NTR Filters | The PTR/NTR (Positive/Negative transition) register determines the type of transition conditions that will set the corresponding bit in the Event Registers. Use the Positive transition filter to view events that change from false to positive, and use the negative transition filter to view events that change from positive to negative. |

| | |
|---|---|
| Positive Transition | 0→1 |
| Negative Transition | 1→0 |

| | |
|---|---|
| Event Register | The PTR/NTR Register will dictate the type of transition conditions will set the corresponding bits in the Event Register. If the Event Register is read, it will be cleared to 0. |
| Enable Register | The Enable register determines which registered Events in the Event Register will be used to set the WAR bit in the Status Byte Register. |

## Standard Event Status Register Group

Overview

The Standard Event Status Register Group indicates if any errors have occurred. The bits of the Event register are set by the error event queue.
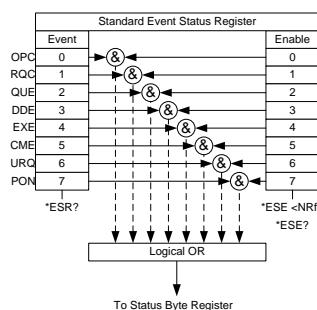


Bit Summary

| Event | Bit # | Bit Weight |
|---|---|---|
| OPC (Operation complete) | 0 | 1 |
| The OCP bit is set when all selected pending operations are complete. This bit is set in response to the *OPC command. | | |
| RQC (Request control) | 1 | 2 |
| QUE (Query Error) | 2 | 4 |
| The Query Error bit is set in response to an error reading the Output Queue. This can be caused by trying to read the Output Queue when there is no data present. | | |
| DDE (Device Dependent Error) | 3 | 8 |
| Device specific error. | | |

| | | |
|---|---|---|
| EXE (Execution Error) | 4 | 16 |
| The EXE bit indicates an execution error due to one of the following: illegal command parameter, parameter out of range, invalid parameter, the command didn't execute due to an overriding operation condition. | | |
| CME (Command Error) | 5 | 32 |
| The CME bit is set when a syntax error has occurred. The CME bit can also be set when a <GET> command is received within a program message. | | |
| URQ (User Request) | 6 | 64 |
| PON (Power On) | 7 | 128 |
| Indicates the power is turned on. | | |

| | |
|---|---|
| Event Register | Any bits set in the event register indicate that an error has occurred. Reading the Event register will reset the register to 0. |
| Enable Register | The Enable register determines which Events in the Event Register will be used to set the ESB bit in the Status Byte Register. |

## Status Byte Register & Service Request Enable Register

Overview

The Status Byte register consolidates the status events of all the status registers. The Status Byte register can be read with the *STB? query and can be cleared with the *CLS command.
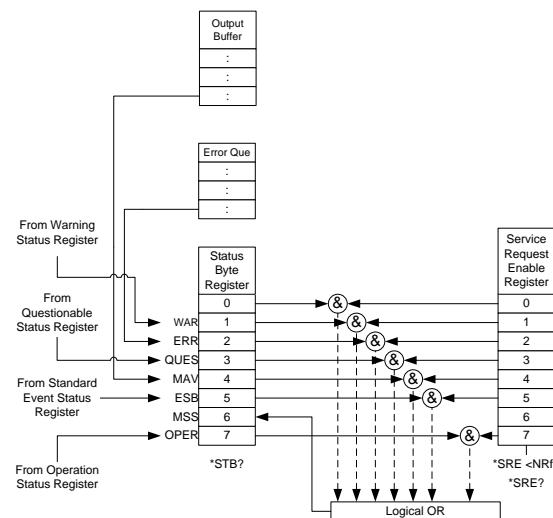


Bit Summary

| Event | Bit # | Bit Weight |
|---|---|---|
| WAR (Warning Status Register) The summary bit for the Warning Status Register group. | 1 | 2 |
| ERR (Error Event/Queue) If data is present in the Error queue, the ERR bit will be set. | 2 | 4 |
| QUES (Questionable Status Register) The summary bit for the Questionable Status Register group. | 3 | 8 |

| | | |
|---|---|---|
| MAV (Message Available) This is set when there is data in the Output Queue waiting to be read. | 4 | 16 |
| (ESB) Event Summary Bit. The ESB is the summary bit for the Standard Event Status Register group. | 5 | 32 |
| MSS Bit<br><br>The MSS Bit is the summary of the Status Byte Register and Service Request register (bits 1-5, 7). This will be set to 1. | 6 | 64 |
| OPER (Operation Status Register)<br>OPER bit is the summary bit for the Operation Status Register Group. | 7 | 128 |

| | |
|---|---|
| Status Byte Register | Any bits set in the Status byte register acts as a summary register for all the three other status registers and indicates if there is a service request, an error in the Error Queue or data in the Output Queue. Reading the Status Byte register will reset the register to 0. |
| Service Request Enable Register | The Service Request Enable Register controls which bits in the Status Byte Register are able to generate service requests. |

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# Error List

## Command Errors

Overview

An <error/event number> in the range [ -199 , -100 ] indicates that an IEEE 488.2 syntax error has been detected by the instrument's parser. The occurrence of any error in this class shall cause the command error bit (bit 5) in the event status register (IEEE 488.2, section 11.5.1) to be set. One of the following events has occurred:

- An IEEE 488.2 syntax error has been detected by the parser. That is, a controller-to-device message was received which is in violation of the IEEE 488.2 standard. Possible violations include a data element which violates the device listening formats or whose type is unacceptable to the device.

- An unrecognized header was received. Unrecognized headers include incorrect device-specific headers and incorrect or unimplemented IEEE 488.2 common commands.

   Events that generate command errors shall not generate execution errors, device-specific errors, or query errors; see the other error definitions in this chapter.

| Error Code | Description |
|---|---|
| -100 Command Error | This is the generic syntax error for devices that cannot detect more specific errors. This code indicates only that a Command Error as defined in IEEE 488.2,11.5.1.1.4 has occurred. |
| -102 Syntax error | An unrecognized command or data type was encountered; for example, a string was received when the device does not accept strings. |
| -103 Invalid separator | The parser was expecting a separator and encountered an illegal character; for example, the semicolon was omitted after a program message unit, MEAS:VOLT:DC?:MEASCURR:DC? |
| -104 Data type error | The parser recognized a data element different than one allowed; for example, numeric or string data was expected but block data was encountered. |
| -108 Parameter not allowed | More parameters were received than expected for the header; for example, the :SYSTem:KLOCk command only accepts one parameter, so receiving SYSTem:KLOCk 1,0 is not allowed. |
| -109 Missing parameter | Fewer parameters were recieved than required for the header; for example, the :SYSTem:KLOCk command requires one parameter, so receiving :SYSTem:KLOCk is not allowed. |
| -111 Header separator error | A character which is not a legal header separator was encountered while parsing the header; for example, no white space followed the header, thus *SRE2 is an error. |

| | |
|---|---|
| -112 Program mnemonic too long | The header contains more that twelve characters (see IEEE 488.2, 7.6.1.4.1). |
| -113 Undefined header | The header is syntactically correct, but it is undefined for this specific device; for example, *XYZ is not defined for any device. |
| -114 Header suffix out of range | The value of a numeric suffix attached to a program mnemonic, see Syntax and Style section 6.2.5.2, makes the header invalid. |
| -115 Unexpected number of parameters | The number of parameters received does not correspond to the number of parameters expected. This is typically due an inconsistency with the number of instruments in the selected group. |
| -120 Numeric data error | This error, as well as errors -121 through -129, are generated when parsing a data element which appreares to be numeric, including the nondecimal numeric types. This particular error message should be used if the device cannot detect a more specific error. |
| -121 Invalid character in number | An invalid character for the data type being parsed was encountered; for example, an alpha in a decimal numeric or a "9" in octal data. |
| -128 Numeric data not allowed | A legal numeric data element was received, but the device does not accept one in this position for the header. |
| -131 Invalid suffix | The suffix does not follow the syntax described in IEEE 488.2, 7.7.3.2, or the suffix is inappropriate for this device. |

| -141 Invalid character data | Either the character data element contains an invalid character or the particular element received is not valid for the header. |
| --- | --- |
| -148 Character data not allowed | A legal character data element was encountered where prohibited by the device. |
| -151 Invalid string data | A string data element was expected, but was invalid for some reason (see IEEE 488.2, 7.7.5.2); for example, an END message was received before the terminal quote character. |
| -158 String data not allowed | A string data element was encountered but was not allowed by the device at this point in parsing. |
| -160 Block data error | This error, as well as errors -161 through -169, are generated when parsing a block data element. This particular error message should be used if the device cannot detect a more specific error. |
| -161 Invalid block data | A block data element was expected, but was invalid for some reason (see IEEE 488.2, 7.7.6.2); for example, an END message was received before the length was satisfied. |
| -168 Block data not allowed | A legal block data element was encountered but was not allowed by the device at this point in parsing. |
| -178 Expression data not allowed | A legal expression data was encountered but was not allowed by the device at this point in parsing. |

## Execution Errors

Overview

An <error/event number> in the range [ -299 , -200 ] indicates that an error has been detected by the instrument's execution control block. The occurrence of any error in this class shall cause the execution error bit (bit 4) in the event status register (IEEE 488.2, section 11.5.1) to be set. One of the following events has occurred:

- A <PROGRAM DATA> element following a header was evaluated by the device as outside of its legal input range or is otherwise inconsistent with the device's capabilities.

- A valid program message could not be properly executed due to some device condition.

  Execution errors shall be reported by the device after rounding and expression evaluation operations have taken place. Rounding a numeric data element, for example, shall not be reported as an execution error. Events that generate execution errors shall not generate Command Errors, device-specific errors, or Query Errors; see the other error definitions in this section.

| Error Code | Description |
|---|---|
| -200 Execution error | This is the generic syntax error for devices that cannot detect more specific errors. This code indicates only that an Execution Error as defined in IEEE 488.2, 11.5.1.1.5 has occurred. |

| -201 Invalid while in local | Indicates that a command is not executable while the device is in local due to a hard local control (see IEEE 488.2, 5.6.1.5); for example, a device with a rotary switch receives a message which would change the switches state, but the device is in local so the message cannot be executed. |
|---|---|
| -203 Command protected | Indicates that a legal password-protected program command or query could not be executed because the command was disabled. |
| -211 Trigger ignored | Indicates that a GET, *TRG, or triggering signal was received and recognized by the device but was ignored because of device timing considerations; for example, the device was not ready to respond. Note: a DT0 device always ignores GET and treats *TRG as a Command Error. |
| -213 Init ignored | Indicates that a request for a measurement initiation was ignored as another measurement was already in progress. |
| -220 Parameter error | Indicates that a program data element related error occurred. This error message should be used when the device cannot detect the more specific errors described for errors -221 through -229. |
| -221 Settings conflict | Indicates that a legal program data element was parsed but could not be executed due to the current device state (see IEEE 488.2, 6.4.5.3 and 11.5.1.1.5.). |

| | |
|---|---|
| -222 Data out of range | Indicates that a legal program data element was parsed but could not be executed because the interpreted value was outside the legal range as defined by the device (see IEEE 488.2, 11.5.1.1.5.). |
| -224 Illegal parameter value | Used where exact value, from a list of possibles, was expected. |

## Device Specific Errors

| | |
|---|---|
| Overview | An <error/event number> in the range [ -399 , -300 ] or [ 1 , 32767 ] indicates that the instrument has detected an error which is not a command error, a query error, or an execution error; some device operations did not properly complete, possibly due to an abnormal hardware or firmware condition. These codes are also used for self-test response errors. The occurrence of any error in this class should cause the device-specific error bit (bit 3) in the event status register (IEEE 488.2, section 11.5.1) to be set. The meaning of positive error codes is device-dependent and may be enumerated or bit mapped; the <error message>string for positive error codes is not defined by SCPI and available to the device designer. |
| | Note that the string is not optional; if the designer does not wish to implement a string for a particular error, the null string should be sent (for example, 42,""). The occurrence of any error in this class should cause the device-specific error bit (bit 3) in the event status register (IEEE 488.2, section 11.5.1) to be set. Events that generate device-specific errors shall not generate command errors, execution errors, |

or query errors; see the other error definitions
in this section.

| Error Code | Description |
|---|---|
| -310 System error | Indicates that some error, termed "system error" by the device, has occurred. This code is device-dependent. |
| -320 Storage fault | Indicates that the firmware detected a fault when using data storage. This error is not an indication of physical damage or failure of any mass storage element. |

## Query Errors

Overview

An <error/event number> in the range [ -499 , -400 ] indicates that the output queue control of the instrument has detected a problem with the message exchange protocol described in IEEE 488.2, chapter 6. The occurrence of any error in this class shall cause the query error bit (bit 2) in the event status register (IEEE 488.2, section 11.5.1) to be set. These errors correspond to message exchange protocol errors described in IEEE 488.2, section 6.5. One of the following is true:

- An attempt is being made to read data from the output queue when no output is either present or pending;

- Data in the output queue has been lost.

  Events that generate query errors shall not generate command errors, execution errors, or device-specific errors; see the other error definitions in this section.

| Error Code | Description |
|---|---|
| -400 Query error | This is the generic query error for devices that cannot detect more specific errors. This code indicates only that a Query Error as defined in IEEE 488.2, 11.5.1.1.7 and 6.3 has occurred. |

# APPENDIX

## APS-7000 Default Settings

The following default settings are the factory configuration settings for the power supply.

For details on how to return to the factory default settings, please see the user manual.

| Continuous Mode | APS-7050 | APS-7100 | APS-7200 | APS-7300 |
|---|---|---|---|---|
| Range | | | 155V | |
| ACV | | | 0.00V | |
| FREQ | | | 60.00Hz | |
| IRMS | 4.20A | 8.40A | 16.80A | 25.20A |
| ON PHS | | | 0° | |
| OFF PHS | | | 0° | |
| V limit | | | 155.0Vrms | |
| F Limit | | | 500.0Hz | |
| Ipeak Limit | 16.80A | 33.60A | 67.20A | 100.8A |

| Simulation Mode | APS-7050 | APS-7100 | APS-7200 | APS-7300 |
|---|---|---|---|---|
| Step | | | Initial | |
| Repeat | | | 1 | |
| Time | | | 0.10s | |
| ON Phs | | | ON, 0 | |
| Vset | | | 0.00 | |
| OFF Phs | | | ON, 0 | |
| Fset | | | 50.00 | |
| Trig Out | | | LO | |
| Range | | | HI | |

| Sequence Mode | APS-7050 | APS-7100 | APS-7200 | APS-7300 |
|---|---|---|---|---|
| Step | | 0 | | |
| Time | | 0.10s | | |
| Jump To | | ON, 1 | | |
| Jump Cnt | | 1 | | |
| Branch1 | | OFF | | |
| Branch2 | | OFF | | |
| Term | | CONTI | | |
| Trig Out | | LO | | |
| ON Phs | | OFF | | |
| OFF Phs | | OFF | | |
| Vset | | 0.00, CT | | |
| Fset | | 50.00 | | |

| Program Mode | APS-7050 | APS-7100 | APS-7200 | APS-7300 |
|---|---|---|---|---|
| Not applicable | | | | |

| Configuration Menu | APS-7050 | APS-7100 | APS-7200 | APS-7300 |
|---|---|---|---|---|
| Surge/Dip Control | | OFF | | |
| Ramp Control | | OFF | | |
| T ipeak, hold(msec) | | 1ms | | |
| Power ON Output | | OFF | | |
| Buzzer | | ON | | |
| SCPI Emulation | | GW | | |
| Program Timer | | SEC (seconds) | | |
| Remote Sense | N/A | N/A | OFF | OFF |
| LAN, Rear USB, Serial Port, GPIB | | N/A | | |
| LCD Contrast | | 50% | | |
| LCD Brightness | | 50% | | |
| LCD Saturation | | 50% | | |

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