

**ELECTRONIC LOAD FAMILY
PROGRAMMING REFERENCE
GUIDE**

**HP MODELS 6060A AND 60501A,
60502A AND 60504A**

HP Part No. 06060-90005

MANUAL CHANGES
Programming Reference Guide
Manual HP P/N 06060-90005

Change Date 6/10/91

Make all the corrections according to ERRATA below, then check the following table for your Electronic Load serial number and enter any listed changes.

SERIAL NUMBER		MAKE CHANGES
prefix	numbers	
ALL		ERRATA

ERRATA:

In addition to the models listed on the title page, this reference guide also applies to the following models:

HP 6063A
HP 60503A
HP 6060B
HP 6063B
HP 60501B
HP 60502B
HP 60503B
HP 60504B
HP 60507B

The command summary information that appears in table 4-1 is superceded by the information in the Programming Ranges and the Factory Default Settings tables located in the operating manual that is shipped with each electronic load.

The EPU (extended power unavailable) status bit discussed in chapter 4 and chapter 5 of this manual has no significance in later "A" version and in all "B" version electronic loads.

PRINTING HISTORY

The manual printing date and part number indicate the current edition. Reprints between editions will have the same printing date and may include change pages with corrections or additions to be made to the manual by the user.

New editions of this manual will have a new printing date and, in some cases, may have a new part number. The new edition will include all changes and corrections made since the previous edition.

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SAFETY GUIDELINES

The beginning of the Electronic Load Operating Manual has a Safety Summary Page. Be sure that you are familiar with the information on that page before programming the electronic load for operation from a controller.

THREE YEAR WARRANTY

The HP Electronic Load Family products have a three year warranty. Please replace the first paragraph of the warranty statement on the inside front cover with the following:

This Hewlett-Packard hardware product is warranted against defects in material and workmanship for a period of three years from date of delivery. HP software and firmware products, which are designated by HP for use with a hardware product and when properly installed on that hardware product, are warranted not to fail to execute their programming instructions due to defects in material and workmanship. If HP receives notice of such defects during the warranty period, HP shall repair or replace software media and firmware which do not execute their programming instructions due to such defects. HP does not warrant that the operation for the software, firmware or hardware shall be uninterrupted or error free.

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Chapter 1 INTRODUCTION

PURPOSE

The purpose of this guide is to enable you to use HPSL commands to remotely control your Hewlett-Packard electronic load from a controller using HPSL programming language. It is assumed that the following has been done:

- The electronic load has been installed and is operating normally from its front panel.
- The controller has been connected to the electronic load and the electronic load's HP-IB address has been set.

NOTE

*The electronic load HP-IB address cannot be set by program. It must be set from the front panel of the electronic load (refer to the **Installation** chapter of your electronic load **Operating Manual**)*

DOCUMENTATION

IMPORTANT!

*Read your electronic load **Operating Manual** before using this guide.*

Supplied

Every Electronic Load comes with the following documentation:

Operating Manual Installation and Basic Operating Instructions, including local front-panel operation. *Be sure to read that document first.*

Programming Reference Guide This guide. For remote operation from a controller.

Recommended

The following reference documents are recommended:

- ¹Tutorial Description of the Hewlett-Packard Interface Bus
 - Highly recommended for those not experienced with IEEE 488.1 and 488.2
- ²ANSI/IEEE Standard 488.2-1987
 - The source document for programming via IEEE 488.1 and IEEE 488.2

¹Contact your local HP Sales Office

²Contact Institute of Electrical and Electronics Engineers, 345 E. 47 Street, New York, NY 10017, USA

HOW TO USE THIS GUIDE

Chapter	Synopsis
2 - Introduction to HPSL	The basics of HPSL to help you understand the terminology and diagrams in <i>Chapter 4</i>
3 - Introduction to Programming	How to understand the command tree diagram and construct typical operating programs
4 - Language Dictionary	An alphabetically ordered description of all electronic load HPSL commands
5 - Status Reporting	An explanation of how the electronic load status registers are affected by the HPSL programming statements.

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WHAT YOU SHOULD ALREADY KNOW

This guide does not assume that you know anything about HPSL or are a programmer. It is assumed that you do know:

- the basics of the Hewlett-Packard Interface Bus (HP-IB)
- how to send and receive ASCII data to and from an HP-IB instrument (or where, in your computer and HP-IB interface documentation, to find instructions for doing this).
- how to incorporate the HPSL statements as ASCII strings within output and input statements of the programming language you are using.
- the basic operating principles of the electronic load as explained in Chapters 2 and 5 of your electronic load *Operating Manual*.

HP-IB CAPABILITIES OF THE ELECTRONIC LOAD

The HP-IB capabilities of a typical electronic load are listed in Table 1-1.

NOTE

*Refer to the General Information chapter of your electronic load **Operating Manual** for its exact capabilities.*

Table 1-1. HP-IB Capability of Electronic Loads

HP-IB Capability	Response	Interface Functions
Talker/Listener	All electronic load functions except for setting the HP-IB address are programmable over the HP-IB. The electronic load can send and receive messages over the HP-IB. Status information is sent using a serial poll. Front panel annunciators indicate the present HP-IB state of the electronic load.	AH1, SH1, T6, L4
Service Request	The electronic load sets the SRQ line true if there is an enabled service request condition. Refer to <i>Chapter 5—Status Reporting</i> for more information.	SR1
Remote/Local	In local mode, the electronic load is controlled from the front panel but will also execute commands sent over the HP-IB. The electronic load powers up in local mode and remains in local mode until it receives a command over the HP-IB. Once the electronic load is in remote mode, the front panel RMT annunciator is on, all front panel keys (except Local) are disabled, and the display is in normal metering mode. Pressing Local on the front panel returns the electronic load to local mode. Local can be disabled using local lockout so that only the controller or the power switch can return the electronic load to local mode.	RL1
Device Trigger	The electronic load will respond to device trigger function.	DT1
Device Clear	The electronic load responds to the Device Clear (DCL) and Selected Device Clear (SDC) interface commands. These cause the electronic load to clear any activity that would prevent it from receiving and executing a new command (including *WAI and *OPC?). DCL and SDC do not change any programmed settings.	DCL, SDC

Chapter 2 INTRODUCTION TO HPSL

WHAT IS HPSL?

HPSL stands for *Hewlett-Packard Systems Language*. It is a programming language developed by Hewlett-Packard for controlling instrument functions. HPSL is intended to function with *standard* HP-IB hardware. HPSL conforms to the *IEEE 488.2 Standard Digital Interface for Programmable Instrumentation*. This standard provides codes, formats, protocols, and common commands not defined in the original *IEEE 488.1* standards. Unless you intend to do some very intricate programming, you need not be expert in the *IEEE 488.2* standard, although it is a good reference document to have available.

NOTE

TMSL (Test and Measurement Systems Language) is a later version of HPSL that has been made available outside of Hewlett-Packard for industry use. Although it is very similiar, the HPSL used in the electronic loads may not be totally compatible with TMSL.

HPSL STATEMENTS

HPSL statements are instrument control commands and queries. A command statement sends an instruction to the electronic load and a command query requests information from the electronic load.

Simple Command Statements

The simplest command statement consists of a command, or keyword, usually followed by a parameter or data:

```
VOLT 25    Simple command statements
CURR 50
TRIG
```

Compound Command Statements

When two or more keywords are connected by colons (:), it creates a compound command statement. The last keyword usually is followed by a parameter or data.

```
VOLT:SLEW 1000    Compound command statements
CURR:RANG 6
TRIG:SOUR BUS
```

Simple Command Queries

The simplest command query consists of a keyword followed by a question mark:

```
VOLT?    Simple command queries
CURR? CHAN?
```

Compound Command Queries

When two or more keywords are connected by colons and followed by a question mark, it creates a compound query statement.

```
VOLT:TRIG?    Compound command queries
CURR:PROT? MEAS:POW?
```

HPSL Keywords

Keywords (also known as "Instrument Control Headers") are recognized by the electronic load's decoder, or "parser". Each keyword is intended to be descriptive of the statement function. Refer to Figure 4-2 in 'Chapter 4—Language Dictionary' for a quick look at all the electronic load keywords.

Forms of Keywords

Every keyword has two forms:

- Long Form** The word is spelled out completely to identify its function. STATUS, RESISTANCE, and TRIGGER are long-form keywords
- Short Form** The word contains only the first three or four letters of the long form. STAT, RES, and TRIG are short-form keywords

Short forms are constructed according to the following rules:

- If the keyword consists of *four or fewer* letters -
 - then all the letters are used
- If the keyword consists of *five or more* letters -
 - and the fourth letter is IS NOT a vowel (*a, e, i, o, u*)
 - then the *first four* letters are used
 - and the fourth letter is a vowel
 - then only the *first three* letters are used

NOTE

The short form provides the fastest program execution.

Keyword Conventions

In keyword definitions and diagrams in this guide, the short-form part of each keyword is emphasized in **boldface** UPPER-CASE letters to help you remember it.

- **TRIG**ger
- **IMM**ediate
- **RES**istance
- **SHOR**t

The HPSL parser (decoder) is not sensitive to case. It will accept *Trig*, *trig*, *trigger*, *TRIGGER*, *triGgER*, etc. Regardless of which form you use, you must spell out all the letters. For example, RESI or TRI will not be recognized.

Keyword Parameters

Parameters are data values that the parser expects to find after certain keywords. All data programmed to or returned from the electronic load is ASCII. The data may be numerical data or character strings. HPSL uses the parameter forms in Section 7 of *IEEE 488.2 Standard Digital Interface for Programmable Instrumentation* with the additions described here.

Numerical Data Formats. HPSL accepts the first four numerical data types listed in Table 2-1 and described in Section 7 of *IEEE 488.2 Standard Digital Interface for Programmable Instrumentation*. In addition, HPSL recognizes an expanded form of decimal numeric value known as **<NRf>**. This allows the characters *MIN* and *MAX* to be entered for the minimum and maximum values that the parameter can be set to under the existing operating conditions.

Table 2-1. Numerical Data Formats

Symbol	Data Form
NR1	Digits with no decimal point. The decimal point is assumed to be to the right of the least-significant digit. For example, 273, 0273
NR2	Digits with a decimal point. E.g., 273., 27.3, .0273
NR3	Digits with a decimal point and an exponent. E.g., 2.73E+2, 2.73E-2
NRf	Flexible decimal form that includes NR1 or NR2 or NR3. E.g., 273, 27.3, 2.73E+2
NRf+	Expanded decimal form that includes NRf and MIN,MAX. E.g., 273, 27.3, 2.73E-2, MIN, MAX. MIN and MAX are the minimum and maximum limit values for the parameter and are implicit in the range specification for the parameter.

Numerical Data Suffixes and Multipliers. Numeric data may be followed by a suffix that dimensions the data. A suffix may be preceded by a multiplier. Section 7 of *IEEE 488.2 Standard Digital Interface for Programmable Instrumentation* describes the approved data suffixes and multipliers. Where no suffix is entered, the dimension is implied by the syntax of the command. The electronic loads make use of the suffixes and multipliers listed in Table 2-2 and Table 2-3. Note the special consideration given to the multiplier for mega. In most cases, mega is represented by *MA*. However, there are exceptions made for megahertz (*MHZ*) and megohm (*MOHM*). In only these two cases, *M* is understood to be $1E+6$. Do not confuse the mega multiplier *MA* with the combination suffix and multiplier *MA*, which represents milliamperes ($1E-3$).

Table 2-2. Suffix Elements

Class	Preferred Suffix	Secondary Suffix	Referenced Unit
Current	A		Ampere
Frequency	Hz	MHZ	Hertz Megahertz
Resistance	OHM	MOHM	Ohm Megohm
Time	s		Second
Amplitude	V		Volt
Power	W		Watt
Slew Rate	A/s V/s		Amperes/Second Volts/Second

Table 2-3. Most-Used Suffix Multipliers

Multiplier	Mnemonic	Definition
1E6	MA	mega
1E3	K	kilo
1E-3	M	milli
1E-6	U	micro
1E-9	N	nano

NOTE

You may construct compound suffixes of multipliers and elements. For example: 1 KHz for 1000 Hz; 1 A/ μ s for 1000000 A/s

Numerical Data Conventions. In this guide, numerical data types are shown in emphasized text within angle brackets, such as **<NR1>** or **<NRf>**. On drawings, numerical data appears within boxes **<NRf>**.

Data suffixes are shown inside brackets within boxes **suffix**. The brackets around the suffix indicate that the entry is optional. That is because there is a default suffix for the data that accompanies each command.

Character Data Formats. For command statements, the **<NRf+>** data format permits entry of required characters. For query statements, character strings may be returned in either of the forms shown in Table 2-4, depending on the length of the returned string.

Table 2-4. Query Character String Formats

Symbol	Character Form
crd	Character Response Data. Permits the return of up to 12 characters
aard	Arbitrary ASCII Response Data. Permits the return of undelimited 7-bit ASCII. This data type is an implied message terminator (refer to "Separators and Terminators").

Character Data Conventions. In this guide, character string parameters are emphasized similarly to keywords, such as ON, OFF, and CONTinuous. This applies both to text and drawings.

Separators and Terminators

In addition to keywords and parameters, HPSL program statements require the following:

Data Separators. Data must be separated from the previous command keyword by a space. This is shown in examples as a space (VOLT 25) and on diagrams by the letters SP inside a circle.

Keyword Separators. Keywords (or headers) are separated by a colon (:), a semicolon (;), or both. For example:

- INP:SHOR
- MEAS:CURR?:VOLT?
- CURR 25::VOLT 50

IMPORTANT

Proper use of the (:) and the (;) is very important to the construction of command messages. This is explained in "Chapter 3—Introduction to Programming"

Program Line Terminators. A terminator informs HPSL that it has reached the end of a statement. Normally, this is sent automatically by your HP-IB programming statements. The termination also occurs with other terminator codes, such as EOI. In this guide, the terminator is assumed at the end of each example line of code. If it needs to be indicated, it is shown by the symbol <nl>, which stands for "new line" and represents the ASCII coded byte 0A hexadecimal (or 10 decimal).

COMMON COMMANDS

Common statements are not derived from HPSL but are generic commands and queries defined by the IEEE 488.2 standard. The following examples are common statements:

- *RST
- *IDN?
- *TRG

Common statements are executed independently of HPSL statements. Their relationship to HPSL statements is described more fully in "Chapter 3". The function of each common statement is summarized in "Chapter 4—Language Dictionary" and fully described in Section 10 of IEEE 488.2 *Standard Digital Interface for Programmable Instrumentation*.

Chapter 3 INTRODUCTION TO PROGRAMMING

TYPES OF COMMANDS AND QUERIES

The electronic load responds to two types of commands and queries, *Common* and *Root*. Common commands were introduced in *Chapter 2—Introduction to HPSL* and are relatively simple to use. The root commands are organized in a hierarchy that is best shown via a command tree diagram.

UNDERSTANDING THE COMMAND TREE

Figure 4-2 in *Chapter 4—Language Dictionary* is a tree diagram of all the root commands for the electronic load. Notice the following:

- The originating point of the diagram is at the *root*. In this case, the diagram resembles an inverted tree. “Root” is not a command, but the origin for all commands.
- The root divides into two major branches—*Channel-Specific* commands and *Channel-Independent* commands. Both types are accepted by all electronic loads.
- Each major branch divides into several branches. The *CURRENT* commands are a branch. The *VOLTage* commands are another branch. So are the *TRIGger* commands.
- Some keywords are within brackets []. These are *implied* keywords. Implied keywords are optional, but you may want to use them in certain situations (see *Implied Keywords*, later in this chapter)

NOTE

For fastest program execution, omit implied keywords.

- Commands followed by ? are queries. They cause the electronic load to store information in its output buffer from where it can be read by the controller over the HP-IB.

UNDERSTANDING A TYPICAL BRANCH

Here are the keywords for the **RESistance** branch as they appear in *Chapter 4—Language Dictionary*:

Command and Function

- RESistance**[:LEVEl][:IMMEDIATE]
Specify input resistance for **RESistance** mode
- RESistance**[:LEVEl]:TRIGgered
Preset input resistance level pending trigger occurrence
- RESistance**:RANGe
Specify full-scale resistance input range
- RESistance**:TLEVEl
Specify resistance level for **TRANSient** function

NOTE

*Ignore the meanings of these commands for now. All keywords are defined in the **Language Dictionary** and command functions are explained in the **electronic load Operating Manual***

Figure 3-1 shows the **RESistance** commands, which form a typical branch that forms a “subtree” of its own. You can see that the **RESistance** branch has three subbranches; **LEVEl**, **RANGe**, and **TLEVEl**. When it reaches the end of a branch, the parser expects a parameter, a question mark (that identifies the keyword as a query), a semicolon or semicolon-colon combination, or an end-of-line terminator.

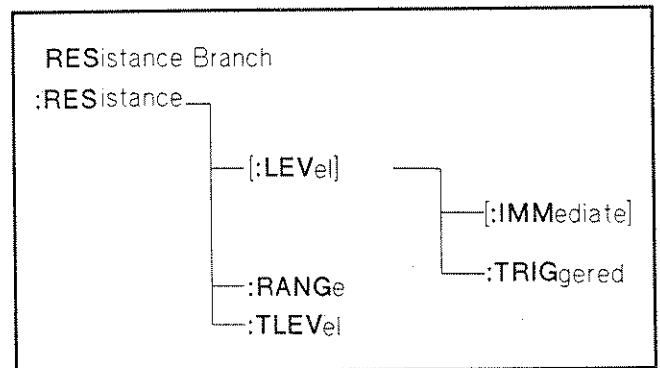


Figure 3-1. RESistance Branch Subtree

Figure 3-2 is the syntax diagram for the **RESistance** branch. You can still identify the tree structure, although it runs from left-to-right instead of from top-to-bottom. Note the following symbols that were discussed in *Chapter 2—Introduction to HPSL*.

- Keywords with the short form shown in bold-faced capital letters. Implied keywords are not within brackets in diagrams.
- Spaces shown as “SP” within circles.
- Boxes showing the form (NRf +) of the parameter.
- Boxes showing optional suffixes. Multipliers are not shown.
- Question marks that convert a command into a query
- Colons (:) that precede each keyword. They are important and are discussed later in more detail.

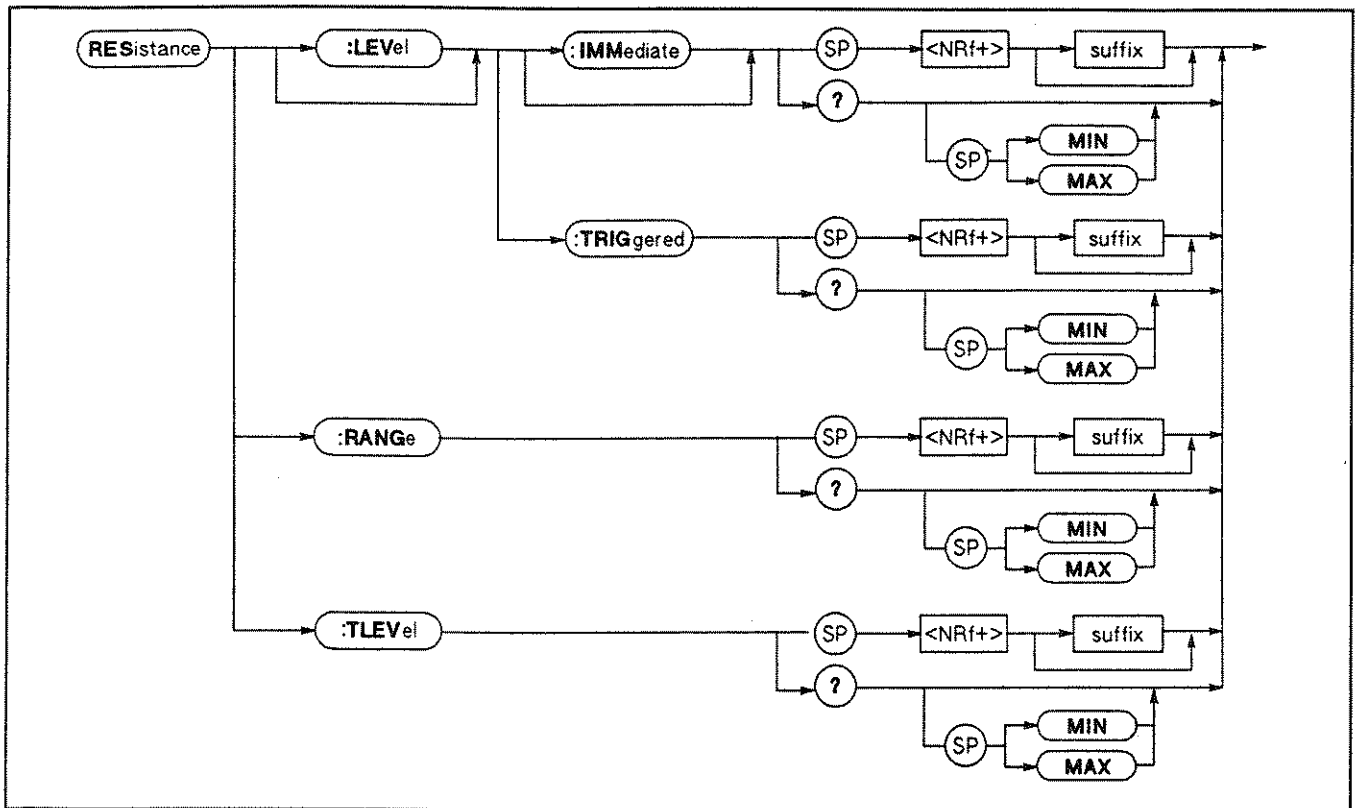


Figure 3-2. RESistance Branch Syntax Diagram

Traversing the RESistance Branch

From Figure 3-2 note that there are two implied keywords that you can usually ignore. This makes two of the commands very simple. If you enter:

```
RES 1.5
```

you will send the electronic load an immediate resistance level command. The command actually is:

```
RES:LEV:IMM 1.5
```

but the parser assumes that the two implied keywords are there. For the same reason, you can query the immediate resistance value with:

```
RES?
```

NOTE

When sending a query, do not enter a space between the keyword and the question mark.

The newline character <nl> or EOI terminator sends the parser back to the root level. Many controllers automatically send this character at the end of each program output string. To program the resistance range and the TLEVeI value, you could send:

```
RES:RANG 1000 <nl>
RES:TLEV 5000 <nl>
```

NOTE

There is an alternate way to do this, which is shown under "Traversing the Command Tree."

Using the NRf+ Format

Referring to Figure 3-2, note that all parameters are of the <NRf+> type. This allows you to easily set a numeric parameter to its maximum or minimum value. If you wanted to increase the immediate resistance of the presently selected range to its maximum value, you could send:

```
RES MAX <nl>
```

NOTE

MAX and MIN are the maximum and minimum values allowed in the present operating mode of the electronic load. For the electronic load this generally means the limits within the present range.

MAX and MIN may also be used with queries to find the maximum and minimum permitted settings of the present mode. For example:

```
RES? MAX Returns the maximum permitted value of the present range
```

TRAVERSING THE COMMAND TREE

NOTE

The HPSL parser traverses the command tree as described in Appendix A of IEEE 488.2 Standard Digital Interface for Programmable Instrumentation. The Enhanced Tree Walking Implementation given in that appendix is not implemented in HPSL. The simplified explanation given here is sufficient for using the electronic load command set in most applications.

Use of the Colon

When you examined the RESistance branch, you noticed the colon (:) that separated keywords from each other. A colon represents a change in branch level. ROOT is the highest level. Whenever you enter a (:), the parser expects it to be followed by a command of the next lower level. For example:

```
INP:PROT:CLE      INP and CURR are root-level
CURR:LEV:TRIG     commands. PROT and LEV are first
                  branches, and CLE and TRIG are
                  second branches. Each (:) instructs
                  the parser to move down to the next
                  branch.
```

NOTE

A colon after a keyword always moves the parser down, never up the command tree.

If you enter INP:PROT:CLE:, you will get an error because the parser expects to find another keyword after the last (:). In this example, you will also get an error if you enter INP:PROT because another keyword is required after PROT. However, a command like MODE:RES is o.k. because no keyword or parameter is expected after RES. You will know what is required in each case by referring to the *Language Dictionary*.

Use of the Semicolon

The semicolon (;) is a "back-up" command. It instructs the parser to return to the previous colon. Figure 3-3 illustrates how the semicolon moves the parser backwards.

NOTE

The semicolon by itself can back the parser up to a colon only within the same branch.

The semicolon allows you to combine command statements on one line to create command messages.

VOLT:SLEW 5000 <nl> Statements are on separate lines

VOLT:TLEV 55 <nl>

VOLT:SLEW 5000;TLEV 55 <nl> Combined statements form a message

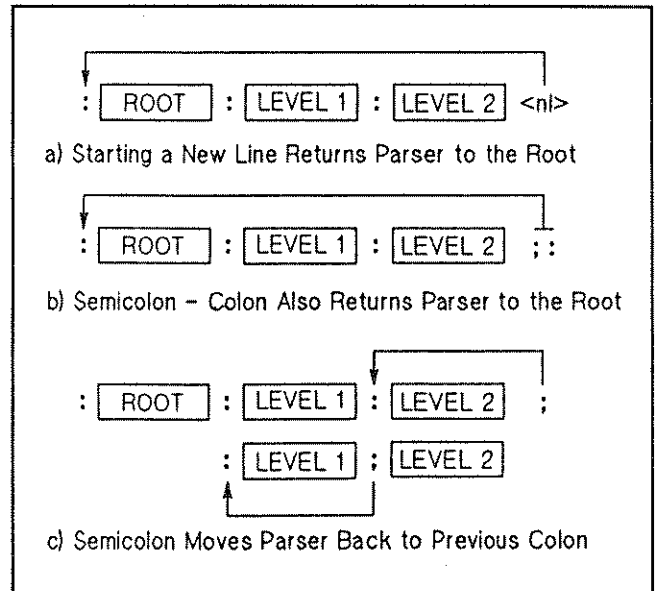


Figure 3-3. What the Semicolon Does

NOTE

There is no single command to move the parser back two colons. In example a above, backing up from Level 2 to Level 1 requires a return to the root.

Getting Back to the Root

To go from a command in one branch to a command in another branch, you must first return to the root. You can do this by:

- entering a new-line character. This is symbolized by (<nl>) and can be any control character that starts a new line, such as:
 - linefeed (LF)
 - an end-of-line (EOI)
- entering a semicolon followed by a colon (;:). This instructs the parser to return to the root.

Looking at Figure 4-2 in the "Language Dictionary", suppose you wanted to set two trigger levels; the CURRent level to 15.5 and the VOLTage level to 25.5. Either of the following commands would do this.

```
CURR:TRIG 15.5 <nl>
VOLT:TRIG 25.5 <nl>
```

or

```
CURR:TRIG 15.5;:VOLT:TRIG 25.5 <nl>
```

Similarly, the following query would return the present values of current, power, and voltage and the state of the output port.

```
MEAS:CURR?;POW?;VOLT?;:PORT0? <nl>
```

NOTE

The <nl> notation is assumed and will be omitted in later programming examples.

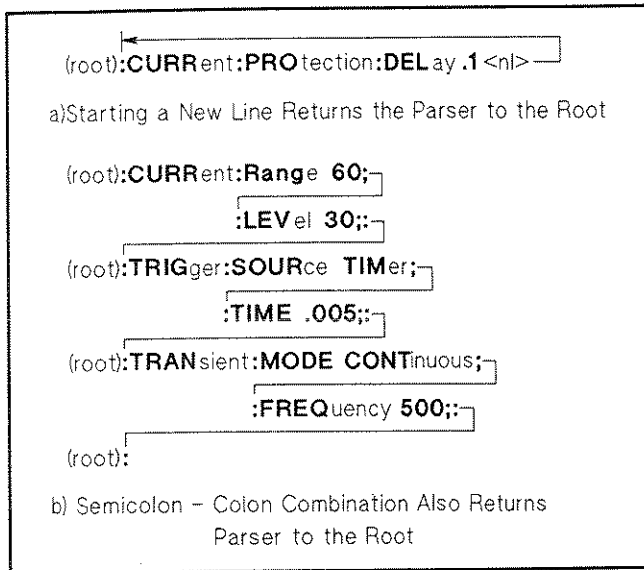


Figure 3-4. Returning the Parser to the Root

Implied Keywords

Keywords shown within brackets, such as **CURR[:LEVEl]**, are implied keywords. If they are omitted, the parser will execute them automatically.

How to Use Implied Keywords. Because [LEVEl] is an implied keyword, the parser regards the following two commands as the same:

```
CURR:LEV 30
CURR 30
```

Under most circumstances, implied keywords are optional and you may omit them as in the above example. Sometimes you may choose to use them in order to make the semicolon move the parser in the desired way. Returning to our previous keyword diagram under Figure 3-2, note that you can set the immediate resistance value with:

```
RES .5
```

The parser automatically assumes that you want to program LEVEl. If you wanted to program both LEV and TLEVEl in one program line and sent:

```
RES .5;TLEV 1 Incorrect parser positioning
```

the parser would end up back at the root and you would get an error because there is no TLEVEl command at the root. The correct statement would be:

```
RES:LEV .5;TLEV 1 Correct parser positioning
or
RES .5;RES:TLEV 1
```

By inserting the implied keyword in RES:LEV .5; you allowed the parser to interpret the (;) as a command to move back to the branch containing RANG and TLEV. Without LEV in the command, the parser would "find" only RES, CURR, STAT, or other root-level commands.

HPSL Queries

You can program more than one query in a single line, such as:

```
CURR?;RES?;VOLT? Return present values of programmed current, resistance, and voltage
```

However, observe the following precautions:

- You must read back the results of the queries before sending another command line to the electronic load. Otherwise, a *Query Interrupted* error will occur and the returned data will be lost.
- Multiple queries must be separated by semicolons and some controllers may have problems interpreting this format. In this case, you must enter each query and its corresponding readback on a separate line.

HPSL COMPATABILITY

The SOURce Implied Keyword

Referring to Figure 4-2 in the *Language Dictionary*, note that several of the Channel-Specific branches include the implied keyword [SOURce]. It is there to make electronic load programs compatible with other HPSL devices. Although the electronic load will accept it, you can omit [SOURce] and consider the Channel-Specific branch as connected directly to the root.

Aliases

Looking at Figure 4-2 you will notice that some electronic load commands will accept two keywords that perform the identical function. For example:

```
MODE|FUNCTION Examples of two commands that do the same thing
INPut|OUTPut
CHANnel|INSTRument
```

These alternate keywords are called "aliases" and are supported by the electronic load in order to make it compatible with other HPSL instruments.

VALUE COUPLING

When you program, you must be aware of the effect known as *value coupling*. Value coupling results when a command directed toward one parameter changes the value of another parameter. For example, the CURREnt branch includes the following keywords:

```
Command
CURREnt[:LEVEl][:IMMEdiate]
CURREnt:RANGe
CURREnt:TLEVEl
```

There is value coupling among the **RANge**, **LEVel**, and **TLEVel** commands. If a previously programmed **LEVel** value is outside a particular range, then changing to that range will affect the value of **LEVel**. There are several instances of value coupling among the electronic load commands and you should always check a command's description in the *Language Dictionary* to determine if it is value coupled to another command.

Common Commands

Common commands, while not part of the command tree, can be mixed in with regular commands. The electronic load responds to the Common commands and queries listed in Figure 4-1 of the *Language Dictionary*. You can mix Common commands in with regular programming statements; the Common command will be executed without affecting the position of the parser.

Programming Examples

The following programming examples are practical applications of the electronic load. Although they are in HP Series 300 Basic, the principles can be applied to any other version of BASIC or even to another language.

Battery Testing

The principal measurement of a battery's performance is its rated capacity. The capacity of a fully charged battery, at a fixed temperature, is defined as the product of the rated discharge current in amperes and the discharge time in hours, to a specified minimum termination voltage in volts (see Figure 3-5). A battery is considered completely discharged when it reaches the specified minimum voltage called the "end of discharge voltage" (EODV).

In this example, the electronic load discharges three nickel-cadmium batteries to determine their discharge rates at a fixed temperature (see Figure 3-6). The batteries are connected in series so that when the EODV is reached, it is still above the minimum operating voltage of the electronic load. The EODV for nickel-cadmium batteries is typically 1.0 volts.

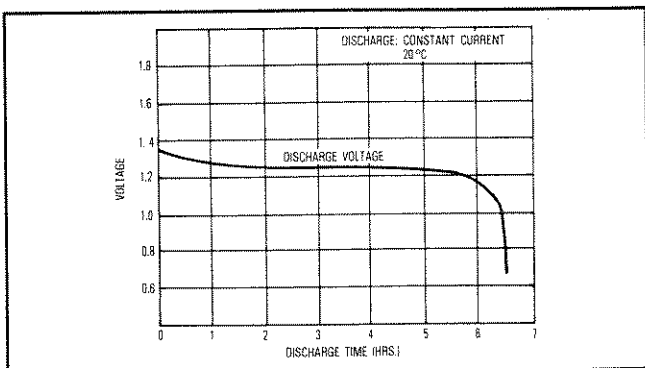


Figure 3-5. Typical Discharge Curve

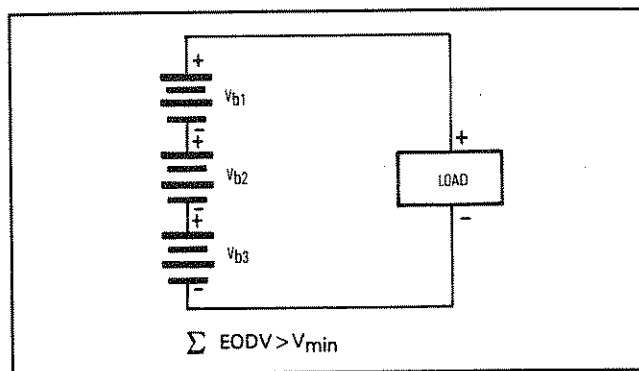


Figure 3-6. Batteries in Series

Power Supply Testing

A typical use for electronic loads when testing power supplies involves power supply burn-in. One of the problems associated with burn-in is what to do if the power supply fails before the test is over. One solution involves continuously monitoring the supply and removing the load if the supply fails during the test (see Figure 3-7.)

In this example, the Electronic Load is used to burn-in a power supply at its rated output current. Because the Electronic Load is operating in CC mode, if the power supply's output current drops below the rated output current during the test, the UNR (unregulated) condition will be set on the Electronic Load. This can be used to indicate that a failure has occurred on the power supply. If the unregulated condition persists for a specified time, the inputs of the Electronic Load are turned off.

The purpose of this example is not to illustrate power supply to testing, but to explain how to program and use the status registers on the Electronic Load. The part of the program that runs the test simply monitors the supply at the rated output current for one hour and stops the test. You can replace this portion of the program with your own routine to test the power supply. Although SRQ (service request) is enabled to interrupt only on the UNR bit in this example, you can modify the program to interrupt on other conditions.

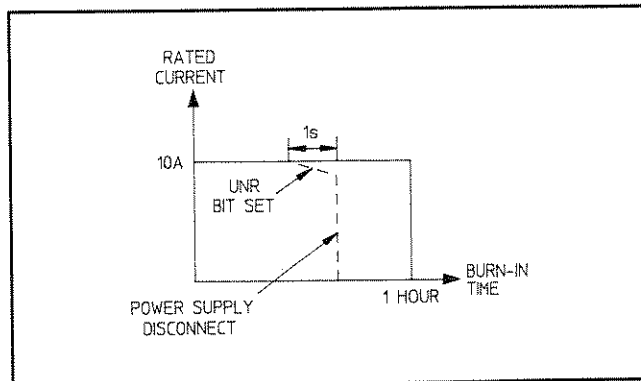


Figure 3-7. Typical Burn-In Test

Battery Test Example Program

```
10 ! Battery Test Example Program
20 !
30 Eodv=1.0 ! End of discharge voltage for single cell
40 Number_of_cells=3 ! Number of cells to be discharged in series
50 Discharge_at=.05 ! Constant current discharge rate in amperes
60 !
70 OUTPUT 705;"INPUT OFF" ! Disables the inputs
80 OUTPUT 705;"MODE:CURRENT" ! Sets CC mode
90 OUTPUT 705;"CURRENT:LEVEL";Discharge_at ! Sets the CC level
100 OUTPUT 705;"INPUT ON" ! Enables the inputs
110 !
120 Start_time=TIMEDATE ! Records test start time
130 !
140 Start_test: ! Starts test routine that
150 OUTPUT 705;"MEASURE:VOLTAGE?" ! continuously measures and reads
160 ENTER 705;Sum_of_volts ! back the voltage and current
170 OUTPUT 705;"MEASURE:CURRENT?" ! until batteries are completely
180 ENTER 705;Actual_current ! discharged
190 !
200 PRINT "Total cell voltage: ";Sum_of_volts
210 PRINT "Actual current: ";Actual_current
220 PRINT "Elapsed time in seconds: ";TIMEDATE-Start_time
230 !
240 IF Sum_of_volts>(Number_of_cells*Eodv) THEN GOTO Start_test
250 ! Checks if the total voltage is less than the
260 ! sum of the minimum cell voltages of all cells
270 !
280 OUTPUT 705;"INPUT OFF" ! Disables the inputs
290 !
300 END
```

Power Supply Test Example Program

```

10 ! Power Supply Test Example Program
20 !
30 Current=10 ! Load current in amperes
40 Burn_in_time=36000 ! One hour burn-in time
50 !
60 ON INTR 7 GOSUB Srq_service ! Set up interrupt linkage
70 ENABLE INTR 7;2 ! Enable interrupts for SRQs
80 !
90 OUTPUT 705;"INPUT OFF" ! Disables the inputs
100 OUTPUT 705;"*SRE 4" ! Enable SRQ (SRQ enable)
110 OUTPUT 705;"STAT:CSUM:ENAB 2" ! Enable Chan 1 (channel summary)
120 OUTPUT 705;"STAT:CHAN:ENAB 1024" ! Enable UNR bit (channel status)
130 OUTPUT 705;"MODE:CURRENT" ! Sets CC mode
140 OUTPUT 705;"CURRENT:LEVEL";Current ! Sets the CC level
150 OUTPUT 705;"INPUT ON" ! Enables the inputs
160 !
170 PRINT "Burn-in test started at ";TIME$(TIMEDATE)
180 !
190 FOR I=1 TO Burn_in_time ! Loop on wait. You can write your
200 WAIT .1 ! own power supply test routine and
210 NEXT I ! insert it in this section.
220 !
230 OUTPUT 705;"INPUT OFF" ! Disables the inputs at end of test
240 PRINT "Burn-in test complete at ";TIME$(TIMEDATE)
250 STOP
260 !
270 Srq_service: ! Service request subroutine
280 Load_status=SPOLL(705) ! Conduct serial poll
290 IF BIT(Load_status,6) THEN ! Check if SRQ bit is set
300 GOSUB Check_unr
310 ELSE
320 PRINT "A condition other than UNR generated SRQ at ";TIME$(TIMEDATE)
330 END IF ! You can also check the other bits
340 ENABLE INTR 7 ! Reenable interrupts before return
350 RETURN
360 !
370 Check_unr: ! Check if UNR bit still set
380 WAIT 1 ! Wait 1 s before reading UNR bit
390 OUTPUT 705;"STAT:CHAN:COND?" ! Read channel condition register
400 ENTER 705;Value
410 IF Bit(Value,10)=0 THEN ! Return value for UNR bit only
420 OUTPUT 705;"*CLS" ! If 0, clear channel event register
430 PRINT "UNR was momentarily asserted at ";TIME$(TIMEDATE)
440 ELSE
450 OUTPUT 705;"INPUT OFF" ! Disables the inputs
460 PRINT "UNR is asserted at ";TIME$(TIMEDATE);" Inputs are turned off"
470 STOP
480 END IF
490 RETURN
500 END

```


Chapter 4

LANGUAGE DICTIONARY

INTRODUCTION

This section gives the syntax and parameters for all the IEEE 488.2 common commands and HPSL commands used by the electronic loads. It is assumed that you are familiar with the material in Chapters 2 and 3, which explain the terms, symbols, and syntactical structures used here and provide an introduction to programming. You should also be familiar with the *Operation Overview* and *Remote Operation* chapters in the electronic load *Operating Manual* that was shipped with the electronic load. Those chapters explain how the electronic load functions and how to write simple programs to perform basic functions from a controller.

Because the versatility of HPSL allows such freedom in programming, the programming examples show just simple applications of the commands. With experience, you will find ways of combining simple statements into more complex compound ones, or forming iterations within compound statements. Because HPSL functions are the same in all electronic loads, the examples in this chapter are generic. If you send a command or query in a manner consistent with the syntax of your programming language, then the statement or query will always perform the specified function.

Keywords

Keyword explanations use the "long form" of the word, but the short form is used in the examples. If you have any concern that the meaning of a keyword in your program listing will not be obvious at some later time, then use the long form to help make your program self-documenting.

Parameters

Most commands require a parameter and most queries will return a parameter. The range for a parameter may vary according to the model of electronic load. For consistency, the examples and explanations use parameters for the Model HP 6060A Electronic Load. However, these examples and explanations are valid for any electronic load. Parameters for all current models can be found in Table 4-1 at the end of this chapter.

Related Commands

Where appropriate, related commands or queries are included. These are listed either because they are directly related by function or because reading about them will clarify or enhance your understanding of the original command or query.

ORDER OF PRESENTATION

All the electronic loads commands and queries are included in this dictionary. The dictionary is organized as follows:

- IEEE 488.2 common commands, in alphabetical order
- Root level commands, in alphabetical order. These consist of:
 - Single commands.
 - Subsystems. The individual commands for a subsystem are listed in alphabetical order under the subsystem.

COMMON COMMANDS

Introduction

Common commands are defined by the IEEE 488.2 standard to perform some of the basic instrument functions, such as identification, reset, determining how status is read and cleared, and how commands and queries are processed. Common commands are accepted and processed when they are sent as separate commands and also when they are included within program messages. Execution of a common command does not change the position of the parser in the program tree but leaves it in the same place it was before the common command was executed (refer to *Chapter 2 - Introduction to HPSL*). This does not mean that a common command has no effect on the rest of a programming message.

The electronic loads respond to the 13 required common commands that control internal operation, synchronization, status and event registers, and system data. Because they have full trigger capability, the electronic loads also respond to *TRG. In addition, the electronic loads accept six optional common commands. The description for each common command or query specifies if it affects status registers. In order to make use of this information, you must refer to *Chapter 5 - Status Reporting*, which explains how to read the status registers and use the information that they return.

Order of Presentation

Figure 4-1 shows the common commands and queries, which are presented in alphabetical order. If a command has a corresponding query that simply returns the data or status specified by the command, then both command and query are included under the explanation for the command. If a query does not have a corresponding command or is functionally different from the command, then the query is listed separately.

Syntax Diagram

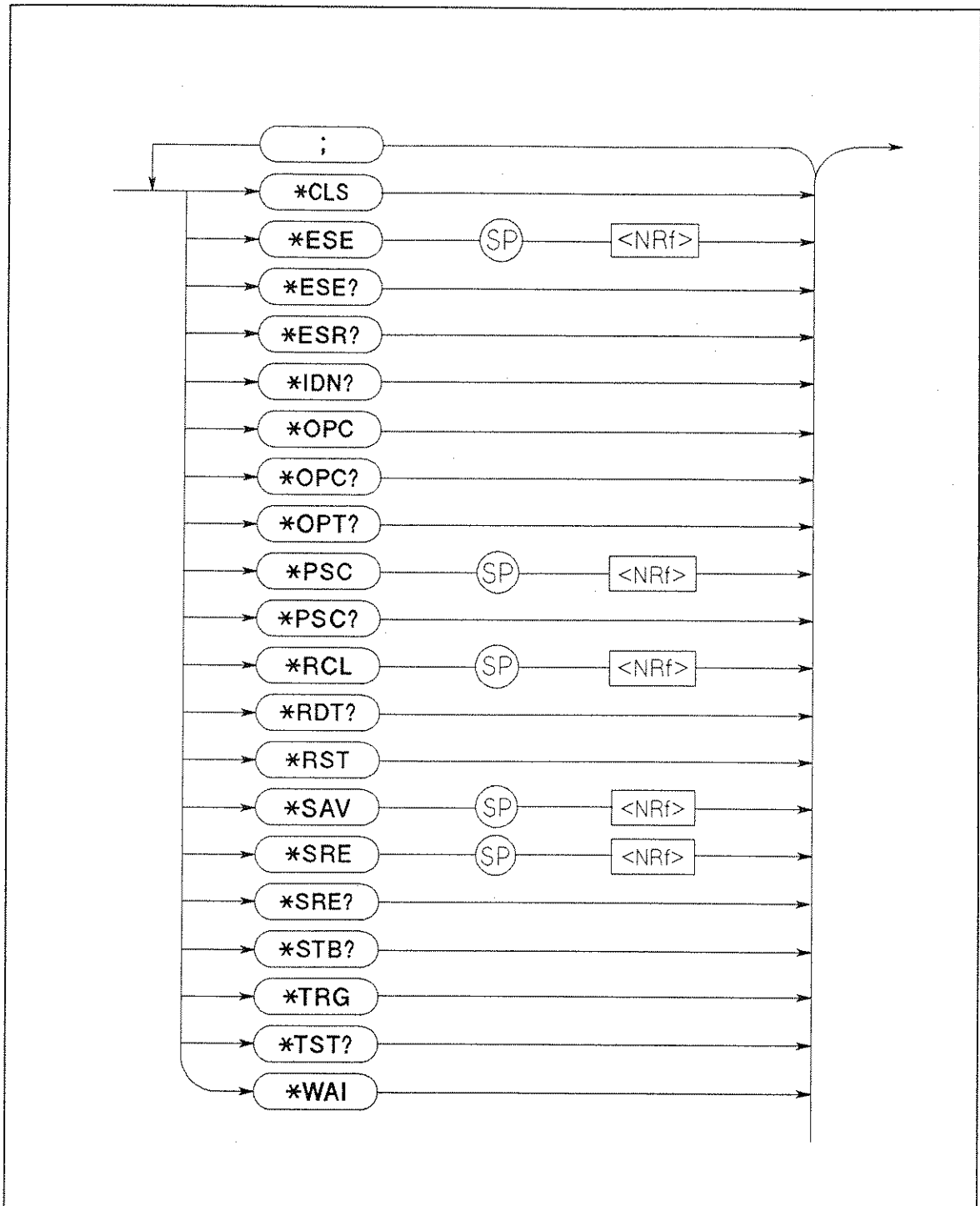


Figure 4-1. Common Commands Syntax Diagram

CLSClear Status Command***Type** Device Status

Description This command causes the following actions (see *Chapter 5 - Status Reporting* for descriptions of all registers):

- Clears the following registers without affecting any corresponding Enable Registers or Transition Filters:
 - Channel Status Event Registers for all channels
 - Channel Summary Event Register
 - Questionable Status Event Register
 - Standard Event Status Event Register
 - Operation Status Event Register
- Clears the Error Queue
- Forces a previously executed *OPC command to appear as if it had been completed. It does *not* do this with the *OPC? command (see *OPC? for more details).
- If *CLS immediately follows a program message terminator (<nl>), then the output queue and the MAV bit are also cleared.

Command Syntax *CLS**Parameters** None**Related Commands** *OPC *OPC?

ESEStandard Event Status Enable Command/Query***Type** Device Status

Description This command sets the condition of the Standard Event Status Enable Register, which determines which events of the Standard Event Status Event Register (see *ESR?) are allowed to set the ESB (Event Summary Bit) of the Status Byte Register. A "1" in the bit position enables the corresponding event. All of the enabled events of the Standard Event Status Event Register are logically ORed to cause the ESB (bit 5) of the Status Byte Register to be set. See *Chapter 5 - Status Reporting* for descriptions of all three registers.

Command Syntax *ESE <NRf>

***ESE**

***ESR?**

Parameters 0 to 255

Suffix None

Example

*ESE 129 *Enables the OPC and PON events of the Standard Event Status Event Register*

Query Syntax *ESE?

Returned Parameters <NR1> Value: 0 to 255

Suffix None

Related Commands *PSC *STB?

***ESR?**

Standard *Event Status Register* Query

Type Device Status

Description This query reads the Standard Event Status Event Register. Reading the register clears it. See *Chapter 5 - Status Reporting* for a detailed explanation of this register.

Standard Event Status Event Register

Bit Position	7	6	5	4	3	2	1	0
Condition	PON	0	CME	EXE	DDE	QYE	0	OPC
Bit Weight	128	64	32	16	8	4	2	1

Query Syntax *ESR?

Returned Parameters <NR1> Value: 0 to 255

Suffix None

Related Commands *OPC *CLS

***IDN?** *Identification Query*

Type System Interface

Description This query requests the electronic load to identify itself.

Query Syntax *IDN?

Returned Parameters <aard> form consisting of four strings separated by commas. The content of each string is:

String	Information
Hewlett-Packard	Manufacturer
xxxxA	Four-digit model number followed by a letter suffix
0	Always returns zero
a.xx.xx	Revision level of the primary interface firmware

Example HEWLETT-PACKARD,6060A,0,A.01.02

This identifies a HP Model 6060A Electronic Load; with primary interface firmware revision A.01.02

Related Commands *OPT? *RDT?

***OPC** *Operation Complete Event Bit Command*

Type Device Status

Description This command causes Bit 0 of the Standard Event Status Event Register to be set when the electronic load has completed all pending operations (see *ESR? for the bit configuration of this register). *Pending operations* are complete when:

- all previous commands have been executed
- any change in the input level caused by previous commands has been completed (effects of slew rate have been accounted for)

*OPC

*OPC?

- no pending trigger level operations are set for the single electronic load or for any channel of the multiple electronic load
- *OPC does not prevent processing of subsequent commands but Bit 0 will not be set until all pending operations are completed.

Command Syntax *OPC

Parameters None

Related Commands *WAI *OPC?

*OPC?

Operation Complete Output Query

Type Device Status

Description This query causes the electronic load to place an ASCII "1" in the Output Queue when all pending operations are completed. *Pending operations* are complete when:

- all commands that were issued before an *OPC? command have been executed
- any change in the input level caused by these previous commands has been completed (effects of slew rate have been accounted for)
- no pending trigger level operations are set for the single electronic load or for any channel of the multiple electronic load

Unlike *OPC, *OPC? prevents processing of all subsequent commands. When all pending operations are completed, an ASCII "1" is placed in the Output Queue. *OPC? is intended to be used at the end of a command line so that the program can then monitor the bus for data until it receives the "1" from the Output Queue.

Caution

Do not follow a :LEV:TRIG command (CURR:TRIG, VOLT:TRIG or RES:TRIG) with *OPC? unless TRIG:SOUR has been previously set to EXTERNAL, LINE, or TIMER. These are the only triggers that can be processed after OPC?. TRIG:IMM, *TRG, and HP-IB bus triggers sent after *OPC? will be prevented from executing, stopping system operation. If this occurs, the only programmable way to restore operation is by sending the electronic load a HP-IB DCL (Device Clear) command.

Command Syntax *OPC?

*OPC?		*OPT?	*PSC
Returned Parameters	<NR1>	ASCII 1 is placed in the Output Queue when the electronic load has completed all pending operations.	
Suffix	None		
Related Commands	*OPC	*TRIG:SOUR	*WAI

*OPT?	<i>Options Identification Query</i>		
Type	Device Options		
Description	This query specifies options installed in the multiple electronic load. The query presently is not supported and returns a zero for all electronic loads.		
Query Syntax	*OPT?		
Returned Parameters	0		
Suffix	None		
Related Commands	*IDN?	*RDT?	

*PSC	<i>Power On Status Clear Command/Query</i>		
Type	Device Initialization		
Description	<p>This command controls the automatic clearing at power turn-on of:</p> <ul style="list-style-type: none"> ■ the Service Request Enable Register ■ the Standard Event Status Enable Register <p>If the command parameter = 0, then the electronic load can be programmed to request service at turn on. Any non-zero parameter causes both registers to be cleared at turn on, preventing the electronic load from being capable of requesting service at that time. See "Chapter 5 - Status Reporting" for details of these registers.</p>		

Command Syntax	*PSC <NRf>	
Parameters	0 or not zero	
Suffix	None	
Query Syntax	*PSC?	
Returned Parameters	<NR1>	<p>0 = power-on clear flag is <i>false</i>; affected registers not cleared at turn on.</p> <p>1 = power-on clear flag is <i>true</i>; affected registers cleared at turn on.</p>
Suffix	None	
Related Commands	None	

***RCL**

Recall Instrument State Command

Type	Device State
Description	<p>This command restores the electronic load to a state that was previously stored in memory with the *SAV command to the specified location (see *SAV). *RCL also does the following:</p> <ul style="list-style-type: none"> ■ forces an ABORt command before resetting any parameters (this removes all pending trigger levels) ■ after all parameters have been recalled, executes an INP:PROT:CLE to clear the electronic load's protection circuits ■ sets CAL:MODE to <i>OFF</i> (see the electronic load <i>Operating Manual</i> for the calibration commands) ■ sets CHAN to <i>1</i> in the multiple electronic load <p>At power turnon, the equivalent of an *RCL 0 is executed to restore the electronic load to the state stored in location 0. This same state is also set if the *RCL command is directed to a location where no state was stored since the last time power was cycled.</p>
Note	*RCL does not affect any Status Enable Registers or Transition Filters.

Command Syntax *RCL <NRf>

Parameters 0 through 6 where:
 States 1-6 Volatile states previously stored by *SAV
 State 0 Nonvolatile state previously stored by *SAV 0

Suffix None

Related Commands *RST *SAV

***RDT?**

Resource Description Transfer Query

Type Device Specification

Description This query returns the model number of a single electronic load or the model number of the module installed in each channel of a multiple electronic load. For multiple electronic loads, a semicolon (;) separates each module and the string is terminated with a LF (line feed).

Query Syntax *RDT?

Returned Parameters <aard> String value as follows:

single electronic load *CHAN1:nnnnL*; where "nnnnL" = model number

multiple electronic load *CHAN<c>:nnnnnL*; where "c"=channel number and "nnnnnL"= number and suffix letter of the module in that channel

Related Commands *IDN? *OPT?

***RST**

Reset Command

Type Device State

Description This command sets the electronic load to its factory-defined state (see Table 4-1 at the end of this chapter). There are no parameters with this command; it sets all channels of the multiple electronic load to the same state.

*RST also does the following:

- forces an **ABORt** command before resetting any parameters
- after all parameters have been reset, executes an **IN:PROT:CLE** to clear the electronic load's protection circuits

Note *RST does not affect any Status Enable Registers or Transition Filters.

Command Syntax *RST

Parameters None

Related Commands *RCL *SAV

***SAV**

Save Command

Type Device State

Description This command stores the present state of the single electronic load and the states of all channels of the multiple electronic load in a specified location in memory. Locations 0 through 6 may be used. Location 0 is in nonvolatile memory and retains its state throughout power cycling. The electronic load will be set to the state in location 0 at power turn-on. If no state has been saved to location 0, then it will still contain the factory-default state (see See Table 4-1 at the end of this chapter). States stored in locations 1 through 6 are lost whenever power is cycled.

Note To restore the factory-default state to Location 0, execute:
*RST;*SAV 0

The parameters stored by *SAV are identical to those affected by *RST (See Table 4-1 at the end of this chapter) *except* that the following states are *not* stored:

- CAL:MODE ON|OFF (Refer to the Electronic Load; *Operating Manual*)
- CHAN

Note

*SAV also does not store the states of Status Enable Registers or Transition Filters.

Command Syntax

*SAV <NRf>

Parameters

0 to 6

Suffix

None

Example

*SAV 2 *Save the present state of the electronic load to location 2*

Related Commands

*RCL *RST

***SRE**

Service Request Enable Command/Query

Type

Device Interface

Description

This command sets the condition of the Service Request Enable Register, which determines which events of the Status Byte Register (see *STB) are allowed to set the MSS (Master Status Summary) bit. A "1" in the bit position enables the corresponding Status Byte bit to set the MSS bit. All the enabled bits are logically ORed to cause Bit 6 (the Master Summary Status Bit) of the Status Byte Register to be set. See "Chapter 5 - Status Reporting" for more details concerning the Status Byte Register.

Command Syntax

*SRE <NRf>

Parameters

0 to 255

Suffix

None

Example

*SRE 20 *Enables either the CSUM or MAV condition to cause a service request*

***SRE**

***STB?**

Query Syntax ***SRE?**

Returned Parameters **<NR1>** Value: *0 to 255*

Suffix None

Related Commands ***PSC**

***STB?**

Read *Status Byte* Query

Type Device Status

Description This query reads the Status Byte Register. Note that the MSS (Master Summary Status) bit and not the RQS bit is returned in Bit 6. This bit indicates whether or not the electronic load has at least one reason for requesting service. ***STB?** does not clear the Status Byte Register, which is cleared only when subsequent action has cleared all its set bits. Refer to "Chapter 5 - Status Reporting" for more information about this register.

Status Byte Register

Bit Position	7	6	5	4	3	2	1	0
Condition	OPER	MSS	ESB	MAV	QUES	CSUM	¹ 0	¹ 0
Bit Weight	128	64	32	16	8	4	2	1
¹ Always zero								

Parameters None

Returned Parameters **<NR1>** Value: *0 to 255*

Suffix None

Related Commands None

***TRG** Immediate *Trigger* Command

Type Device Trigger

Description This command, which is essentially the same as the Group Execute Trigger (<GET>), generates a trigger to the electronic load only if TRIG:SOUR is set to BUS (refer to the TRIGger Subsystem Root commands).

Command Syntax *TRG

Parameters None

Related Commands <GET> TRIG:SOUR

***TST?** Self *Test* Query

Type Device Test

Description This query causes the electronic load to go through a limited self test (a more complete one is done at power turn on). The testing does not alter the mode or parameter settings of the electronic load.

Query Syntax *TST?

Returned Parameters <NR1> 0 = test passed

Nonzero indicates a self-test failure. For single electronic loads, the returned value is of concern only to service personnel. For multiple electronic loads, the returned values indicate failures in the following modules:

multiple electronic load Failure Bit Map

Bit Position	6	5	4	3	2	1	0
Failed Channel	6	5	4	3	2	1	Mainframe
Bit Weight	64	32	16	8	4	2	1

Suffix None

Related Commands None

*WAI

***WAI**

Wait-to-Continue Command

Type Device Status

Description This command instructs the electronic load not to process any further commands until all pending operations are completed. "Pending operations" are as defined under the *OPC command. *WAI can be aborted only by sending the electronic load an HP-IB DCL (Device Clear) command.

Command Syntax *WAI

Parameters None

Related Commands *OPC *OPC?

Root-Level Commands

Introduction

Root-level commands are those that are specific to the family of Electronic Loads. The commands are grouped as either channel-specific or channel-independent commands. In the Multiple Electronic Load, channel-specific commands are directed (via the CHANnel command) to specific modules in the mainframe.

Tree Diagram

Figure 4-2 is a tree diagram of the root-level commands. Commands starting at the root directory are listed as either single commands or command subsystems. Command subsystems may consist of a single command, but usually are comprised of a set of commands that extend two or more levels below the root. Refer to *Chapter 3 - Introduction to Programming* for rules for traversing the command tree and for examples.

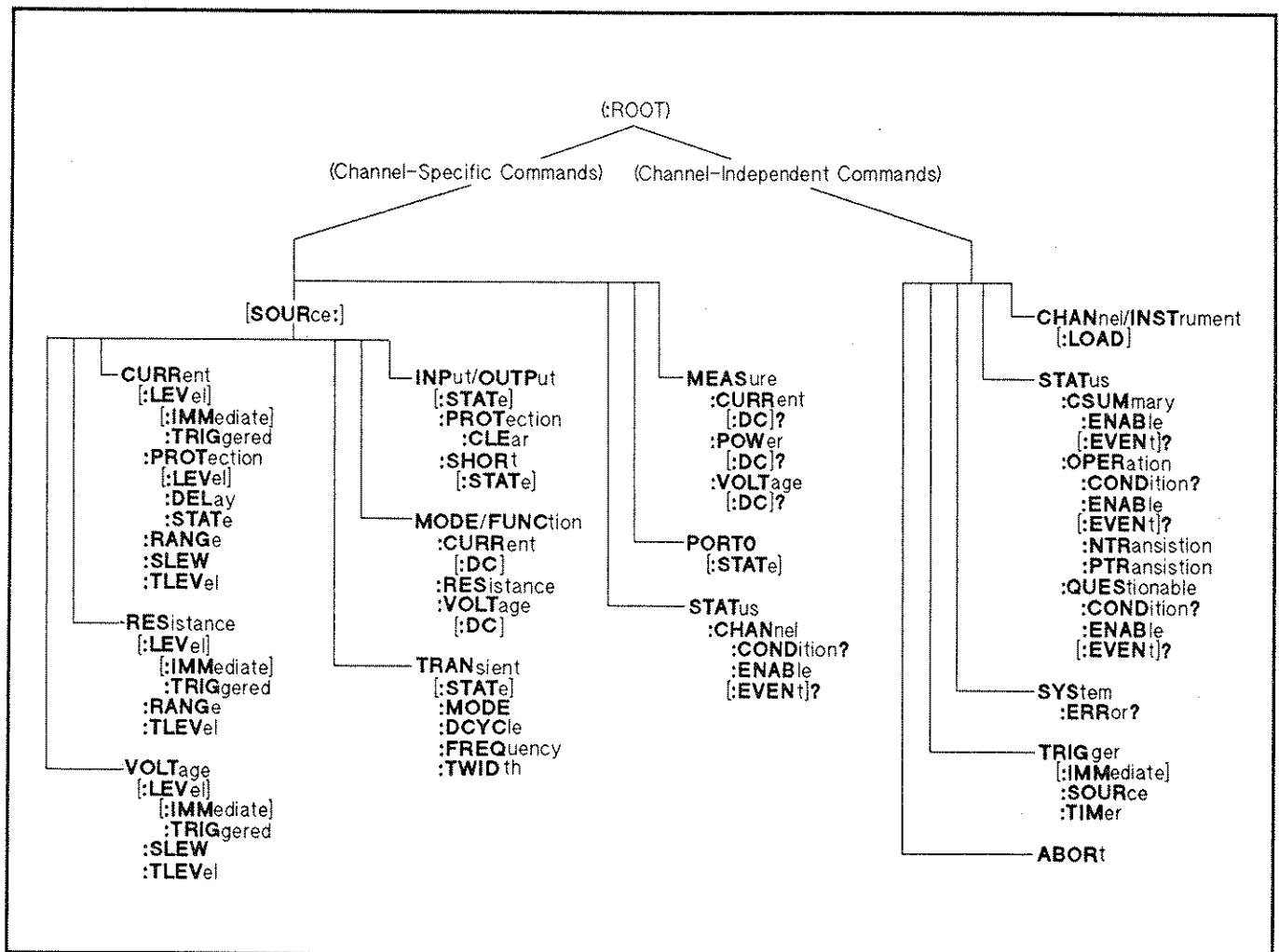


Figure 4-2. Electronic Loads Tree Diagram

ABORt

Channel-Independent Termination Command

Description This command applies only to trigger functions. It cancels all pending [:LEVel]:TRIG operations (such as CURR:TRIG) in all operating modes and on all channels. As a result, subsequent triggers have no effect on the input level. This command resets the WTG bit of the Operation Condition Register (refer to “Chapter 5 - Status Reporting”) and has the same effect on status as the receipt of a trigger. ABORt has no affect on the Transient Subsystem.

Command Syntax ABORt

Parameters None

Examples

ABOR *Aborts all pending trigger level operations in the Current, Resistance, or Voltage Subsystems*

CURR 10;CURR:TRIG 20;:ABOR;:TRIG *Cancels the programmed trigger level so that the triggered input remains at 10 amps*

Query None

Related Commands CURR[:LEV]:TRIG VOLT[:LEV]:TRIG STAT:OPER:COND?

CHANnel

Channel-Independent Command/Query

Note This command is for the multiple electronic load but is supported in single electronic loads for compatibility.

Description CHANnel selects the multiple electronic load channel to which all subsequent channel-specific commands will be directed. If the specified channel number does not exist or is outside the MIN/MAX range, an error code is generated (see Table 4-2 at the end of this chapter). When used with the single electronic load the only valid parameter is 1.

Note This command and INSTRument are the *only* channel commands for electronic loads. No other methods of channel selection are supported.

Command Syntax CHANnel[:LOAD] <NRf+>

Parameters (See Table 4-1 at the end of this chapter)

Examples

CHANNEL:LOAD 5 *Select Channel 5*
CHAN 5

CHAN MAX *Select highest existing channel in a multiple electronic load.*

Query Syntax CHAN? CHAN? MAX CHAN? MIN

Returned Parameters <NR1> CHAN? returns number of channel presently selected.
CHAN? MAX returns the number of channels installed in the multiple electronic load. If none are installed, 0 is returned. For single electronic loads CHAN? MAX returns 1. CHAN? MIN always returns 1 for either single or multiple loads.

Suffix None

Related Commands None

Alternate Syntax INSTrument can be used as an alias for CHANnel

CURRent Subsystem

Channel-Specific Current Programming Function

Description

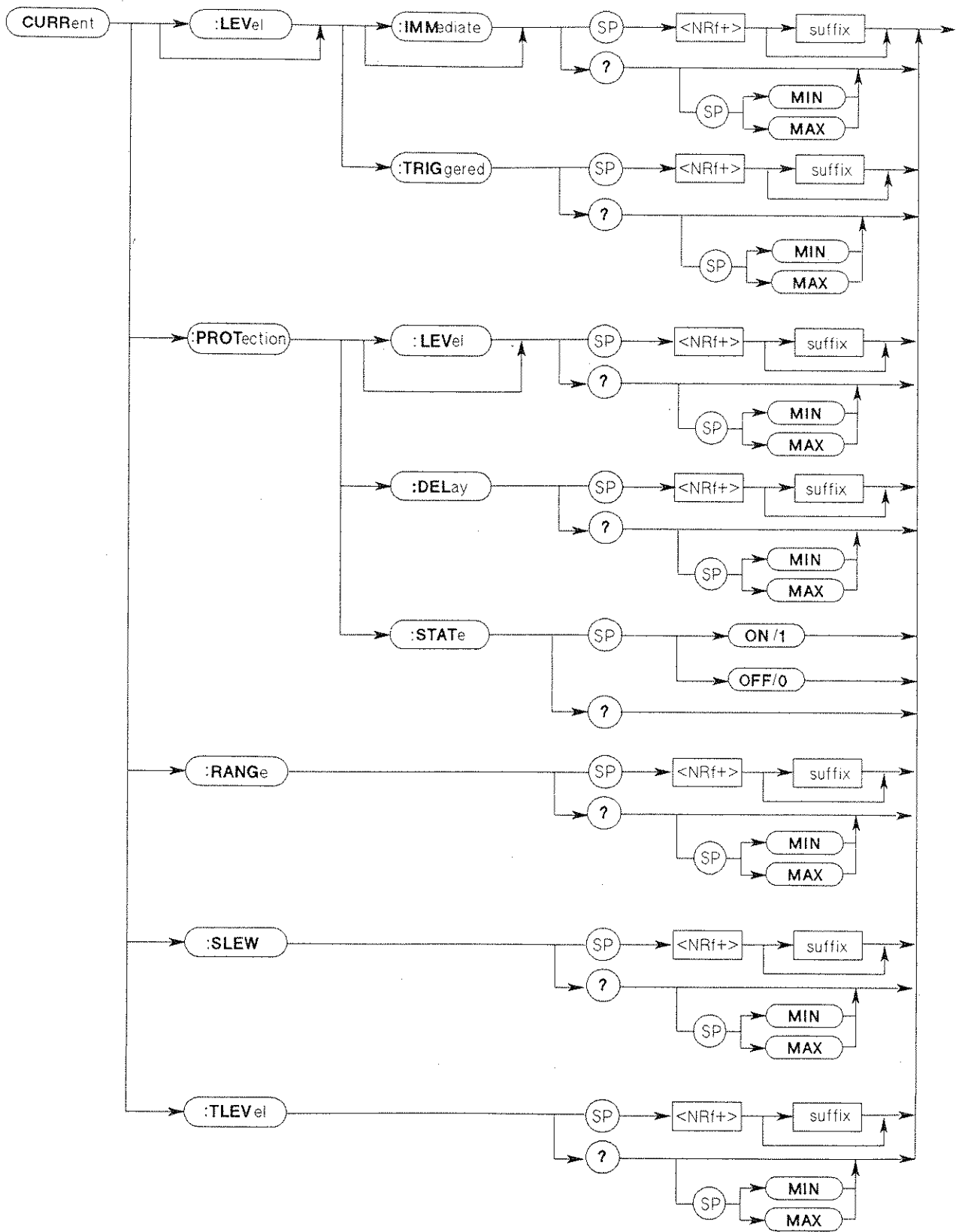
This subsystem programs the CC (constant-current mode) function of a single electronic load or a single channel of a multiple electronic load.

Keywords

<i>Command</i>	<i>Function</i>
CURRent[:LEVel][:IMMEdiate]	Specify the input current level for the CURRent mode
CURRent[:LEVel]:TRIGgered	Preset a new input current level to be valid when a trigger occurs
CURRent:PROTection[:LEVel]	Set current limit at which protection occurs
CURRent:PROTection:DELay	Set time for which protection current limit may be exceeded
CURRent:PROTection:STATe OFF 0	Disable protection function
CURRent:PROTection:STATe ON 1	Enable protection function
CURRent:RANGe	Specify full-scale input current range
CURRent:SLEW	Specify the current level rate of change for all current ranges and for the middle and maximum resistance ranges
CURRent:TLEVel	Specify input current level used with the TRANsient Subsystem

Related Subsystems RESistance VOLTage

Syntax Diagram



CURR[:LEVel]*Channel-Specific Current Command/Query***Description**

This is an implied keyword that specifies the value of the programmed current level and whether that level is to be applied immediately or on occurrence of a trigger. If the specified channel is in the CC (constant-current) Mode, an IMMEDIATE current level is transferred to the input as soon as the command is executed. A TRIGGERED level is stored and then transferred to the electronic load input when a trigger occurs. At that time, the change to the input level occurs at the slew rate presently in effect. Following the trigger event, subsequent triggers will not affect the input level unless the electronic load has been sent another TRIGGERED level command.

If the electronic load is not in the CC (Constant-Current) Mode when an IMMEDIATE or TRIGGERED level command is sent, the programmed levels are saved for the time the electronic load is placed in the CC mode. Triggered levels are processed by the Current Subsystem even when the electronic load is not in the CC Mode. In this case, the TRIGGERED level becomes a stored IMMEDIATE level that takes effect when the electronic load is again in the CC Mode.

Note

Setting an IMM current level to the same value as the most recent TRIG current level will not deactivate a pending TRIG level. You must use ABORT to deactivate it.

The present current level changes to the pending level on any of the following conditions:

- On a TRIG[:IMM] command (always)
- On receipt of an external trigger signal (if TRIG:SOUR is set to EXT)
- On the next line voltage cycle (if TRIG:SOUR is set to LINE)
- On receipt of *TRG (unless TRIG:SOUR is set to HOLD)
- On receipt of an HP-IB <GET> (if TRIG:SOUR is set to BUS)
- On the next trigger timer pulse (if multiple electronic load is set to TRIG:SOUR TIM)

The programmed current level (whether IMMEDIATE or TRIGGERED) can be implicitly changed with a RANGE command (see "Chapter 3 - Introduction to Programming" for information concerning value coupling).

Command Syntax

CURRENT[:LEVel][:IMMEDIATE] <NRf+>
CURRENT[:LEVel]:TRIGGERED <NRf+>

CURR:PROTection

Channel-Specific Current Limiting Command/Query

Description

This command sets a limit to the input current that the electronic load will sink. A current limit may be specified for the single electronic load or for a channel of the multiple electronic load. When the input current reaches the current limit for the specified delay period, the input of the electronic load or channel is shut off and draws no current. This, in effect, provides a “soft circuit breaker” for the input current. The **INPUt:PROTection:CLEar** command (or front panel key) re-enables the input current. The trigger-activated current functions (**CURR[:LEV]:TRIG** and **CURR:TLEV**) automatically keep track of incoming triggers while the input is shut down and will respond to the trigger as soon as the protection fault is cleared.

The **:PROTection:DELAy** command specifies the time that the input current may equal or exceed **[:LEVEl]** before the soft circuit breaker is actuated. The **PROTection:STATe** command enables or disables the soft circuit breaker function.

Note

If the soft circuit breaker function causes the input to shut down, it will not affect **INP[:STATe]**. If **INP:STAT** is programmed **ON**, it will remain so even after the **CURR:PROT** has turned the electronic load off.

Command Syntax

<i>Command</i>	<i>Function</i>
CURRent:PROTection[:LEVEl]<NRf+>	Set immediate current limit
CURRent:PROTection:DELAy <NRf+>	Set time that current may be at or above :LEVEl before input is turned off
CURRent:PROTection:STATe OFF 0	Disable protection function
CURRent:PROTection:STATe ON 1	Enable protection function

Parameters See Table 4-1 at the end of this chapter

Examples

CURR:PROT:LEVEL 35 *Set input current limit to 35 amperes*
CURR:PROT:STAT ON

CURR:PROT 35;DELAy .025 *Set input current limit to 35 amperes and*
CURR:PROT 35;DEL 25MS *allow it to be exceeded for 25 milliseconds*

Query Syntax	<p>CURR:PROT?</p> <p>CURR:PROT? MIN CURR:PROT? MAX</p> <p>CURR:PROT:DEL?</p> <p>CURR:PROT:DEL? MIN CURR:PROT:DEL? MAX</p> <p>CURR:PROT:STAT?</p>
Returned Parameters	<p><NR3> CURR:PROT? returns the value of existing current limit</p> <p> CURR:PROT? MAX and CURR:PROT? MIN return the maximum and minimum programmable values for the current limit.</p> <p><NR3> CURR:PROT:DEL? returns the value of existing delay.</p> <p> CURR:PROT:DEL? MAX and CURR:PROT:DEL? MIN return the maximum and minimum programmable delay values.</p> <p><NR1> CURR:PROT:STAT? returns the state of the protection circuit where 1 is <i>ON</i> and 0 is <i>OFF</i></p>
Related Commands	<p>CURR:RANG INP:PROT:CLE</p>

CURR:RANGe

Channel-Specific Current Command/Query

Description

This command selects the full-scale current range of the electronic load. Programming any value within the low range automatically selects the low range and programming any value within the high range automatically selects that range. In the HP 6060A for example, programming a value from 6 to 60 amperes automatically selects the 60-ampere range.

Important

Whenever the electronic load changes range, it momentarily goes into the OFF (minimum current) state.

When CURR:RANG is executed, the values of the current levels (IMMEdiate, TRIGgered and TLEVel) are adjusted as follows:

<i>If</i>	<i>Then</i>
The existing current setting is within the new range	the current level does not change
The existing current setting is not within the new range	the current level is set to the maximum of the new range

CURR:RANGe

For example, assume the electronic load is in the 60 A range and the main current level (**CURR:LEV**) is 30 A. Switching to the 6 A range will reduce the current to the maximum of that range, or 6 A. However, if another parameter (such as **CURR:TRIG**) was already within the new range (e.g., 4 A), then it will remain at that level in the new range. Of course, there is no change in value when switching from the lower range to the higher range. However, the accuracy of the programmed value may be compromised because of the reduced resolution of the higher range.

Command Syntax **CURRent:RANGe** <NRf+>

Parameters See Table 4-1 at the end of this chapter

Value Coupling This command affects the following parameters:
CURR:LEVel **CURR:TLEVel**

Examples

CURR:RANG 60;LEV 25.25 *Set current to 25.25 A on 60-ampere range*

CURR:RANG 6;:TRIG 4.5 *In previous example, change range to 6 A and set Triggered level to 4.5 A. Due to coupling, the main level will drop to 6 A and remain there until a trigger occurs*

Query Syntax **CURR:RANG?**
CURR:RANG? MAX
CURR:RANG? MIN

Returned Parameters <NR3> **CURR:RANG?** returns the present current range in amperes.
CURR:RANG? MAX and **CURR:RANG? MIN** return the maximum and minimum programmable ranges for the electronic load.

Related Commands **CURR:[LEV]** **CURR:TRIG** **CURR:TLEV**

CURR:SLEW*Channel-Specific Current Command/Query*

Description This command sets the current programming slew rate for both CC mode ranges and the resistance programming slew rate for the middle and high CR mode ranges. The programmed slew rate is used for all programmed current changes except **INPut ON** or **OFF**. The hardware implements discrete slew rates (refer to the *Electronic Load Operating Manual*) and automatically selects the one that is closest to the programmed value. To determine the actual rate, use the query (**CURR:SLEW?**).

Command Syntax **CURRent:SLEW** <NRf+>

Parameters See Table 4-1 at the end of this chapter

Examples

CURRENT:SLEW MAX *Set slew rate for maximum of present current range*

CURR:RANGE MAX;SLEW 4E5 *Set range to 60 A and slew rate to 400,000 A/s (400 mA/μs)*

Note Programming a slew rate value greater than **MAX** sets the slew rate to maximum without generating an error message.

Query Syntax **CURR:SLEW?**
CURR:SLEW? MAX
CURR:SLEW? MIN

Note This query is not applicable to CR mode when it is operating in the low-resistance range

Returned Parameters <NR3> **CURR:SLEW?** returns the internally selected slew rate (in A/S) that was chosen as closest to the programmed value within the permissible range. **CURR:SLEW? MAX** and **CURR:SLEW? MIN** return the maximum and minimum programmable slew rates for the present range.

Related Commands None

CURR:TLEVel*Channel-Specific Current Command/Query*

Description	This command specifies the value of the programmed current level for the TRANSient input when the electronic load is in the CC Mode. When the Transient Subsystem is on, the electronic load input current will switch (under control of the Transient Subsystem) between the main level and TLEVel at a rate determined by the present value of SLEW. In order for the input current level to switch, TLEVel must be set to a value greater than the main level. If TLEVel is set to a value below the main level, no error is generated but switching will not occur until the main level is subsequently below the value of TLEVel. If TLEVel is programmed outside the specified range, an error is generated (see Table 4-2 at the end of this chapter).	
Command Syntax	CURRent:TLEVel <NRf>	
Parameters	See Table 4-1 at the end of this chapter	
Value Coupling	If CURR:RANGe is set to a range that is below TLEVel, then TLEVel will assume the MAX value of that range.	
Examples	<p>CURR:TLEV MAX <i>Set transient level to maximum current for the range</i></p> <p>CURR:RANG 6;TLEV 5.5 <i>Set range to 6 A and Transient level to 5.5 A</i></p>	
Query Syntax	<p>CURR:TLEV?</p> <p>CURR:TLEV? MAX</p> <p>CURR:TLEV? MIN</p>	
Returned Parameters	<NR3>	<p>CURR:TLEV? returns the transient current level for present current range. If the electronic load is not in CC Mode, the level will still be set, even if it is less than the presently programmed input level.</p> <p>CURR:TLEV? MAX and CURR:TLEV? MIN return the maximum and minimum programmable values for the present range.</p>
Related Commands	CURR:RANG	also see TRANSient Subsystem

INPut Subsystem

Channel-Specific Input Programming Functions

Description This subsystem has commands for:

- Turning the electronic load input on or off
- Placing a short across the electronic load input
- Clearing any input software protection circuits that have been set

For multiple electronic loads these commands function only on the presently specified channel.

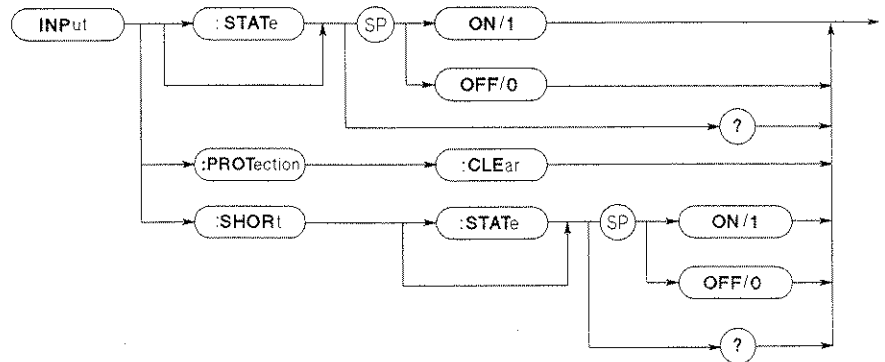
Keywords

Command	Function
INPut[:STATe] ON 1	Turn electronic load input circuit ON
INPut[:STATe] OFF 0	Turn electronic load input circuit OFF
INPut:PROTection:CLEar	Reset input protection circuits
INPut:SHORt[:STATe]:ON 1	Place short across electronic load input
INPut:SHORt[:STATe]:OFF 0	Remove short from electronic load input

Alternate Syntax OUTPut can be used as an alias for INPut.

Related Subsystems CURRent RESistance VOLTage

Syntax Diagram



Input Subsystem Syntax Diagram

INP:PROT:CLEAr*Channel-Specific Input Command*

Description This command resets the electronic load latched protective features (such as overvoltage, overcurrent, overpower, etc.). If an electronic load protective circuit has shut down the input and no **INPut:OFF** command has been sent, **INPut:CLEAr** will restore the input to the **ON** state and restore the previously existing operating mode and its parameters. Of course, if the cause of a shutdown condition is not corrected, it will reoccur.

If a trigger is received during the time a protection circuit has shut down the input, any triggered levels (**CURR:TRIG**, **RES:TRIG**, etc) are stored and will be transferred to the main level after the protection is cleared. Triggers received during protective shutdown are also applied to the Transient Subsystem. This ensures that after the shutdown is cleared, the transients on the restored channel will still be synchronized with those of other channels.

Command Syntax **INPut:PROTect:CLEAr**

Parameters None

Query Syntax None

Related Commands **CURR:PROT[:LEV]** **CURR:PROT:DEL** **CURR:PROT:STAT**

INP:SHORT*Channel-Specific Input Command/Query*

Description This command applies the equivalent of an electronic short across the input of the electronic load. The actual condition of the electronic load under a short condition depends on its operating mode as follows:

Mode of Operation	Shorted Condition ¹
High-Range CC Mode	MAX current
Low-Range CC Mode	MAX current
Low-Range CR Mode	MIN resistance
Middle-Range CR Mode	MIN resistance
High-Range CR Mode	MIN resistance
CV Mode	MIN voltage

¹See Table 4-1 for specific values.

If a mode or current or resistance range is changed, the short will be reapplied to the new mode or range. If a trigger is received while **SHORT** is **ON**, any triggered levels (**CURR:TRIG**, **RES:TRIG**, etc.) are stored and will be transferred to the main level after **SHORT** is programmed **OFF**. Triggers received during **SHORT:ON** are also applied to the Transient Subsystem. This ensures that after the short is programmed off, the transients on the shorted channel will still be synchronized with those of channels that had remained unshorted.

Executing **INPut:SHORT** does not affect any programmed settings and the electronic load will return to them when the short is removed. This command is subordinate to **INPut:[STATe]**. If **INPut:[STATe]** is programmed **OFF**, then the effect of **INPut:SHORT ON** will not be observed until **INPut:[STATe]:ON** is sent to the electronic load.

Command Syntax **INPut:SHORT[:STATe] <NRf+>**

Parameters

Value Range	Units	*RST Default
OFF or 0	None	0
ON or 1	None	

Examples

INP:SHOR ON *Set shorted input condition*
INP:SHOR 1

CHAN 2;INP:SHOR 1;;CHAN 1;INP:SHOR 0

On multiple electronic load, short Channel 1 and unshort Channel 2

Query Syntax **INP:SHOR?**

Returned Parameters <NR1> Value; 0 for *unshorted*, 1 for *shorted*

Related Commands **INP[:STAT]**

INP[:STATe]*Channel-Specific Input Command/Query***Description**

This implied keyword turns the electronic load input ON and OFF. When INPut is OFF, the electronic load will draw minimal current at its input. INP[STAT]e:OFF overrides INPput:SHORT:ON. The presently programmed slew rate setting is not used when turning the input on or off; the current and voltage change at their maximum rates.

Command Syntax

INPut [:STATe] <NRf+>

Parameters

Value Range	Units	*RST Default
OFF or 0	None	0
ON or 1	None	

Examples

INP:STAT OFF *Turn electronic load input off*
 INP 0

INP:STAT OFF;SHOR ON;:INP ON *Turn input off, short the input, and turn input on*

Query Syntax

INP?

Returned Parameters

<NR1> Value; 0 for OFF, 1 for ON

Related Commands

CURR:PROT INP:SHOR

MEASure*Channel-Specific Measurement Query***Description**

This function consists of queries that return the current, voltage, and power at the input of the electronic load.

Query Syntax

Query	Value Returned
MEASure:CURRent[:DC]?	electronic load input current
MEASure:POWer[:DC]?	Computed electronic load input power
MEASure:VOLTage[:DC]?	electronic load input voltage

Returned Parameters <NR3> Value representing amperes, watts, or volts

Note

If the input voltage or current exceeds the maximum measurement capability of the electronic load, an 9.9E+37 out-of-range indication will be returned in place of the normal measurement reading.

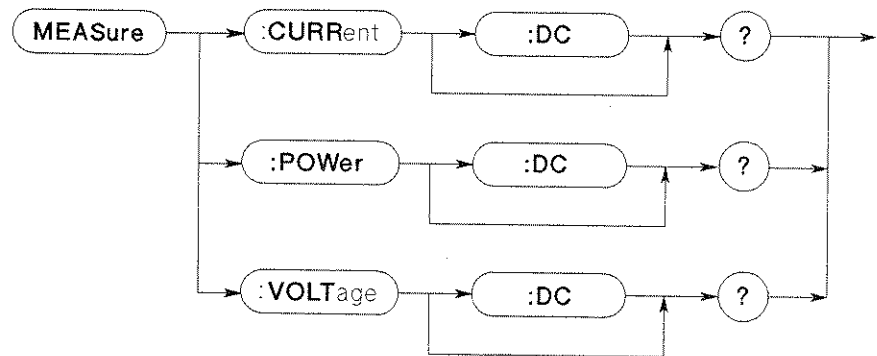
Examples

MEAS:VOLT? *Return input voltage*

MEAS:CURR?;VOLT?;POW? *Return input current, voltage and power*

CHAN 1;:MEAS CURR?;:CHAN 2;:MEAS POW? *Return Channel 1 current & Channel 2 power*

Related Commands None

Syntax Diagram

Measure Query Syntax Diagram

MODE

Channel-Specific Command/Query

Description

This command selects the operating mode of the electronic load, which can be:

CURRent Constant-current (CC) input
RESistance Constant-resistance (CR) input
VOLTage Constant-voltage (CV) input

MODE

If the mode is changed while the input is on, the input is momentarily turned off as if **INPUT[:STATE] OFF** were executed. However, changing modes does not change the state of the input nor does it turn off the **TRANSient** function. For multiple electronic loads, the mode of each channel is programmed independently.

Command Syntax

Command	Function
MODE:CURRent[:DC]	Sets electronic load to constant-current mode
MODE:RESistance	Sets electronic load to constant-resistance mode
MODE:VOLTage[:DC]	Sets electronic load to constant-voltage mode

Parameters

Enter the desired mode as a string variable in either the full or abbreviated format. There are no units. The *RST Default is *CURRent*.

Examples

MODE:CURR *Set electronic load input to CC mode*

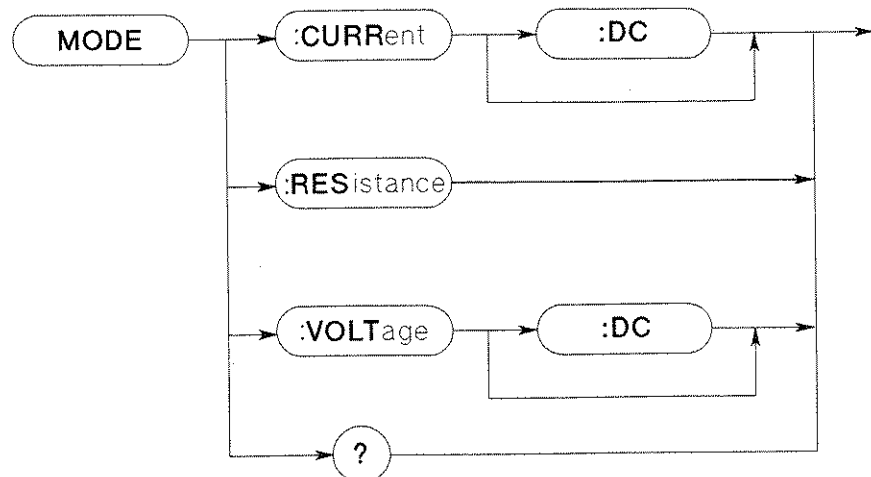
CHAN 1;: MODE:CURR;:CHAN 2;:MODE:RES *Set Channel 1 input to CC mode and Channel 2 input to CR mode*

Query Syntax MODE?

Returned Parameters <aard> String value: *CURR*, *RES*, or *VOLT*

Alternate Syntax FUNCTION can be used as an alias for MODE.

Syntax Diagram



PORT0

Channel-Specific Output Command/Query

Description This command controls the general-purpose digital port on the rear of each electronic load or each channel of the multiple electronic load. The state of the port is with respect to the common side of the electronic load input. Setting a port to the **OFF** or **0** state connects it to the common; setting a port to the **ON** or **1** state disconnects it from common and sets it to a TTL logical high.

The command is the same for both single and multiple electronic loads. To control a port in a multiple electronic load you must first select the channel and then use **PORT0** on that channel.

Command Syntax PORT0[:STATE] <NRf+>

Note This command does not have a four-character short form. You must always include the fifth character (zero).

Parameters

Value Range	Units	*RST Default
OFF or 0	None	0
ON or 1	None	

Examples PORT0 ON *Set the port output high (logical 1)*

CHAN 1;: PORT0 ON;:CHAN 2;:PORT0 OFF *Set Channel 1 port high and Channel 2 port low*

Query Syntax PORT0?

Returned Parameters <NR1> 1 for ON or 0 for OFF

Related Commands None

RESistance Subsystem

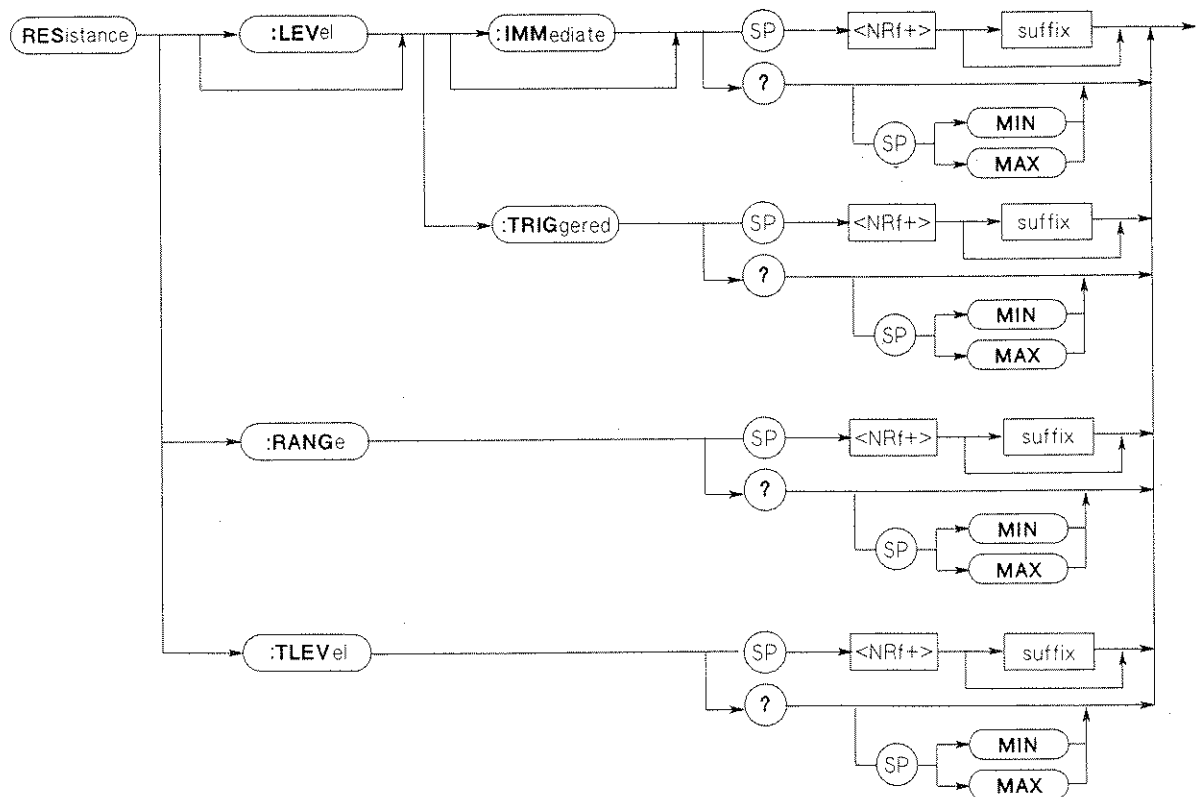
Channel-Specific Resistance Programming Function

Description This subsystem programs the constant-resistance (CR) mode function of a single electronic load or a single channel of a multiple electronic load. There is no **SLEW** command in this subsystem. In the lowest resistance range the level changes in Volts/sec at the rate specified by the present **VOLT:SLEW** command. The middle and high ranges change level in Amps/sec at the rate specified by the present **CURR:SLEW** command.

Keywords

Command	Function
RESistance[:LEVel][:IMMEDIATE]	Specify input resistance for CR mode
RESistance[:LEVel]:TRIGgered	Preset a new input resistance to be valid when a trigger occurs
RESistance:RANGe	Specify full-scale input resistance range
RESistance:TLEVel	Specify input resistance used with TRANSient Subsystem

Syntax Diagram



Resistance Subsystem Syntax Diagram

Related Subsystems **CURRent** **VOLTage**

RES[:LEVel]*Channel-Specific Resistance Command/Query*

Description This is an implied keyword that specifies the value of the programmed input resistance and whether that value is to be applied immediately or on occurrence of a trigger. If the specified channel is in the CR (constant-resistance) Mode, an **IMM**ediate resistance level is transferred to the input as soon as the command is executed. A **TRIG**gered level is stored and transferred to the electronic load input when the trigger occurs. At that time, the change to the input level occurs at the presently active voltage slew rate (for the lowest resistance range) or presently active current slew rate (for the middle and highest ranges). Following the trigger event, subsequent triggers will not affect the input level unless the electronic load has been sent another **TRIG**gered level command.

If the electronic load is not in the CR Mode when an **IMM**ediate or **TRIG**gered level command is sent, the programmed levels are saved for the next time the electronic load is placed in the CR Mode. Triggered levels are processed by the Resistance Subsystem even when the electronic load is not in the CR Mode. Thus, the **TRIG**gered level becomes a stored **IMM**ediate level that takes effect when the electronic load is again in the CR mode.

Note Setting an **IMM** resistance level to the same value as the most recent **TRIG** resistance level will not deactivate a pending **TRIG** level. You must use **ABOR**t to deactivate it.

The present resistance level of each channel changes from the present level to the pending level on any of the following:

- On a **TRIG**[:**IMM**] command (always)
- On receipt of an external trigger signal (if **TRIG**:**SOUR** is set to **EXT**)
- On the next line voltage cycle (if **TRIG**:**SOUR** is set to **LINE**)
- On receipt of ***TRG** (unless **TRIG**:**SOUR** is set to **HOLD**)
- On receipt of an HP-IB <GET> (if **TRIG**:**SOUR** is set to **BUS**)
- On the next trigger timer pulse (if multiple electronic load is set to **TRIG**:**SOUR** **TIM**)

The programmed resistance level (whether **IMM**ediate or **TRIG**gered) can be implicitly changed with a **RANG**e command (refer to “Chapter 3 - Introduction to Programming” for information concerning value coupling).

Command Syntax RESistance[:LEVel][:IMMEDIATE] <NRf+>
RESistance[:LEVel]:TRIGgered <NRf+>

Parameters See Table 4-1 at the end of this chapter

RES:RANGe*Channel-Specific Resistance Command/Query*

Description This command selects the full-scale resistance range of the electronic load. See Table 4-1 for the ranges of each model. Programming any value equal to or greater than zero (≥ 0) and less than or equal to (\leq) the maximum value of the lowest range automatically selects that range. Programming any value greater than the minimum range and less than or equal to (\leq) the maximum value of the middle range automatically selects that range. *There is no overlap between the low and middle ranges.* Programming a value greater than the maximum value of the middle range automatically selects the highest range.

Note Whenever the electronic load changes resistance range, the input momentarily goes into the OFF (minimum current) state.

The values of the input resistance (IMMediate, TRIGgered and TLEVel) are adjusted as follows:

<i>If</i>	<i>Then</i>
The existing resistance setting is within the new range	the resistance value does not change
The existing resistance value is not within the new range	the resistance is set to the closest limit of the new range

For example, assume the HP 6060A Electronic Load; is in the 10000-ohm range and the input resistance (RES:LEV) is 2000 ohms. Switching to the 1000-ohm range will reduce the resistance to the closet limit of that range, or 1000 ohms. However, if another parameter (such as RES:TRIG) was already within the new range (e.g., 500 ohm), then it will remain at that level in the new range. When switching between two ranges that overlap, the accuracy of the programmed value may be compromised because of reduced resolution when going from a lower to a higher range.

Command Syntax RESistance:RANGe <NRf+>

Parameters See Table 4-1 at the end of this chapter

Value Coupling This command affects the following parameters:

RES:LEV RES:TLEV

Examples

RES:50 *Set resistance 50 ohms*

RES:RANG 1;:TRIG 45E-3 *Change range to 1 ohm and set Triggered resistance to 45 milliohms. The main resistance will drop to 1 ohm and remain there until a trigger occurs*

Query Syntax

RES:RANG?
RES:RANG? MAX RES:RANG? MIN

Returned Parameters

<NR3> RES:RANG? returns the present resistance range in ohms.
RES:RANG? MAX and RES:RANG? MIN return the maximum and minimum programmable ranges for the electronic load.

Related Commands

RES:[LEV] RES:TRIG RES:TLEV

RES:TLEVel

Channel-Specific Resistance Command/Query

Description

This command specifies the value of the programmed resistance level for the TRANSient input when the electronic load is in the CR (constant-resistance) Mode. When the Transient Subsystem is on, the electronic load input resistance will switch (under control of the Transient Subsystem) between the main resistance and TLEVel at a rate determined by the present value of VOLT:SLEW (lowest resistance range) or by CURR:SLEW (middle and high resistance ranges). In order for input resistance level switching to occur, TLEVel must be programmed as follows:

Lowest range TLEVel > LEVel
Middle and highest ranges TLEVel < LEVel

If the above rules are not followed, no error is generated but transient switching will not occur. If the main resistance is subsequently programmed to the proper level with respect to TLEVel, switching will begin provided the TRANSient subsystem is on. If TLEVel is programmed outside the specified range, an error is generated (see Table 4-2 at the end of this chapter).

Command Syntax RESistance:TLEVel <NRf>

Parameters See Table 4-1 at the end of this chapter

Value Coupling The higher values of resistance levels have less resolution. Programmed levels are set to the nearest value obtainable by the hardware.

Examples

RES:TLEV MAX *Set transient level to maximum resistance for the range*

RES:RANG 1000 *Since TLEV > LEV on the 1k range, no transient switching occurs*
RES 200;:RES:TLEV 400;:TRAN ON

RES:TLEV 100 *Now TLEV < LEV and input switches from 100 to 200 ohms*

Query Syntax RES:TLEV?

Returned Parameters <NR3> Transient resistance value for present range. If the electronic load is not in Resistance Mode, the value will still be set, even if it is less than the presently programmed input resistance.

Related Commands See TRANsient Subsystem

STATUS Subsystem

Channel-Specific & Channel-Independent Status Commands/Queries

Description The electronic load has the following four groups of device-dependent status registers:

Register Group	Registers
Channel Status	Condition, Enable, Event
Channel Summary	Enable, Event
Questionable Status	Condition, Enable, Event
Operation Status	Condition, Enable, Event, Transition Filters

Note

See "Chapter 5 - Status Reporting" for details concerning the functions of these four groups of registers.

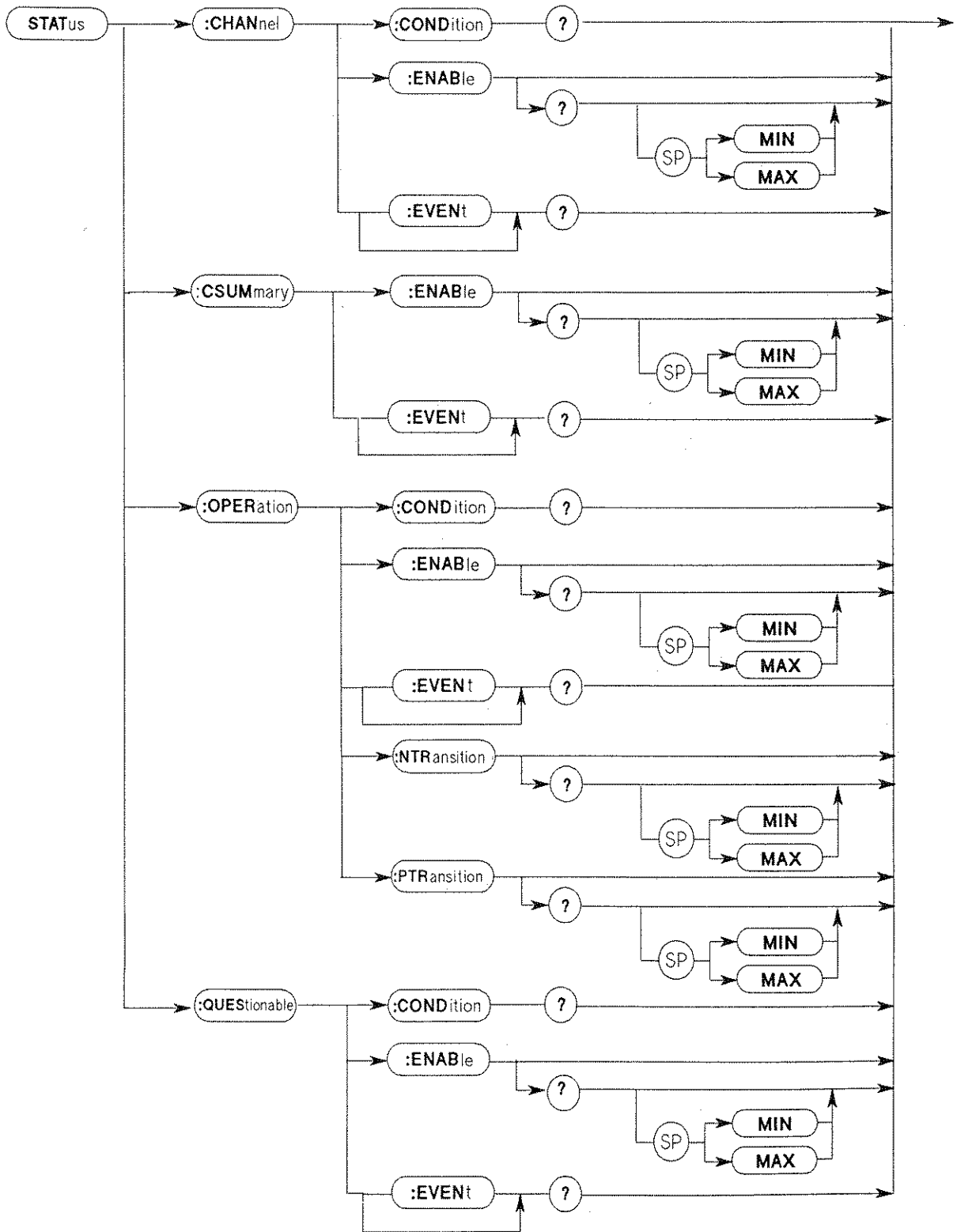
There are four groups of status command/queries corresponding to the above registers. The groups are placed in alphabetical order in the rest of this subsystem. The keywords for all groups are summarized below.

Keywords

STATus:CHANnel :CONDition?
STATus:CHANnel :ENABLE :ENABLE? :ENABLE? MAX ENABLE? MIN
STATus:CHANnel [:EVENT]?
STATus:CSUMmary :ENABLE :ENABLE? :ENABLE? MAX ENABLE? MIN
STATus:CSUMmary :EVENT?
STATus:OPERation :CONDition?
STATus:OPERation :ENABLE :ENABLE? :ENABLE? MAX ENABLE? MIN
STATus:OPERation [:EVENT]?
STATus:OPERation :NTRansition :NTRansition? :NTRansition? MAX NTRansition? MIN
STATus:OPERation :PTRansition :PTRansition? :PTRansition? MAX PTRansition? MIN
STATus:QUEStionable :CONDition?
STATus:QUEStionable :ENABLE :ENABLE? :ENABLE? MAX ENABLE? MIN
STATus:QUEStionable [:EVENT]?

Related Commands/Queries *CLS *ESE *ESR? *SRE *STB

Syntax Diagram



Status Subsystem Syntax Diagram

STAT:CHANnel

Channel-Specific Channel Status Command/Queries

Description

The Channel Status group consists of a set of registers for each channel. Each channel register set monitors all events for that channel and sums them into a corresponding summary bit in the Event register of the Channel Summary group.

The following Channel Status registers are associated with each channel:

- Condition Real-time (“live”) channel status
- Event Records all channel events that occurred since the last time the register was read
- Enable Mask for selecting which bits in the Event register are allowed to be summed into the corresponding channel bit of the Channel Summary Event register

Bit Configuration of Channel Status Registers¹

Bit Position	15,14	13	12	11	10	9	8-5	4	3	2	1	0
Condition	² NU	PS	OV	RV	UNR	EPU	NU	OT	OP	NU	OC	VE
Bit Weight		8192	4096	2048	1024	512		16	8	4	2	1

¹See Chapter 5 - Status Reporting for explanations of the bit mnemonics. ²NU = Always zero

Command/Query Syntax

<i>Command/Query</i>	<i>Function</i>
STATus:CHANnel:CONDition?	Returns the binary value of the Channel Status Condition register, which represents the present status. A condition exists if the corresponding bit = 1.
STATus:CHANnel[:EVENT]?	Returns the binary value of the Channel Event register, which latches 0-to-1 transitions of the channel conditions the first time they occur. The Event bit remains 1 even if the condition has since disappeared. <i>Reading this register resets it to zero.</i>
STATus:CHANnel:ENABle	A mask that specifies which bits of the Channel Status Event register will be allowed to be summed into the appropriate channel bit of the Channel Summary register. Set the bit to 1 to enable the condition. Program MAX to enable all allowable bits or MIN to disable them.
STATus:CHANnel:ENABle?	Returns the binary mask value of the Channel Status Enable register.

Remember

The STAT:CHAN commands are channel specific. For the multiple electronic load first send a CHANnel command to select the desired channel.

Returned Parameters

<NR1> Register binary value

Examples

STAT:CHAN? *Returns the value of the Event register in a single electronic load or of the presently addressed channel Event register in a multiple electronic load*

STAT:CHAN:ENAB 18 *Programs the Channel Enable register to allow the occurrence of either an OC or an OT condition to set the corresponding bit in the Channel Summary Event register for the present channel*

STAT:CHAN:EVEN?;COND? *Returns the values of the Event and Condition registers for the present channel. The Condition value is the status as it existed at the moment the Condition register was read*

CHAN 2;STAT:CHAN:ENAB 19 *Programs the Channel Status Enable register to enable OV, OC, and OT conditions to set the Channel Summary Event bit for Channel 2*

**Related
Commands/Queries**

STAT:CSUM STAT:QUES *CLS INP:PROT:CLE *CLS
INP:PROT:CLE

STAT:CSUMmary

Channel-Independent Channel Summary Command/Queries

Description

The Channel Summary group of registers provides a convenient way to determine if any enabled CHAN:STAT Events have occurred on a particular channel. The Channel Summary group is primarily intended for use with multiple electronic loads. However, all commands in this group are valid with single electronic loads. The following registers comprise the Channel Summary group:

STAT:CSUMmary

Event Register	Indicates all channels on which an enabled STAT:CHAN Event has occurred since the last time the register was read.
Enable Register	Mask for selecting which bits in the Channel Event register are allowed to be summed into the CSUM (Channel Summary) bit of the Status Byte register.

The bit maps for these registers are:

Bit Configuration of Channel Summary Registers¹

Bit Position	12	11	10	9	8	7	6	5	4	3	2	1	0
Channel	12	11	10	9	8	7	6	5	4	3	2	1	NU
Bit Weight	8192	4096	2048	1024	256	128	64	32	16	8	4	2	1

¹Not all channel bits may be used. NU = always zero

The following command/queries are associated with this register group:

Command/Query Syntax

<i>Command/Query</i>	<i>Function</i>
STATus:CSUMmary[:EVENT]?	Returns the binary value of the Channel Summary Event register. A 1 in the bit position indicates that there is an event from that channel. <i>Reading this register resets it to zero.</i>
STATus:CSUMmary:ENABLE	A mask that specifies which bits of the Channel Summary Event register can be selected to set the Status Byte register CSUM bit. Set the bit to 1 to enable the bit. Program MAX to enable all allowable bits or MIN to disable them.
STATus:CSUMmary:ENABLE?	Returns the binary mask value of the Channel Summary Enable register.

Returned Parameters <NR1> Register binary value

Examples

STAT:CSUM? *Returns the value of the CSUMmary EVENT register*

STAT:CSUM:ENAB 18 *Programs the Channel Summary Enable register to allow the Channel Summary Event register to set the error summary bits for Channels 1 and 4*

**Related
Commands/Queries**

STAT:QUES *CLS

STAT:OPERation

Channel-Independent Operation Status Command/Queries

Description

The Operation Status registers provide information about the following operating conditions:

- WTG A 1 indicates that at least one channel of the electronic load is waiting for a trigger to occur
- CAL A 1 indicates that the calibration constants of the channel are presently being recalculated. Unless you are explicitly calibrating the electronic load, this bit is always 0

The WTG bit is used to detect if the electronic load is waiting to complete the transfer of a pending trigger level. When the bit is set, it means that the electronic load has processed a trigger level command (e.g., CURR:TRIG 25) but is waiting for a trigger in order to execute that command.

Note

Refer to the electronic load *Operating Manual* for information concerning Calibration commands.

The following registers are associated with Operation Status commands:

- | Register | Function |
|-----------|---|
| Condition | Real-time ("live") operating status |
| PTR/NTR | Programmable filters that determine what type of transition (0-to-1 or 1-to-0) in the Condition register will set the corresponding bit in the Event register |
| Event | Records all channel conditions that occurred since the last time the register was read |
| Enable | Mask for selecting which bits in the Event register are allowed to be summed into the OPER (Operation Summary) bit of the Status Byte register |

Bit Configuration of Operation Status Registers

Bit Position	11 - 6	5	4 - 1	0
Condition	¹ NU	WTG	¹ NU	CAL
Bit Weight		32		1
¹ NU = Not Used				

STAT:OPERation

The following command\queries are associated with this register group:

Command/Query Syntax

Register	Function
STATus:OPERation:CONDition?	Returns the binary value of the Operation Status Condition register, which represents the present status. The condition is occurring whenever the bit is <i>1</i>
STATus:OPERation:PTRansition	A filter that specifies whether or not a <i>0-to-1</i> transition in the Condition register will set the corresponding bit in the Event register. Program the bit position to <i>1</i> to enable the transition requirement.
STATus:OPERation:PTRansition?	Returns the binary value of the PTRansition filter
STATus:OPERation:NTRansition	A filter that specifies whether or not a <i>1-to-0</i> transition in the Condition register will set the corresponding bit in the Event register. Program the bit position to <i>1</i> to enable the transition requirement.
STATus:OPERation:NTRansition?	Returns the binary value of the NTRansition filter
STATus:OPERation[:EVENT]?	Returns the binary value of the Operation Event register, which latches specified transitions in the Operation Condition register the first time they occur. The event bit remains <i>1</i> even if the condition has since disappeared. <i>Reading this register resets it to zero.</i>
STATus:OPERation:ENABle	A mask that specifies which bits of the Operation Status Event register are allowed to be summed into the OPER (Operation) bit of the Status Byte register. Set the bit to <i>1</i> to enable the corresponding condition. Program <i>MAX</i> to enable all allowable bits or <i>MIN</i> to disable them.
STATus:OPERation:ENABle?	Returns the binary mask value of the Operation Status Enable register.

Note

To specify a bit to be set on either a *0-to-1* or a *1-to-0* transition, program both filters (NTR and PTR) for that bit to *1*. To prevent a bit from being sent under any conditions, program that bit in both filters to *0*.

Returned Parameters

<NR1> Register binary value

Examples

STAT:OPER? *Returns the binary value of the Operation Status Event register*

STAT:OPER:COND? *Returns the status of the Electronic Load as it existed the instant the register was read*

STAT:OPER:PTR 32;NTR 32 *Program a recorded event on any transition of the WTG bit*

Note

ABORt can also cause a WTG bit event if the corresponding NTRansition bit is set to 1.

**Related
Commands/Queries**

ABOR *CLS TRIG *TRG

STAT:QUESTionable

Channel-Independent Questionable Status Command/Queries

Description

The Questionable Status register group provides information that some data or parameters may be unreliable. The Questionable Status registers monitor the same conditions as the Channel Status group. However, the Questionable status monitors a specified condition for all channels in the multiple electronic load and sums them into the QUES (Questionable Summary) bit of the Status Byte register. This permits the controller to use a single command to determine if the specified condition exists on any of the channels. All commands associated with this group are valid with single electronic loads, but in that case the Questionable and Channel Status registers will hold the same information. The following three Channel Status registers are associated with each channel:

- Condition Real-time ("live") recording of Questionable data
- Event Records all Questionable conditions that occurred since the last time the register was read
- Enable Mask for selecting which bits on the Event register are allowed to be summed into the QUES bit of the Status Byte register

Bit Configuration of Questionable Status Registers

Bit Position	15,14	13	12	11	10	9	8-5	4	3	2	1	0
Condition	¹ NU	PS	OV	RV	UNR	EPU	NU	² TE	² PE	NU	² CE	² VE
Bit Weight		8192	4096	2048	1024	512		16	8		2	1

¹NU = Not Used.

²All signals are the same as the Channel Status Condition register. Different mnemonics are required by the HP-SL standard.

Note

See "Chapter 5 - Status Reporting" for a explanations of the bit mnemonics.

STAT:QUESTIONable

Command/Query Syntax

<i>Query</i>	<i>Function</i>
STATus:QUESTIONable:CONDition?	Returns the binary value of the Questionable Status Condition register, which represents real-time status of possible Electronic Load malfunctions. A condition exists if the corresponding bit = 1.
STAT:QUESTIONable[:EVENT]?	Returns the binary value of the Questionable Status Event register, which latches each 0-to-1 transition of the condition of the Questionable Condition register the first time it occurs. The bit remains 1 even if the original condition has since disappeared. <i>Reading this register resets it to zero.</i>
STATus:QUESTIONable:ENABle	A mask that specifies which bits of the Questionable Event register can be summed into the QUES bit of the Status Byte register. Set the bit to 1 to enable the corresponding event. Program <i>MAX</i> to enable all allowable bits or <i>MIN</i> to disable them.
STATus:QUESTIONable:ENABle?	Returns the binary mask value of the Questionable Status Enable register.

Returned Parameters <NR1> Register binary value

Examples

STAT:QUES? *Returns the binary value of the Questionable Status Event register and clears it*

STAT:QUES:EVEN?;ENAB? *Returns the binary values of the Questionable Status Event and Enable registers*

STAT:QUES:ENAB 19 *Programs the Questionable Status Enable register to enable OV, OC, and OT conditions to set the Status Byte register QUES bit*

**Related
Commands/Queries** *CLS :INP:PROT:CLE

SYST:ERRor?

Channel-Independent Error Query

Description

This query reads the remote programming error queue of the electronic load. The queue, which operates in a FIFO (first-in, first-out) mode, records only programming errors - not front panel errors. As it is read, each error is removed from the queue. When all errors have been read, a zero is returned.

Negatively numbered errors are generic HP-SL errors and positively numbered errors are specific to the electronic load. (see Table 4-2 at the end of this chapter) If the error queue should become full, error -350 will be returned.

Query Syntax

SYSTem:ERRor?

Returned Parameters

<aard or crd>	Gives the error number and a short description of the error
Error Number Range	-32768 to 32767

Note

For an error summary list, see Table 4-2 at the end of this chapter.

Examples

SYST:ERR? *Returns the oldest (first) error currently in the system error queue*

Related Queries

None

TRANSient Subsystem

Channel-Specific Transient Programming Function

Description The Transient Subsystem may be used with Constant-Current, Constant-Resistance, or Constant-Voltage load operation. The transient function provides an alternate input level (**TLEVEL**) that occurs periodically under programmed control.

The three transient modes are:

- CONTInuous** A continuous pulse train that alternates between **LEVEL** and **TLEVEL** under control of an internal oscillator
- PULSe** A one-shot pulse that alternates between **LEVEL** and **TLEVEL** upon occurrence of an explicit trigger
- TOGGle** Each explicit trigger causes the input to alternate between **LEVEL** and **TLEVEL**

The input levels (**LEVEL** and **TLEVEL**) are programmed from the Current, Resistance, or Voltage Subsystems. So is **SLEW**, which determines the rate at which the input changes from one level to the other.

Note For a detailed description of transient subsystem operation, see *Operation Overview* in the *Electronic Load Operating Manual*.

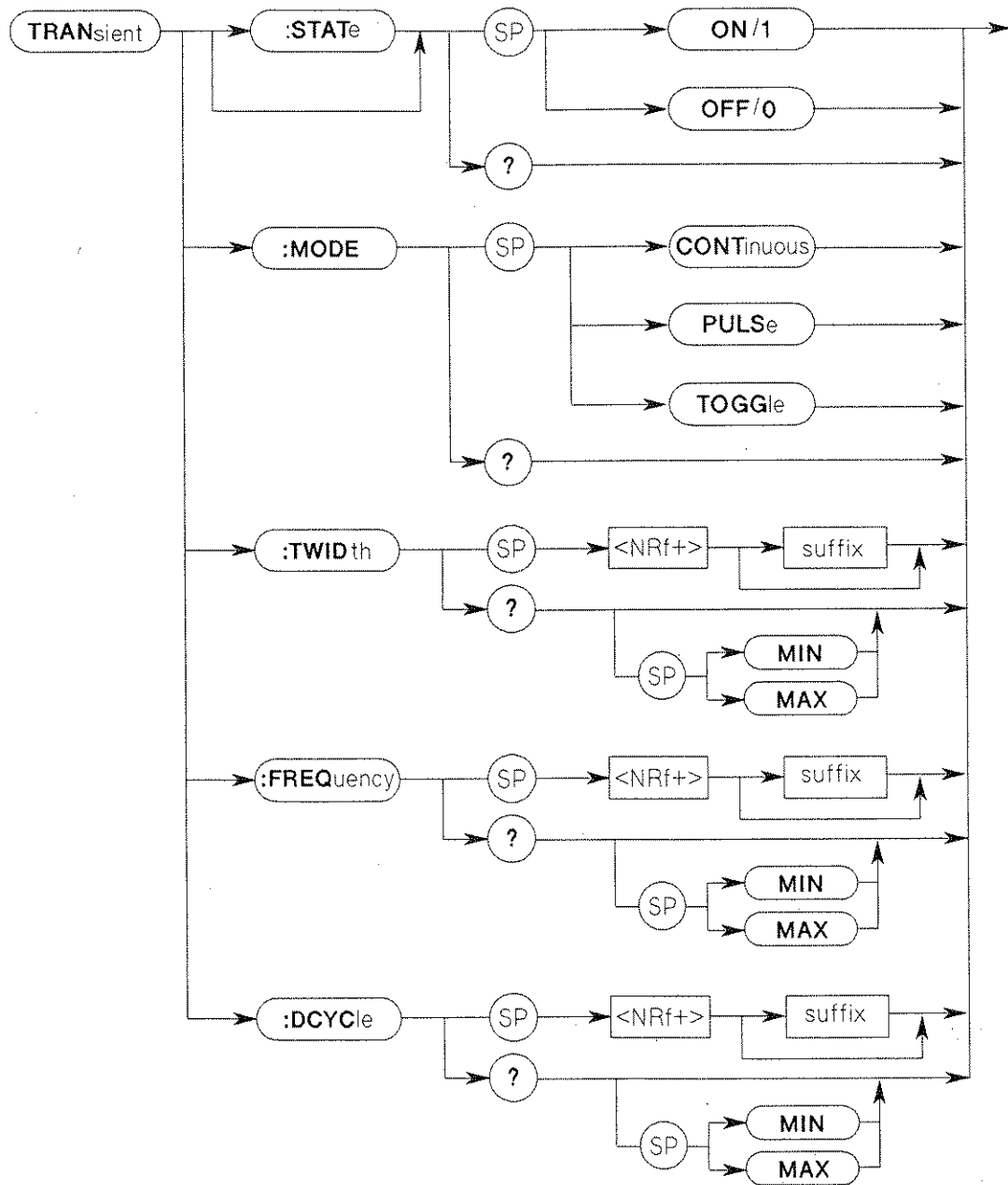
Keywords

<i>Command</i>	<i>Function</i>
TRANSient[:STATe] ON 1	Enable Transient function
TRANSient[:STATe] OFF 0	Disable Transient function
TRANSient:MODE CONTInuous	Select continuous pulse train varying between LEVEL and TLEVEL at FREQUENCY
TRANSient:MODE PULSe	Select single triggered pulses of duration TWIDTH
TRANSient:MODE TOGGle	Select pulses that switch between LEVEL and TLEVEL on alternate triggers
TRANSient:DCYClE	Set pulse duty cycle of CONTInuous mode
TRANSient:FREQUency	Set pulse frequency of CONTInuous mode
TRANSient:TWIDTH	Set pulse duration of PULSe mode

Related Commands **LEVEL** <GET> ***TRG** **SLEW** **TLEVEL**

Related Subsystem **TRIGger** Subsystem

Syntax Diagram



Transient Subsystem Syntax Diagram

TRAN:DCYClE*Channel-Specific Transient Command/Query*

Description DCYClE specifies the duty cycle of TLEV, as a percent of the total cycle, when the electronic load is in the CONTInuous mode. If programmed when the electronic load is in the PULSe or TOGGle mode, DCYClE is stored until the next time the electronic load is in CONTInuous mode. If a value is specified outside the parameter limits, an error is generated (see see Table 4-2 at the end of this chapter).

Command Syntax TRANsient:DCYClE <NRf+>

Parameters See Table 4-1 at the end of this chapter

Examples

TRAN:DCYC 10 *Set Continuous output to TLEVel for 10% of the cycle*

TRAN:MODE CONT;FREQ 500;DCYC 10;STAT 1 *Set Transient Generator to continuous mode, 500 Hz at 10% duty cycle and enable the generator*

Query Syntax TRAN:DCYC? TRAN:DCYC? MAX TRAN:DCYC? MIN

Returned Parameters <NR3> TRAN:DCYC? returns present value of Continuous Mode duty cycle in per cent
TRAN:DCYC? MAX and TRAN:DCYC? MIN return the maximum and minimum programmable duty cycle values

Related Commands TRAN:FREQ

TRAN:FREQuency*Channel-Specific Transient Command/Query*

Description FREQuency specifies the pulse frequency of the CONTInous mode. If specified in a PULSe or TOGGle mode, FREQuency will be stored for the next time the electronic load is in the CONTInuous mode. If a value is specified outside the parameter limits, an error is generated (see Table 4-2 at the end of this chapter).

Command Syntax TRANsient:FREQuency <NRf+>

Parameters See Table 4-1

Examples

TRAN:FREQ 100 *Set Transient Generator frequency to 100 Hz*

TRAN:FREQ 10 KHZ *Set Transient Generator frequency to 10 kHz*

TRAN:MODE CONT;FREQ 560;DCYC 50;STAT 1 *Set Transient Generator to continuous mode, frequency to 560 Hz, duty cycle to 50% and enable the generator*

TRAN:STAT OFF;FREQ 2E4;STAT ON *Turn off Transient Generator, change frequency to 20 kHz, and turn generator on*

Query Syntax TRAN:FREQ? TRAN:FREQ? MAX TRAN:FREQ? MIN

Returned Parameters <NR3> TRAN:FREQ? returns the value representing continuous mode FREQuency in Hz
TRAN:FREQ? MAX and TRAN:FREQ? MIN? return the maximum and minimum programmable frequency values

Related Commands TRAN:DCYC

TRAN:MODE

Channel-Specific Transient Command/Query

Description

Selects the type of operation provided by the transient generator for each channel.

- CONTinuous mode provides periodic pulses of programmable frequency and duty cycle, which are not related to TWIDth in any way. Each channel has its own oscillator that runs asynchronously with respect to oscillators of other channels.

TRAN:MODE

- **PULSe** mode provides a triggered one-shot pulse with a programmable pulse duration. When a trigger occurs, the input goes to **TLEV** for the duration of **TWID**th (which is not related to **FREQuency** or **DCYCLe** in any way) and then returns to **LEV**el. This mode is not retriggerable; triggers that occur while the input is at **TLEV**el are ignored. In multiple electronic loads, the trigger is applied to all channels simultaneously and **TRIG:SOUR** **TIMER** can be used to produce synchronized load waveforms (see **TRIGer** Subsystem).
- **TOGGle** mode causes the input to switch between **LEV**el and **TLEV**el on alternate triggers. Odd triggers set **TLEV**; even triggers set **LEV**. **FREQ**, **DCYC**, and **TWID** have no effect on this mode. Triggers are applied to all channels simultaneously in the multiple electronic load.

Note

The Operation Status Condition register **WTG** bit (see “Chapter 5 - Status Reporting”) is not affected by setting either the **PULSe** or **TOGGle** modes.

Command Syntax **TRANsient:MODE** <aard>

Parameters

Value Range	*RST Default
<i>CONT,PULS,TOGG</i>	<i>CONT</i>

Examples

TRAN:MODE PULS *Set Transient Generator to pulse mode*

TRAN:STAT 0;MODE CONT;STAT 1 *Turn off Transient Generator, change mode to continuous, and turn generator on*

Query Syntax **TRAN:MODE?**

Returned Parameters Character string *CONT*, *PULS*, or *TOGG*

Related Commands See **TRIGger** Subsystem

TRAN[::STATE]*Channel-Specific Transient Command/Query*

Description STATE is an implied keyword that enables or disables the Transient Subsystem. When the subsystem is disabled, TLEVEL inputs cannot occur. However, they may be programmed while the subsystem is disabled and will take effect when the subsystem is enabled. The enable or disable state may be programmed with either characters or equivalent numerics.

Command Syntax TRANsient[::STATE] <NRf+>

Parameters

Value Range	*RST Default
ON or 1;OFF or 0	0

Examples

TRAN ON *Enable Transient Generator function*

TRAN:STAT 1;MODE TOGG *Enable Transient Generator function and set to toggle mode*

TRAN:STAT 0;MODE PULS;TWID 10E-3;STAT ON *Disable Transient Generator function, set generator to Pulse Mode with a 10-millisecond pulse, and re-enable the generator function*

Query Syntax TRAN:STAT?

Returned Parameters <NR1> Value; 0 for OFF, 1 for ON

Related Commands None

TRAN:TWIDth*Channel-Specific Transient Command/Query*

Description TWIDth specifies the duration of TLEVEL during the PULSE mode. If specified when the electronic load is in the CONTinuous or TOGGLE mode, TWIDth is stored until the next use of PULSE mode. If a value is entered outside the specified parameters, an error is generated (see Table 4-2 at the end of this chapter).

TRAN:TWIDth

Command Syntax TRANsient:TWIDth <NRf+>

Parameters See Table 4-1 at the end of this chapter

Examples

TRAN:TWID 5E-5 *Set Transient Generator pulse duration to 50 microseconds*

TRAN:STAT 1;MODE PULS;TWID .500 *Enable Transient Generator function, set mode to pulse, and program pulse width to 500 milliseconds*

Query Syntax TRAN:TWID? TRAN:TWID? MAX TRAN:TWID? MIN

Returned Parameters <NR3> TRAN:TWID? returns value representing duration of TLEV in seconds
TRAN:TWID? MAX and TRAN:TWID? MIN return the maximum and minimum programmable duration values

Related Commands None

TRIGger Subsystem

Channel-Independent Trigger Programming Function

Description

In a multiple electronic load triggering can be initiated from the controller, the a-c line, the external **Trigger** jack, or the mainframe timer. single electronic loads may be triggered from their external **Trigger** jack, or from the controller. Any trigger signal generated by a single electronic load or multiple electronic load also exists at the **Trigger** output jack and may be used as a trigger source for any other electronic load.

Note

For a detailed explanation of the effects of triggers, see *Operation Overview* in the electronic load *Operating Manual*.

Keywords

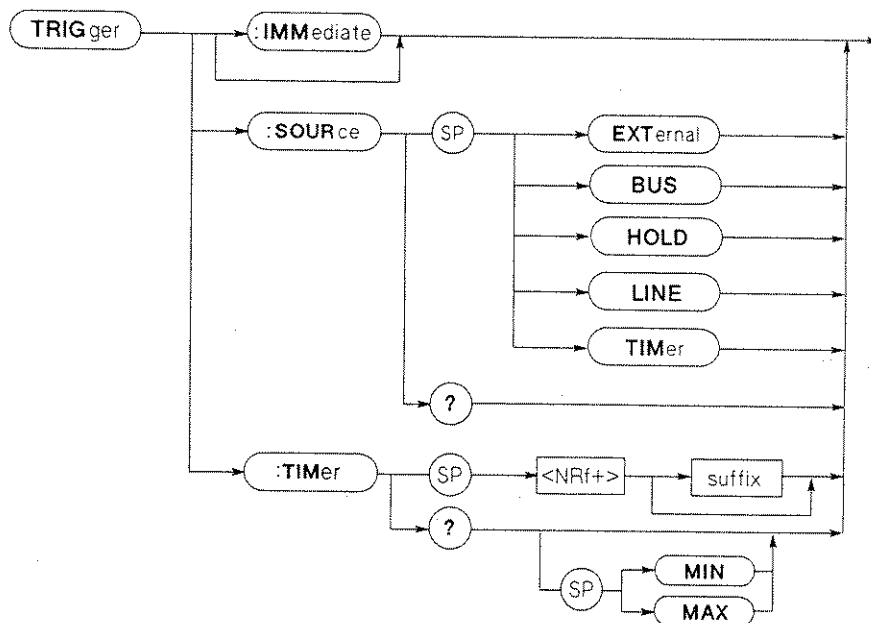
<i>Command</i>	<i>Function</i>
TRIGger[:IMMEDIATE]	Trigger-true input from the controller
TRIGger:SOURce EXTERNAL	Selects trigger source at external Trigger jack
TRIGger:SOURce BUS	Selects HP-IB *TRG or <GET> as trigger source
TRIGger:SOURce HOLD	Disables all trigger inputs except the TRIG:IMM command
¹ TRIGger:SOURce LINE	Selects the internal a-c line frequency detector as the trigger source
¹ TRIGger:SOURce TIMer	Selects internal trigger oscillator as the trigger source

¹ These commands apply only to multiple electronic loads

Related Commands *TRG <GET>

Related Subsystems TRANsient Subsystem

Syntax Diagram



Trigger Subsystem Syntax Diagram

TRIG[:IMMediate]Implied *Channel-Independent* Trigger Command**Description**

This implied keyword generates a trigger signal to the electronic load, regardless of which trigger **SOURce** is currently in effect. This is the only command that overrides **TRIG:SOUR HOLD**. When **TRIG:IMM** is executed, all pending triggered levels are transferred to the electronic load's input. The input also is affected if the Transient generator is enabled in either the **PULSe** or **TOGGle** mode. In a multiple electronic load, a trigger is applied simultaneously to all channels.

Note

When **TRIG:IMM** is executed in a single electronic load there is brief period ($\leq 100 \mu s$) during which the electronic load can also respond to either an external trigger or a **<GET>** command. This situation does not occur with multiple electronic loads.

TRIG:IMM affects the WTG bit of the Operation Status Event register (see "Chapter 5 - Status Reporting").

Command Syntax

TRIGger

Parameters

None

Examples

TRIG *Immediate trigger commands*
TRIG:IMM

Related Commands

None

TRIG:SOURce*Channel-Independent* Trigger Command/Query**Description**

TRIGger:SOURce selects the electronic load trigger source as follows:

BUS

Accepts a HP-IB **<GET>** signal or ***TRG** command as the trigger source. This mode guarantees that all previous commands will be completed before the trigger is executed.

EXternal Selects the electronic load's external **Trigger** jack as the trigger source. The **EXternal** trigger is processed asynchronously with respect to other commands. The user must ensure that the trigger occurs at a valid time with respect to commands that are already being processed or are pending.

Note

When **TRIG:SOUR BUS** is specified for a single electronic load there is brief period(100 μ s) during which the electronic load can also respond to an external trigger. This situation does not occur with multiple electronic loads.

HOLD Only the **TRIGger:IMMediate** command causes a trigger in this mode. All others, including ***TRG**, are ignored.

¹**LINE** This generates triggers in synchronization with the a-c line frequency

¹**TIMer** Selects the multiple electronic load's internal trigger oscillator as the trigger source. The oscillator begins running as soon as this command is executed. The oscillator period is selected with the **TRIG:TIM** command. **TRIG:SOUR TIM** can be used with **TRAN:MODE PULS** to generate synchronous, continuous transient waveforms on multiple channels.

¹These modes exist only in the multiple electronic load. Programming them in a single electronic load will generate an error.

Command Syntax TRIGger:SOURce

Parameters

¹ Value Range	Units	*RST Default
<i>BUS, EXternal, HOLD,</i>	None	<i>HOLD</i>
<i>LINE, TIMer</i>		

¹The long or short form may be used

Examples

TRIG *Send immediate bus trigger*
 TRIG:IMM

TRIG:SOUR HOLD;IMM *Disable all sources and send immediate bus trigger*

Query Syntax	TRIG:SOUR?
Returned Parameters	BUS EXT HOLD LINE TIM
Related Commands	&410 <GET> *TRG

TRIG:TIMer

Channel-Independent Trigger Command/Query

Description This command determines the period of the trigger pulses generated by the multiple electronic load's internal trigger oscillator. The trigger oscillator begins running as soon as this command is executed. If the command is executed when the **TRIG:SOUR** is not **TIMer**, the programmed period will take effect when the next **TRIG:SOUR:TIM** statement is executed. If the **TIM** parameter is out of the specified limits, an error is generated (see Table 4-2 at the end of this chapter).

Note Do not confuse this command with **TRIG:SOUR TIM**. In that command, **TIM** is a parameter for **SOURce**. This **TIM** is on the same tree level as **SOURce** and has its own parameter.

Command Syntax TRIGger:TIMer <NRf+>

Parameters See Table 4-1 at the end of this chapter

Examples

TRIG:SOUR TIM;TIM .001 *Select timer mode with frequency = 1 kHz*

TRIG:TIM 5E-5 *Change trigger frequency to 20 kHz*

Query Syntax TRIG:TIM?

Returned Parameters <NR3> Value representing period in seconds

Related Commands None

VOLTage Subsystem

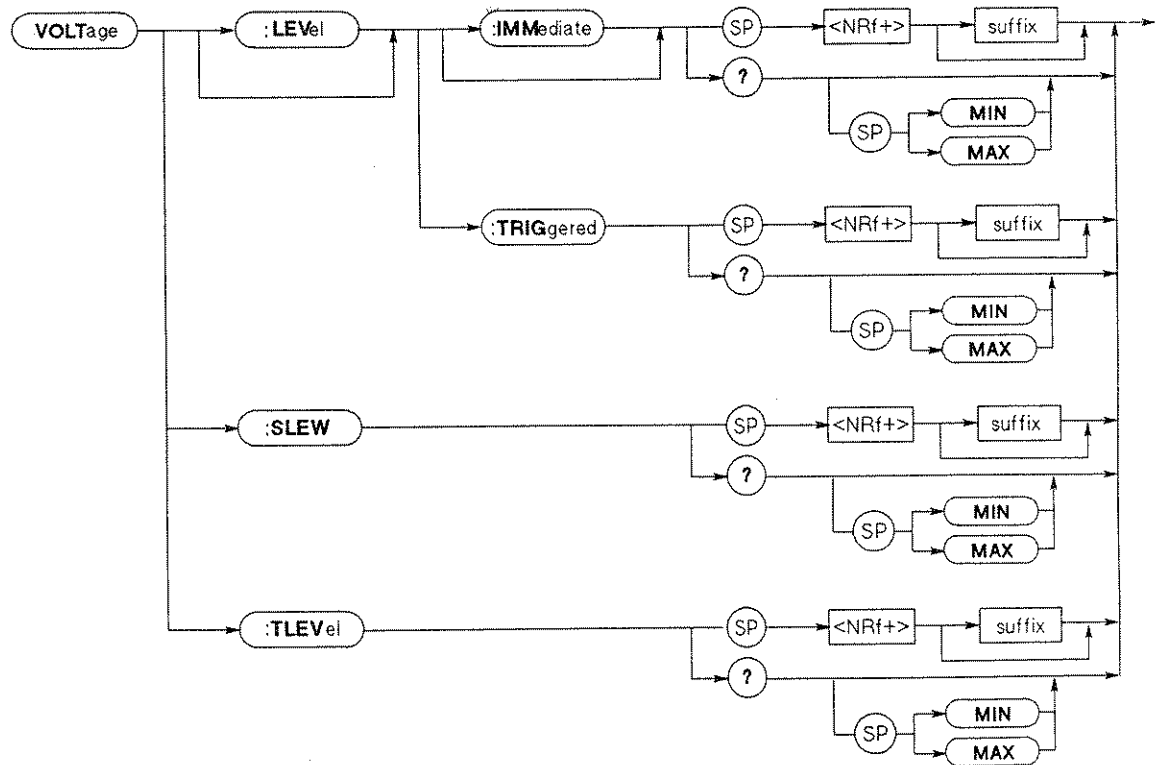
Channel-Specific Voltage Programming Function

Description This subsystem programs the voltage-mode function of a single electronic load or a single channel of a multiple electronic load.

Keywords

<i>Command</i>	<i>Function</i>
VOLTage[:LEVel][:IMMEDIATE]	Specify main level for CV Mode
VOLTage[:LEVel]:TRIGgered	Preset voltage level pending trigger occurrence
VOLTage:SLEW	Specify voltage level rate of change
VOLTage:TLEVel	Specify input voltage level used by TRANsient subsystem

Syntax Diagram



Voltage Subsystem Syntax Diagram

Related Subsystems CURRent RESistance

VOLT[:LEVel]*Channel-Specific Voltage Command/Query*

Description	<p>This implied keyword specifies the value of the programmed voltage level and whether that level is to be applied immediately or on occurrence of a trigger. If the specified channel is in the Voltage Mode, an IMMediate voltage level is transferred to the input as soon as the command is executed. A TRIGgered level is stored and transferred to the input when a trigger occurs. At that time, the change to the input level occurs at the slew rate presently in effect. Following the trigger event, subsequent triggers will not affect the input level unless the electronic load has been sent another TRIGgered level command.</p> <p>If the electronic load is not in the CV (Constant-Voltage) Mode when an IMMediate or TRIGgered level command is sent, the programmed levels are saved for the next time the electronic load is placed in the CV Mode. Triggered levels are processed by the Voltage Subsystem even when the electronic load is not in the CV Mode. Thus, the TRIGgered level becomes a stored IMMediate level that takes effect when the electronic load is again in the CV Mode.</p>
Note	<hr/> <p>Setting an IMM voltage level to the same value as the most recent TRIG voltage level will not deactivate a pending TRIG level. You must use ABORt to deactivate it.</p> <hr/> <p>The present voltage level changes to the pending level on any of the following conditions:</p> <ul style="list-style-type: none"> ■ On a TRIG[:IMM] command (always) ■ On receipt of an external trigger signal (if TRIG:SOUR is set to EXT) ■ On the next line voltage cycle (if TRIG:SOUR is set to LINE) ■ On receipt of *TRG (unless TRIG:SOUR is set to HOLD) ■ On receipt of an HP-IB <GET> (if TRIG:SOUR is set to BUS) ■ On the next trigger timer pulse (if multiple electronic load is set to TRIG:SOUR TIM)
Command Syntax	<p>VOLTage[:LEVel][:IMMEDIATE] <NRf+> VOLTage[:LEVel]:TRIGgered <NRf+></p>
Parameters	See Table 4-1 at the end of this chapter
Status and Errors	TRIG gered level commands affect the WTG bit in the Operation Condition register and the OPC bit in the Standard Event Status Event register (refer to “Chapter 5 - Status Reporting”)

Examples

VOLT:SLEW 5E6 *Set slew rate for 5,000,000 Volts/Sec*
 VOLTAGE:SLEW MAX

VOLT:TRIG 60MV;:VOLT:SLEW 1E4 *Triggered input of 60 mV to be
 slewed at 10000 volts/second*

Note

Programming the slew rate value greater than *MAX* sets the slew rate to maximum without generating an error message.

Query Syntax

VOLT:SLEW?
 VOLT:SLEW? MAX
 VOLT:SLEW? MIN

Returned Parameters

<NR3> **VOLT:SLEW?** returns the internally selected slew rate (in V/s) that was chosen as closest to the programmed value within the permissible range. **VOLT:SLEW? MAX** and **VOLT:SLEW? MIN** return the maximum and minimum programmable slew rates for the present range.

Related Commands

None

VOLT:TLEVel

Channel-Specific Voltage Command/Query

Description

This command specifies the value of the programmed voltage level for the **TRANS**ient input when the electronic load is in the CV (constant-voltage) Mode. When the Transient Subsystem is on, the electronic load input voltage will switch (under control of the Transient Subsystem) between the main level and **TLEVel** at a rate determined by the present value of **SLEW**. In order for input voltage level switching to occur, **TLEVel** must be greater than the main level. If **TLEVel** is set to a value below the main level, no error is generated but switching will not occur until the main level is subsequently programmed below the value of **TLEVel**. If **TLEVel** is programmed outside the specified range, an error is generated (see Table 4-2 at the end of this chapter).

Command Syntax

VOLTage:TLEVel <NRf>

Parameters

See Table 4-1 at the end of this chapter

Examples

VOLT:TLEV MAX *Set transient level to maximum voltage*

VOLT 40;TLEV 60 *Set main voltage level to 40 V and transient level to 60 V*

Query Syntax

VOLT:TLEV?
 VOLT:TLEV? MAX
 VOLT:TLEV? MIN

Returned Parameters

<NR3>

VOLT:TLEV? returns the transient voltage level for present range. If the electronic load is not in CV Mode, the level will still be set, even if it is less than the presently programmed input level.

VOLT:TLEV? MAX and **VOLT:TLEV? MIN** return the maximum and minimum programmable values for the present range.

Related Commands

TRANsient Subsystem

COMMAND PARAMETERS

Table 4-1 lists the programming parameters for all the electronic loads. The four-digit models (e.g., HP 6060A) are single electronic loads, while the five-digit models (e.g., HP 60502A) are modules within the mainframe of the multiple electronic load.

ERROR MESSAGES

Table 4-2 lists the error numbers and associated error messages that apply to the electronic load. The error number is the value that is placed in the electronic load's error queue. This can be read back using the **SYST:ERR?** query, which returns the error number into a variable, and both the error number and error message into a string. Information inside the brackets is not part of the standard error message, but is included for clarification. Command errors (-100 through -199) set bit 5 in the Standard Event Status register. Execution errors (-200 through -299) set bit 4 in the Standard Event Status register. Device-dependent errors (-300 through -399) set bit 3 in the Standard Event Status register. Query errors (-400 through -499) set bit 2 in the Standard Event Status register. See *Chapter 5—Status Reporting* for a complete description of the Standard Event Status register.

Hardware Errors During Turn-On Selftest

If an HP-IB failure occurs during selftest, the electronic load may or may not be able to communicate with the controller. If it can, error -330 (Self Test Error) is placed in the error queue. If an electronic load input error occurs during selftest, error -330 and error -240 (Hardware Error) are placed in the queue. If input errors occur, the electronic load will generate one or more -240 errors for each command it cannot process. Use the **SYST:ERR?** query to read the error queue after turn-on to ensure that no -330 or -240 errors are present. Any electronic load value returned by a query (such as **CURR?**) should be assumed to be invalid.

Hardware Errors During Operation

If an error does not occur during selftest but after the electronic load has been operating correctly for a time, error -240 is placed in the error queue. Most subsequent commands will not be executed and will also cause one or more -240 errors to be placed in the queue after each attempt. If your application requires the controller to be signalled if the electronic load fails, program the status registers to allow Execution errors or Device-dependent errors to generate an SRQ to the controller. See *Chapter 5—Status Reporting* for more details.

Table 4-1. Summary of Command Parameters

Command	Value Range			Units	*RST Default		
	HP 6060A/60502A	HP 60501A	HP 60504A		HP 6060A HP 60502A	HP 60501A	HP 60504A
CHAN	1 to maximum number of channels; MIN; MAX			None	1		
CURR[:LEV] CURR:TRIG							
Low Range	0 to 6 ; MIN ; MAX	0 to 3 ; MIN ; MAX	0 to 12 ; MIN ; MAX	A	0		
High Range	0 to 60 ; MIN ; MAX	0 to 30 ; MIN ; MAX	0 to 120 ; MIN ; MAX	A	0		
CURR:PROT [:LEV]	0 to 61.2 ; MIN ; MAX ¹	0 to 30.6 ; MIN ; MAX ¹	0 to 122.4 ; MIN ; MAX ¹	A	61.2	30.6	122.4
DEL	0 to 60			s	15		
STAT	0 or OFF ; 1 or ON			None	0		
CURR:RANG	6 ; 60 ; MIN ; MAX	3 ; 30 ; MIN ; MAX	12 ; 120 ; MIN ; MAX	A	60	30	120
CURR:SLEW							
Low Range	.0001 to .5 ; MIN ; MAX	.00005 to .25 ; MIN ; MAX	.0002 to 1 ; MIN ; MAX	A/ μ S			
High Range	.001 to 5 ; MIN ; MAX	.0005 to 2.5 ; MIN ; MAX	.002 to 10 ; MIN ; MAX	A/ μ S	5	2.5	10
CURR:TLEV							
Low Range	0 to 6 ; MIN ; MAX	0 to 3 ; MIN ; MAX	0 to 12 ; MIN ; MAX	A	0		
High Range	0 to 60 ; MIN ; MAX	0 to 30 ; MIN ; MAX	0 to 120 ; MIN ; MAX	A	0		
INP:SHOR	OFF or 0 ; ON or 1			None	0		
INP[:STAT]	OFF or 0 ; ON or 1			None	1		
MODE	CURR ; RES ; VOLT			None	CURR		
PORT0	OFF or 0 ; ON or 1			None	0		
RES[:LEV] RES:TRIG							
Low Range	0 to 1 ; MIN ; MAX	0 to 2 ; MIN ; MAX	0 to 0.5 ; MIN ; MAX				
Middle Range	1 to 1000 ; MIN ; MAX	2 to 2000 ; MIN ; MAX	0.5 to 500 ; MIN ; MAX	Ω	1000	2000	500
High Range	10 to 10000 ; MIN ; MAX	20 to 10000 ; MIN ; MAX	5 to 5000 ; MIN ; MAX				
RES:RANGE	1;1000;10000;MIN;MAX	2;2000;10000;MIN;MAX	0.5;500;5000;MIN;MAX	Ω	1000	2000	500
RES:TLEV							
Low Range	0 to 1 ; MIN ; MAX	0 to 2 ; MIN ; MAX	0 to 0.5 ; MIN ; MAX				
Middle Range	1 to 1000 ; MIN ; MAX	2 to 2000 ; MIN ; MAX	0.5 to 500 ; MIN ; MAX	Ω	1000	2000	500
High Range	10 to 10000 ; MIN ; MAX	20 to 10000 ; MIN ; MAX	5 to 5000 ; MIN ; MAX				
TRAN:DCYC	3 to 97 ; MIN ; MAX			%	50		
TRAN:FREQ	0.25 to 10,000 ; MIN ; MAX			Hz	1000		
TRAN:MODE	CONT ; PULS ; TOGG			None	CONT		
TRAN[:STAT]	OFF or 0 ; ON or 1			None	1		
TRAN:TWID	.00005 to 4 ; MIN ; MAX			s	.0005		
TRIG:SOUR	BUS ; EXT ; HOLD ; LINE ² ; TIM ²			None	HOLD		
TRIG:TIM ²	.000008 to 4 ; MIN ; MAX			s	.001		
VOLT[:LEV] VOLT:TRIG	0 to 60 ; MIN ; MAX			V	60		
VOLT:SLEW	.001 to 5 ; MIN ; MAX			V μ S	5		
VOLT:TLEV	0 to 60 ; MIN ; MAX			V	60		

¹ Protection level is 102% of normal maximum.

² Available only with Multiple Electronic Loads.

Table 4-2. Summary of Error Messages

Error Number	Error String [Description/Explanation/Examples]
-100	Command error [generic]
-101	Invalid character
-102	Syntax error [unrecognized command or data type]
-103	Invalid separator
-104	Data type error [e.g., "numeric or string expected, got block data"]
-105	GET not allowed
-108	Parameter not allowed [too many parameters]
-109	Missing parameter [too few parameters]
-112	Program mnemonic too long [maximum 12 characters]
-113	undefined header [operation not allowed]
-121	Invalid character in number [includes "9" in octal data "#q", etc.]
-123	Exponent too large [numeric overflow; exponent magnitude >32 k]
-124	Too many digits [number too long; more than 255 digits received]
-128	Numeric data not allowed
-131	Invalid suffix [unrecognized units, or units not appropriate]
-138	Suffix not allowed
-141	Invalid character data [bad character, or unrecognized]
-144	Character data too long [maximum length is 12 characters]
-148	Character data not allowed
-150	String data error
-151	Invalid string data [e.g., END received before close quote]
-158	String data not allowed
-160	Block data error
-161	Invalid block data [e.g., END received before length satisfied]
-168	Block data not allowed
-170	Expression error
-171	Invalid expression [e.g., illegal character in expression]
-178	Expression data not allowed
-180	Macro error
-181	Invalid outside macro definition [e.g., '\$1' outside macro definition.]
-183	Invalid inside macro definition
-200	Execution error [generic]
-220	Parameter error
-221	Settings conflict [uncoupled parameters]
-222	Data out of range [e.g., frequency too high for this instrument]
-223	Too much data [out of memory; block, string, or expression too long]
-240	Hardware error
-310	System error
-313	Calibration memory lost [out of cal due to memory failure]
-330	Self-test failed [more specific data after ";;"]
-350	Too many errors [error queue overflow]
-400	Query error
-410	Query INTERRUPTED [query followed by DAB or GET before response complete]
-420	Query UNTERMINATED [addressed to talk, incomplete program message received]
-430	Query DEADLOCKED [input buffer and output buffer full; can't continue]
-440	Query UNTERMINATED after indefinite response [indefinite response request not the last request in message unit]

COMMAND SUMMARY

This summary lists all electronic load common commands in alphabetical order, followed by all root-level commands

Command	Parameters	Command	Parameters	Type ¹
Common Commands				
*CLS	(none)	*RCL	(space)<Nrf>	CI
*ESE	(space)<Nrf>	*RDT?	(none)	
*ESE?	(none)	*RST?	(none)	
*ESR?	(none)	*SAV	(space)<Nrf>	
*IDN?	(none)	*SRE	(space)<Nrf>	
*OPC	(none)	*SRE?	(none)	
*OPC?	(none)	*STB?	(none)	
*OPT?	(none)	*TRG	(none)	
*PSC	(space)<Nrf>	*TST?	(none)	
*PSC?	(none)	*WAI	(none)	

Command	Parameters	Type ¹
Root-Level Commands		
ABOR	(none)	CI
CHAN[:LOAD]	(space)<Nrf+>	CI
CHAN[:LOAD]?	(none) or (space)MIN or (space)MAX	
<i>NOTE: INST may be used as an alias for CHAN</i>		
CURR[:LEV][:IMM]	(space)<Nrf+>[suffix]	CS
CURR[:LEV][:IMM]?	(none) or (space)MIN or (space)MAX	
CURR[:LEV]:TRIG	(space)<Nrf+>[suffix]	
CURR[:LEV]:TRIG?	(none) or (space)MIN or (space)MAX	
CURR:PROT[:LEV]	(space)<Nrf+>[suffix]	
CURR:PROT[:LEV]?	(none) or (space)MIN or (space)MAX	
CURR:PROT:DEL	(space)<Nrf+>[suffix]	
CURR:PROT:DEL?	(none) or (space)MIN or (space)MAX	
CURR:PROT:STAT	(space)OFF or 0 ; (space)ON or 1	
CURR:PROT:STAT?	(none)	
CURR:RANG	(space)<Nrf+>[suffix]	
CURR:RANG?	(none) or (space)MIN or (space)MAX	
CURR:SLEW	(space)<Nrf+>[suffix]	
CURR:SLEW?	(none) or (space)MIN or (space)MAX	
CURR:TLEV	(space)<Nrf+>[suffix]	
CURR:TLEV?	(none) or (space)MIN or (space)MAX	
INP:PROT:CLE	(none)	CS
INP:SHOR[:STAT]	(space)OFF or 0 ; (space)ON or 1	
INP:SHOR[:STAT]?	(none)	
INP[:STAT]	(space)OFF or 0 ; (space)ON or 1	
INP[:STAT]?	(none)	
<i>NOTE: OUTP may be used as an alias for INP</i>		
MEAS:CURR[:DC]?	(none)	CS
MEAS:POW[:DC]?	(none)	
MEAS:VOLT[:DC]?	(none)	
MODE:CURR[:DC]	(none)	CS
MODE:RES	(none)	
MODE:VOLT[:DC]	(none)	
MODE?	(none)	
<i>NOTE: FUNC may be used as an alias for MODE</i>		
PORT0	(space)OFF or 0 ; (space)ON or 1	CS
RES[:LEV][:IMM]	(space)<Nrf+>[suffix]	CS
RES[:LEV][:IMM]?	(none) or (space)MIN or (space)MAX	
RES[:LEV]:TRIG	(space)<Nrf+>[suffix]	
RES[:LEV]:TRIG?	(none) or (space)MIN or (space)MAX	
RES:RANG	(space)<Nrf+>[suffix]	
RES:RANG?	(none) or (space)MIN or (space)MAX	
RES:TLEV	(space)<Nrf+>[suffix]	
RES:TLEV?	(none) or (space)MIN or (space)MAX	

in alphabetical order. See Table 4-1 for numerical parameters for each model of electronic load. See Chapter 2 if you are not familiar with the representations used for data types.

Command	Parameters	Type ¹
STAT:CHAN:COND?	(none)	CS
STAT:CHAN:ENAB	(space)<Nrf+>	
STAT:CHAN:ENAB?	(none) or (space)MIN or (space)MAX	
STAT:CHAN[:EVEN]?	(none)	CI
STAT:CSUM:ENAB	(space)<Nrf+>	
STAT:CSUM:ENAB?	(none) or (space)MIN or (space)MAX	
STAT:CSUM[:EVEN]?	(none)	
STAT:OPER:COND?	(none)	
STAT:OPER:ENAB	(space)<Nrf+>	
STAT:OPER:ENAB?	(none) or (space)MIN or (space)MAX	
STAT:OPER[:EVEN]?	(none)	
STAT:OPER:NTR	(space)<Nrf+>	
STAT:OPER:NTR?	(none) or (space)MIN or (space)MAX	
STAT:OPER:PTR	(space)<Nrf+>	
STAT:OPER:PTR?	(none) or (space)MIN or (space)MAX	
STAT:QUES:COND?	(none)	
STAT:QUES:ENAB	(space)<Nrf+>	
STAT:QUES:ENAB?	(none) or (space)MIN or (space)MAX	
STAT:QUES[:EVEN]?	(none)	
SYST:ERR?	(none)	CI
TRAN:DCYC	(space)<Nrf+>[suffix]	CS
TRAN:DCYC?	(none) or (space)MIN or (space)MAX	
TRAN:FREQ	(space)<Nrf+>[suffix]	
TRAN:FREQ?	(none) or (space)MIN or (space)MAX	
TRAN:MODE	(space)CONT or (space)PULS or (space)TOGG	
TRAN:MODE?	(none)	
TRAN[:STAT]	(space)OFF or 0 ; (space)ON or 1	
TRAN[:STAT]?	(none)	
TRAN:TWID	(space)<Nrf+>[suffix]	
TRAN:TWID?	(none) or (space)MIN ; or (space)MAX	
TRIG[:IMM]	(none)	CI
TRIG:SOUR	(space)BUS or (space)EXT or (space)HOLD or (space)LINE or (space)TIM	
TRIG:SOUR?	(none)	
TRIG:TIM	(space)<Nrf+>	
TRIG:TIM?	(none) or (space)MIN or (space)MAX	
<i>NOTE: LINE and TIM not valid for Single Electronic Loads</i>		
VOLT[:LEV][:IMM]	(space)<Nrf+>[suffix]	CS
VOLT[:LEV][:IMM]?	(none) or (space)MIN or (space)MAX	
VOLT[:LEV]:TRIG	(space)<Nrf+>[suffix]	
VOLT[:LEV]:TRIG?	(none) or (space)MIN or (space)MAX	
VOLT:SLEW	(space)<Nrf+>[suffix]	
VOLT:SLEW?	(none) or (space)MIN or (space)MAX	
VOLT:TLEV	(space)<Nrf+>[suffix]	
VOLT:TLEV?	(none) or (space)MIN or (space)MAX	

¹CI = channel independent; CS = channel specific.

Chapter 5 STATUS REPORTING

This chapter discusses the status data structure of the electronic loads as shown in Figure 5-1. The Standard Event Status register group, the Output Queue, and the Status Byte and Service Request Enable registers perform standard HP-IB functions and are defined in *IEEE 488.2 Standard Digital Interface for Programmable Instrumentation*. Other status register groups implement the status reporting requirements of the electronic load. The Channel Status and Channel Summary groups are primarily used by multiple electronic loads. This is because each channel in a multiple electronic load has its own Status register to provide status information for that channel.

GENERAL REGISTER MODEL

The Condition register represents the present or "live" state of various electronic load signals. Reading the Condition register does not change the state of its bits. Only changes in electronic load conditions change the contents of this register. Not all status register groups have a Condition register. In some cases, such as the Standard Event Status registers, conditions are directly input into an Event register. In other cases, such as the Channel Summary registers, summary information from other registers is directly input into an Event register.

The Event register captures changes in conditions. Each bit in an Event register either corresponds to a condition bit in a Condition register, or to a specific condition in the electronic load. An event becomes true when the associated condition makes one of the following electronic load-defined transitions:

- Positive TRansition (0-to-1)
- Negative TRansition (1-to-0)
- Positive or Negative TRansition (1-to-0 or 0-to-1)

The PTR/NTR filters determine what type of condition transitions set the bits in the Event register. Only the Operation Status registers allow transitions to be programmed. All other register groups use an implied 0-to-1 condition transition to set bits in the Event register. Reading an Event register clears the register (all bits set to zero). When the electronic load is turned on, Event registers are set to zero, and the PTR/NTR filters are set to their firmware-assigned states.

The Enable register selects which bits in the corresponding Event register are logically-ORed into the Summary bit. At turn-on, Enable registers are set to zero. However, the Standard Event Enable register and the Service Request Enable register are not set to zero if the *PSC command is programmed. These registers are set to the most recent values

saved in non-volatile memory before the Electronic Load was last turned off.

CHANNEL STATUS

The Channel Status registers inform you that one or more channel status conditions, which indicate the presence of certain errors or faults, have occurred on a specific channel. Table 5-1 describes the channel status conditions that apply to the electronic load.

The Channel Status Condition register represents the present status of a channel; the bits are set when the indicated condition is true.

The Channel Status Event register records all of the channel conditions that have occurred since the last time this register was read. A condition transition from 0-to-1 on a bit in the Channel Status Condition register will set the corresponding bit in the Channel Status Event register. Reading the Channel Status Event register resets it to zero.

The Channel Status Enable register can be programmed to specify which channel status event bits are logically-ORed to become the corresponding channel bit in the Channel Summary Event register.

CHANNEL SUMMARY

The Channel Summary registers can summarize the channel status conditions of up to six channels. The channel/bit assignments in the Channel Summary registers are as follows:

Channel	Bit	Value
Channel 1	1	2
Channel 2	2	4
Channel 3	3	8
Channel 4	4	16
Channel 5	5	32
Channel 6	6	64

When an enabled bit in the Channel Status Event register is set, it causes the corresponding channel bit in the Channel Summary Event register to be set. Reading the Channel Summary Event register resets it to zero.

The Channel Summary Enable register can be programmed to specify which channel summary event bits from the existing channels are logically-ORed to become Bit 2 (CSUM bit) in the Status Byte register. For single electronic loads, only Channel 1 exists.

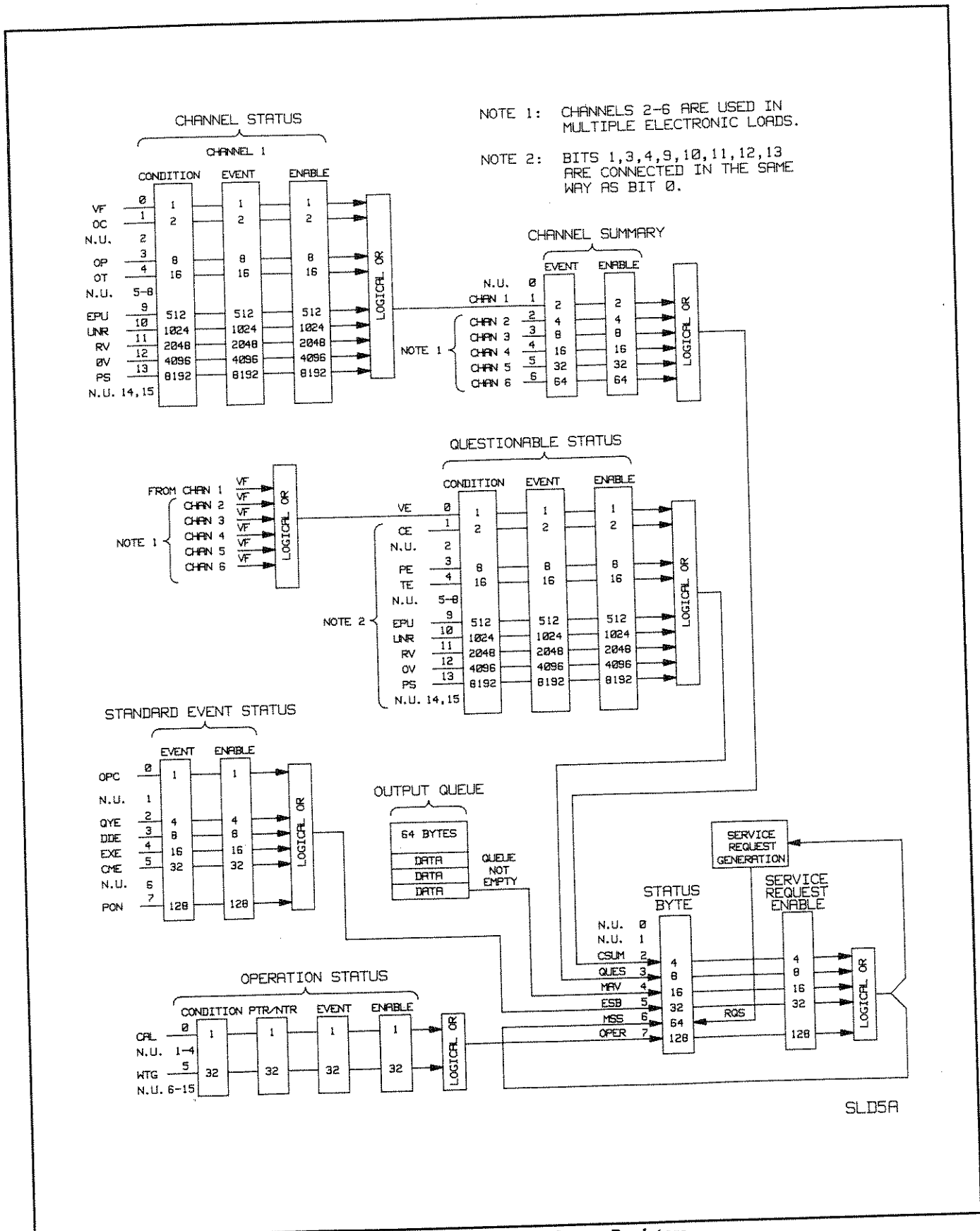


Figure 5-1. Electronic Load Status Registers

Table 5-1. Channel Status Bit Description

Mnemonic	Bit ¹	Value	Meaning
VF	0	1	<i>Voltage Fault.</i> Either an overvoltage or a reverse voltage condition has occurred on a channel. When either of these conditions occur, Bit 0 is set and remains set until INP:PROT:CLE is programmed. Note that this bit reflects the active state of the Fit pin on the back of the unit.
OC	1	2	<i>Overcurrent.</i> An overcurrent condition has occurred on a channel. This condition sets Bit 1 if the current exceeds 102% of the rated current, or if the current exceeds the user-programmed current protection level. If the overcurrent condition is removed, Bit 1 is cleared. However, if the user-programmed overcurrent condition persists beyond the user-programmed current protection delay time, Bit 13 is also set and the channel is turned off. In this case, Bits 1 and 13 remain set until the overcurrent condition is removed and INP:PROT:CLE is programmed.
OP	3	8	<i>Overpower.</i> An overpower condition has occurred on a channel. This condition sets Bit 3 when the internal overpower protection circuit is limiting the input power. This occurs if the unit exceeds the rated power of a channel when extended power is unavailable (see EPU). At low operating temperatures, the overpower limits are raised so that the unit can operate beyond the rated power (see EPU). If the overpower condition is removed, Bit 3 is cleared. However, if an overpower condition occurs and persists for more than 3 seconds, Bit 13 (PS bit) is also set and the channel is turned off. In this case, Bits 3 and 13 remain set until the overpower condition is removed and INP:PROT:CLE is programmed.
OT	4	16	<i>Overtemperature.</i> An overtemperature condition has occurred on a channel. When this occurs, both Bit 4 and Bit 13 (PS bit) are set and the channel is turned off. Bits 4 and 13 remain set until the channel (or unit) has cooled down well below the overtemperature trip point and INP:PROT:CLE is programmed.
EPU	9	512	<i>Extended Power Unavailable.</i> At high operating temperatures, the unit cannot be operated beyond the rated power of a channel. This condition sets Bit 9. At low operating temperatures, Bit 9 is cleared and extended power is available. This allows up to 33% greater power dissipation than the rated power of a channel for a period of time. The overpower limits are adjusted accordingly (see OP).
UNR	10	1024	<i>Unregulated input.</i> A channel is unregulated. This condition sets Bit 10. When the load becomes regulated, Bit 10 is cleared. Unregulated input does not occur in CV mode or in the 1 ohm range of CR mode.
RV	11	2048	<i>Reverse Voltage on input.</i> A channel has a reverse voltage applied to it. When this occurs, both Bit 11 and Bit 0 (VF bit) are set. When the reverse voltage is removed, Bit 11 is cleared. However, Bit 0 remains set until INP:PROT:CLE is programmed.
OV	12	4096	<i>Overvoltage.</i> An overvoltage condition has occurred on a channel. When this occurs, both Bit 12 and Bit 0 (VF bit) are set and the FETs are turned on as hard as possible to lower the voltage. Bits 12 and 0 remain set until the overvoltage condition is removed and INP:PROT:CLE is programmed.
PS	13	8192	<i>Protection Shutdown.</i> A channel has turned off because of an overcurrent, overpower, or overtemperature condition. When any of these three conditions occur, Bit 13 is set and remains set until INP:PROT:CLE is programmed.

¹ Bits 2, 5-8, 14, and 15 are not used by the electronic load.

QUESTIONABLE STATUS

The Questionable Status registers inform you that one or more questionable status conditions, which indicate the presence of certain errors or faults, have occurred on at least one channel. This lets you check for specific errors or faults that have occurred without having to poll each channel individually. Table 5-2 lists the questionable status conditions that apply to the electronic load. These conditions are the same as the channel status conditions. Refer to Table 5-1 for a complete description.

The Questionable Status Condition register represents the present status of all channel conditions; the bits are set when the indicated condition is true.

The Questionable Status Event register represents all of the conditions that have occurred since the last time this register was read. A condition transition from 0-to-1 on a bit in the Questionable Status Condition register will set the corresponding bit in the Questionable Status Event register. Reading the Questionable Status Event register resets it to zero.

The Questionable Status Enable register can be programmed to specify which questionable status event bits are logically-ORed to become Bit 3 (QUES bit) in the Status Byte register.

Table 5-2. Questionable Status Bit Description

Mnemonic	Bit ¹	Value	Meaning
VE/VF	0	1	Voltage Error (Voltage Fault)
CE/OC	1	2	Current Error (Overcurrent)
PE/OP	3	8	Power Error (Overpower)
TE/OT	4	16	Temperature Error (Overtemperature)
EPU	9	512	Extended Power Unavailable
UNR	10	1024	Unregulated input
RV	11	2048	Reverse Voltage on input
OV	12	4096	Overvoltage
PS	13	8192	Protection Shutdown

¹ Bits 2, 5-8, 14, and 15 are not used.

OUTPUT QUEUE

The Output Queue is a data structure that stores output messages until they are read from the electronic load. The Output Queue stores messages sequentially on a FIFO (first-in, first-out) basis. When there is data in the queue, it sets Bit 4 (MAV bit) in the Status Byte register.

STANDARD EVENT STATUS

The function of the Standard Event Status register is standard on all IEEE 488.2 devices. Table 5-3 describes the standard events that apply to the electronic load. Note that all programming errors that have occurred will set one or more of the error bits in the Standard Event Status register. Programming errors are listed in Table 4-2.

The Standard Event Status register represents all of the standard events that have occurred since the last time this register was read. Reading the Standard Event Status register resets it to zero.

The Standard Event Enable register can be programmed to specify which standard event bits are logically-ORed to become Bit 5 (ESB bit) in the Status Byte register.

NOTE

*The present settings of the Standard Event Enable register can be saved in non-volatile memory if *PSC is programmed to zero. The next time the unit is turned on, the Standard Event Enable register will be programmed according to the saved settings.*

Table 5-3. Standard Event Status Bit Description

Mnemonic	Bit ¹	Value	Meaning
OPC	0	1	<i>Operation Complete.</i> The electronic load has completed all pending operations. Programming *OPC causes this bit to be set when the electronic load completes all pending operations.
QYE	2		<i>Query Error.</i> The output queue was read when no data was present or the data in the queue was lost. Errors in the range of -499 thru -400 can set this bit.
DDE	3	8	<i>Device Dependent Error.</i> Memory was lost, or self-test failed. Errors in the range of -399 thru -300 can set this bit.
EXE	4	16	<i>Execution Error.</i> A command parameter was outside the legal range or inconsistent with the electronic load's operation, or the command could not be executed due to some operating condition. Errors in the range of -299 thru -200 can set this bit.
CME	5	32	<i>Command Error.</i> A syntax or semantic error has occurred or the electronic load received a <GET> within a program message. Errors in the range of -199 thru -100 can set this bit.
PON	7	128	<i>Power On.</i> The electronic load has been turned on or off since the last time this register was read. This bit is always set when the electronic load is turned on.

¹ Bits 1 and 7 are not used by the electronic load.

OPERATION STATUS

The Operation Status registers let you determine whether either of the operation conditions described in Table 5-4 presently exist on the electronic load.

The Operation Condition register represents the present status of the electronic load; the bits are set when the indicated condition is true.

The PTR/NTR filter determines what type of transition in the Operation Condition register will set the bit in the corresponding Operation Event register.

- Programming a bit in the PTR filter causes a 0-to-1 transition in the Operation Condition register to set the corresponding bit in the Operation Event register.
- Programming the NTR filter causes a 1-to-0 transition to set the bit.
- Programming both filters causes either transition to set the bit.

If the transition filters are not programmed, the bit is disabled.

NOTE

When the unit is turned on, the PTR filter is programmed on for the CAL bit, and the NTR filter is programmed on for the WTG bit.

The Operation Event register represents all of the filtered operation conditions that have occurred since the last time this register was read. Reading the register resets it to zero.

The Operation Enable register can be programmed to specify which operation event bits are logically-ORed to become Bit 7 (OPER bit) in the Status Byte register.

NOTE

Refer to the Electronic Load Operating Manual for information about calibration.

STATUS BYTE REGISTER

The Status Byte register summarizes all of the status events from all status registers. Table 5-5 describes the status events that apply to the electronic load.

The Status Byte register can be read with a serial poll or *STB? query. When a serial poll is sent in response to a service request, Bit 6 of the Status Byte register will contain the RQS bit. The RQS bit is the only bit that is automatically cleared after a serial poll. The other bits in the Status Byte register (including the MSS bit) are unaffected by a serial poll.

When the Status Byte register is read with a *STB? query, Bit 6 of the Status Byte register will contain the MSS bit. The MSS bit indicates that the load has at least one reason for requesting service. It is the inclusive-OR of the enabled bits (excluding bit 6) of the Status Byte Register. *STB? does not affect the status byte. The Status Byte register is cleared when a *CLS command clears all of the associated status registers.

SERVICE REQUEST ENABLE REGISTER

The Service Request Enable register can be programmed to specify which bits in the Status Byte register will generate service requests. All bits except Bit 6 (RQS/MSS) can be enabled to generate service requests. In addition to generating a service request, the enabled bits in the Service Request Enable register are logically-ORed to become the MSS bit in the Status Byte register.

NOTE

*The present settings of the Service Request Enable register can be saved in non-volatile memory if *PSC is programmed to zero. The next time the unit is turned on, the Service Request Enable register will be programmed according to the saved settings.*

Table 5-4. Operation Status Bit Description

Mnemonic	Bit ¹	Value	Meaning
CAL	0	1	<i>Calibrating.</i> A calibration calculation is in progress. (Refer to the <i>Operating Manual</i> for details of calibration commands.)
WTG	5	32	<i>Waiting for trigger.</i> At least one channel is waiting for a trigger to occur. Any TRIG command for any mode on any channel sets this bit. When a trigger is received, the bit is reset. ABORT also resets this bit.

¹ Bits 1-4, and 6-15 are not used by the electronic load.

Table 5-5. Status Byte Bit Description

Mnemonic	Bit¹	Value	Meaning
CSUM	2	4	<i>Channel Summary</i> . Indicates if an enabled channel event has occurred. Affected by Channel Condition, Channel Event, and Channel Summary Event registers.
QUES	3	8	<i>Questionable</i> . Indicates if an enabled questionable event has occurred. Affected by Questionable Condition and Questionable Event registers.
MAV	4	16	<i>Message Available</i> . Indicates if the Output Queue contains data.
ESB	5	32	<i>Event Status Bit</i> . Indicates if an enabled standard event has occurred. Affected by Standard Event register.
RQS/MSS	6	64	During a serial poll, RQS (<i>Request Service</i>) is returned and cleared. For an *STB? query, MSS (<i>Master Summary Status</i>) is returned without being cleared.
OPER	7	128	<i>Operation</i> . Indicates if an enabled operation event has occurred. Affected by Operation Condition and Operation Event registers.

¹ Bits 0 and 1 are not used by the electronic load. They will be read back as zeroes.

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