



Sorensen
XTR 850 Watt Series
Programmable DC Power Supply
(for firmware version 1.09 and below)
Operation Manual

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Important Safety Instructions

Before applying power to the system, verify that your product is configured properly for your particular application.

	Hazardous voltages may be present when covers are removed. Qualified personnel must use extreme caution when servicing this equipment. Circuit boards, test points, and output voltages also may be floating above (below) chassis ground.
	The equipment used contains ESD sensitive parts. When installing equipment, follow ESD Safety Procedures. Electrostatic discharges might cause damage to the equipment.

Only *qualified personnel* who deal with attendant hazards in power supplies, are allowed to perform installation and servicing.

Ensure that the AC power line ground is connected properly to the Power Rack input connector or chassis. Similarly, other power ground lines including those to application and maintenance equipment *must* be grounded properly for both personnel and equipment safety.


Always ensure that facility AC input power is de-energized prior to connecting or disconnecting any cable.

In normal operation, the operator does not have access to hazardous voltages within the chassis. However, depending on the user's application configuration, **HIGH VOLTAGES HAZARDOUS TO HUMAN SAFETY** may be normally generated on the output terminals. The customer/user must ensure that the output power lines are labeled properly as to the safety hazards and that any inadvertent contact with hazardous voltages is eliminated.


Guard against risks of electrical shock during open cover checks by not touching any portion of the electrical circuits. Even when power is off, capacitors may retain an electrical charge. Use safety glasses during open cover checks to avoid personal injury by any sudden component failure.


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SAFETY SYMBOLS

 **WARNING**
Risk of Electrical Shock


 **CAUTION**
Refer to Accompanying Documents


 Off (Supply)

 Direct Current (DC)

 Standby (Supply)

 Alternating Current (AC)

 On (Supply)

 Three-Phase Alternating Current

 Protective Conductor Terminal

 Earth (Ground) Terminal

 Fuse

 Chassis Ground

**Product Numbers (FGAs)
(firmware v1.09 and below)**

XTR6-110	XTR60-14
XTR8-100	XTR80-10.5
XTR12-70	XTR100-8.5
XTR20-42	XTR150-5.6
XTR33-25	XTR300-2.8
XTR40-21	XTR600-1.4

Part Numbers for Rack Mount Kits

Rack Mount Kit	Part Number
Dual XTR 850 Watt	RM-D-XTR1
Single XTR 850 Watt	RM-S-XTR1
Rack mount rails for XTR Series	RM-XTR

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About This Manual (firmware v1.09 and below)

Purpose

The Operating Manual provides installation and operating information for the XTR 850 Watt Series Programmable DC Power Supply.

Scope

The Manual provides safety information, features and specifications, installation procedures, functional test procedures, and operating procedures for both local (front panel) operation and remote operation.

The Manual does not provide information on the GPIB and Ethernet (ENET) interface options. See the *XTR 850 Watt GPIB and Ethernet Interface Option Operating Manual (Part number M370046-06)*.

Audience

The Manual is intended for the user who is familiar with electronic power supplies, Constant Voltage and Constant Current operating modes, and the control of output power. The user should be familiar with practicing safe techniques while making supply or pin connections.

Conventions Used

The following conventions are used in this guide.



WARNING

Warnings identify conditions or practices that could result in personal injury or loss of life.



CAUTION

Cautions identify conditions or practices that could result in damage to the unit or other equipment.

Important: Important notes provide information that is important for you to know. They are not as serious as Warnings or Cautions.

Related Information

For related information on this product, see also:

- *XTR 850 Watt GPIB and Ethernet Interface Option Operating Manual (Part number M370046-06)* provides information on the GPIB and Ethernet interface option.
- *XTR 850 Watt Series Programmable DC Power Supply: Quick Reference Guide (Part number M370046-04)* is included with your power supply and provides an introduction to using the front panel interface.
- *Rack Mount Kit Options Installation Instructions (Part number M370046-05)* provides information on rack mounting a single or dual XTR 850 Watt.

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Acronyms

Acronym	Definition
APG	Analog Programming
AUX	Auxiliary
ENET	Ethernet
FGA	Finished Goods Assembly
ISOL	Isolated Analog Programming
OTP	Over Temperature Protection
OVP	Over Voltage Protection
PSU	Power Supply Unit
TVS	Transient Voltage Suppressor
UVP	Under Voltage Protection

Font Conventions

This Manual uses the following typographical conventions:

<i>7 5E9iEnt</i>	For display and readback information on the output voltage and current displays.
Command body text	Represents SCPI commands.

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1

Introduction

Chapter 1, Introduction, describes the features of the XTR 850 Watt Series Programmable DC Power Supply.

Features and Options

The XTR 850 Watt Series Programmable DC Power Supply provides stable, variable output voltage and current for a broad range of development and system requirements. The power supplies have a high power density and numerous industry standard interfaces:

- RS-232, RS-485, analog programming (APG), isolated analog programming (ISOL), and USB built-in ports.
- Optional GPIB or Ethernet (ENET) control for remote operation and readback.
- Seamless switching between front panel and any digital interface (RS-232, RS-485, USB, GPIB or ENET).
- Simultaneous digital displays for both voltage and current.
- Front panel control by rotary Adjust/Enter knob, permitting high resolution output setting.
- Active Power Factor Correction (PFC) reduces input current and input current harmonics.
- Automatic crossover system allowing the power supply to switch between Constant Current and Constant Voltage operating modes.
- Parallel or series connection among multiple units to produce greater diversity or to use in higher power applications.
- Short-circuit protection of DC outputs providing greater operating safety.
- Built-in APG and ISOL interface to provide a galvanically isolated analog voltage control of the output, master/slave output tracking, and remote Enable/disable for safety and precision.
- Remote output voltage sensing to automatically compensate for cable losses.
- Software calibrated.
- Three user setting memory locations.

XTR 850 Watt Models (firmware v1.09 and below)

Table 1-1 lists the models in the XTR 850 Watt series covered by this Manual.

Table 1-1 XTR 850 Watt Series Voltage and Current Ranges

Model	Output Voltage	Output Current
6-110	0–6 V	0–110 A
8-100	0–8 V	0–100 A
12-70	0–12 V	0–70 A
20-42	0–20 V	0–42 A
33-25	0–33 V	0–25 A
40-21	0–40 V	0–21 A
60-14	0–60 V	0–14 A
80-10.5	0–80 V	0–10.5 A
100-8.5	0–100 V	0–8.5 A
150-5.6	0–150 V	0–5.6 A
300-2.8	0–300 V	0–2.8 A
600-1.4	0–600 V	0–1.4 A

Front Panel

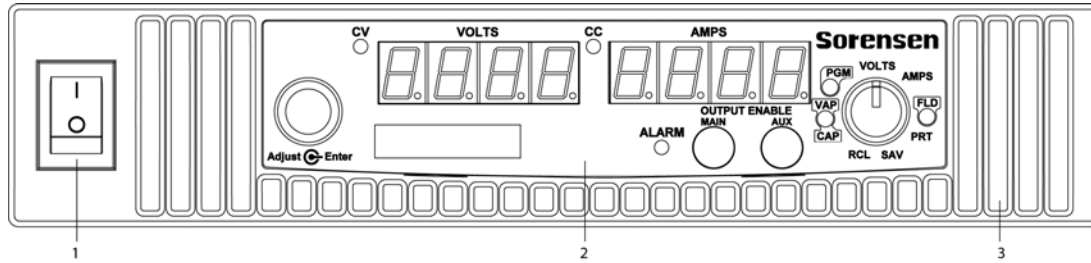


Figure 1-1 XTR 850 Watt Front Panel

Item	Description
1	Front panel power switch
2	Front panel display. See Figure 1-2 for details.
3	Air Intake Vents

Front Panel Display and Controls

1

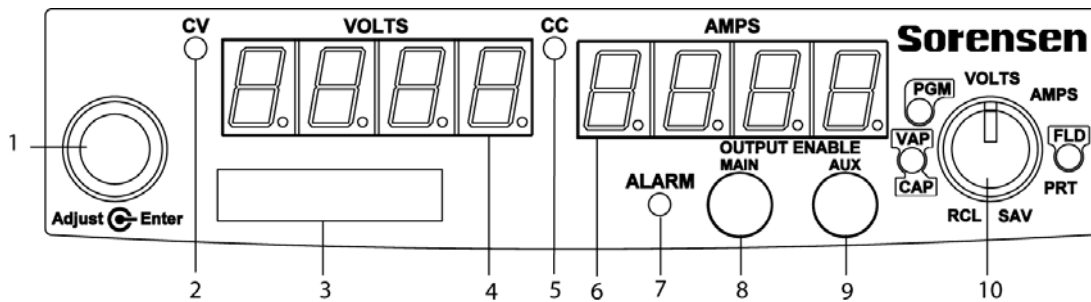


Figure 1-2 Front Panel Display and Controls

Item	Description
1	Rotary Adjust/Enter control
2	Constant Voltage (CV) Mode LED (green)
3	Model Identification Label
4	Output Voltage Display
5	Constant Current (CC) Mode LED (green)
6	Output Current Display
7	Alarm Indicator LED (red)
8	OUTPUT ENABLE Main button
9	OUTPUT ENABLE Aux button
	9-Position Mode Control (For detailed information, see “Configuring Settings from the Front Panel” on page 3–2).

Rear Panel Connectors

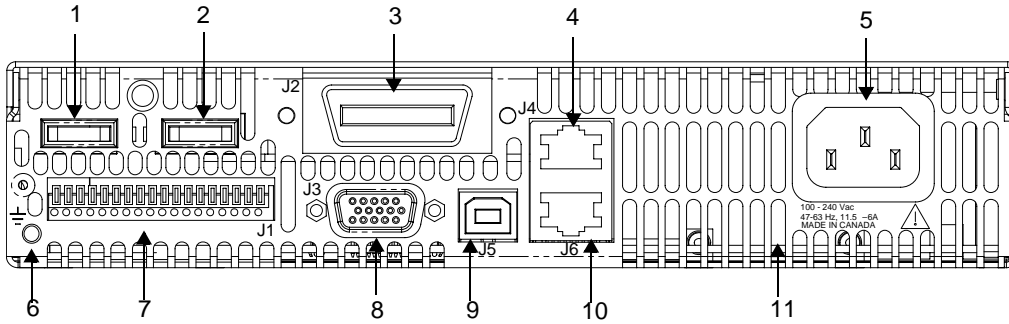


Figure 1-3 Rear Panel: 6 V to 40 V Models

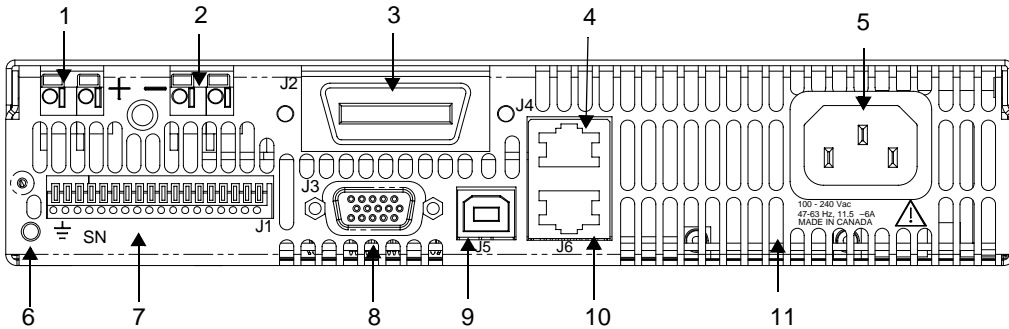


Figure 1-4 Rear Panel: 60 V to 150 V Models

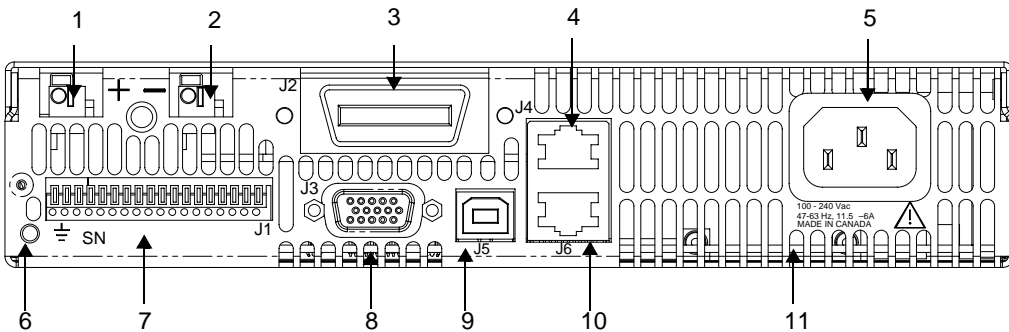


Figure 1-5 Rear Panel: 300 V to 600 V Models

Item	Description
1	6 V– 40 V Models: DC Output Terminal Positive 60 V–150 V Models: DC Output Connectors Positive (6.5 mm hole diameter) 300 V–600 V Models: DC Output Connectors Positive (6.5 mm hole diameter)
2	6 V– 40 V Models: DC Output Terminal Negative 60 V–150 V Models: DC Output Connectors Negative (6.5 mm hole diameter) 300 V–600 V Models: DC Output Connectors Negative (6.5 mm hole diameter)
3 (J2)	Ethernet (ENET) or GPIB Connector (optional)
4 (J4)	RS-232/RS-485 Connector In Port
5	AC Input Connector (IEC Type)
6	Chassis Ground Stud
7 (J1)	Analog Programming (APG) Connector. For pin information, see page 4–5.
8 (J3)	AUX Output and Isolated Analog Programming (ISOL) Connector. For pin information, see page 4–20.
9 (J5)	USB Connector
10 (J6)	RS-485 Connector Multichannel Port
11	Fan Exhaust Vents

2

Installation

Chapter 2, Installation, provides information and procedures for inspecting, installing, and testing the power supply.

Basic Setup Procedure

Table 2-1 provides a summary of the basic setup procedure with references to the relevant sections in this chapter. Refer to this table if you are unfamiliar with the installation requirements for the power supply. Complete each step in the sequence given.

Table 2-1 Basic Setup Procedure

Step	Description	Action	Reference
1	Inspect	Inspect the power supply.	“Step 1: Inspecting and Cleaning” on page 2–3.
2	Install	Install the power supply (benchtop or rack mount). Ensure adequate ventilation.	“Step 2: Location and Mounting” on page 2–4.
3	Connect Input Power	Connect AC input power.	“Step 3: Connecting AC Input Power” on page 2–5.
4	Select Wires	Select wires that are correctly rated for the maximum DC output current.	“Step 4: Selecting Load Wires” on page 2–6.
5	Test	Perform functional tests for voltage mode operation, current mode operation, and front panel controls.	“Step 5: Performing Functional Tests” on page 2–8.
6	Connect Loads	Connect the load wires to the DC output.	“Step 6: Connecting Loads” on page 2–10.
7	Connect Remote Sensing (if required)	Connect remote sensing connectors on power supply to load.	“Step 7: Connecting Remote Sensing” on page 2–13.

Step 1: Inspecting and Cleaning

Initial Inspection

When you first receive your unit, perform a physical check:

1. Inspect the unit for any scratches and cracks, broken switches, connectors or displays.
2. Ensure that the packing box contains the 7.5 foot (2.5 m) power cord.
3. If you see external damage or suspect internal damage, contact the carrier immediately.

2

Periodic Cleaning

The power supply only requires periodic cleaning, not routine servicing. Whenever a unit is removed from operation, clean the metal surfaces with naphtha or an equivalent solvent, and clean the front panel with a weak solution of soap and water. Use low-pressure compressed air to blow dust from components on the printed circuit boards.

Step 2: Location and Mounting

The power supply may be rack-mounted or used in benchtop applications.

Rack Mounting

The XTR 850 Watt power supply is designed to fill half of a standard 19 inch (483 mm) equipment rack.

Units can be combined with the same models in the 850 W series for customer applications.

Purchasing Rack Mount Kits

Contact Customer Service (see “Contact Information” on page i) about purchasing the Rack Mount Kit options for XTR 850 Watt. For a list of the part numbers, see “Part Numbers for Rack Mount Kits” on page iv. Installation information for the different rack mount options are provided with the rack mount kits.

For XTR product support, visit www.programmablepower.com and navigate to the XTR home page.

Ventilation

Whether operating the power supply in a rack or on a bench, allow air to reach the ventilation inlets on the front and rear of the unit for cooling. The direction of airflow is from the front of the unit to the back of the unit. Ventilation space is not required at the top, bottom or sides of the power supply.

Step 3: Connecting AC Input Power



WARNING: Shock hazard

Disconnect AC power from the unit before removing the cover. Even with the front panel power switch in the Off position, live line voltages are exposed when the cover is removed. Repairs must be made by an Authorized Service Center.



WARNING: Shock hazard

There is a potential shock hazard if the power supply chassis and cover are not connected to an electrical ground via the safety ground in the AC input connector. Ensure that the power supply is connected to a grounded AC outlet with the recommended AC input cord configured for the available line voltage as described in this section.



WARNING: Shock hazard

The AC input cord is the disconnect device for the power supply. The plug must be a non-locking plug which is readily identifiable by and accessible to the operator. The input cord must be no longer than 9.84 feet (3 m).

AC Input Connector

The AC input connector is a standard IEC 16 A 250 V male connector located on the rear panel of the power supply. The AC input cord provided is rated for 30 A, 300 V and appropriate for use in any country.

Step 4: Selecting Load Wires

This section provides recommendations for selecting minimum load wire sizes.

Load Wiring

To select the wiring for connecting the load to the power supply, consider the following factors:

- Insulation rating of the wire.
- Current carrying capacity of the wire.
- Maximum load wiring length for operation with remote sense lines.
- Electrical noise and impedance effects of the load lines.

Insulation Rating

Use load wiring with a minimum insulation rating equivalent to the maximum output voltage of the power supply.

Current Carrying Capacity

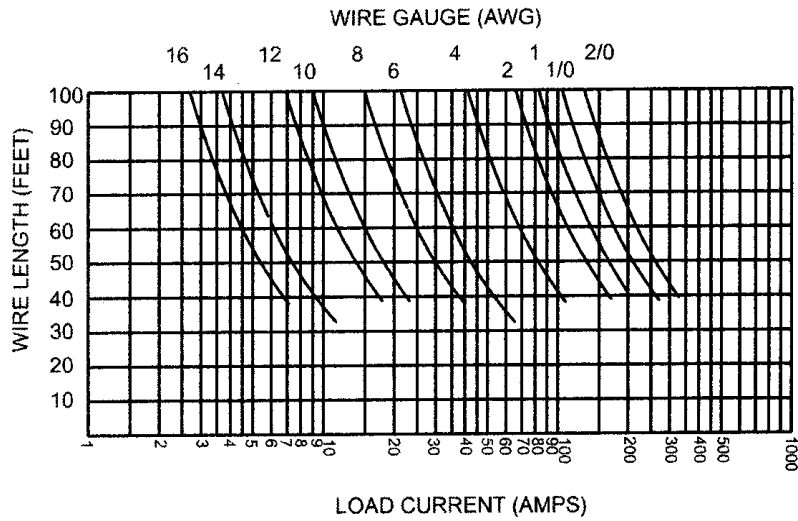
The load wiring must have a current carrying capacity greater than the output rating of the power supply to ensure that the load wiring will not be damaged if the load is shorted. Table 2-2 shows the maximum current rating for various gauges of wire rated for 105 °C operation, based on a maximum current density of 450 A/cm².

Operating at the maximum current rating shown in Table 2-2 results in an approximately 30 °C temperature rise for an appropriately-sized load wire operating in free air. Where load wiring must operate in areas with elevated ambient temperatures or bundles with other wiring, use larger gauges or wiring rated for higher temperatures.

Table 2-2 Current Carrying Capacity for Load Wiring

Wire Size (AWG)	Maximum Current (Amps)	Wire Size (AWG)	Maximum Current (Amps)
20	2.5	6	61
18	4	4	97
16	6	2	155
14	10	1	192
12	16	1/0	247
10	21	2/0	303
8	36		

Maximum Load Wiring Length For Operation With Sense Lines



2

Figure 2-1 Maximum Load Wire Length for 1 V Line Drop

Noise and Impedance Effects

To minimize noise pickup or radiation, use shielded twisted pair wiring of the shortest possible length for load sense wires. Connect the shield to the power supply chassis. Where shielding is impossible or impractical, simply twisting the wires together will offer some noise immunity.

Step 5: Performing Functional Tests

The functional test procedures include:

- Power-on and front panel functional checks
- Voltage mode operation and current mode operation checks.

For information on local operation, see “Local Operation” on page 3–1 for adjusting front panel controls and settings.

Powering the Power Supply On/Off

To power on the power supply:

1. Ensure that the front panel power switch is in the Off position.
2. Ensure that the AC line voltage is within operating range.
3. Connect the line cord to a grounded AC outlet.
4. Turn the front panel power switch to the On position.

After a short power-on delay, *EEEE EEEE* illuminates on the output voltage and current displays, followed by *PSU On*.

After approximately 1 second, the display returns to normal status.

To power off the power supply:

- ◆ Turn the front panel power switch to the Off position.

AC FAIL will blink on the display. The ALARM LED illuminates. After a short delay, all lights on the display will not be illuminated.

Voltage and Current Mode Operation Checks

To perform the voltage and current mode operation checks:

1. Ensure that the front panel power switch is in the On position and the output is disconnected.
2. If the OUTPUT ENABLE Main button is illuminated, press the button to turn off the output.
3. To check voltage mode operation, turn the 9-position mode control to the VOLTS position.

The voltage set point will blink dimming and then return to full brightness. For more information, see “Local Operation” on page 3–1.

4. Adjust the voltage to 5 V.
5. To check current mode operation, turn the 9-position mode control to AMPS position.

Verify that the current set point is blinking in the output current display.

6. Adjust the current to 1 A.
7. Press the OUTPUT ENABLE Main button to turn On.
8. Turn the front panel power switch to the Off position.
9. Turn the front panel power switch to the On position.
10. Connect a short circuit across the output terminals. Use leads of sufficient current carrying capacity. (See “Step 4: Selecting Load Wires”.)
11. Press the OUTPUT ENABLE Main button to enable the output. The button will be illuminated when the output is enabled.
CC Mode LED illuminates and the voltage and current are displayed.
CV Mode LED illuminates and the preset load current is displayed.
12. Turn the front panel power switch to the Off position.

Step 6: Connecting Loads

This section describes how to connect loads to the power supply for both single and multiple loads.



WARNING: Shock hazard

There is a shock hazard at the power supply output when operating at an output greater than 40 V. To protect personnel against accidental contact with hazardous voltages, ensure that the load and its connections have no accessible live parts.



CAUTION: Cable damage

When making connections to the output terminals, ensure terminals of opposite polarity do not touch. Load cables and sense wires should be provided with strain relief.

DC Output Connectors



WARNING: Shock hazard

Disconnect the AC input before making any connections. A shock hazard may be present at the output terminals. Allow 15 seconds after the AC power has been removed before making any connections.

6 V–40 V Models

The 6 V–40 V models are equipped with output terminals, as shown in Figure 1-3.

60 V–150 V Models

The 60 V–150 V models are equipped with output connectors, as shown in Figure 1-4. These models have output currents that may require users to use wire diameters that would not fit into a single output connector, so there are two output connectors in parallel to increase the potential current carrying capacity of load wiring.

300 V–600 V Models

The 300 V–600 V models are equipped with output connectors, as shown in Figure 1-5.

Inductive Loads and Batteries



CAUTION

The XTR power supply requires freewheeling and blocking diodes across the output while driving inductive loads or batteries to protect the power supply from damage caused by power being fed back into the supply and from high voltage transients.

Selecting Diodes

The diode must have a voltage rating at least 20% greater than the power supply's output voltage and have a current rating greater than or equal to the power supply's output rating. Connect the cathode to the positive output and the anode to the return.

Where positive load transients such as back EMF from a motor may occur, connect a Transient Voltage Suppressor (TVS) or a varistor across the output to protect the power supply. The breakdown voltage rating for the TVS or varistor must be approximately 10% higher than the rated supply output.

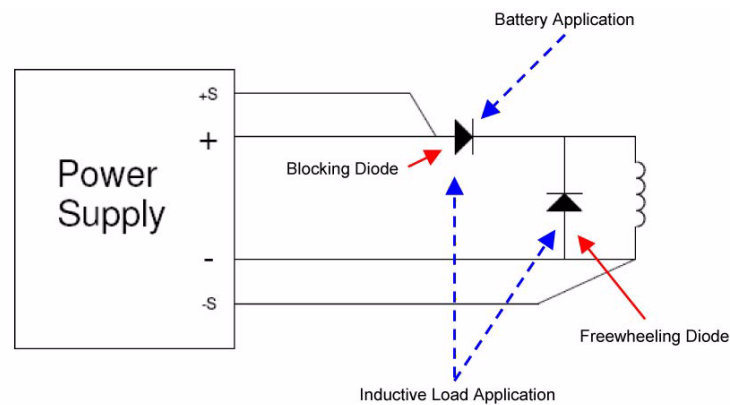


Figure 2-2 Diode Placement

For a detailed Application Note, please go to:
www.programmablepower.com and click SUPPORT.

Connecting Single Loads

Figure 2-3 shows the recommended load connections for a single load which is sensing its voltage locally. Local sense lines shown are the default connections at the rear panel APG J1 connector (see Figure 4-1 on page 4–5). The load lines should use the largest gauge and shortest length of wire possible to ensure optimal performance.

You do not need remote sensing for basic operation of your power supply. However, if you wish to correct any small drops in your load lines, then use the remote sensing feature. See “Step 7: Connecting Remote Sensing” on page 2–13 for more information.

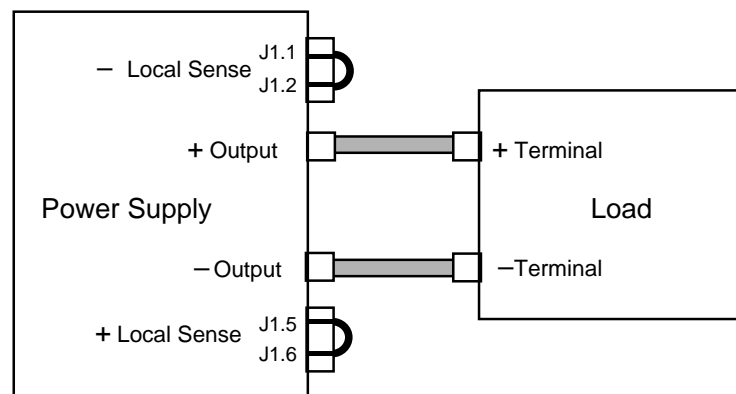


Figure 2-3 Connecting Single Loads

Connecting Multiple Loads

The proper connection of distributed loads is an important aspect of power supply use. The common method of connection is a radial load connection. Power is connected to each load individually from a single pair of terminals designated as the positive and negative distribution terminals. This pair of terminals may be the power supply output terminals, the load terminals, or a distinct set of terminals especially established for distribution use. In this scheme, there are no ground loops and the effect of one load upon another is minimized.

Step 7: Connecting Remote Sensing



WARNING: Shock hazard

There is a potential shock hazard at the sense connectors when using a power supply at an output greater than 40 V. Select wiring with a minimum insulation rating equivalent to the maximum output voltage of the power supply for use as local sense jumpers or for remote sense wires. Ensure that connections at the load end are shielded to prevent contact with hazardous voltages.

2

Remote sensing permits you to shift the regulation point of the power supply from the output terminals to the load or other distribution terminals.

Use shielded twisted pair wiring of 20 to 26 AWG for best noise performance. Make sure that the shielded twisted pair wiring insulation is rated higher than the maximum output voltage of the power supply. If possible, one end of the shield of the sense lines should be attached to the chassis ground of the power supply.

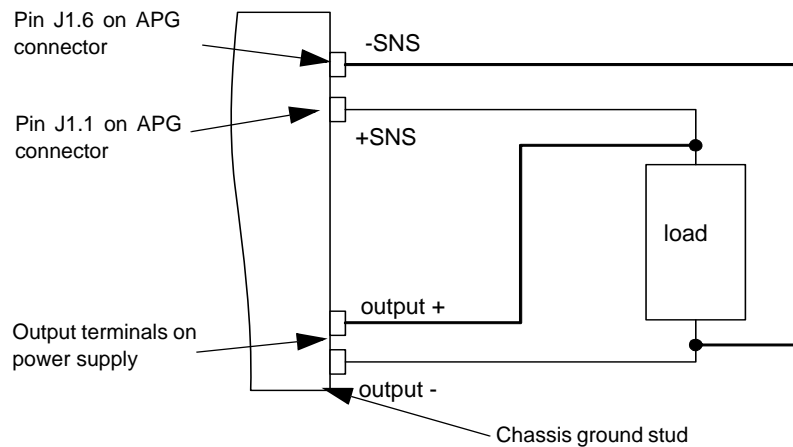


Figure 2-4 Remote Sense Connection

To connect the remote sense wires:

1. Ensure that the front panel power switch is in the Off position.
2. Using a small flat blade screwdriver, remove the two sense jumpers from pins J1.1 and J1.2, and from pins J1.5 and J1.6 on the APG Connector. See Figure 4-1, “APG Connector Terminals” on page 4–5.

3. Connect one end of the shield of the twisted pair wire to the chassis ground point on the power supply.
4. Connect the positive sense line (+SNS) from the positive regulation point as close as possible to the load terminals to pin J1.1.
5. Connect the negative sense line (-SNS) from the return of the load to pin J1-6.

To compensate for losses in power leads connected to the output, the power supply provides sense connections beside the output terminals. With remote sense leads in place, the power supply regulates to the displayed voltage at the point where the sense lines are connected to the output leads. With the sense lines disconnected, the power supply regulates the voltage at the output terminals.



CAUTION: Equipment damage

Do not operate the power supply with sense lines connected to the load without also connecting the load power leads to the output terminals.



CAUTION: Reverse polarity

Avoid reversing positive (+) and negative (-) sense connections.

When using remote sense to compensate for load line losses, ensure that the positive sense line is connected to the positive load terminal and the negative sense line is connected to the negative load terminal. Do not reverse these connections or the power supply may be damaged.

Important: Long load leads with large capacitance at the load and remote sensing can cause voltage instability due to inductance of the load leads. Measures to reduce inductance and/or capacitance (raising resonant frequency) or using local sense can be beneficial in stabilizing the system.

4

Analog Programming (APG) and Isolated Analog Programming (ISOL)

Chapter 4, Analog Programming (APG) and Isolated Analog Programming (ISOL), provides information and procedures for analog and isolated analog programming of the power supply.

Introduction

The rear panel connectors J1 and J3 provide an option to control and monitor the output of the power supply with analog signals. Connector J1 provides a non-isolated analog interface where all signals are referenced to the negative output terminal of the power supply. Connector J3 is an isolated interface and also provides an isolated auxiliary voltage output to aid analog programming.

Analog Programming (APG) of Output Voltage and Output Current

Analog programming allows control of the power supply's output voltage, output current or both to be controlled from analog input sources. As the programming source is varied within the configured analog programming range (2–10 volts/k Ω max), the power supply's output varies proportionally over its output range. For example, if you set the programming scale to 10 V voltage source and apply 5 V to the programming pins, the power supply will be programmed to 50% of the output capability for your power supply.

While analog programming mode is configured, you will not be able to make adjustments to the set points from the front panel or through the remote interfaces.

The front panel will display *APG* in the output current display when the 9-position mode control is turned to VOLTS or AMPS positions for the parameter(s) that are configured to be controlled by analog programming. If an adjustment of a parameter controlled by APG is attempted using a SCPI command, a “-221 Settings Conflict” error will be pushed onto the error queue.

Using analog programming requires that you make connections to the Isolated Analog Programming Connector or Analog Programming Connector on the rear panel of the power supply. Depending on your model, see “Rear Panel Connectors” on page 1–6 or “” on page 1–7.

Remote Programming Options

Analog Monitor Signals

There are four monitor lines for analog programming the pin name and the related APG mode, which are listed in Table 4-1. All of these lines are provided to give analog feedback. The output from these monitor lines is a value scaled to the Analog Programming level set for the corresponding analog programming type. For example, the voltage monitor and isolated voltage monitor lines are both scaled to the analog programming level that is set in the VAP mode.

Table 4-1 Monitor Lines

Related APG Mode	Reference Line Name	Connector
Non-Isolated Voltage Analog Programming	VOL_MON	J1.13
Isolated Voltage Analog Programming	IS_MON_VOL	J3.5
Non-Isolated Current Analog Programming	CUR_MON	J1.14
Isolated Current Analog Programming	IS_MON_CUR	J3.10

Important: Analog control monitor lines will reflect the output of the power supply even when the unit is not set to operate in analog programming mode.

Important: Isolated monitor lines are only valid when isolated analog programming modes are used for the respective voltage and current control. If local (front panel) control is used or non-isolated APG is used, these values will be inaccurate and should not be used for monitoring. Conversely, if isolated APG is used, the non-isolated monitor lines will be inaccurate.

Auxiliary Outputs

The auxiliary outputs are an additional isolated source. The auxiliary output has two outputs: +5 V output on J3.9 and a +15 V output on J3.11. The auxiliary output operates independently of the main output. It is enabled or disabled from the front panel by pressing the OUTPUT ENABLE Aux button. When the Aux output is enabled, the OUTPUT ENABLE Aux button is illuminated. Like the main output of the power supply, the Aux also has the ability to Autostart at power up. See “Output Auto Start Mode (Auto Restart)” on page 3–16 and “Auxiliary Auto Start Mode” on page 3–17 for details on controlling this feature.

Table 4-2 provides a summary of the options available for programming output voltage and current set point using an analog source.

Table 4-2 Remote Programming Options

Control of...	Programming Scale ¹	For more info...
Output voltage	2–10 V Voltage source (adjustable)	See page 4–10.
Current set point	2–10 V Voltage source (adjustable)	See page 4–12.
Output voltage	2–10 k Ω Resistive source (adjustable)	See page 4–15.
Current set point	2–10 k Ω Resistive source (adjustable)	See page 4–17.

1. The resolution can be adjusted in increments of 0.1 volts.

Analog Programming (APG) Connector J1

The APG connector is an 18-pin connector. See Figure 4-1.

The APG connector provides access to the following functions:

- Sense control
- Analog programming and monitoring.

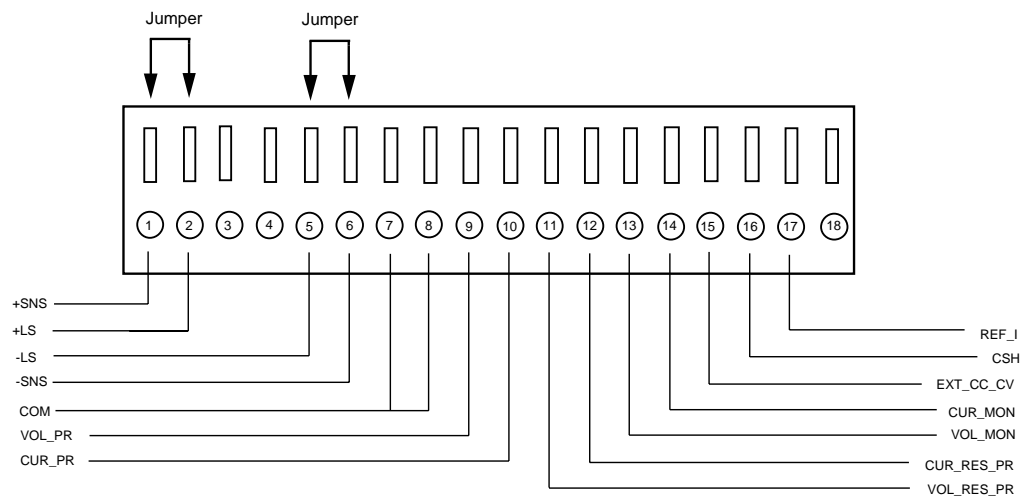


Figure 4-1 APG Connector Terminals

Table 4-3 APG Pins and Functions J1

Pin	Reference	Function
J1.1	+SNS Positive (+)	Sense Local Sense } Jumper. Factory default condition.
J1.2	+LS Positive (+)	
J1.3	-NC	
J1.4	-NC	
J1.5	-LS Negative (-)	Local Sense } Jumper. Factory default condition. Sense
J1.6	-SNS Negative (-)	
J1.7	COM Analog Common	Same as power supply negative sense (-SNS)
J1.8	COM Analog Common	Same as power supply negative sense (-SNS)

Table 4-3 APG Pins and Functions J1

Pin	Reference	Function
J1.9	VOL_PR	Analog Voltage Programming Input
J1.10	CUR_PR	Analog Current Programming Input
J1.11	VOL_RES_PR	Voltage Resistive Programming Input
J1.12	CUR_RES_PR	Current Resistive Programming Input
J1.13	VOL_MON ¹	Voltage Monitor. The scale of this output is set by the APG voltage input range selected (see Important note below).
J1.14	CUR_MON ¹	Current Monitor. The scale of this output is set by the APG current input range selected (see Important note below).
J1.15	EXT_CC_CV	External CC/CV. Indicates the state of the operate mode. When in CV mode, logic high is output and when in CC mode, logic low is output. Logic is TTL/CMOS compatible.
J1.16	CSH	Current Share. Used to hook up units for current sharing. Output from master unit. Slave units should be left open.
J1.17	REF_I	Current Reference Input. Slave input from current share output on the master unit.
J1.18	NC	

1.Important: Non-isolated monitor lines are only valid in local control, digital remote and non-isolated analog programming modes for the respective voltage and current control. If isolated analog programming is used, the isolated monitor lines should be used as the non-isolated monitoring lines will not accurately reflect the output state of the power supply.

Making Control Connections

**CAUTION: Equipment damage**

Before making connections from external circuits to the Analog Programming Connector, turn the front panel power switch to Off and wait until the front panel displays are not illuminated.

**CAUTION: Equipment damage**

Program/monitor signal and return are internally connected to the power supply negative output (-S). Do not attempt to bias these away from that potential.

To connect the output wires to the APG and DC output connector:

1. Insert a 3/32 inch slot-head screwdriver into the orange-colored box of the connector until the end of the spring is reached. See Figure 4-2.
2. Hold the connector open and insert the applicable output wire.
3. Remove the screwdriver.

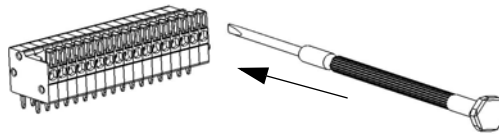


Figure 4-2 Inserting Screwdriver into Spring Terminal Block

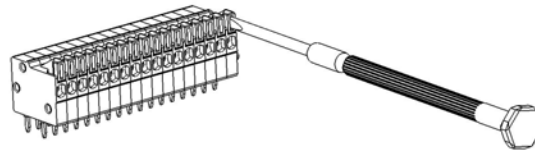


Figure 4-3 APG and DC Output Connector

Wiring



WARNING: Shock hazard

There is a potential shock hazard at the output when using a power supply with a rated output greater than 60 V. Use load wiring with a minimum insulation rating equivalent to the maximum output voltage of the power supply. For example, select TEW, 105 °C, 600 V wiring for use with a 600 V, 1.4 A power supply.

For most connectors and jumpers, use any suitable wire such as 20 to 26 AWG stranded wire. For lowest noise performance, use shielded twisted pair wiring of 20 to 26 AWG of the shortest length possible. Ground the shield to pin J1.7 (analog common) on the Analog Programming Connector or to the chassis via one of the Analog Programming Connector screws.

Analog Programming Mode

For more details about connections for your particular model, see “Rear Panel Connectors” on page 1–6 or “” on page 1–7.



CAUTION: Equipment damage

The program/monitor signal and return are internally connected to the power supply’s negative output. Do not attempt to bias these away from that potential. See “Making Control Connections” on page 4–7.

Analog Programming With External Voltage Source

The pin numbers are described in Table 4-3 on page 4–5.

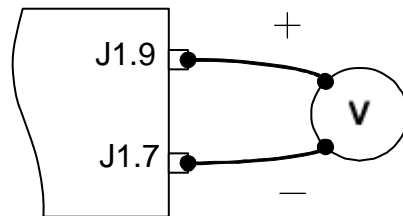


Figure 4-4 Programming Output Voltage using an External Voltage Source

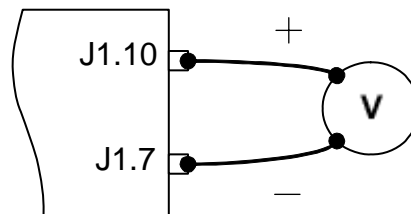


Figure 4-5 Programming Output Current using an External Voltage Source

Voltage-Controlled Voltage APG Setup

Activating APG Voltage Mode

To activate APG voltage mode using an external voltage source:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
VAPr is displayed on the output voltage display.
2. Turn the rotary Adjust/Enter control to select *Un 15* (voltage source from non-isolated connector).
3. Press the rotary Adjust/Enter control to commit the selected mode.
LE U is displayed on the output voltage display.
4. Once the desired level has been selected, press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Deactivating APG Voltage Mode

To deactivate the APG voltage mode:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
2. *VAPr* is displayed on the output voltage display.
3. Turn the rotary Adjust/Enter control to select *nonE*.
4. Press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Query for Analog Voltage Input Level

To query for analog voltage input level from non-isolated input:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
VAP is displayed on the output voltage display.
2. If the mode is currently *nonE* then select any other APG mode. If this step is done, be sure to restore the APG setting to *nonE* when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current APG mode.
3. Press the rotary Adjust/Enter control to select the APG mode.
The output voltage display should read *LE U* and the output current display will display APG level.
4. Press the rotary Adjust/Enter control to return to normal mode.
5. If the APG mode was modified in step 2, execute the procedure to deactivate the APG voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI commands for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMOte:SOURce[ :VOLtAge ] <? | LOcal
|AVOLtAge | IAVoltage | ARESistive | IAREsistive>
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel [ :VOLtAge ]
[ : ISOLated ]
[ : ]MEASure[ <channel> ] [ : SCALar ] :APROgram [ :VOLtAge ] [ :DC ]?
```

Voltage-Controlled Current APG Setup

Activating APG Current Mode

To activate APG current mode using an external voltage source:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the mode control is already at the CAP position.
CAP is displayed on the output voltage display.
2. Turn the rotary Adjust/Enter control to select source *Un IS* (Voltage source from non-isolated connector).
3. Press the rotary Adjust/Enter control to commit the selected mode.
LE C is displayed on the output voltage display.
4. Select the input source level using the rotary Adjust/Enter control.
5. Once the desired level has been selected, press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Deactivating APG Current Mode

To deactivate the APG current mode:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the mode control is already at the CAP position.
2. *CAP* is displayed on the output voltage display.
3. Turn the rotary Adjust/Enter control to select *nonE*.
4. Press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Query for Analog Current Input Level

To query for analog current input level from non-isolated input:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the mode control is already at the CAP position.

\overline{CAP} is displayed on the output voltage display.

2. If the mode is currently \overline{nonE} then select any other APG mode. If this step is done, be sure to restore the APG setting to \overline{nonE} when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current APG mode.

3. Press the rotary Adjust/Enter control to select the APG mode.

The output voltage display should read \overline{LE} and the output current display will display APG level.

4. Press the rotary Adjust/Enter control to return to normal mode.
5. If the APG mode was modified in step 2, execute the procedure to deactivate the APG voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command (s) for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMote:SOURce:CURRent <? | LOCal
|AVOLTage| IAVoltage| ARESistive| IAREsistive>
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel:CURRent
[ : ISOLated]
[ : ]MEASure[ <channel> ][ : SCALar ]:APROgram:CURRent [ : DC ]?
```

Analog Programming With External Resistor

The pin numbers are described in Table 4-3 on page 4-5.

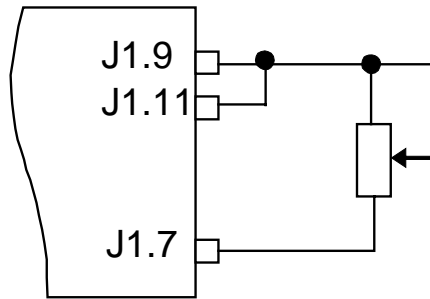
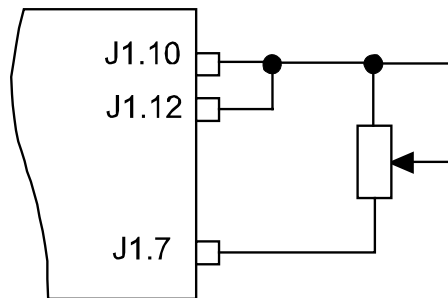


Figure 4-6 Programming Output Voltage using an External Resistor



APG Connector

Figure 4-7 Programming Output Current using an External Resistor

Resistive-Controlled Voltage APG Setup

To activate APG voltage mode using an external resistor:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
VAPr is displayed on the output voltage display.
2. Turn the rotary Adjust/Enter control to select *rn 15* (resistor source from non-isolated connector).
3. Press the rotary Adjust/Enter control to commit the selected mode.
LE U is displayed on the output voltage display.
4. Select the input source level using the rotary Adjust/Enter control.
5. Once the desired level has been selected, press the rotary Adjust/Enter control to commit the change.

The display will return to the normal display.

Deactivating APG Voltage Mode

To deactivate the APG voltage mode:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
2. *VAPr* is displayed on the output voltage display.
3. Turn the rotary Adjust/Enter control to select *nonE*.
4. Press the rotary Adjust/Enter control to commit the change.

The display will return to the normal display.

Query for Analog Voltage Input Level

To query for analog voltage input level from non-isolated input:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
VAP is displayed on the output voltage display.
2. If the mode is currently *nonE* then select any other APG mode. If this step is done, be sure to restore the APG setting to *nonE* when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current APG mode.
3. Press the rotary Adjust/Enter control to select the APG mode.
The output voltage display should read *LE U* and the output current display will display APG level.
4. Press the rotary Adjust/Enter control to return to normal mode.
5. If the APG mode was modified in step 2, execute the procedure to deactivate the APG voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMOte:SOURce[ :VOLtAge ] <? | LOCal  
| AVOLtAge | IAVoltage | AREsistive | IAREsistive>  
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel[ :VOLtAge ]  
[ : ISOLated ]  
[ : ]MEASure[ <channel> ] [ : SCALar ]:APROgram[ :VOLtAge ] [ : DC ]?
```

Resistive-Controlled Current APG Setup

To activate APG current mode using an external resistor source:

1. Turn the 9-position mode control to the CAP position to press the rotary Adjust/Enter control if the control knob is already at CAP position.
CAP is displayed on the output voltage display.
2. Turn rotary Adjust/Enter control to select $r_n I_5$ (voltage source from non-isolated connector).
3. Press the rotary Adjust/Enter control to commit the selected mode.
LE \bar{I} is displayed on the output voltage display.
4. Once the desired level has been selected, press the rotary Adjust/Enter control to commit the change.

The display will return to the normal display.

Deactivating APG Current Mode

To deactivate the APG current mode:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the mode control is already at the CAP position.
CAP is displayed on the output voltage display.
2. Turn the rotary Adjust/Enter control to select $n_0 n E$.
3. Press the rotary Adjust/Enter control to commit the change.

The display will return to the normal display.

Query for Analog Current Input Level

To query for analog current input level from non-isolated input:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the mode control is already at the CAP position.
CAP is displayed on the output voltage display.
2. If the mode is currently nonE then select any other APG mode. If this step is done, be sure to restore the APG setting to nonE when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current APG mode.
3. Press the rotary Adjust/Enter control to select the APG mode.
The output voltage display should read LE E and the output current display will display APG level.
4. Press the rotary Adjust/Enter control to return to normal mode.
5. If the APG mode was modified in step 2, execute the procedure to deactivate the APG voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMOte:SOURce:CURRent <? | LOCal  
| AVOLtage | IAVoltage | ARESistive | IAREsistive>  
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel:CURRent  
[ : ISOLated ]  
[ : ]MEASure[ <channel> ] [ : SCALar ]:APROgram:CURRent [ : DC ]?
```

Voltage and Current Readback

The pin numbers are described in Table 4-3 on page 4-5.

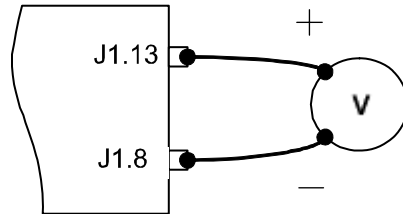


Figure 4-8 Voltage Readback Using APG Connector J1

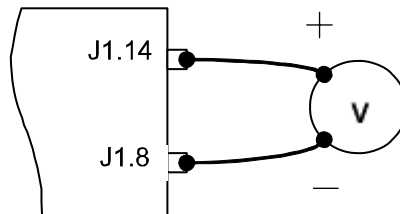


Figure 4-9 Current Readback Using APG Connector J1

Isolated Analog Programming Mode (ISOL)

See “Rear Panel Connectors” on page 1–6 or “” on page 1–7 for more details about connections.

AUX Output and Isolated Analog Programming (ISOL) Connector

The AUX Output and Isolated Analog Programming (ISOL) Connector is a 15-pin female DSUB connector. See Figure 4-10. All pins on this connector are electrically isolated from the output of the power supply.

The AUX Output and ISOL Connector provides access to the following functions:

- Auxiliary +5 V and +15 V outputs
- OUTPUT ENABLE Aux
- Power On Status (output)
- SD—Shutdown (input)
- Interlock
- ISOL programming and monitoring.

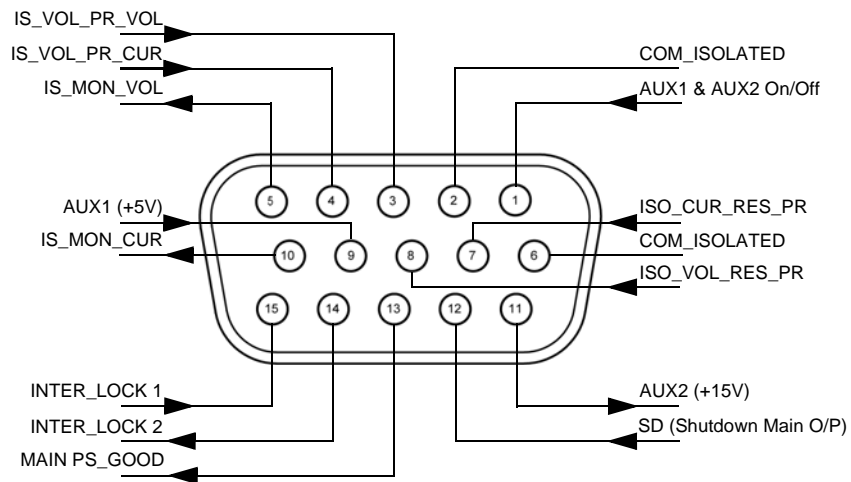


Figure 4-10 AUX Output and ISOL Connector Pinout

Table 4-4 AUX Output and ISOL Connector Pins and Functions J3

PIn	Reference	Function
J3.1	AUX_ON_OFF	Auxiliary enable/disable
J3.2	COM_ISOLATED	Isolated Common (Isolated from Main Output and Communication. Return wire for +5 V, +15 V Auxiliary Voltage.
J3.3	IS_VOL_PR_VOL	Isolated Analog Voltage Programming Input
J3.4	IS_VOL_PR_CUR	Isolated Analog Current Programming Input
J3.5	IS_MON_VOL ¹	Isolated Voltage Monitor. Scaled to the value of the Voltage Analog Programming Level.
J3.6	COM_ISOLATED	Isolated Common (Isolated from Main Output and Communication. Return wire for control signals, monitoring and programming.
J3.7	ISO_CUR_RES_PR	Isolated Current Resistive Programming
J3.8	ISO_VOL_RES_PR	Isolated Voltage Resistive Programming
J3.9	+AUX 1 ²	+5 V Isolated Output
J3.10	IS_MON_CUR ¹	Isolated Current Monitor. Scaled to the value of the Voltage Analog Programming Level.
J3.11	+AUX 2 ²	+15 V Isolated Output
J3.12	SD	Shutdown. Input to power supply to disable output. This input has user selectable negative logic operation via front panel or remote digital input/output.
J3.13	PS_GOOD	PS_GOOD. Power supply output enabled.
J3.14	INTER_LOCK 1	Interlock. Dry contact type. Shorting pins J3.14 and J3.15 while the interlock functionality is enabled, will enable the output of the power supply.
J3.15	INTER_LOCK 2	Interlock

1.Important: Isolated monitor lines are only valid when Isolated analog programming modes are used for the respective voltage and current control. If local control, digital control or non-isolated APG is used, the non-isolated monitor lines should be used as the isolated monitor lines will not accurately reflect the output state of the power supply.

2.Use unshielded cable up to 9.84 feet (3 m) length with high-density D-Sub type connector and a ferrite bead (Fair-Rite part number 0443164251).



CAUTION: Equipment damage

Do not drive or apply a voltage to pins J3.14 (Inter_Lock 1) or to pins J3.15 (Inter_Lock 2).

Making ISOL Control Connections



CAUTION: Equipment damage

Before making connections from external circuits to the Isolated Analog Programming Connector, turn the front panel power switch to off and wait until the front panel displays have gone out.

For most connectors and jumpers, use any suitable wire such as 22 AWG stranded wire. For lowest noise performance, use shielded twisted pair wiring of 22 AWG. Use the shortest leads possible. +5 V and +15 V Auxiliary Output reference to pin 2 and 6 (isolated common) on the ISOL Connector.

ISOL Programming With External Voltage Source

The pin numbers are described in Table 4-4 on page 4-21.

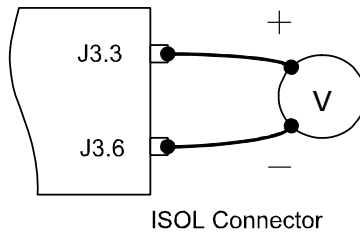


Figure 4-11 Programming Output Voltage using an Isolated External Voltage Source

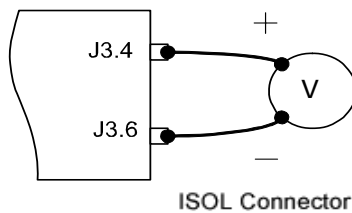


Figure 4-12 Programming Output Current using an Isolated External Voltage Source

Voltage-Controlled Voltage ISOL Setup

Activating ISOL Programming Voltage Mode

To activate ISOL programming voltage mode with an external voltage source:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
VAP is displayed on the output voltage display.
2. Turn rotary Adjust/Enter control to select *U I 5* (voltage source from isolated connector).
3. Press the rotary Adjust/Enter control to commit the selected mode.
LE U is displayed on the output voltage display.
4. Select the input source level using the rotary Adjust/Enter control.
5. Once the desired level has been selected, press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Deactivating ISOL Voltage Mode

To deactivate the ISOL voltage mode:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the mode control is already at the VAP position.
VAP is displayed on the output voltage display.
2. Turn the rotary Adjust/Enter control to select *normE*.
4. Press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Query for ISOL Voltage Input Level

To query for ISOL voltage input level from non-isolated input:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the control knob is already at the VAP position.
VAPr is displayed on the output voltage display.
2. If the mode is currently *nonE* then select any other ISOL mode. If this step is done, be sure to restore the ISOL setting to *nonE* when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current ISOL mode.
3. Press the rotary Adjust/Enter control to select the ISOL mode.
The output voltage display should read *LE U* and the output current display will display ISOL level.
4. Press the rotary Adjust/Enter control to return to normal mode.
5. If the ISOL mode was modified in step 2, execute the procedure to deactivate the ISOL voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMote:SOURce[:VOLTage] <?|LOCAL
|AVOLTage|IAVOLTage|AREsistive|IAResistive>
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel
[:VOLTage][:ISOLated]
[ : ]MEASure[ <channel> ][:SCALAR]:APROgram[:VOLTage]
:ISOLated[:DC]?
```

Voltage-Controlled Current ISOL Setup

Activating ISOL Programming Current Mode

1. Turn the 9-position mode control to the CAP position or press the rotary adjust/Enter control if the control knob is already at the CAP position.
CAP is displayed on the output voltage display.
2. Turn the rotary Adjust/Enter control to select $U \ 5$ (voltage source from isolated connector).
3. Press the rotary adjust/Enter control to commit the selected mode.
LE \square is displayed on the output voltage display.
4. Select the input source level using the rotary adjust/Enter control.
5. Once the desired level has been selected, press the rotary adjust/Enter control to commit the change.
The display will return to the normal display.

Deactivating ISOL Current Mode

To deactivate the ISOL current mode:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the control knob is already at the VAP position.
2. CAP is displayed on the output voltage display.
3. Turn the rotary Adjust/Enter control to select none.
4. Press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Query for ISOL Current Input Level

To query for ISOL current input level from non-isolated input:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the control knob is already at the CAP position.
CAP is displayed on the output voltage display.
2. If the mode is currently nonE then select any other ISOL mode. If this step is done, be sure to restore the ISOL setting to nonE when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current ISOL mode.
3. Press the rotary adjust/Enter control to select the ISOL mode.
The output voltage display should read LE E and the output current display will display ISOL level.
4. Press the rotary adjust/Enter control to return to normal mode.
5. If the ISOL mode was modified in step 2, execute the procedure to deactivate the ISOL voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMote:SOURce:CURRent: <?|LOCAL
|AVOLtage|IAVoltage|AREsistive|IAResistive>
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel:CURRent
[ : ISOLated]
[ : ]MEASure[ <channel> ] [ : SCALar ] :APROgram:CURRent
:ISOLated[ :DC]?
```

Analog Programming With External Resistor

The pin numbers are described in Table 4-4 on page 4-21.

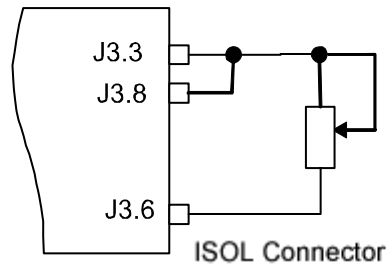


Figure 4-13 Programming Output Voltage using an Isolated External Resistor

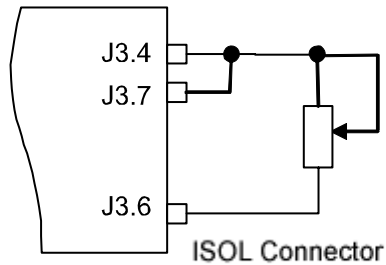


Figure 4-14 Programming Output Current using an Isolated External Resistor

Resistive-Controlled Voltage ISOL Setup

Activating ISOL Programming Voltage Mode

To activate ISOL programming voltage mode using an external resistor:

1. Turn the 9-position mode control to the VAP position or press the rotary adjust/Enter control if the control knob is already at the VAP position.
 $VAPr$ is displayed on the output voltage display.
2. Turn the rotary Adjust/Enter control to select $r \ 5$ (resistor source from isolated connector).
3. Press the rotary adjust/Enter control to commit the selected mode.
 $LE \ V$ is displayed on the output voltage display.
4. Select the input source level using the rotary adjust/Enter control.
5. Once the desired level has been selected, press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

4

Deactivating ISOL Voltage Mode

To deactivate the ISOL voltage mode:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the control knob is already at the VAP position.
2. $VAPr$ is displayed on the output voltage display.
3. Turn the rotary Adjust/Enter control to select $nonE$.
4. Press the rotary adjust/Enter control to commit the change.
The display will return to the normal display.

Query for ISOL Voltage Input Level

To query for ISOL voltage input level from non-isolated input:

1. Turn the 9-position mode control to the VAP position or press the rotary Adjust/Enter control if the control knob is already at the VAP position.

VAP is displayed on the output voltage display.

2. If the mode is currently *nonE* then select any other ISOL mode. If this step is done, be sure to restore the ISOL setting to *nonE* when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current ISOL mode.
3. Press the rotary adjust/Enter control to select the ISOL mode.
The output voltage display should read *LE U* and the output current display will display ISOL level.
4. Press the rotary adjust/Enter control to return to normal mode.
5. If the ISOL mode was modified in step 2, execute the procedure to deactivate the ISOL voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMOte:SOURce[ :VOLtage ] <? | LOCAL  
| AVOLtage | IAVoltage | AREsistive | IAREsistive>  
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel  
[ :VOLtage ][ :ISOLated ]  
[ : ]MEASure[ <channel> ][ :SCALAR ]:APROgram[ :VOLtage ]  
:ISOLated[ :DC ]?
```

Resistive-Controlled Current ISOL Setup

Activating ISOL Resistive-Controlled Current Setup

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the control knob is already at the CAP position.
CAP is displayed on the output voltage display.
2. Turn rotary Adjust/Enter control to select r 1 5 (voltage source from isolated connector).
3. Press the rotary Adjust/Enter control to commit the selected mode.
LE CAP is displayed on the output voltage display.
4. Select the input source level using the rotary Adjust/Enter control.
5. Once the desired level has been selected, press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Deactivating ISOL Current Mode

To deactivate the ISOL current mode:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the control knob is already at the CAP position.
2. CAP is displayed on the output voltage display.
3. Turn the rotary Adjust/Enter control to select none.
4. Press the rotary Adjust/Enter control to commit the change.
The display will return to the normal display.

Query for ISOL Current Input Level

To query for ISOL current input level from non-isolated input:

1. Turn the 9-position mode control to the CAP position or press the rotary Adjust/Enter control if the control knob is already at the CAP position.
CAP is displayed on the output voltage display.
2. If the mode is currently nonE then select any other ISOL mode. If this step is done, be sure to restore the ISOL setting to nonE when the operation is complete. Otherwise, do not rotate the rotary Adjust/Enter control to keep the current ISOL mode.
3. Press the rotary Adjust/Enter control to select the ISOL mode.
The output voltage display should read LE E and the output current display will display ISOL level.
4. Press the rotary Adjust/Enter control to return to normal mode.
5. If the ISOL mode was modified in step 2, execute the procedure to deactivate the ISOL voltage mode.

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMOte:SOURce:CURRent <?|LOCAL  
|AVOLtage|IAVoltage|AREsistive|IAResistive>  
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel:CURRent  
[ : ISOLated ]  
[ : ]MEASure[ <channel> ] [ : SCALar ]:APROgram:CURRent  
:ISOLated [ :DC ]?
```

Voltage and Current Readback (Isolated)

The pin numbers are described in Table 4-4 on page 4-21.

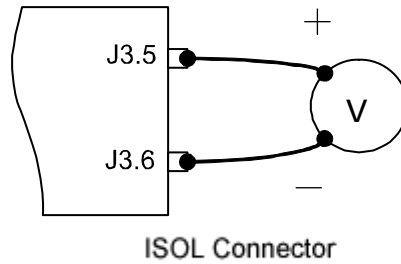


Figure 4-15 Isolated Voltage Monitoring

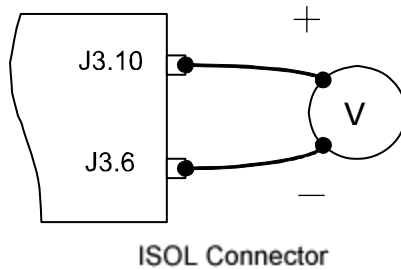


Figure 4-16 Isolated Current Monitoring

Query Remote Control Source State

Quick Tip
Remote operation uses these SCPI commands. See page 5-1.

The SCPI command for these instructions are:

```
[ : ]SYSTem[ <channel> ]:REMOte:SOURce[ :VOLTage ]?
```

```
[ : ]SYSTem[ <channel> ]:REMOte:SOURce:CURREnt?
```


5

Remote Operation

Chapter 5, Remote Operation, describes the remote operation of the XTR power supply via the communication ports.

Introduction

In addition to the front panel interface, the XTR can be remotely controlled through the various remote interfaces. The XTR implements the SCPI standard as its command line interface for remotely controlling the power supply. Additionally, a small subset of legacy commands has been provided for ease of use and backwards compatibility. All of the remote interfaces use the same command line interface.

This chapter is divided into two parts:

- **Hardware and Connection Setup** provides information on how to setup a connection to the different remote interfaces available on the XTR. The remote interfaces covered include RS-232, RS-485, USB, GPIB and ENET.
- **Command Line Interface and SCPI** explains how to send commands to the power supply using the SCPI commands and the theory behind SCPI.

Hardware and Connection Setup

This section provides information on setting up the hardware and is organized into setup for each hardware type. Once the setup has been successfully completed, data can be sent to and responses received from the power supply. Select which hardware interface to use and follow the instructions and diagram for that hardware set up.

Configuring Remote Control Using RS-232

To configure remote control using RS-232:

1. Use the top J4 connector of the two 8-pin RJ-45 jacks, as shown in Figure 5-1, to connect to the RS-232 remote interface.
2. Connect from PC to power supply using a cable that meets the cabling specifications listed in Table 5-1.

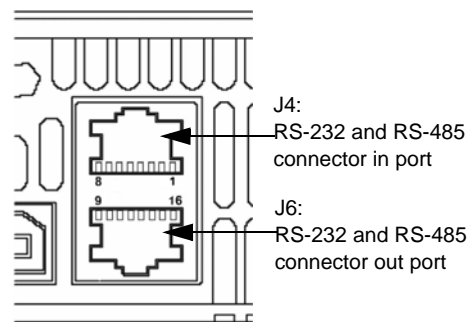


Figure 5-1 Remote Control Connectors

Table 5-1 Remote Control Connector Pins and Functions J4 and J6¹

Pin	Reference	Direction	Function
J4.1	RX-232	Input	RS-232
J4.2	TX-232	Output	RS-232
J4.3	RXD+	Input	RS-485 receiving
J4.4	RXD-	Input	RS-485 receiving
J4.5	TXD+	Output	RS-485 transmitting
J4.6	TXD-	Output	RS-485 transmitting
J4.7	GND	–	Ground
J4.8	NC	–	–
J6.9	NC	–	–

Table 5-1 Remote Control Connector Pins and Functions J4 and J6¹

Pin	Reference	Direction	Function
J6.10	NC	–	–
J6.11	RXD+	Input	RS-485 receiving
J6.12	RXD–	Input	RS-485 receiving
J6.13	TXD+	Output	RS-485 transmitting
J6.14	TXD–	Output	RS-485 transmitting
J6.15	GND	–	Ground
J6.16	NC	–	–

1.All references and directions indicated in this table are with respect to the XTR.

RS-232 Communication Cable with RJ-45 to DB-9

Communication control cable with DB-9 connector (male) on the PC side and RJ-45 shielded connector on the power supply. The cable length should be 9.84 feet (3 m) or longer.

Table 5-2 DB-9 Pinouts

Pin	Name	Description
1	NC	No connection
2	RX	Receive data
3	TX	Transmit data
4	NC	No connection
5	GND	Ground
6, 7, 8, 9	NC	No connection

Table 5-3 RJ-45 Pinouts

Pin	Name	Description
1	RX	Receive data
2	TX	Transmit data
3, 4, 5, 6	NC	No connection
7	GND	Ground
8	NC	No connection

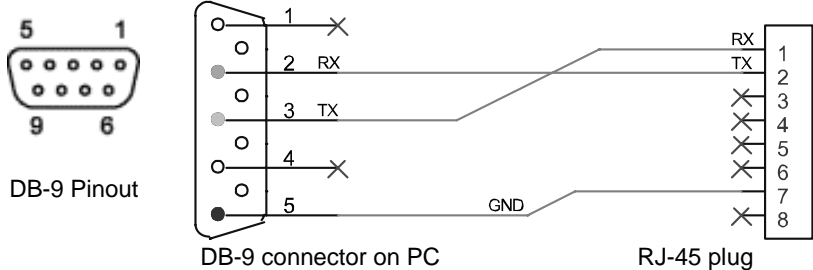


Figure 5-2 RS-232 Communication Cable with DB-9 Pinout

RS-232 Communication Cable with RJ-45 to DB-25

Communication control cable with DB-25 pinout (male) on the PC side and RJ-45 shielded connector on the power supply. The cable length should be 9.84 feet (3 m) or longer.

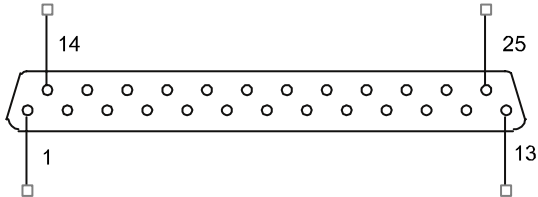


Figure 5-3 DB-25 Pinout

Table 5-4 DB-25 Pinouts

Pin	Name	Description
1	NC	No connection
2	TX	Transmit data
3	RX	Receive data
4, 5, 6	NC	No connection
7	GND	Ground
8, 9	NC	No connection

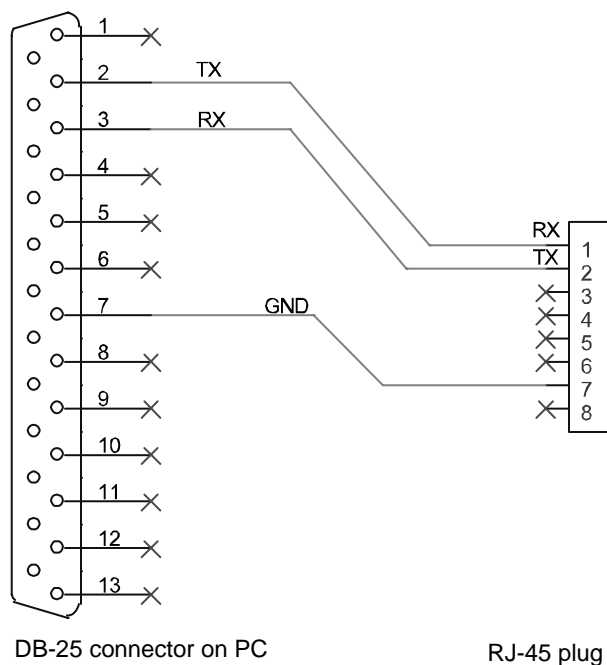


Figure 5-4 RS-232 Communication Cable with DB-25 Pinout

Completing the Setup

To complete the setup:

- ◆ Configure the XTR to use the *232* remote interface and set up the terminal that will be used on the connected PC.

See the sections entitled “Selecting the Appropriate Communication Port” on page 5–20 and “Terminal Configuration” on page 5–17 for more details.

Configuring Remote Control Using RS-485

RS-485 Communication Cable with RJ-45 to DB-9

Communication control cable with DB-9 pinout (female) on the PC side (see Figure 5-2) and RJ-45 shielded connector on the power supply. The cable length should be 9.84 feet (3 m) or longer.

Table 5-5 DB-9 Pinouts

Pin	Name	Description
1	GND	Ground
2, 3	NC	No connection
4	RXD+	Receive data
5	RXD-	Receive data
6, 7	NC	No connection
8	TXD+	Transmit data
9	TXD-	Transmit data

Table 5-6 RJ-45 Plug Pinouts

Pin	Name	Description
1, 2	NC	No connection
3	TXD+	Transmit data
4	TXD-	Transmit data
5	RXD+	Receive data
6	RXD-	Receive data
7	GND	Ground
8	NC	No connection

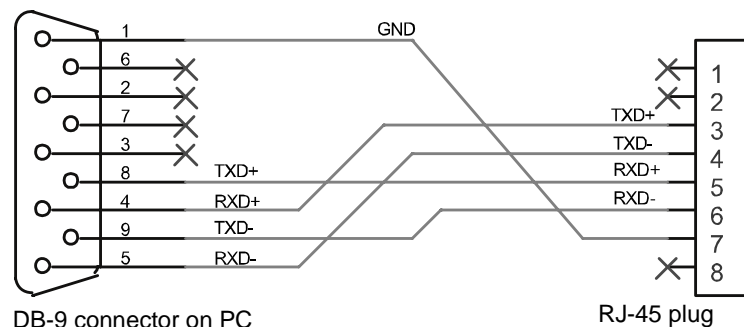


Figure 5-5 RS-485 Communication Cable with DB-9

RS-485 Communication Cable with Two RJ-45s

Use the top connector of the two 8-pin RJ-45 jacks, as shown in Figure 5-1, to connect to the RS-485 remote interface. Communication cable with two RJ-45 shielded connectors (see Figure 5-3) connecting the master unit to the slave unit. The cable length should be 9.84 feet (3 m) or longer. The pinouts for the RJ-45 plug on the master unit are the same as described in Table 5-7.

Table 5-7 RJ-45 Plug on Slave Unit

Pin	Name	Description
1, 2	NC	No connection
3	RXD+	Receive data
4	RXD-	Receive data
5	TXD+	Transmit data
6	TXD-	Transmit data
7	GND	Ground
8	NC	No connection

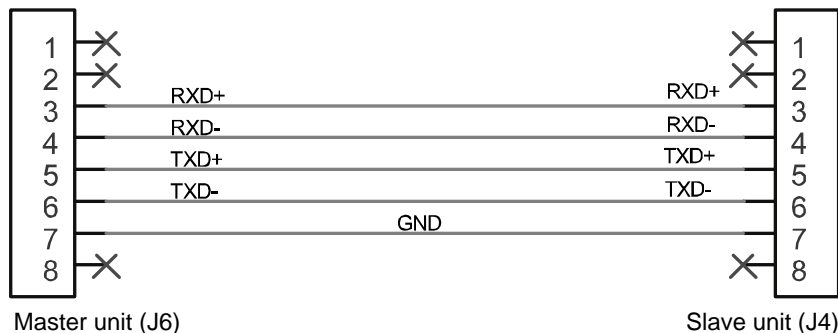


Figure 5-6 RS-485 Communication Cable from Master to Slave Unit

Completing the Setup

To complete the setup:

- ◆ Configure the XTR to use the 485 remote interface and setup the terminal that will be used on the connected PC.
See sections entitled “Selecting the Appropriate Communication Port” on page 5–20 and “Terminal Configuration” on page 5–17 for more details.

Configuring Remote Control using the USB Connector

The power supply can be controlled from a remote terminal using a USB interface. The standard USB connector is located on the rear panel of the XTR 850 Watt, as shown in Figure 1-3. Use a standard USB shielded cable up to 9.84 feet (3 m) in length.

Setting Up the PC to Use the USB Connection

Installing USB to Serial Converter and Serial Port

To set up the USB connection, you'll need to download the latest driver from Future Technology Devices International Ltd. or from www.programmablepower.com.

To download and install a virtual COM port (VCP) driver:

1. Go to www.programmablepower.com and navigate to the XTR product web page.
2. Click the download link to download the driver.
3. Download the appropriate virtual COM port (VCP) drivers for your operating system (with enhanced BM series support).
4. Create a folder C:\FTDI.
5. Unzip files from the archive into this folder.
6. Connect your device to a spare USB port on your computer.

The Found New Hardware Wizard automatically launches, as shown in Figure 5-7.



Figure 5-7 Found New Hardware Wizard

7. Click Next.
8. On the Install Hardware Device Driver screen, select “Search for a suitable driver for my device (recommended)” and click Next. See Figure 5-8.

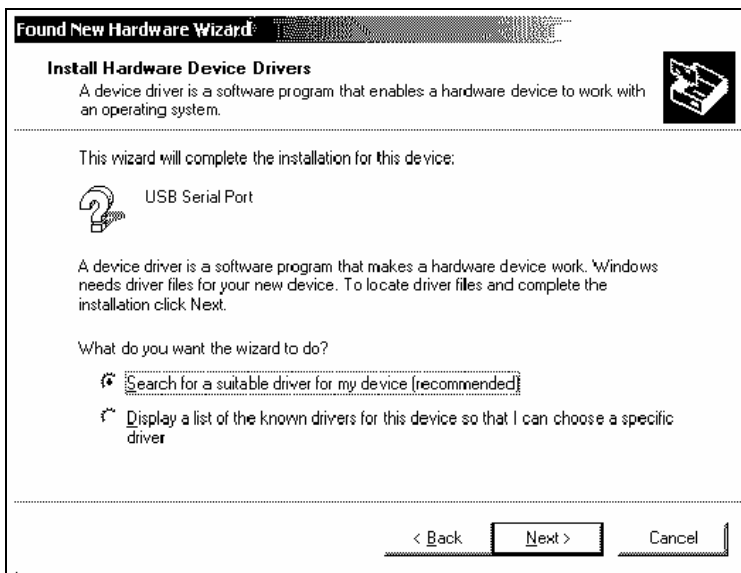


Figure 5-8 Install Hardware Device Drivers

9. In the Locate Driver Files dialog box, in the field Optional Search Locations, select Specify A Location and click Next.
10. On the next screen, enter the file path “C:\FTDI” and click OK.
11. On the next screen, select “Driver Files Search Results” and click Next.
12. In Completing the Found New Hardware Wizard, see Figure 5-9, click Finish to complete the installation.



Figure 5-9 Completing the New Hardware Wizard

This completes the first part of the installation during which the USB to serial converter is installed. The second part involves the installation of a serial port, which should follow automatically once the converter installation is complete. Installation of the serial port does not require any user intervention.

Verifying Installation

Once the installation of the serial port has completed, verify that the installation has been successful by looking under Device Manager of the System Properties screen. The device should have installed as a USB Serial Port (COMx) attached to USB High Speed Serial Converter.

To verify that the device has been installed:

1. In Control Panel, go to System, click the Hardware tab and click on Device Manager.
2. On the View menu, select Devices by Type.
3. To change the virtual COM port properties, select the USB Serial Port and then Click Properties.

This allows you to change serial port properties such as data rate (bps) and data bits. You are also able to change the COM port which is assigned to your device.

4. Click the Port Settings tab, then click Advanced.

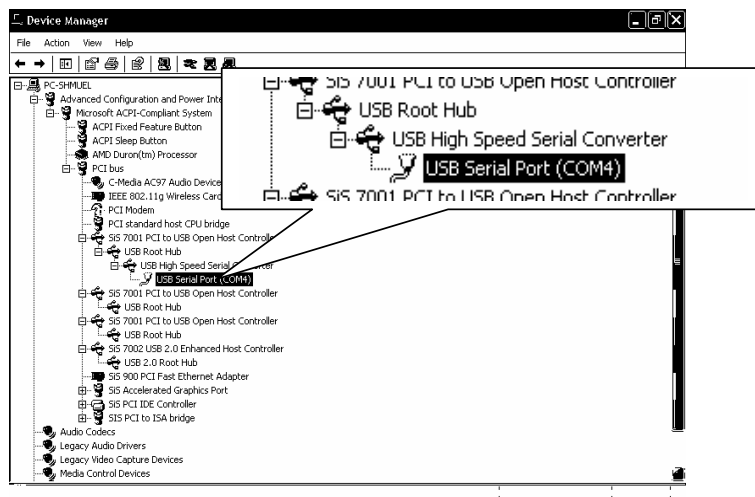


Figure 5-10 Device Manager

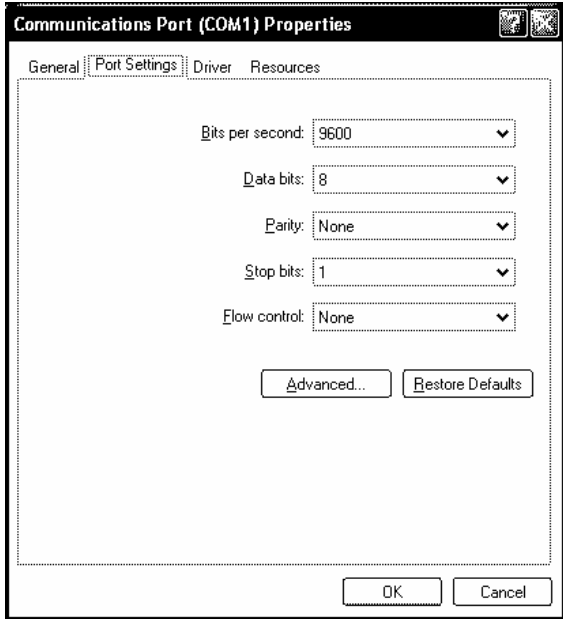


Figure 5-11 Communications Port (COM1) Properties

5. In the COM port list, scroll to the required COM port.

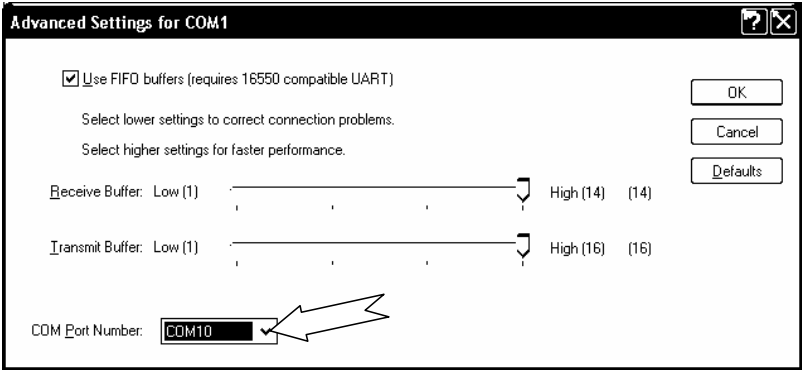


Figure 5-12 Completing the new hardware wizard

6. Click OK.

Ensure that you do not select a COM port which is already in use. This selection is particularly useful for programs, such as HyperTerminal, which only work with COM1 through to COM4.

Complete the Setup

To complete the setup:

- ◆ Configure the XTR to use the USB remote interface and set up the terminal that will be used on the connected PC.

See “Selecting the Appropriate Communication Port” on page 5–20 and “Terminal Configuration” on page 5–17 for more details.

Ethernet (ENET) or GPIB Connector (Optional)

The power supply can be programmed from a remote terminal using a General Purpose Interface Bus (GPIB interface) or Ethernet (ENET). If you have a GPIB or ENET card, see the *XTR 850 Watt GPIB and Ethernet Interface Option Operating Manual (Part number M370046-06)*.

The GPIB interface is an 8-bit parallel data bus having a host of bus commands for synchronization and up to one megabyte data transfer rate. Use standard IEEE-486, 26 AWG GPIB cable up to 3 metres length.

For connecting the power supply to ENET, use a LAN RJ-45 and RJ-45 STP, Cat 5 cross-cable 9.84 feet (3 m) in length or longer. Use a standard RJ-45 and RJ-45 cross-cable.

Multiple Power Supply Connections to RS-485 Bus

Up to 30 units may be connected to the RS-485 bus. The first unit (master unit) connects to the controller via any appropriate port, and the other units (slave units) are connected with the RS-485 bus via the J6 connector. All units connected together should also have unique multichannel addresses.

A standard straight-through RJ-45 ethernet network cable can be used to provide the connection between the power supplies. See Figure 5-13.

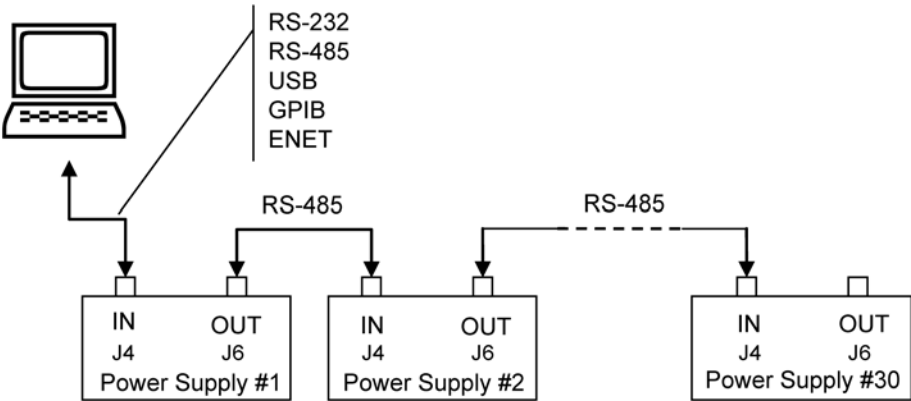


Figure 5-13 Multi Power Supply Connection to RS-485 Bus

Multiple Power Supply Setup

Master Setup:

- ◆ Configure the master XTR by selecting the communication interface you wish to use to communication with the Master and follow the setup instruction in this chapter.

Important: If either RS-232 or RS-485 are used for communication with the master, the data rate must be configured for 9600 bps to properly communicate with the slave units.

Slave Setup:

1. Turn the 9-position mode control to PGM.
rE is displayed in the output voltage display.
2. Turn the rotary Adjust/Enter control to select *5L#* and press the Enter button.
3. Set a unique address. See “Multichannel Address Setting” on page 5–21.

Terminal Configuration

The terminal program allows serial communication with the power supply. To use a terminal program, set it up using the parameters from the following sections. If you wish to use HyperTerminal, see “HyperTerminal” on page 5–17 for instructions setting it up.

Data Format

Serial data format is 8 bit, one stop bit. No parity bit. Flow control: none.

End of Message

The end of message is the Carriage Return character (ASCII 13, 0x0D). The power supply ignores the Line Feed (ASCII 10, 0x0A) character.

HyperTerminal

The HyperTerminal program is a standard windows program and can be found in **Start >All Programs >Accessories >Communications >HyperTerminal**.

Setting up a HyperTerminal connection

To set up a HyperTerminal connection:

1. When HyperTerminal opens, it will immediately enter the New Connection wizard.
 - If you don't already have a connection saved, continue.
 - If you do, click cancel and then open the pre-existing connection and skip the remaining steps in this procedure.
2. Enter a name.

Include the name of the interface you are intending to use for the connection as part of the name.
3. Click OK.
4. Select the COM port that is connected to the interface you wish to use to connect to the XTR.

This is the COM port that you have your serial cable hooked up to or in the case of USB the one that was configured to be used in the FDTI software.

5. Click OK when done.
6. Setup the data format to be used. See “Data Format” on page 5–17 for details.
7. Set up the Hyper terminal you will need to configure the properties.
8. Click **File>Properties** to bring up the connection properties dialog and click on the Settings tab.

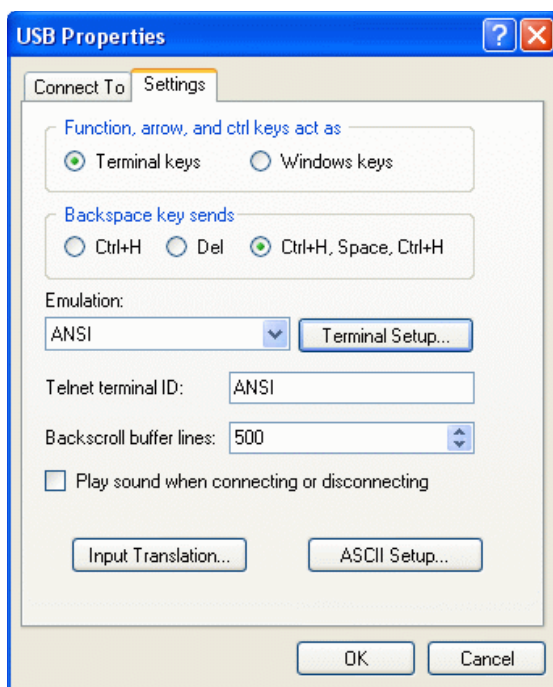


Figure 5-14 USB Settings

9. Fill out the following selections in the connection properties dialog:
 - Terminal keys
 - Ctrl+H, Space, Ctrl+H.
 - On the Emulation list, select ANSI.
10. Click on the ASCII Setup button to bring up the ASCII Setup dialog.

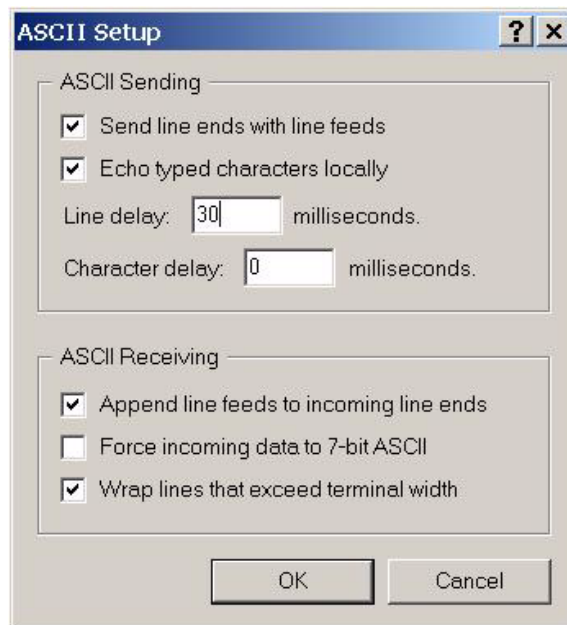


Figure 5-15 ASCII Setup

11. Check the following boxes:
 - Send line ends with line feeds.
 - Echo typed characters locally.
 - Append line feeds to incoming line ends.
 - Wrap lines that exceed terminal width.
12. Change the Line delay to 30 milliseconds.
13. Click OK in the ASCII Setup window.
14. Click OK in the Properties window.

HyperTerminal has now been configured to communicate with the XTR.

Selecting the Appropriate Communication Port

Five ports are available for remote digital programming and readback:

- RS-232
- RS-485
- USB
- GPIB (optional)
- ENET (optional)

To select a communication port:

1. Turn the 9-position mode control to PGM.
rE is displayed in the output voltage display.
2. Turn the rotary Adjust/Enter control to select one of the communication ports: *232*, *485*, *GPI b*, *USB*, *LAN*.
LOCK LOC is also an available option which lets you lock the front panel to prevent the settings from being changed.

Important: The remote interface that was previously configured when the local lock setting was activated will still be available for remote control while the front panel is locked.

Data Rate Setting (Kbps)

The data rate setting is available for RS-232 and RS-485 protocols only. Five optional rates are possible: 1.2, 2.4, 4.8, 9.6 (default), 19.2, 38.4, and 57.6 kilo bits per second (Kbps).

To select the desired rate:

1. Turn the 9-position mode control to PGM.
rE is displayed in the output voltage display.
2. Turn the rotary Adjust/Enter control to select *232* (RS-232) or *485* (RS-485) communication ports.
3. Press the rotary Adjust/Enter control.
HbPS is displayed on the output voltage display and the currently set data rate is displayed on the output current display.
4. Turn the rotary Adjust/Enter control to select the desired data rate.
5. Press enter to commit the new data rate.
The multichannel address setting will now be configured.

Multichannel Address Setting

The power supply multichannel address can be set to any address between 1 to 30. All units that are connected together via the RS-232 or RS-485 connector must have a unique multichannel address.

To set the address:

1. Select the appropriate communication port as described “Selecting the Appropriate Communication Port” on page 5–20.

If more than one unit has the same multichannel address when connected through the RS-485 connector, then collisions are possible, resulting in garbled responses to queries.

2. Press the rotary Adjust/Enter control.
Addr is displayed on the output voltage display.
3. Turn the rotary Adjust/Enter control to select the desired multichannel address between 1 to 30.
4. Press the rotary Adjust/Enter control to commit the new address.

Remote Interface Addressing

All commands must be issued with a multichannel address or the device must be selected using the:

`*adr` or `:SYST[<channel>]:COMM[:MCH]:ADDR` commands.

Once a device is selected all commands sent without a multichannel address will be handled by the selected device. The use of multichannel addresses supersedes the selected device as the destination for a message. For more details on how multichannel addresses affect responses, see Table 5-8.

To change the selected device simply issue the `*adr` or `:SYST[<channel>]:COMM[:MCH]:ADDR` command with a different multichannel address. The previously selected device will be deselected and the new device will be selected. From that point on, all messages without a multichannel address will be destined for the newly selected device. It is possible to deselect all devices by using the aforementioned commands with the broadcast address, 0.

The SCPI Commands for these instructions are:

`[:]SYSTem:COMMunicate[:MCHannel]:ADDRess <address>`

or

`*ADR <address>`

Where:

<address> is the multichannel address of the device to be selected. The address is an integer value from 1 to 30.

Multichannel Commands Explained

The use of multichannel addressing allows you to send messages to one device, more than one device or to all devices. Any of the remote interface types can be used to send a multichannel command through the device that is physically connected to the PC to all the devices, provided that all other devices are connected to via the RS-485 bus. In order to use multichannel addressing, the setup of the wiring should be completed as described in “Multiple Power Supply Connections to RS-485 Bus” on page 5–15.

All SCPI commands in the XTR support the use of multichannel addressing; however, only one device can respond to a message. Responses will be sent according to the conditions set out in Table 5-8.

Table 5-8 Rules for Multichannel Responses

Condition	Response	Example
No multichannel address used	Only the device selected using the *adr or :SYST[<address>] :COMM[:MCH] :ADDR commands will respond.	SYSTem:VERSion?
Single multichannel address specified	The device addressed in the command will respond regardless of if it has been selected.	SYSTem2:VERSion?
ALL or broadcast multichannel address specified	Only the device selected using the *adr or :SYST[<channel>] :COMM[:MCH] :ADDR commands will respond. If none of the devices have been selected then no response will be seen.	:SYSTem ALL:VERSion? or :SYSTem0:VERSion?
Multiple multichannel addresses specified	Only the device selected using the *adr or :SYST[<address>] :COMM[:MCH] :ADDR commands will respond. If none of the device have been selected then no response will be seen.	SYSTem 1,2,4,5,6:VERSion?

Multichannel commands are particularly useful for configuring groups of devices that require identical configurations.

The SCPI Commands for these instructions are:

```
[:]<root command> <ALL|addr1>[, [ ]<addr2>][, [ ]<addr3>][, ...]:<command> <parameter>
```

For example:

```
sour 1, 2, 3, 7:volt 4.5  
syst4,5,6:oper:enab 255  
syst ALL:clear  
output0:stat on
```

Status Reporting in SCPI

The status reporting implemented in the XTR is primarily dictated by the SCPI standard. This section provides a high level review of the standard status reporting required by SCPI and then covers the XTR specific reporting that is implemented within the SCPI status reporting framework.

Figure 5-16 is taken from the SCPI 99 standard and shows the minimum status reporting requirements for a SCPI compliant device.

Throughout this chapter, figures are used to explain the relationship between the registers, enable/disabling register and their summary bits. The figures use four logical symbols to demonstrate the relationship between the register. The “!” block represents logical not or complement of the input signal. The “&” block represents the logical AND operator. The “|” block represents the logical OR operation. The “+” block represents the logical OR of all the bits from the enable register. The model has several ellipses which are there to indicate that the pattern of logic shown is repeated for all bits in the registers.

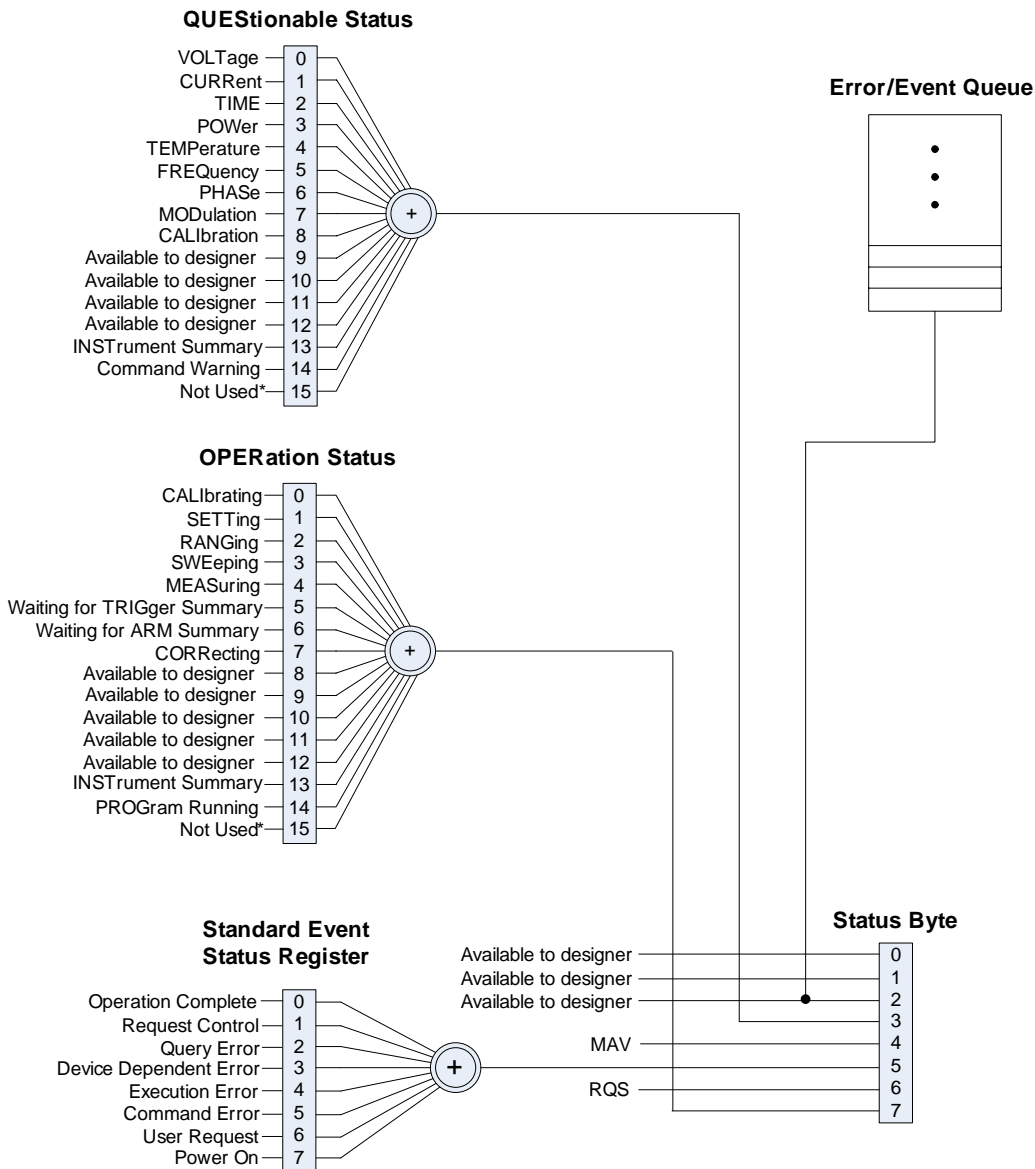


Figure 5-16 SCPI Status Reporting Model

Status Registers Model from IEEE 488.2

The IEEE 488.2 registers shown in the bottom rectangle of Figure 5-16 follow the IEEE 488.2 model for status registers. The IEEE 488.2 register only has enable registers for masking the summary bits. Figure 5-17 shows the details on the relationship between the mask/enable registers and the summary bits. Sections describing the bits for both registers will follow Figure 5-17.

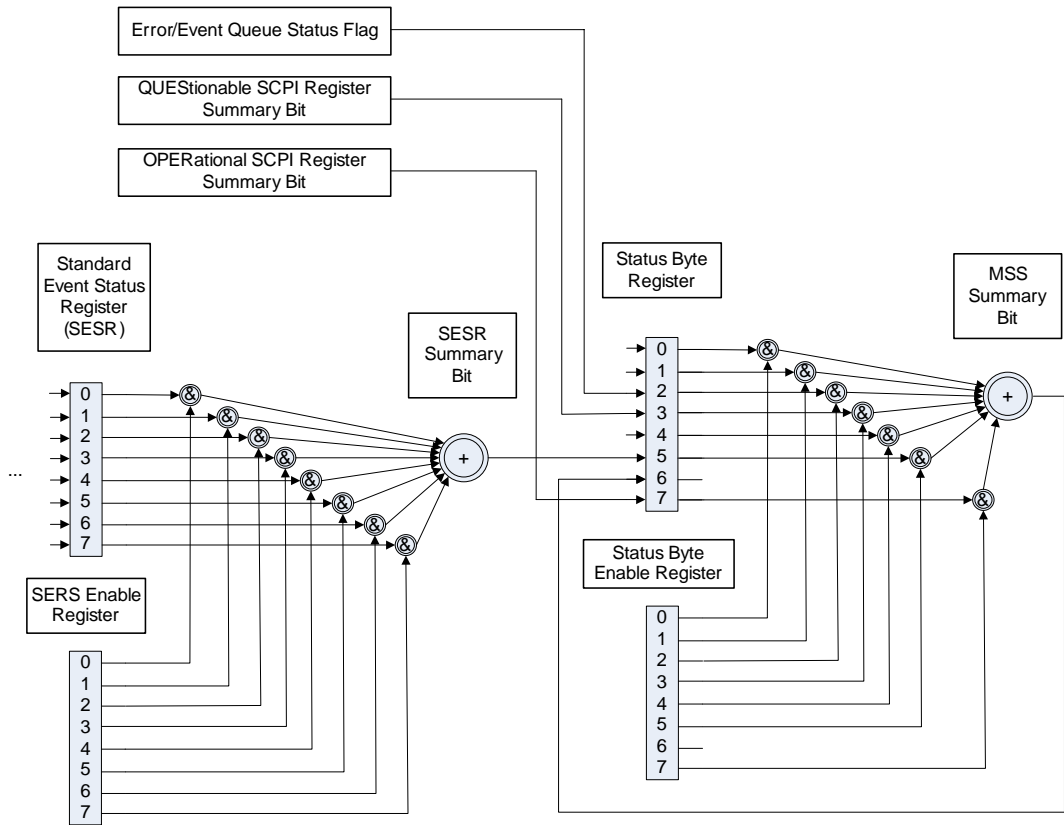


Figure 5-17 IEEE 488.2 Register Model

Status Byte

The Status byte register contains the STB and RQS (MSS) messages as defined in 488.1. You can read the status byte register using a 488.1 serial poll or the 488.2 *STB? common command.

The *STB? query causes the device to send the contents of the Status Byte Register and the Master Summary Status (MSS) summary message. The *STB? query does not alter the status byte, MSS, or RQS.

Table 5-9 Status Byte Summary Register

Bit	Bit Weight	Bit Name	Description
0	1	Reserved	Reserved
1	2	Reserved	Reserved
2	4	Error/Event Queue (ERR)	Set if any errors are present in the Error/Event queue.
3	8	Questionable Status Register (QSR)	Set if any bits are set in the Questionable Status Event register.
4	16	Message Available (MAV)	Indicates whether the output queue is empty. MAV is TRUE if the device is ready to accept a request from the controller.
5	32	Standard Event Status Bit Summary (ESB)	A summary of the Standard Event Status Register.
6	64	Request Service (RQS) / Master Status Summary (MSS)	Not Implemented / MSS indicates that the device has at least one reason for requesting service.
7	128	Operation Status Register (OSR)	Present if a bit is set in the Operation status register.

Error/Event Queue (ERR)

This bit is TRUE if any errors are present in the Error/Event Queue.

Questionable Status Register Summary (QSR)

This bit is TRUE when a bit in the Questionable Event Status Register is set and its corresponding bit in the Questionable Status Enable Register is TRUE.

Message Available (MAV)

This bit is TRUE whenever the power supply is ready to accept a request by the Digital Programming Interface to output data bytes. This message is FALSE when the output queue is empty.

Standard Event Status Summary (ESB)

This bit is TRUE when a bit is set in the Standard Event Status Register.

Master Summary Status (MSS)

This is caused by one of the following:

- Status Byte bit 0 AND Service Request Enable Register bit 0
- Status Byte bit 1 AND Service Request Enable Register bit 1
- Status Byte bit 2 AND Service Request Enable Register bit 2
- Status Byte bit 3 AND Service Request Enable Register bit 3
- Status Byte bit 4 AND Service Request Enable Register bit 4
- Status Byte bit 5 AND Service Request Enable Register bit 5
- Status Byte bit 7 AND Service Request Enable Register bit 7.

Request Service (RQS)

RQS is TRUE if the Service Request Enable Register has a bit set and there is a corresponding bit within the Status Byte.

Operation Status Register Summary (OSR)

This bit is TRUE when a bit in the Operation Event Status Register is set and its corresponding bit in the Operation Status Enable Register is set.

Service Request Enable Register

The Service Request Enable Register allows you to select the reasons for the power supply to issue a service request. The Service Request Enable Register allows you to select which summary messages in the Status Byte Register may cause service requests.

To clear the Service Request Enable Register send `*SRE 0`. A cleared register does not allow status information to generate a service request.

For example:

Sending `*SRE 8` sets bit 3 of the Service Request Enable Register. This will cause the Summary bit of the Questionable Status register (bit 3) in the Status Byte to generate a service request message whenever it gets set. (See “Status Byte” on page 5–28 for details.)

Command:

```
*SRE <Service-Request-Enable>, *SRE?
```

The SCPI equivalent for multichannel use:

```
[ : ]STATus[ <channel> ]:SREQuest[ :ENABLE ] <status-enable>
[ : ]STATus[ <channel> ]:SREQuest[ :ENABLE? ]
```

Query the Status Byte

The status byte query will return the contents of the status byte register and the MSS (Master Summary Status) message. The response is in the format of a weighted decimal value representing the status byte register and the MSS message (bit 6). Thus, the response to `*STB?` is identical to the response to a serial poll except that the MSS message appears in bit 5 in place of the RQS message. (See “Status Byte” on page 5–28 for details.)

Command:

```
*STB?
```

SCPI equivalent:

```
[ : ]STATus[ <address> ]:SBYTE[ :EVENT ]?
```

Standard Event Status Register (SESR)

The standard event status register sets bits for specific events during power supply operation. All bits in the standard event status registers are set through the error event queue. The register is defined by IEEE 488.2 register and is controlled using 488.2 common commands: *ESE, *ESE?, and *ESR? as well as SCPI aliases for multichannel use.

Standard Event Status Enable Register

The Event Summary Enable command determines which bits in the Standard Event Status Register are summarized in the Event Summary Bit (ESB) of the Status Byte. This register will be cleared at power up. To enable events, you must make the logical sum of all values for the events that you to be reported and send this parameter in decimal format.

See Table 5-9 for values for the events to be enabled in <status-enable> parameter.

For example, sending *ESE 16 sets bit 4 of the Standard Event Status Enable Register. This will cause the Event Summary bit (ESB) in the Status Byte to be set whenever the Execution Error bit (bit 4) in the Standard Event Status Register gets set.

Command:

```
*ESE <status-enable>, *ESE?
```

The SCPI equivalent for multichannel use:

```
[ : ]STATUS[ <channel(s)> ]:STANDARD:ENABLE <status-enable>
[ : ]STATUS[ <channel(s)> ]:STANDARD:ENABLE?
```

Standard Event Status Register

The Standard Event Status Register query allows you to determine the current contents of the Standard Event Status Register. (See “Standard Event Status Register (SESR)”. Reading this register clears it.

Command:

```
*ESR?
```

The SCPI equivalent for multichannel use:

```
[ : ]STATUS[ <channel(s)> ]:STANDARD[ :EVENT ]?
```

Figure 5-18 summarizes the Standard Event Status Register.

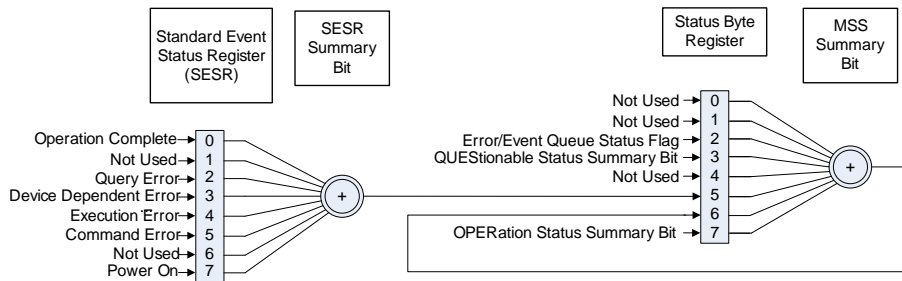


Figure 5-18 Summary of Standard Event Status Register

Table 5-10 Standard Event Status Register

Bit	Bit Weight	Bit Name	Description
0	1	Operation Complete (OPC)	Set if *OPC command has been received and all pending operations have been completed.
1	2	Request Control (RQC)	Not implemented. Always set to 0.
2	4	Query Error (QYE)	Not implemented.
3	8	Device Dependent Error (DDE)	Set if there is a device-specific error. See “Device-Specific Error List” on page B–5 for a list possible error codes and descriptions.
4	16	Execution Error (EXE)	Set if a program data element, following a header, was evaluated by the power supply as outside of its legal input range, or is otherwise inconsistent with the power supply’s capabilities. Suggests that a valid program message could not be properly executed due to some power supply condition. See “Execution Error List” on page B–4 for a list of possible error codes and descriptions.

Table 5-10 Standard Event Status Register

Bit	Bit Weight	Bit Name	Description
5	32	Command Error (CME)	Set if an IEEE488.2 syntax error has been detected by the parser, an unrecognized header was received, or a group Execute Trigger was entered into the input buffer inside an IEEE 488.2 program message. See “Command Error List” on page B-3 for a list of possible error codes and descriptions.
6	64	User Request (URQ)	Not Implemented
7	128	Power ON (PON)	Not Implemented
8–15	N/A	Reserved	Reserved for possible future use by IEEE. Bit values are reported as zero.

Operation Complete

The Operation Complete command causes the power supply to generate the operation complete message in the Standard Event Status Register when all pending operations have been finished. See bit 0 in Table 5-10 for more details.

Command:

*OPC, *OPC?

Wait-to-Continue Command

The Wait-to-Continue command prevents the power supply from executing any further commands or queries until the no-operation-pending flag is TRUE.

Command:

*WAI

Standard SCPI Register Structure

All registers except the SERS and Status registers will have the following structure which control how they report status information. In all subsequent figures that have SCPI registers, this structure will be condensed down into a single block to simplify the figures. The simplified block will show a 16-bit register and the summary bit. See Figure 5-19 for details on the structure used for each standard SCPI register.

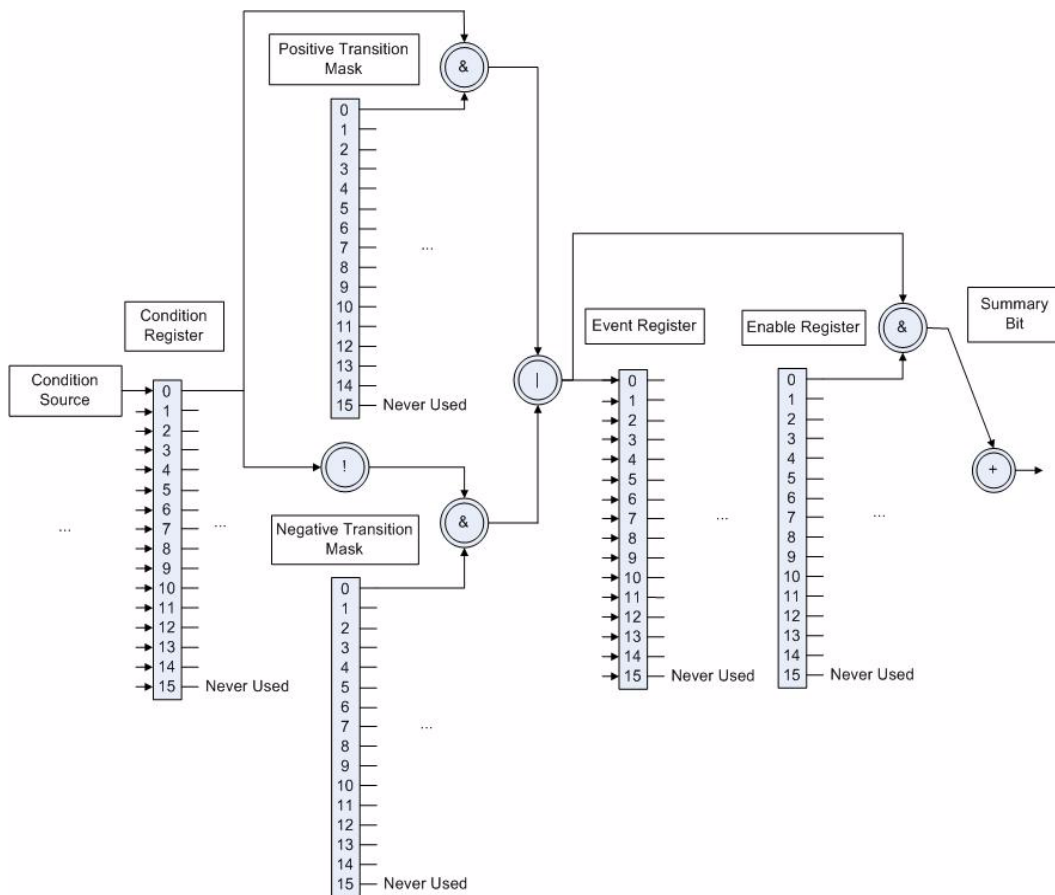


Figure 5-19 SCPI Register Model

OPERation Status Register

The operation status register is a standard SCPI, 16-bit register which contains information about conditions which are part of the power supply's normal operation. The Operation Status data structure has the operation status register and two sub-registers to represent shutdown and protection shutdown. Each of the sub-registers is summarized in a summary bit.

Figure 5-20 represents the Operation Status data structure. The “+” represents the logical summation/or of bits in a register. Table 5-11, Table 5-12, and Table 5-13 describe the meanings of each bit as well as the bit number and bit weight.

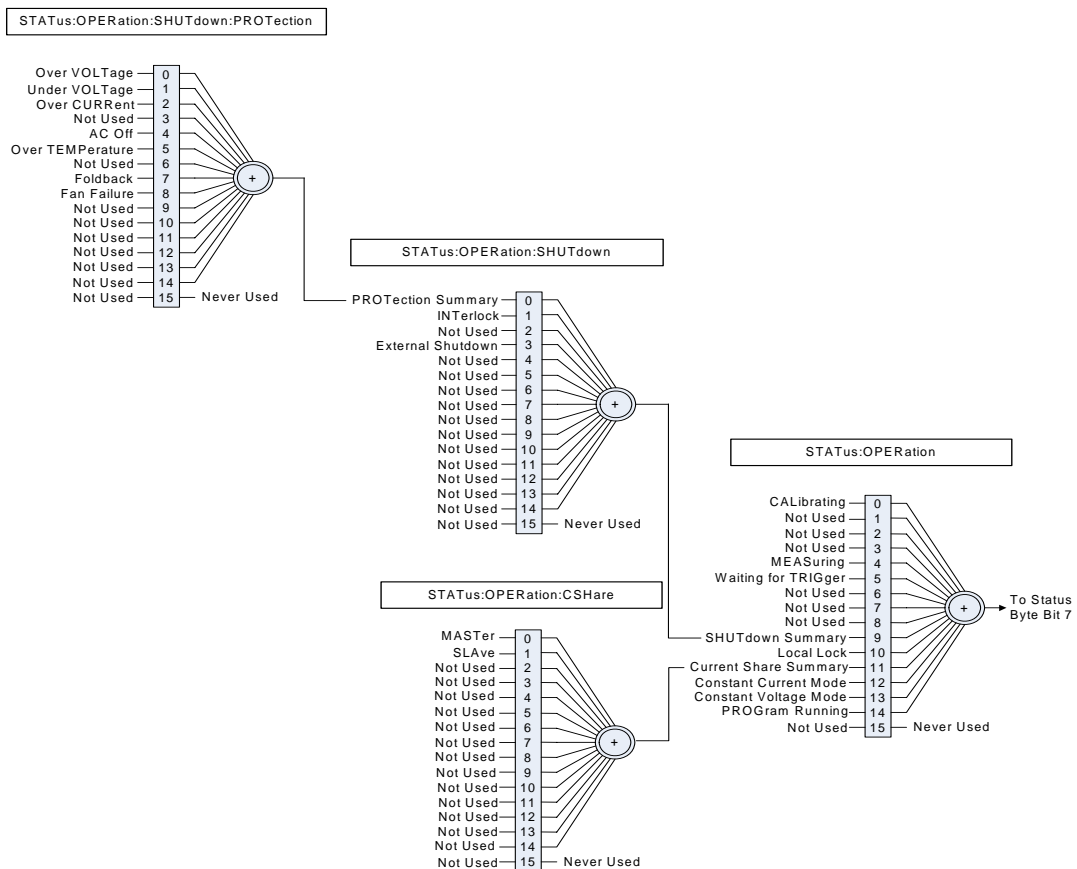


Figure 5-20 Operation Status Register Fanout

Table 5-11 OPERation Status Register

Bit	Bit Weight	Bit Name	Description
0	1	CALibrating	Indicates that the supply is in CALibration Mode.
1	2	SETTling	Not implemented
2	4	RANGing	Not implemented
3	8	SWEeping	Not implemented
4	16	MEASuring	Not implemented
5	32	Waiting for Arm	Not implemented
6	64	Waiting for Trigger	Not implemented
7	128	CORRecting	Not implemented
8	256	Not Used	Not Used
9	512	SHUTdown Summary	Reflects the summary of the SHUTdown Sub-Register.
10	1024	Local Lockout	Front panel lockout
11	2048	Current Share Summary	Reflects the summary of the CShare Sub-Register.
12	4096	Constant Voltage Mode	Reflects the output mode of the supply.
13	8192	Constant Current Mode	Reflects the output mode of the supply.
14	16384	Program Running	Indicates if an Autosequence program is currently running.

The operation shutdown status register describes the cause of the power supply shutting down the output. More than one bit may be active and multiple actions will be required to restart the unit. The protection shutdown sub-register indicates which protection mechanisms have caused the power supply to shutdown.

Table 5-12 OPERation SHUTdown Status Register

Bit	Bit Weight	Bit Name	Description
0	1	PROTection	Reflects the summary of the PROTection sub-register.
1	2	INTeRlock	The power supply is shut down by INTeRlock signal.
2	4	Not Used	Not Used
3	8	External Shutdown	The power supply is shut down by External Shutdown signal.

Table 5-13 OPERation SHUTdown PROTection Status Register

Bit	Bit Weight	Bit Name	Description
0	1	OVP	Over Voltage protection has tripped.
1	2	UVP	Under Voltage protection has tripped.
2	4	OCP	Over Current protection has tripped.
3	8	Not Used	Not Used
4	16	AC Off	AC failure protection has tripped.
5	32	OTP	Over Temperature protection has tripped.
6	64	Not Used	Not Used
7	128	Foldback	Foldback protection has tripped.
8	256	Fan	Fan failure protection has tripped.

Current SHare Sub-Register

This register shows the state of the current share configuration, which can either be set through the front panel Current Share Config menu, or through the SCPI command.

The SCPI command (s) for these instructions are:

`[[:]SOURCE]:COMBine:CSHare[:MODE]`

Table 5-14 OPERation CSHare Status Register

Bit	Bit Weight	Bit Name	Description
0	1	MASTer	The power supply is configured to be a Current Share Master.
1	2	SLAVe	The power supply is configured to be a Current Share Slave.

Operation Status Register Commands

The response format for all register queries will be in decimal notation.

Query Operation Status Register Event

SCPI command:

```
[:]STATUS[<channel>]:OPERation[:EVENT]?
```

Query Operation Status Register Condition

SCPI command:

```
[:]STATUS[<channel>]:OPERation:CONDition?
```

Enable Operation Status Register

SCPI command:

```
[:]STATUS[<channel>]:OPERation:ENABLE <status-enable>
```

Query Format:

```
[:]STATUS[<channel>]:OPERation:ENABLE?
```

Set Operation Status Positive Transition Filter

SCPI command:

```
[:]STATUS[<channel>]:OPERation:PTRansition <status-enable>
```

Query Format:

```
[:]STATUS[<channel>]:OPERation:PTRansition?
```

Set Operation Status Negative Transition Filter

SCPI command:

```
[:]STATUS[<channel>]:OPERation:NTRansition <status-enable>
```

Query Format:

```
[:]STATUS[<channel>]:OPERation:NTRansition?
```

Current Sharing Sub-Register Commands

Query Current Share Event

SCPI command:

```
[:]STaTus[<channel>]:OPERation:CSHare[:EVENT]?
```

Query Current Share Condition

SCPI command:

```
[:]STaTus[<channel>]:OPERation:CSHare:CONDition?
```

Enable Current Share Sub-Register

SCPI command:

```
[:]STaTus[<channel>]:OPERation: CSHare:ENABle  
<statusenable>
```

Query format:

```
[:]STaTus[<channel>]:OPERation:CSHare:ENABle?
```

Set Current Share Positive Transition Filter

SCPI command:

```
[:]STaTus[<channel>]:OPERation:CSHare:PTRansition  
<status-enable>
```

Query format:

```
[:]STaTus[<channel>]:OPERation:CSHare:PTRansition?
```

Set Current Share Negative Transition Filter

SCPI command:

```
[:]STaTus[<channel>]:OPERation:CSHare:NTRansition  
<status-enable>
```

Query format:

```
[:]STaTus[<channel>]:OPERation:CSHare:NTRansition?
```

Shutdown Sub-Register Commands

Query Shutdown Event

SCPI command:

```
[ : ]STATUS[ <channel> ]:OPERation:SHUTdown[:EVENT]?
```

Query Shutdown Condition

SCPI command:

```
[ : ]STATUS[ <channel> ]:OPERation:SHUTdown:CONDition?
```

Enable Shutdown Sub-Register

SCPI command:

```
[ : ]STATUS[ <channel> ]:OPERation: SHUTdown:ENABLE <status-  
enable>
```

Query format:

```
[ : ]STATUS[ <channel> ]:OPERation:SHUTdown:ENABLE?
```

Set Shutdown Positive Transition Filter

SCPI command:

```
[ : ]STATUS[ <channel> ]:OPERation:SHUTdown:PTRansition  
<status-enable>
```

Query format:

```
[ : ]STATUS[ <channel> ]:OPERation:SHUTdown:PTRansition?
```

Set Shutdown Negative Transition Filter

SCPI command:

```
[ : ]STATUS[ <channel> ]:OPERation:SHUTdown:NTRansition  
<status-enable>
```

Query format:

```
[ : ]STATUS[ <channel> ]:OPERation:SHUTdown:NTRansition?
```

Protection Sub-Register Commands

Query Protection Event

SCPI command:

```
[ : ]STATus[ <channel> ]:OPERation:SHUTdown:PROTection[:EVENT]?
```

Query Protection Condition

SCPI command:

```
[ : ]STATus[ <channel> ]:OPERation:SHUTdown:PROTection:CONDition?
```

Enable Protection Sub-Register

SCPI command:

```
[ : ]STATus[ <channel> ]:OPERation: SHUTdown:PROTection:ENABLE  
<status-enable>
```

Query format:

```
[ : ]STATus[ <channel> ]:OPERation:SHUTdown:PROTection:ENABLE?
```

Set Protection Positive Transition Filter

SCPI command:

```
[ : ]STATus[ <channel> ]:OPERation:SHUTdown:PROTection:PTRansition  
<stats-enable>
```

Query format:

```
[ : ]STATus[ <channel> ]:OPERation:SHUTdown:PROTection:PTRansition?
```

Set Protection Negative Transition Filter

SCPI command:

```
[ : ]STATus[ <channel> ]:OPERation:SHUTdown:PROTection:NTRansition  
<status-enable>
```

Query format:

```
[ : ]STATus[ <channel> ]:OPERation:SHUTdown:PROTection:NTRansition?
```

QUESTIONable Status Register

The Questionable Status register is a standard SCPI, 16-bit register that stores information about questionable events or status during power supply operation. That is, bits in these registers may indicate that the output of the supply is of undesirable or questionable quality.

The Questionable Status data structure consists of a questionable status register and two sub-registers representing the status of the voltage outputs and temperature.

Figure 5-21 gives an overview of the Questionable Status data structure. The “+” represents the logical summation of bits in a register. Table 5-15, Table 5-16, and Table 5-17 describe the meanings of each bit as well as the bit number and bit weight.

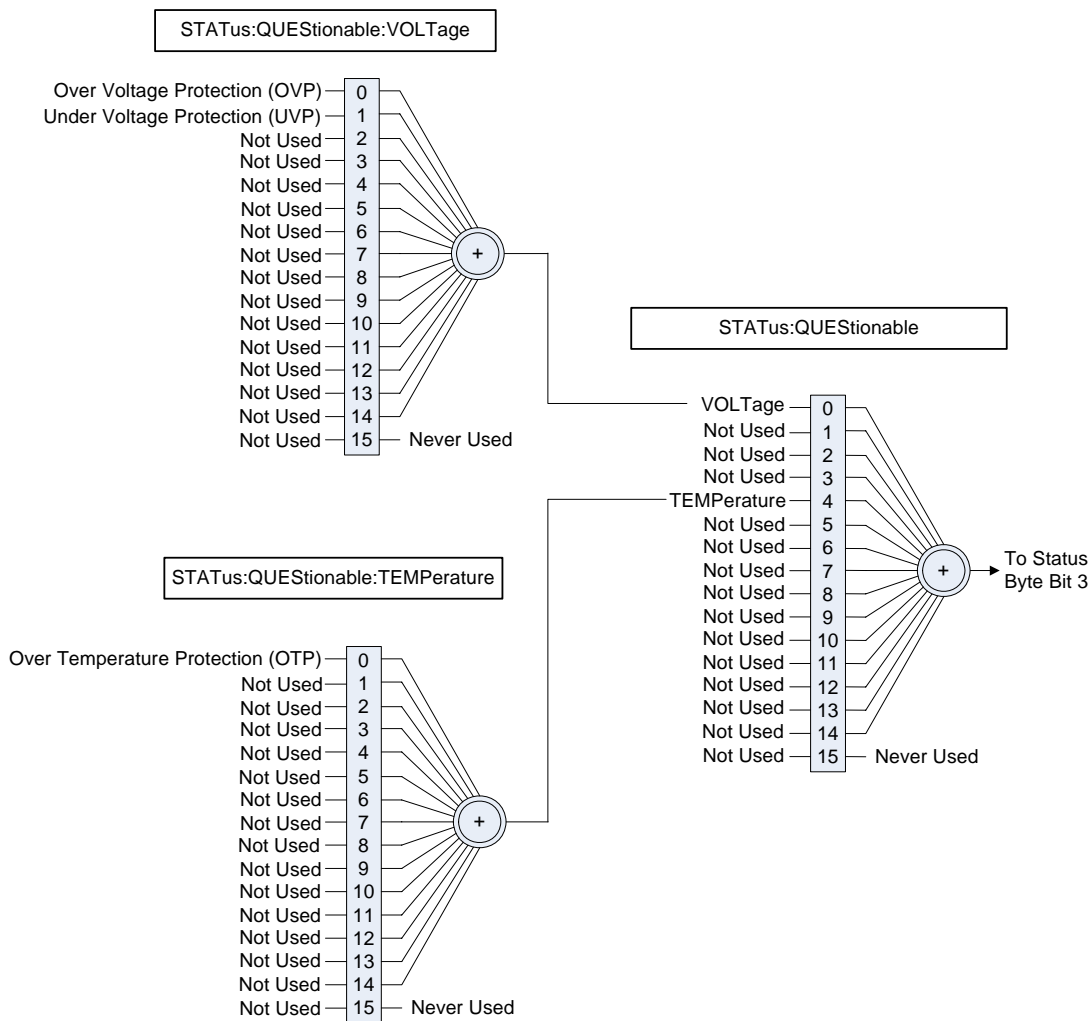


Figure 5-21 SCPI QUESTIONable Registers Fanout

Table 5-15 QUESTionable Status Register

Bit	Bit Weight	Bit Name	Description
0	1	VOLTage	Summary of Voltage Register
1	2	CURRent	Not Implemented
2	4	TIME	Not Implemented
3	8	POWer	Not Implemented
4	16	TEMPerature	Summary of Temperature Register
5	32	FREQuency	Not Implemented
6	64	PHASe	Not Implemented
7	128	MODulation	Not Implemented
8	256	CALibration	Not Implemented
9	512	Not Used	Not Used
10	1024	Not Used	Not Used
11	2048	Not Used	Not Used
12	4096	Not Used	Not Used
13	8192	Not Used	Not Used
14	16384	Not Used	Not Used
15	32768	Not Used	Not Used

VOLTage Sub-Register

This shows whether the present voltage level is over or under the specified trip limit.

Table 5-16 QUEStionable VOLTage Status Register

Bit	Bit Weight	Bit Name	Description
0	1	OVP	Over Voltage Protection
1	2	UVP	Under Voltage Protection

TEMPerature Sub-Register

This shows whether the temperature of critical components is near or over the maximum operating temperature.

Table 5-17 QUEStionable TEMPerature Status Register

Bit	Bit Weight	Bit Name	Description
0	1	OTP	Over Temperature Protection

Questionable Status Register Commands

Query Questionable Status Register Event

SCPI command:

```
[:]STATUS[<channel>]:QUESTIONABLE[:EVENT]?
```

Query Questionable Status Register Condition

SCPI command:

```
[:]STATUS[<channel>]:QUESTIONABLE:CONDITION?
```

Enable Questionable Status Register

SCPI command:

```
[:]STATUS[<channel>]:QUESTIONABLE:ENABLE <status-enable>
```

Query Format:

```
[:]STATUS[<channel>]:QUESTIONABLE:ENABLE?
```

Set Questionable Status Positive Transition Filter

SCPI command:

```
[:]STATUS[<channel>]:QUESTIONABLE:PTRANSITION <status-enable>
```

Query Format:

```
[:]STATUS[<channel>]:QUESTIONABLE:PTRANSITION?
```

Set Questionable Status Negative Transition Filter

SCPI command:

```
[:]STATUS[<channel>]:QUESTIONABLE:NTRANSITION <status-enable>
```

Query Format:

```
[:]STATUS[<channel>]:QUESTIONABLE:NTRANSITION?
```

Voltage Status Register Commands

Query Voltage Status Register Event

SCPI command:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE[:EVENT]?
```

Query Voltage Status Register Condition

SCPI command:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE:CONDition?
```

Enable Voltage Status Register

SCPI command:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE:ENABLE  
<status-enable>
```

Query Format:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE:ENABLE?
```

Set Voltage Status Positive Transition Filter

SCPI command:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE:PTRansition  
<status-enable>
```

Query Format:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE:PTRansition?
```

Set Voltage Status Negative Transition Filter

SCPI command:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE:NTRansition  
<status-enable>
```

Query Format:

```
[:]STaTus[<channel>]:QUEStionable:VOLTagE:NTRansition?
```

Temperature Status Register Commands

Query Temperature Status Register Event

SCPI command:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
[ :EVENT ]?
```

Query Temperature Status Register Condition

SCPI command:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
:CONDition?
```

Enable Temperature Status Register

SCPI command:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
:ENABLE <status-enable>
```

Query Format:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
:ENABLE?
```

Set Temperature Status Positive Transition Filter

SCPI command:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
:PTRansition <status-enable>
```

Query Format:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
:PTRansition?
```

Set Temperature Status Negative Transition Filter

SCPI command:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
:NTRansition <status-enable>
```

Query Format:

```
[ : ]STATUS[ <channel> ]:QUESTionable:VOLTage:TEMPerature
:NTRansition?
```

SCPI Error/Event Queue

The error/event queue contains items that include a numerical and textual description of the error or event. Querying for the full queue item (for example, with `SYSTem:ERRor[:NEXT]?`) will return a response with the following syntax:

```
<Error/Event Number>, "<Error/Event  
Description>;<Optional Device Dependent Info>"
```

The `<Error/event_number>` is a unique integer in the range [-32768, 32767]. All positive numbers are instrument-dependent. All negative numbers are reserved by the SCPI standard with certain standard error/event codes described in the SCPI 1999 standard document. The value, zero, is also reserved to indicate that no error or event has occurred.

The second parameter of the full response is a quoted string containing an `<Error/event_description>` followed by optional `<Device-dependent info>` text. Each `<Error/event_number>` has a unique and fixed `<Error/event_description>` associated with it.

The maximum string length of `<Error/event_description>` plus `<Device-dependent_info>` is 255 characters.

As errors and events are detected, they are placed in a queue. This queue is first in, first out. If the queue overflows, the last error/event in the queue is replaced with error:

```
-350,"Queue overflow"
```

Any time the queue overflows, the least recent errors/events remain in the queue, and the most recent error/event is discarded. The error queue implemented in the XTR is capable of holding 4 errors.

When the error queue is not empty the error queue bit in the Status register will be set.

Querying For the Errors

Executing a query of the event queue will respond with the oldest error currently on the queue. This error is removed. The response format is discussed in the error/event queue description section.

Command:

```
[ : ]SYSTem:ERRor[:EVENT]?
```

Examples:

```
SYST:ERR?
```

```
SYST:ERR:EVENT?
```

Responses might be:

```
-102, "syntax error;"
```

```
0, "No Error;"
```

Querying For the Error Code Only

It is possible to query for only the error code. When querying the error code only the response will be the numeric error code only, no additional description will be given. The error queried will be removed from the queue.

Command:

```
[ : ]SYSTem:ERRor:CODE[ :EVENT ]?
```

Example:

```
:SYST:ERR:CODE?
```

```
SYST:ERR:CODE:EVENT?
```

Responses might be:

```
-102
```

```
0
```

Querying For the Number of Errors in the Queue

To query the device for the number of errors currently stored in the error queue you should use the following command.

Command:

```
[ : ]SYSTem:ERRor:COUNt?
```

Example:

```
:SYST:ERR:COUN?
```

Response might be:

```
3
```

Reset Command

The Reset command performs a device reset. The Reset command is the third level of reset in a three level reset strategy, set out in IEEE 488.2 (see IEEE 488.2 standard, section 17.1.2).

The Reset command shall do the following:

1. Set the device-specific functions to a known state that is independent of the past-use history of the device. See Table 3-9, “Power Supply Default Settings” on page 3–39 for details.
2. Force the device into the OCIS state, (see IEEE 488.2 standard, section 12.5.2).
3. Force the device into the OQIS state, (see IEEE 488.2 standard, section 12.5.3).

The reset command explicitly shall NOT affect the following:

1. The state of the IEEE 488.1 interface.
2. The selected IEEE 488.1 address of the device.
3. The Output Queue.
4. The Standard Status Register Enable setting.
5. The Standard Event Status Enable (SESR) setting.
6. The Operation and Questionable SCPI status registers and their fan out registers.
7. Calibration data that affects device specifications.
8. The Protected User Data query response.

Commands:

```
*RST  
[:]SYSTem[<channel>]:RESet
```

Clear All Status Registers

Clear Status Command

Clears all Event Registers, including the Status Byte, the Standard Event Status and the Error Queue.

Command:

*CLS

[:]STATUS[<channel>]:CLear

SCPI Preset Status

Configures the status data structures to ensure that certain events are reported at a higher level through the status-reporting mechanism. These events are summarized in the mandatory structures, the Operation Status Register and Questionable Status Register.

The PRESet command affects only the enable registers and the transition filter registers of the status data structures. PRESet does not clear any of the event registers or any item from the error/event queue. The *CLS command is used to clear all event registers and queues in the device status-reporting mechanism.

For the device-dependent status data structures, the PRESet command sets the enable register to all 1s and the transition filter register to report only positive transitions. For the SCPI mandatory status data structures, the PRESet command sets the transition filter registers to recognize only positive transitions and sets the enable register to 0s. The following will not be affected by this command: Service Request Enable Register, Parallel Poll Enable Register, the memory register associated with the *SAV command, the power supply address, Output Queue, and the power-on-status-clear flag setting.

Table 5-18 Preset Values of User Configurable Registers

Register	Filter/Enable	Preset Value
Operational	Operational Enable Register	0
	Positive Transition Filter	1
	Negative Transition Filter	0
Questionable	Questionable Enable Register	0
	Positive Transition Filter	1
	Negative Transition Filter	0
All others	All other Enable Register	1
	Positive Transition Filter	1
	Negative Transition Filter	1

SCPI command:

```
[ : ]STATus[ <channel> ]:PRESet
```

Command Line Help System

The Help system is made up of a series of commands that can be used to get help on all available commands and details on their syntax.

The Help commands are:

```
[ : ]SYSTem[ <channel> ]:HELP[ :HEADers ]?
[ : ]SYSTem[ <channel> ]:HELP:SYNTax? '<command for which you
want help>'
[ : ]SYSTem[ <channel> ]:HELP:LEGacy?
```

Querying Help for all Command Headers

The [:]SYSTem[<channel>]:HELP[:HEADers]? query shall return all SCPI commands and queries and IEEE 488.2 common commands and common queries implemented. No single line will be longer than 80 characters long. The full path for every command and query shall be returned separated by line feeds.

A <SCPI header> is defined as:

It shall contain all the nodes from the root. The <SCPI program mnemonic> contains the node in standard SCPI format. The short form shall use uppercase characters while the additional characters for the long form shall be in lowercase characters. Default nodes shall be surrounded by square brackets ([]).

Command:

```
[ : ]SYSTem[ <channel> ]:HELP[ :HEADers ]?
```

For example:

```
:SYST1:HELP:HEAD?
```

Might return:

```
*IDN?/qonly/
*RST/nquery/
*TST?/qonly/
*OPC/nquery/
*OPC?/qonly/
*WAI/nquery/
*CLS/nquery/
*ESE
```

```
*ESR?/qonly/  
*SRE  
*SRE?/qonly/  
*STB?/qonly/  
*SAV  
*RCL  
*TRG/nquery/  
*ADR  
*HELP?/qonly/  
*ERR?/qonly/  
[:]SYSTem:PROTection[:MASK]  
[:]SYSTem:ERRor[:NEXT]?/qonly/  
[:]SYSTem:ERRor:CODE[:NEXT]?/qonly/  
[:]SYSTem:ERRor:COUnT?/qonly/  
...  
[:]OUTPut:PROTection:FOLDback[:MODE]  
[:]OUTPut:PROTection:FOLDback:  
[:]OUTPut:POLarity  
[:]OUTPut[:POWer][:STATE]  
[:]OUTPut[:POWer]:PON[:STATE]  
[:]OUTPut:AUXilliary[:STATE]  
[:]OUTPut:AUXilliary:PON[:STATE]  
[:]MEASure[:SCALar][:VOLTage][:DC]?/qonly/  
[:]MEASure[:SCALar]:CURRent[:DC]?/qonly/  
[:]MEASure[:SCALar]:APRogram[:VOLTage][:DC]?/qonly/  
[:]MEASure[:SCALar]:APRogram[:VOLTage]:ISOLated[:DC]?/  
qonly/  
[:]MEASure[:SCALar]:APRogram:CURRent[:DC]?/qonly/  
[:]MEASure[:SCALar]:APRogram:CURRent:ISOLated[:DC]?/qonly/  
[:]INITiate:IMMediate/nquery/  
[:]CALibration:REStore/nquery/  
[:]CALibration[:VOLTage]:PROTection[:OVER][:DATA]/nquery/  
[:]CALibration:OUTPut[:VOLTage][:DATA]/nquery/  
[:]CALibration:OUTPut:CURRent[:DATA]/nquery/  
[:]CALibration:OUTPut:ANALog[:VOLTage][:DATA]/nquery/  
[:]CALibration:OUTPut:ANALog[:VOLTage]:ISOLated[:DATA]/  
nquery/
```

Querying Help for Legacy Command Headers

The `[:]SYSTem[<channel>]:HELP:LEGacy?` query is essentially the same as the `[:]SYSTem[<channel>]:HELP[:HEADers]?` command, but it lists legacy commands. If executed it returns all legacy commands and queries implemented. The response shall be on a page by page basis. No single line will be longer than 80 characters and each page will be 23 lines long. The full path for every command and query shall be returned separated by line feeds. After a full page of headers has been displayed you will be prompted to press any key to continue or the ESC key to stop any further listing of the command headers.

Command:

```
[ : ]SYSTem[ <channel> ]:HELP:LEGacy?
```

For example:

```
:SYST2:HELP:LEG?
```

Might return:

```
AUX
OUT
ERR?/qonly/
CLR/nquery/
FOLD
DLY
VSET
ISET
TRG/nquery/
OVP
UVP
HELP?/qonly/
HLP?/qonly/
```

Querying Help for Command Syntax

The `SYSTem[<channel>]:HELP:SYNTAX?` query causes the device to return a string containing the syntax specification of the command associated with the `<command_header>`, a description of the command function and any aliases to the command. Each line of the response is tabbed to the right for readability.

Any `<command_header>` that is not a valid command header being recognized by the device, shall cause the device to return a null string (`""`). E.g. if the `<command_header>` contains only a part of the header, contains an illegal numeric suffix, etc.

The response shall have the following format:

```
<Description of command>
<command header> <Command parameters>
Alias: <list of command that perform the same
function>
```

Command:

```
[:]SYSTem[<channel>]:HELP:SYNTAX? {<string command>}
```

Where:

`<string command>` is the command to look up the syntax help on.

The following examples demonstrate how to use the syntax help command.

Example 1:

```
:SYST:HELP:SYNT? '*ADR'
```

Gets the response:

```
Select the PSU (power supply) to communicate with
*ADR ?|<NR1>
Aliases: :SYSTem:COMMunicate[:SELF]:ADDRESS
```

Example 2:

```
:SYST:HELP:SYNTAX? "INIT:IMM"
```

Gets the response:

```
Triggers the Autosequence Program
[:]INITiate:IMMEDIATE
Aliases: *TRG
```

Example 3:

```
:SYST:HELP:SYNT? ':VOLT'
```

Gets the response:

```
Set Voltage Setpoint (Immediate)
```

```
[[:]SOURce]:VOLTage[:LEVel][:IMMediate][:AMPLitude]  
?|<NR2>|MAXimum|MINimum
```

```
Aliases:
```

Locking and Unlocking the Front Panel

Locking out the front panel will prevent any of the buttons from functioning. All the buttons and knobs on the front panel will display the `LOCK LOC` message to be display on the Current and Voltage displays if pressed or rotated. This mode prevents any changes to the unit from the front panel. See the following procedure to lock and unlock the front panel.

The SCPI Commands for these instructions are:

```
[[:]SYSTem[<channel>]:REMOte:STATe {?|LOCal|REMOte}
```

Where:

LOCal is used to set the front panel mode to local.

REMOte is used to set the front panel into locked mode (remote).

For example:

```
SYST:REM:STAT REM Front panel is locked (remote digital programming mode only).
```

```
SYST:REM:STAT LOC Front panel is unlocked.
```

```
SYST:REM:STAT? Query for status
```

Auto Sequence Programming

Auto Sequence programming lets you execute a program stored in the power supply's memory. The program that can be stored in memory can be composed of any of the SCPI commands described in this Manual.

For example, Auto Sequence programming allows you to set the timer to turn the power output of the supply Off or On after a time interval or to program voltage sequences.

When a program is activated each command stored in the buffer is executed as if the operator had sent the command by typing it in. A variable delay time called dwell is spent between commands. The dwell time can range from 0 seconds to 180 seconds. See "Setting Dwell Time" on page 5-61.

The Auto Sequence program will be cleared after AC power is turned off; however, a procedure exists for storing it in a text file which can be reloaded at a later date.

Setting Dwell Time

The dwell time is the amount of time that is delayed between each command during the execution of an Auto Sequence program. The dwell time can be from 0 to 180 seconds and can be changed during the program execution. The dwell time has a minimum step size of 1 second.

Command:

```
[ : ]PROGram[ <channel> ][ :STEP ]:DWELl { ? | <dwell time> }
```

Where:

<dwell time > is an integer value from 0 to 180.

For Example:

:PROG:DWEL 12 Results in 12 seconds of wait time after each command is executed.

Storing an Auto Sequence Program:

Loading a program into memory is done by using the [:]PROGram[<channel>][:RECOrd]:STARt command. After the start command has been issued, the XTR will record all subsequent commands into the auto sequence program buffer. The commands will be recorded into the buffer until the :PROGram[<channel>][:RECOrd]:STOP command is issued.

Commands:

```
[ : ]PROGram[ <channel> ][ :RECOrd ]:STARt
```

```
[ : ]PROGram[ <channel> ][ :RECOrd ]:STOP
```

Important: If the start recording command is executed then any previously stored Auto Sequence program is deleted.

For example:

```
:PROG:STAR
:VOLT 12
:OUTP ON
:PROG:DWEL 60
:OUTP OFF
:OUTP ON
:OUTP OFF
```

:PROG:DWEL 0

:PROG:STOP

This program will send a 12 V square wave with 120 seconds 50% duty cycle. When the program is finished, the dwell time is restored to 0 seconds.

Saving an Auto Sequence Program to File:

The following procedure indicates how to save an Auto Sequence program to a text file on the attached PC.

To save an Auto Sequence Program to a file:

1. Start the text capture by selecting **Transfer>Capture Text ...** from the Hyper Terminal program.
2. Set the location and name of the auto sequence to be captured.
3. Click the **Start** button.
4. Execute a program read back by sending:
:PROG[<channel>] :READ?
5. Stop the text capture by selecting **Transfer>Capture Text>Stop** from the Hyper Terminal program.
6. Using any text editor open the file which you captured the Auto Sequence program to.
7. Remove the first line which should read
":PROG[<channel>]:READ?" and the first blank line. This makes the first line of the program the first line of the file.
8. Save the file and exit the text editor.

The Auto Sequence program has not been stored and can be sent to any unit. See "Reloading an Auto Sequence Program:" on page 5–63 for details.

Readback and Troubleshooting an Auto Sequence Program:

Since the Auto Sequence programming function records the commands at program time without verifying the syntax, it can be difficult to spot an error in the sequence, for example, if a typo was made when entering a command during the record phase. A readback command has been provided to output the stored auto sequence program currently in memory.

Another benefit to the readback command is it allows the auto sequence program to be captured and stored on the client side for reloading when the program is to persist beyond power cycles.

Command:

```
[ : ]PROGram[ <channel> ] :READback?
```

For Example:

```
:PROG:START
*CLS
:VOLT 5.4
:CURR 0.25
*IDN?
:PROG:STOP
:PROG:READ?
```

Response:

```
*CLS
:VOLT 5.4
:CURR 0.25
*IDN?
:PROG:STOP
```

Reloading an Auto Sequence Program:

The following procedure will demonstrate how to store a command beyond a power cycle of the unit.

Important: This functionality is only available through USB, RS-232 and RS-485. It is not possible to reload an auto sequence program over the GPIB and ENET cards.

To reload Auto Sequence program from file:

1. Set the data rate of the device to be 1200 bps.
2. Close the connection to the hyperterminal program and configure the connection data rate to be 1200 bps.
3. Execute the program recording command:
:PROG:START

4. From the Hyper Terminal (or any other terminal program) select the **Transfer>Send Text File...**
5. Navigate to and select the text file that was previously stored. Click the Open button.
6. Execute the program recording stop command:
:PROG:STOP
7. Execute the readback command to verify the entire program was transferred correctly:
PROG:READ?
8. Set the data rate back to the original speed.
9. Close the connection to the HyperTerminal program and configure the connection data rate to be the original speed.

Running an Auto Sequence Program:

Once an auto sequence program has been stored, there are a few commands that can be used to run the program. Once a program begins running, it will continue running until completion and then repeat the number of times specified by the repeat command. The default at power on is to have repeat set to 1.

Commands:

```
*TRG  
[:]INITiate[<channel>][:IMMediate]  
[:]PROGram[<channel>]:STATE {?|RUN|STOP|PAUSE}
```

Where:

RUN causes the program to begin execution.

STOP causes the program to stop execution

PAUSE causes the program to stop executing at the current command. If a subsequent run is sent, the program will resume executing with the next command in the program.

For Example:

```
:PROG:STAR  
*IDN?  
*IDN?  
:PROG:STOP
```

```
:PROG:STAT RUN
```

The output after the last command might be as follows:

```
AMETEK, XTR 150-5.6, SN# E00123456, 1.00 Build 10, 21/
11/2005
```

```
AMETEK, XTR 150-5.6, SN# E00123456, 1.00 Build 10, 21/
11/2005
```

Important: Execution of the program may be terminated at any time by pressing the Esc key in the MS Windows Hyper Terminal window. The power supply can be controlled during program execution.

Deleting an Auto Sequence Program:

It is possible to delete the current Auto Sequence Program using the SCPI noted below.

Command:

```
[:]PROG:am[<channel>]:DELEte[:ALL]
```

Repeating an Auto Sequence Program:

An Auto Sequence Program can be configured to repeat any number of times or infinitely. The default at power up is to have the repeat count default to once. The program will repeat if the repeat count can be changed using the :PROG:am[<channel>]:REPeat command. If a program is running or pause the :PROG:am[<channel>]:REPeat command will not work.

Commands:

```
[:]PROG:am[<channel>]:REPeat {?|<count>|INFinity}
```

Where:

<count> is the repeated count from 1 to 65 534.

INFinity is the character mnemonic for repeating without end.

For Example:

```
:PROG:STAR
```

```
*IDN?
```

```
*IDN?
```

```
:PROG:STOP
```

```
:PROG:REP 2  
:PROG:STAT RUN
```

The output after the last command might be as follows:

```
AMETEK, XTR 150-5.6, SN# E00123456, 1.00 Build 10, 21/  
11/2005  
AMETEK, XTR 150-5.6, SN# E00123456, 1.00 Build 10, 21/  
11/2005  
AMETEK, XTR 150-5.6, SN# E00123456, 1.00 Build 10, 21/  
11/2005  
AMETEK, XTR 150-5.6, SN# E00123456, 1.00 Build 10, 21/  
11/2005
```

Configure Other Protection Mechanisms

Foldback Protection

Foldback protection causes the output of the power supply to shut down if the selected regulation mode is entered and the configured delay time expires. A delay time may be specified as well. The only way to clear foldback is by pressing the rotary Adjust/Enter control for 3 seconds and executing the Clear command.

Command:

```
[ : ]OUTPut [ <channel> ] : PROTection : CLear
```

Setting the Foldback Mode

The following command will set the foldback mode. The mode selected by the character mnemonic sent will indicate which mode will trigger the foldback alarm to begin counting. For example, if the command is sent with the CV mnemonic and the output is enabled with no load attached (open circuit), the unit will operate in constant voltage mode and the foldback counter will begin counting. If the CC mode was set and the output was enabled with no load connected, the unit will operate in CV mode and the foldback counter will not trigger.

To set the foldback mode, send the command:

Command:

```
[ : ]OUTPut [ <channel> ] : PROTection : FOLDback { ? | CC | CV | NONE }
```

Where:

NONE indicates foldback protection is disabled.

CC indicates the supply will shut down due to constant current condition.

CV indicates the supply will shut down due to constant voltage.

The default value is NONE.

To set the foldback delay, send the command:

Command:

```
[ : ]OUTPut [ <channel> ] : PROTection : FOLDback : DELay  
<delay_time>
```

Where:

<delay_time> is a value in the range of 0.5-50 seconds. The unit of second is the default and no units should be used with this parameter. (Increments of 0.1seconds are allowed.).

The default value is 0.5 seconds.

Over Temperature Protection

The over temperature protection (OTP) is the alarm that protects the unit in case of ventilation blockage, fan failure, or some other event that cause the unit to overheat. The OTP can be masked to disable it. To mask an alarm, see “Alarm Masking” on page 3–21 which maps out the bit position for each of the flags.

The alarm masking command can be entered using the SCPI command.

The SCPI command (s) for these instructions are:

```
[ : ]SYSTem[ <channel(s)> ]:PROTection:LATCh  
[ : ]SYSTem[ <channel(s)> ]:PROTection:MASK
```

The OTP alarm can also be have its output latch on clearing. See “Alarm Output Latching” on page 3–22. The On setting shown by the front panel (“Using Over Temperature Protection Lock (OTP)” on page 3–29) maps to having the OTP latch flag set. The OFF setting maps to having the OTP latch flag cleared. The default is to have the flag cleared.

Interlock Enable/Disable

The interlock feature is explained in “Interlock Function” on page 3–32. Use the following command to enable and disable interlock. Enabling interlock will allow the interlock feature to trigger based on the conditions described in “Interlock Function” on page 3–32. This feature can only be controlled using a SCPI command as there is no front panel equivalent. The default value of the interlock is to be disabled.

Important: The Interlock alarm cannot be masked or latched through the alarm protection mechanisms. It can only be enabled or disabled using the following command.

Commands:

```
[ : ]SENSe[ <channel> ]:INTerlock[ :STATe ] { ? | ON | OFF }
```

Where

ON enables the use of interlock protection.

OFF disables the use of interlock protection.

Save and Recall

The save and recall of user settings can be done using commands as well as at the front panel. Executing the save and recall commands will have the same outcome as following the procedure outlined in “Saving User Setting Memory Locations” on page 3–35 and “Recalling User Setting Memory Locations” on page 3–36.

Commands:

```
[ : ]SYSTem[ <channel> ]:SAVE { <user settings slot> }
[ : ]SYSTem[ <channel> ]:RECall { <user settings slot> }
```

Where

<user settings slot> is any integer between 1 and 3. The value corresponds to you the setting to be operated on.

Set Analog Programming Level

Setting the analog programming level is used to define the range from 0 to the level that will be input into the analog programming lines to control the output. The command is equivalent to the procedure described in “Analog Programming Mode” on page 4–9.

Commands:

```
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel
[ :VOLTage][ :ISOLated] { ? | <level> }
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel
[ :VOLTage] { ? | <level> }
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel
:CURRent[ :ISOLated] { ? | <level> }
[ : ]SYSTem[ <channel> ]:COMMunicate:APROgram:LEVel
:CURRent { ? | <level> }
```

Where

<level> is the maximum voltage or resistance that will be input to the analog inputs. The acceptable range is from 2 to 10 V and 2 to 10kΩ.

Set Remote Programming Interface

The remote source can be select using the following SCPI commands. These commands are equivalent to the procedure on “Voltage-Controlled Voltage APG Setup” on page 4–10 and “Voltage-Controlled Current APG Setup” on page 4–12.

Commands:

```
[ : ]SYSTem[ <channel> ]:REMote:SOURce[ :VOLtage]
{ ? | LOCAL | AVOLtage | ARESistive }

[ : ]SYSTem[ <channel> ]:REMote:SOURce:CURRent
{ ? | LOCAL | AVOLtage | ARESistive }
```

Where:

LOCAL indicates the value is controlled by the set point.

AVOLtage is used to set the output to be controlled by an analog voltage input.

ARESistive is used to set the output to be controlled by a resistor circuit.

IAVoltage is used to set the output to be controlled by the isolated analog voltage input.

IAResistive is used to set the output to be controlled by the isolated analog resistor circuit.

Protection Mask (Enable Alarms)

The protection mask allows for the different alarms to be masked, completely disabling them. This means that the SCPI status and operations registers will not detect the alarms. You will have no way of knowing the current operation state of the alarm. The protection mask is a feature that is only accessible using the SCPI command noted below.

Command:

```
[ : ]SYSTem[ <channel> ]:PROTection[:MASK] { ? | <mask> }
```

Where

<mask> is the bit mask for disabling the alarms. See Table 5-19 for details.

Table 5-19 Alarms Bit Mask

Bit	Bit Weight	Bit Name	Description
0	1	AC Fail	Not used. Always 1.
1	2	OTP	Over Temperature protection.
2	4	N/A	Not used.
3	8	Fan Stop	Fan on the main board.
4	16	N/A	Not used.
5	32	Interlock	Not used. Always 1.
6	64	OVP	Not used. Always 1.
7	128	OCP	Not used. Always 1.
8	256	Foldback	Foldback protection.
9	512	Shutdown	External Shutdown pin
10	1024	UVP	Under Voltage protection.

See “Alarms and Errors” on page 3–18.

6

Calibration and Troubleshooting

Chapter 6, Calibration and Troubleshooting, contains information and procedures for calibrating and troubleshooting the power supply.

Introduction

The calibration of the power supply is software dependent, and there are no potentiometers to adjust.

Calibration is performed via SCPI commands.

The following items need to be calibrated:

- Programmed voltage
- Voltage readback
- Programmed current
- Current readback
- Non-isolated voltage monitoring
- Isolated voltage monitoring
- Non-isolated current monitoring
- Isolated current monitoring
- Isolated source for analog programming
- Non-isolated source for analog programming
- Over voltage protection system



CAUTION: Equipment damage

Calibration procedures should only be performed by qualified user.

Main Voltage and Current Calibration Principle

Understanding the Problem

Figure 6-1 illustrates two sources of analog programming error: gain error and offset error. Gain error is the departure from the ideal slope of the measured versus programmed line. Offset error is the magnitude of the measured value when the programmed value is zero.

For best results, the next recommended action is gain calibration for 90% of maximum value and offset calibration for 10% of maximum value. Perform gain calibration again.

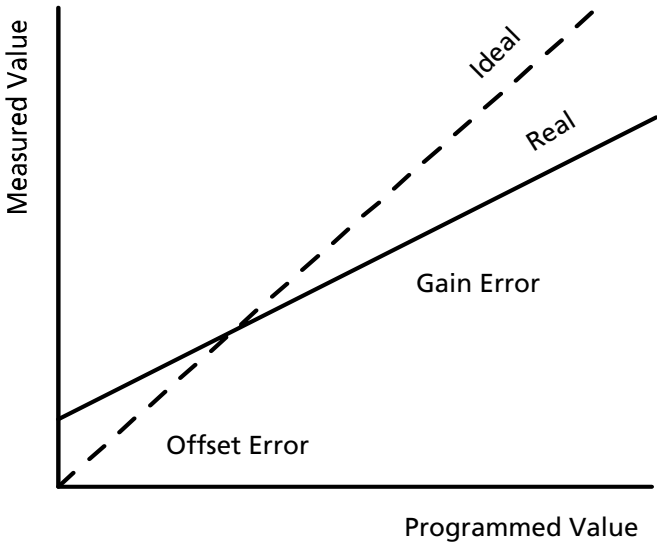


Figure 6-1 Offset (Intercept) Error and Gain (Slope) Error

Step 1: Gain Calibration

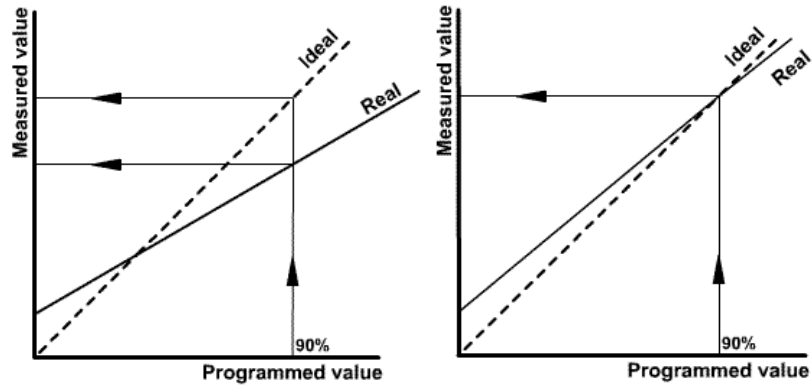


Figure 6-2 Calibration: Step 1 Gain Calibration

Adjust the gain so that the real line and ideal line intersect at a programmed value of 90%.

Step 2: Offset Calibration

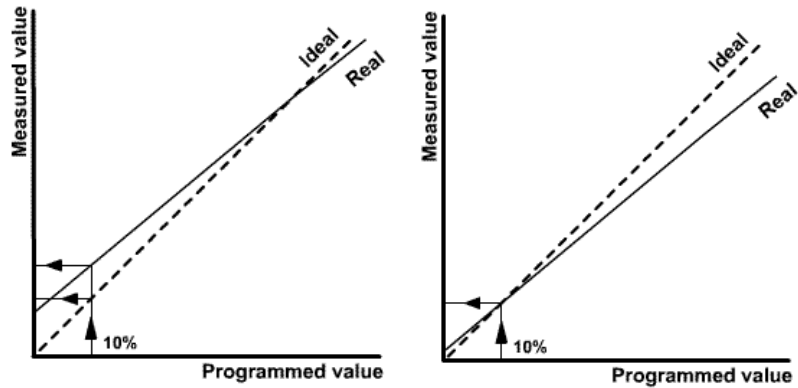


Figure 6-3 Calibration: Step 2 Offset Calibration

Adjust the offset so that the real and ideal lines intersect at a programmed value of 10%.

Step 3: Recalibrate Gain

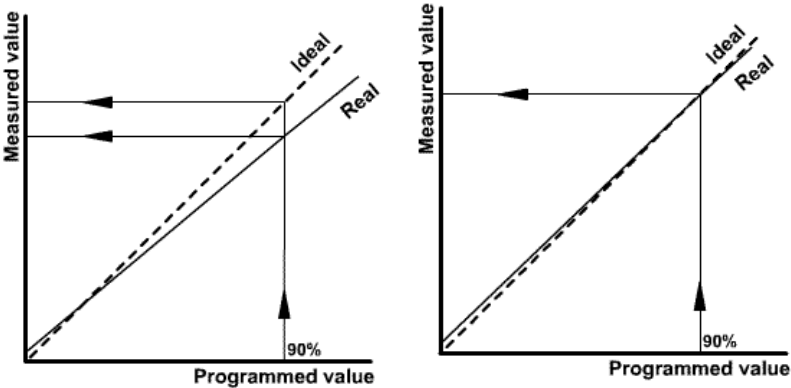


Figure 6-4 Calibration: Step 3 Recalibrate Gain

Repeat Step 1 for best results.

Calibrating the Output Voltage

Gain calibration of the power supply has the greatest affect on the accuracy in the high voltage range. Offset calibration has the greatest affect on accuracy of the power supply at low voltages. The same calibration command is used for the gain and offset calibrations. The type of calibration is determined internally by the XTR depending on if the set point is above 10% of the maximum output voltage value or not. If it is above 10% of the maximum voltage, the calibration is a gain calibration; if it is below 10%, it is an offset calibration.

Gain Calibration

To perform gain calibration:

1. Disconnect the power supply from the load.
2. Connect the output terminals to a precision voltmeter.
3. Turn both the power supply and the voltmeter to On.
4. Set the current set point to maximum. Set the supply output to 90% of the nominal voltage level.
5. Turn on the output power.
6. Read the voltage value on voltmeter display.
7. Type the SCPI command with voltage value as parameter “data”.
For example, type :CAL:OUTP 138.3 if you had an XTR 150-5.6 calibrating with the voltage set point set to 135 V and the voltmeter was reading 138.3 volts

Offset Calibration

To perform offset calibration:

1. After performing gain calibration, set the programmed voltage 10% from nominal.
2. Read the voltage value on the voltmeter display.
3. Type the SCPI command with voltage value as parameter “data”.
For example, you would type :CAL:OUTP12.3 if you had an XTR 150-5.6 calibration with the voltage set point set to 10V and the voltmeter was reading 12.3 volts.

After performing offset calibration, it is recommended that you repeat gain calibration.

Important: For best results, both calibrations may be repeated several times.

The SCPI Command (s) for these instructions are:

```
[:]CALibration[<channel>]:OUTPut{:VOLTage}{<voltmeter  
reading in volts>}
```

Calibrating the Output Current

Gain Calibration

To perform gain calibration:

1. Disconnect the power supply from the load.
2. Connect the output terminals to a load representing a short circuit using a precision ammeter.
3. Turn both the power supply and the load On.
4. Set the voltage set point to maximum. Set the supply output to 90% of the nominal current level.
5. Turn on the output power.
6. The power supply starts up in Constant Current mode.
7. Read the current value on the ammeter display.
8. Type SCPI command with current value as parameter “data”.

For example, type `:CAL:OUTP 5.07` if you had an XTR 150-5.6 calibrating with the current set point set to 5.04 A and the ammeter was reading 5.07 amps.

Offset Calibration

Offset calibration of the power supply provides the best accuracy in low-range current.

To perform offset calibration:

1. After performing gain calibration, set the current to 10% from the nominal.
2. Read the current value on the ammeter display.
3. Type SCPI command with the current value as parameter "data".

For example, you would type `:CAL:OUTP:CURR 0.50` if you had an XTR 150-5.6 calibrating with the current set point set to 0.56 A and the actual current measured was 0.50A.

After performing offset calibration, it is highly recommended that you repeat gain calibration.

Important: For best results, both calibrations may be repeated several times. To maintain the high current accuracy of the XTR series of power supplies, user current calibration should only be done with a high accuracy calibrated shunt resistor of at least 0.025% tolerance.

SCPI Command

```
[:]CALibration[<channel>]:OUTPut:CURRent {<ammeter  
reading in amps>}
```

Over Voltage Protection Calibration

Important: The Voltage Calibration must be done before performing this procedure. If this is not done the OVP calibration will be inaccurate.

To calibrate the over voltage protection:

1. Turn on the power supply.
2. Select the VAP mode to be Off.
3. Set the voltage set point to be 90% of the model voltage and the current to be 10% of the model current.
4. Turn on the main power output.
5. Execute the OVP calibration SCPI command:
`:CAL:PROT <output value set in step 3>`
6. The power supply will enter into self-calibration mode. The output voltage display blinks OVP CAL. After several seconds, the calibration will complete and the display will return to normal operation with output off.

Calibration of the power supply is complete.

Important: The output (main) voltage must be precalibrated.

The SCPI command (s) for these instructions are:

```
[:]CALibration[:VOLTage]:PROTection[:OVER]  
{<expected output value>}
```

Non-isolated Analog Programming Calibration

Prior to this, the main output must be calibrated first.

Important: In calibration commands, when + or – keys are expected, any other key will exit from the calibration mode.

Non-isolated Voltage Monitoring Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in steps 3 and 8.

To calibrate the non-isolated voltage monitoring:

1. Disconnect the load and connect the voltmeter to the output.
2. Connect the voltmeter to the non-isolated voltage monitoring output lines (J1.13 - J1.7).
3. Set the Voltage APG level to 4 V. Send the SCPI command:
`SYST:COMM:APR:LEV 4`
4. Set the input source as Local. Send the SCPI command:
`SYST:REM:SOUR LOC`
5. Set the main output voltage to 100% by sending the command:
`SOUR:VOLT <ModelVolt>`
or use the rotary adjust/Enter control.
6. Turn the main output On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
7. Enter interactive calibration mode by sending the SCPI command:
`CAL:MON`
8. Press on the terminal keys – or + to reduce or increase monitoring value. Adjust the monitoring value displayed on the voltmeter that was set up in Step 1 to read as close as possible to 4.000 V.
9. Press any key other than the + or – keys to exit from interactive calibration mode.

Non-isolated Current Monitoring Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in steps 3 and 8.

To calibrate the non-isolated current monitoring:

1. Short the main output with a shunt. Connect a multimeter to measure the voltage across the shunt.
2. Connect the voltmeter to the non-isolated current monitoring output lines (J1.12 - J1.7).
3. Set the Current APG level to 4 V. Send the SCPI command:
`SYST:COMM:APR:LEV:CURR 4`
4. Set the input source as Local.
5. The SCPI command is:
`SYST:REM:SOUR:CURR LOC`
6. Set the main output voltage to 100% by sending the command `SOUR:VOLT <ModelVolt>` or use the rotary adjust/Enter control.
7. Turn the main output On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
8. Enter interactive calibration mode by sending SCPI command:
`CAL:MON:CURR`
9. Press on the terminal keys – or + to reduce or increase the monitoring value. Adjust the monitoring value displayed on the voltmeter that was set up in Step 1 to read as close as possible to 4.000 V.
10. Press any key other than the + or – keys to exit from interactive calibration mode.

Non-isolated Voltage Programming of Voltage Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in steps 3 and 4.

To calibrate the non-isolated voltage programming of voltage:

1. Disconnect the load and connect the voltmeter to the output.
2. Connect the input voltage source to the non-isolated connector, voltage programming (J1.9 - J1.7).
3. Set the Voltage APG level to 4 V. Send the SCPI command:
`SYST:COMM:APR:LEV 4`
4. Set input source voltage to 4.000 V.
5. Set the input source as Voltage Non-Isolated for Voltage Programming. The SCPI command is:
`SYST:REM:SOUR AVOL`
6. Turn the main output to On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
7. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL`
8. Press the terminal keys – or + to reduce or increase the main output voltage value. Adjust the main output voltage to 100%, measured on the external voltmeter on the output.
9. Press any key other than the + or – keys to exit from interactive calibration mode.

Non-isolated Resistive Programming of Voltage Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating resistance level in steps 2 and 3.

To calibrate the non-isolated resistive programming of voltage:

1. Disconnect the load and connect the voltmeter to the output.
2. Connect the 4.000k Ω resistor to the non-isolated connector, resistive programming of voltage, and voltage programming (J1.9-J1-11, and J1.7).
3. Set the resistive APG level to 4k Ω . The SCPI command is:
`SYST:COMM:APR:LEV 4`
4. Set the input source as Resistive Non-Isolated for Voltage Programming. The SCPI command is:
`SYST:REM:SOUR ARES`
5. Turn the main output On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
6. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL:RES`
7. Press the terminal keys – or + to reduce or increase main output voltage value. Adjust the main output voltage to 100%.
8. Press any key other than the + or – keys to exit from interactive calibration mode.

Non-isolated Voltage Programming of Current Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in steps 3 and 4.

To calibrate the non-isolated voltage programming of current:

1. Short the main output with a shunt. Connect a multimeter to measure the voltage across the shunt.
2. Connect the input voltage source to the non-isolated connector, current programming (J1.10 - J1.7).
3. Set the Voltage APG level to 4 V. The SCPI command is:
`SYST:COMM:APR:LEV:CURR 4`
4. Set the input source voltage to 4.000 V.
5. Set the input source as Voltage Non-Isolated for Current. The SCPI command is:
`SYST:REM:SOUR:CURR AVOL`
6. Turn the main output On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
7. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL:CURR`
8. Press the terminal keys – or + to reduce or increase the main output current value. Adjust the main output current to 100%.
9. Press any key other than the + or – keys to exit from interactive calibration mode.

Non-isolated Resistive Programming of Current Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating resistance level in steps 2 and 3.

To calibrate the non-isolated resistive programming of current:

1. Short the main output with a shunt. Connect a multimeter to measure the voltage across the shunt.
2. Connect the 4.000 k Ω resistor to the non-isolated connector (APG - J1), one terminal to resistive programming of current (J1.12) and voltage programming of current (J1.10), and the other terminal to the common (J1.7).
3. Set the resistive APG level to 4 k Ω . The SCPI command is:
`SYST:COMM:APR:LEV:CURR 4`
4. Set the input source as Resistive Non-Isolated for Current Programming. The SCPI command is:
`SYST:REM:SOUR:CURR ARES`
5. Turn the main output to On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
6. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL:CURR:RES`
7. Press the terminal keys – or + to reduce or increase the main output current value. Adjust the main output current to 100%.
8. Press any key other than the + or – keys to exit from interactive calibration mode.

Calibration Procedure for Isolated Modes

The main output and the non-isolated mode must be calibrated first.

Isolated Voltage Monitoring Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in steps 3 and 8.

To calibrate the isolated voltage monitoring:

1. Disconnect the load and connect the voltmeter to the output.
2. Connect the voltmeter to the isolated voltage monitoring output lines (J3.5 - J3.6).
3. Set the Voltage APG level to 4 V. The SCPI command is:
`SYST:COMM:APR:LEV 4`
4. Set the input source to local for voltage analog programming. The SCPI command is:
`SYST:REM:SOUR LOC`
5. Set the main output voltage to 100% by sending the command:
`SOUR:VOLT <ModelVolt>`
or use the rotary adjust/Enter control.
6. Turn the main output to On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
7. Enter the interactive calibration mode by sending the SCPI command:
`CAL:MON:ISOL`
8. Press the terminal keys – or + to reduce or increase the monitoring value. Adjust the monitoring value displayed on the voltmeter that was setup in Step 1 to read as close as possible to 4.000 V.
9. Press any key other than the + or – keys to exit from interactive calibration mode.

Isolated Current Monitoring Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in steps 3 and 8.

To calibrate the isolated current monitoring:

1. Short the main output with a shunt. Connect a multimeter to measure the voltage across the shunt.
2. Connect the voltmeter to the Isolated monitoring output lines (J3.10 and J3.6).
3. Set the current APG level to 4 V. The SCPI command is:
`SYST:COMM:APR:LEV:CURR 4`
4. Set the input source to local for voltage analog programming. the SCPI command is:
`SYST:REM:SOUR:CURR LOC`
5. Set the main output voltage to 100% by sending the command:
`SOUR:VOLT <ModelVolt>`
or use the rotary Adjust/Enter control.
6. Turn the main output to On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
7. Enter the interactive calibration mode by sending the SCPI command:
`CAL:MON:CURR:ISOL`
8. Press the terminal keys – or + to reduce or increase the monitoring value. Adjust the monitoring value displayed on the voltmeter that was set up in Step 1 to read as close as possible to 4.000 V.
9. Press any key other than the + or – keys to exit from interactive calibration mode.

Isolated Voltage Programming of Voltage Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in step 3.

To calibrate the isolated voltage programming of voltage:

1. Disconnect the load and connect the voltmeter to the output.
2. Connect the input voltage source to the Isolated connector (J3.3 and J3.6).
3. Set the Voltage APG level to 4 V. The SCPI command is:
`SYST:COMM:APR:LEV 4`
4. Set the input source voltage to 4.000 V.
5. Set the input source as Voltage Isolated for Voltage. The SCPI command is:
`SYST:REM:SOUR AVOL`
6. Turn the main output to On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
7. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL:ISOL`
8. Press on the terminal keys – or + to reduce or increase the main output voltage value. Adjust the main output voltage to 100%.
9. Press any key other than the + or – keys to exit from interactive calibration mode.

Isolated Resistive Programming of Voltage Calibration

Important: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating resistance level in step 3.

To calibrate the isolated resistive programming of voltage:

1. Disconnect the load and connect the voltmeter to the output.
2. Connect the 4.000 k Ω resistor to the isolated connector. One terminal to resistive programming of voltage (J3.8), and voltage programming of voltage (J3.3), and the other to common (J3.2).
3. Set the resistive APG level to 4 k Ω . The SCPI command is:
`SYST:COMM:APR:LEV 4`
4. Set input source as Resistive Isolated for Voltage Programming. The SCPI command is:
`SYST:REM:SOUR IAR`
5. Turn the main output to On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
6. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL:RES:ISOL`
7. Press on the terminal keys – or + to reduce or increase the main output voltage value. Adjust the main output voltage to 100%.
8. Press any key than the + or – keys to exit from interactive calibration mode.

Isolated Voltage Programming of Current Calibration

Important:: For maximum accuracy at a specific APG level. Follow the calibration procedure again but use the intended operating voltage level in step 3.

To calibrate the isolated voltage programming of current:

1. Short the main output with a shunt. Connect a multimeter to measure the voltage across the shunt.
2. Connect the input voltage source to the Isolated connector (J3.4 - J3.6).
3. Set the Current APG level to 4 V. The SCPI command is:
`SYST:COMM:APR:LEV:CURR 4`
4. Set the input source voltage to 4.000 V.
5. Set the input source as Voltage Isolated for Current. The SCPI command is:
`SYST:REM:SOUR:CURR IAV`
6. Turn the main output to On by pressing the OUTPUT ENABLE Main button on the front panel or send the command:
`:OUTP ON`
The OUTPUT ENABLE Main button will illuminate.
7. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL:CURR:ISOL`
8. Press the terminal keys – or + to reduce or increase the main output current value. Adjust the main output current to 100%.
9. Press any key other than the + or – keys to exit from the interactive calibration mode.

Isolated Resistive Programming of Current Calibration

To calibrate the isolated resistive programming of current:

1. Short the main output with a shunt. Connect a multimeter to measure the voltage across the shunt.
2. Connect the 4.000 k Ω resistor to the isolated connector. One terminal to resistive programming of current (J3.7), and voltage programming of current (J3.3), and the other to common (J3.2).
3. Set the Resistive APG level to 4 k Ω . The SCPI command is:
`SYST:COMM:APR:LEV:CURR 4`
4. Set the input source as Resistive Isolated for Current Programming. The SCPI command is:
`SYST:REM:SOUR:CURR IAR`
5. Turn the main output On or send the command:
`:OUTP ON`
6. Enter the interactive calibration mode by sending the SCPI command:
`CAL:OUTP:ANAL:CURR:RES:ISOL`
7. Press the terminal keys – or + to reduce or increase the main output current value. Adjust the main output current to 100%.
8. Press any key other than the + or – keys to exit from the interactive calibration mode.

Calibrating the Input Voltage APG Signal

The input voltage APG calibration is necessary to ensure accurate measurements when using the `:MEAS:APR?` and `:MEAS:APR:ISOL?` SCPI command queries to monitor the APG input signal.

Gain Calibration

To calibrate the VAP APG input gain:

1. Connect a voltmeter and a DC voltage source to the non-isolated voltage APG input lines (J1.9 and J1.7).
2. Turn the power supply On.
3. Set the Voltage APG level to 4 V.
Send the SCPI command: `SYST:COMM:APR:LEV 4`
4. Set the input source as Voltage analog APG. Send the SCPI command: `SYST:REM:SOUR:VOLT AVOL`
5. Set the voltage source attached to the non-isolated voltage APG input to 90% of the nominal voltage level, in this case 3.6 V.
6. Turn the output power on.
7. The power supply starts up in Constant Voltage mode.
8. Read the input voltage value from the voltmeter connected in step 1.
9. Type the SCPI input Voltage calibration command with voltage noted in step 8 as the parameter “data”.

For example, you would type `:CAL:INP:ANAL 3.53` if you were reading 3.53 volts from the voltmeter.

Offset Calibration

Offset calibration of the power supply provides the best accuracy in low-range input voltage.

To perform offset calibration:

1. Set the voltage source attached to the non-isolated Voltage APG input to 10% of the nominal voltage level, in this case 0.400 V.
2. Turn on the output power.
3. Read the input voltage value from the voltmeter connected in step 1 of the gain calibration.

4. Type SCPI input Voltage calibration command with voltage noted in step 3 as the parameter “data”.

For example, you would type `:CAL:INP:ANAL:CURR 0.43` if you read 0.43 volts from the voltmeter.

After performing offset calibration, it is highly recommended that you repeat gain calibration.

SCPI Command

```
[:]CALibration[<channel>]:INPut:ANALog[:VOLTage]
{<voltmeter reading in volts>}
```

Calibrating the Input Current APG Signal

The input voltage APG calibration is necessary to ensure accurate measurements when using the `:MEAS:APR?` and `:MEAS:APR:ISOL?` SCPI command queries to monitor the APG input signal.

Gain Calibration

To calibrate the CAP APG input gain calibration:

1. Connect a short across the power supply output.
2. Connect a voltmeter and a DC voltage source to the non-isolated current APG input lines (J1.10 and J1.7).
3. Turn the power supply On.
4. Set the Current APG level to 4 V. Send the SCPI command:
`SYST:COMM:APR:LEV:CURR 4`
5. Set the input source as Voltage analog APG. Send the SCPI command: `SYST:REM:SOUR:CURR AVOL`
6. Set the voltage source attached to the non-isolated current APG input to 90% of the nominal current level, in this case 3.6 V.
7. Turn the output power on.
8. The power supply starts up in Constant Current mode.
9. Read the input voltage value from the voltmeter connected in step 2.
10. Type the SCPI input current calibration command with voltage noted in step 9 as the parameter “data”.

For example, you would type `:CAL:INP:ANAL:CURR 3.49` if you were reading 3.49 volts from the voltmeter.

Offset Calibration

Offset calibration of the power supply provides the best accuracy in low-range input current.

To perform offset calibration:

1. Set the voltage source attached to the non-isolated current APG input to 10% of the nominal current level, in this case 0.400 V.
2. Turn the output power on.
3. Read the input voltage value from the voltmeter connected in step 2 of the gain calibration.
4. Type SCPI input current calibration command with voltage noted in step 3 as the parameter “data”.

For example, you would type `:CAL:INP:ANAL:CURR 0.43.`

After performing offset calibration, it is highly recommended that you repeat gain calibration.

SCPI Command

```
[:]CALibration[<channel>]:INPut:ANALog:CURRent{<voltmeter reading in volts>}
```

Storing and Loading Calibration Parameters

It is recommended that you save all the calibration parameters in a text file so they can be reloaded in the event of a flash failure or a mistake in calibration.

To get the calibration data, execute the following commands and save the response in a text file:

The SCPI command (s) to download all the calibration data are:

```
[ : ]CALibration:PARAmeter[ :OUTPut ]
[ : ]CALibration:PARAmeter:APROgram?
[ : ]CALibration:PARAmeter:INPut?
```

The response to these commands are in the 488.2 Arbitrary Program Block Data format.

If the calibration ever needs to be restored, you can execute the same commands and write the arbitrary block data response that was received in the query as the parameter.

For example, downloading the parameter data can be done from the hyper terminal as follows.

```
:cal:par?
#262#h2710,#h0000,#h2710,#h0000,#h2710,#h0000,#h2710,
#h0000,#h1AA4
:cal:par:apr?
#259#h7B,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h
7F,#h7F
:cal:par:inp?
#227#h2710,#h00,#h2710,#h00
```

To restore the XTR with a set of previously saved calibration values can be done as follows.

```
:cal:par
#262#h2710,#h0000,#h2710,#h0000,#h2710,#h0000,#h2710,#h0
000,#h1AA4
:cal:par:apr
#259#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h7F,#h
7F,#h7F
:cal:par:inp
#h227#h2710,#h00,#h2710,#h00
```

By saving and reloading the calibration parameters using these commands, you can calibrate the XTR for maximum accuracy for a specific load and then switch loads and load a calibration set that is accurate at maximum accuracy for the new load.

Restore Factory Calibration

Important: Factory calibration is not the same as the shipped calibration. Using this command will likely necessitate recalibrating all controls.

To restore factory calibration, use the SCPI command for returning the power supply to factory calibration settings.

The SCPI Command (s) for these instructions are:

```
[:]CALibration:REStore
```

User Diagnostics

If your power supply is not performing as described in this Manual, read through the procedures and checks in this chapter before calling your service technician. These procedures are limited to operator level functions only. They do not require cover-off servicing of the unit.

Emergency Shutdown

In an emergency, carry out these steps:

1. Shut the power supply OFF immediately.
2. Disconnect the mains supply.
3. Disconnect the power supply from the load.

Unusual or Erratic Operation

If the power supply displays any unusual or erratic operation, follow these steps:

1. Shut the power supply OFF immediately.
2. Disconnect the power supply from the load and external programming.
3. Test the power supply with no load, running the tests in “Step 5: Performing Functional Tests” on page 2–8.
4. If the tests show that the power supply is functioning normally, check all load, programming, and monitoring connections and circuits.
5. Check the AC input for correct voltage and frequency.

If the problem is not solved after you have followed this procedure, or if the unit fails to operate correctly upon retesting, call your service technician.

Troubleshooting for Operators

Refer to Table 6-1 to ensure that the power supply is configured and connected for normal operation. If you require any further troubleshooting assistance, call your service technician. See “Contact Information” on page iv.

Table 6-1 Troubleshooting

Symptom	Check	Further Checks and Corrections
The power supply is not operating. <i>FLA FAIL</i> is displayed.	Flash memory check sum error.	Do a reset. See page 3–39.

Important: The power supply will boot with default options and calibration values for the 6 V-110 A model.

A

SCPI Command Reference

Appendix A, SCPI Command Reference, provides a summary of the Standard Commands for Programmable Instruments (SCPI) that are supported by the XTR 850 Watt Series Programmable DC Power Supply.

SCPI Conformance Information

Codes and Standards

This power supply conforms to the following international standards:

- IEEE Std. 488.2-1992, “IEEE Standard Codes, Formats, Protocols, and Common Commands For Use With IEEE Std. 488.1-1987”
- IEEE Std. 488.1-1987 “IEEE Standard Digital Interface for Programmable Instrumentation”
- TIA/EIA-232F
- Standard Commands for Programmable Instruments (SCPI) Version 1999.0

IEEE 488.2 Requirements

GPIB control implements all IEEE 488.2 requirements.

SCPI Requirements

The power supply conforms to the following SCPI requirements:

- SCPI mandated commands
- Questionable Status Register (QSR), Condition, Event, Enable
- Operation Status Register (OSR), Condition, Event, Enable
- Status Byte Register (SBR)
- Standard Event Status Register (SESR)

IEEE 488.2/SCPI Syntax and Style

Parameters: Units of Measure and Multipliers

Refer to IEEE 488.2, section 7.7.3 for the definition of units of measure.

The default units of measure include:

- V (Volt – voltage)
- A (Ampere – current)
- W (Watt – power)
- S (seconds – time)

These units are only supported as defaults. To place the unit in the command will cause an error to be pushed into the error queue.

SCPI Command Hierarchy

A

SCPI is an ASCII-based command language designed for use in test and measurement equipment. The command structure is organized around common roots, or nodes, which are the building blocks of SCPI subsystems. An example of a common root is CALibration, and some of the commands that reside in the CALibration subsystem are:

```
[:]CALibration
  [:OUTPut]
    [:VOLTage]
      [:DATA] <NR1>
    :CURRent
      [:DATA] <NR1>
```

CALibration is the root keyword of the command. OUTPut is a second-level keyword, and VOLTage and DATA are third-level keywords. A colon (:) is used to separate a command keyword from a lower-level keyword.

Using SCPI Commands

This Manual shows SCPI commands in the following format:

```
CALibration:CURRent:LEVel {<current>|MIN|MAX}
```

The command is expressed as a mixture of upper- and lowercase letters. The uppercase letters suggest how the command can be abbreviated into a short form. SCPI commands can be sent in long or short forms. The short form is better for data entry. The long form is better for readability.

Command strings are not case sensitive: CURR, Curr, and curr are all acceptable abbreviations for CURRent. As for the long form, CURRENT, Current, and current are all acceptable. It is not possible to write for example, CALibrat:CURR:LEV because the extra first node does not explicitly match the short or long form of the calibration node.

The command strings include punctuation. While some punctuation is sent with the string, other markings are used to identify different elements of the command syntax and are not sent with the string.

The following punctuation is sent with the command string:

- **Colons (:)** separate command keywords from lower-level keywords. For example, CAL:CURR:STAT.
- **Blank spaces** separate command keywords from parameter values. For example, CURR 0.1.
- **Commas** separate parameters from each other when more than one parameter is sent in the same string. For example, CAL:STAT OFF,"1234."
- **Semicolons (;)** separate multiple commands from the same subsystem. This allows for greater efficiency.
For example: CAL:CURR:LEV MIN;VOLT:LEV MIN

is the same as typing:

```
CAL:CURR:LEV MIN
```

```
CAL:VOLT:LEV MIN
```

- **Colons and semicolons** can be used together to link commands from different subsystems. For example:

```
CAL:CURR:LEV MIN;:MEAS:CURR?
```

The short form is made up of 3 or 4 letters. There can only be an absolute short or long form. For example, it is not possible to write CALibrat:CURR:LEV because the extra the first node does not match explicitly the short or long form of the calibration node.

The following punctuation is not sent with the command string:

- **Braces** ({ }), or curly brackets, identify a selection of choices. Choose one of the enclosed values.
- **Vertical bars, or pipes**, (|) can be read as “or” and is used to separate the choices found within the braces.
- **Angle brackets** (< >) identify where specific values must be entered for a parameter. For example, in the example at the top of the page, the parameter <current> appears in the command string. To set the current set point to 0.1A, the syntax is `CAL:CURR:LEV 0.1`.
- **Square brackets** ([]) identify optional parameters. If an optional parameter is not sent with the command string, a default parameter is sent in its place.

Using Minimum and Maximum

In the following example, Minimum and Maximum are offered as alternative choices to declaring a specific parameter value.

```
CAL:CURRENT:LEVEL {<current>|MIN|MAX}
```

The string `CAL:CURR:LEV MIN` sets the current calibration level to the minimum model value.

Using Queries

A question mark lets you query the present value for most parameters. For example, to query the current calibration state use:

```
CAL:SEC:STAT?
```

You can also use the following to query minimum and maximum allowed values for most parameters:

```
:VOLT? MIN  
:VOLT? MAX
```

Important: If you send two queries, it is best to read and respond to the first response before trying to read the second. Otherwise, you may receive an incomplete first response followed by a complete second response. To avoid this, you can either wait for and read the first response before sending the second query, or send a device clear message before sending the second query.

Terminating Characters

Every command string must end with a terminating <new line> character. It is also acceptable to use a <carriage return> followed by a <new line>. Terminating a command string always resets the SCPI command path to the root level.

Common Commands

The IEEE-488.2 standard includes a set of common commands for functions such as reset and self-test. These common commands always start with an asterisk (*), contain 4 or 5 characters, and may have one or more parameters. The command is always separated from the parameter by a blank space. Multiple commands sent in the same string are separated by a semi-colon (;). The following is an example of how 3 common commands can be sent together in the same string:

```
*OPC; *PSC Off; *TRG
```

Parameter Types

Several different data types are defined for use in program messages and response messages.

A

Boolean Parameters

Boolean parameters are single binary conditions such as 1 and 0, or ON and OFF. The following is an example of a command that uses Boolean parameters:

```
SYST:COMM:GPIB:PONS {ON|OFF|1|0}
```

Discrete Parameters

Discrete parameters are used when program settings have a limited number of values. If you query a discrete parameter, the response will always be in the short form with all uppercase letters. The following is an example of a command that uses discrete parameters:

```
TRIG:SOUR {BUS|EXT|IMM|NONE}
```

Numeric Parameters

Numeric parameters are number representations such as decimal points, optional signs, and scientific notation. Values such as MINimum and MAXimum are accepted as substitutes for numbers. When DEFault is provided as a parameter, the machine selects the default value automatically. No units' suffix should be included with the parameter, only support for defaults units is available. In cases where specific numeric values are accepted, the power unit will round the input parameters. The following is an example of a command that uses numeric parameters:

```
VOLT:PROT {<voltage>|MAX|MIN}
```

String Parameters

String parameters are used when a series of ASCII characters is required. Strings must be enclosed within single or double quotations. The beginning and ending quotation marks must be matching. Quote delimiters may be included in the string by typing the quotation marks twice without any characters in between. The following is an example of a command that uses string parameters:

```
CAL:STAT ON, "0000"
```

SCPI Command Tree

The SCPI commands are organized into a tree structure. To illustrate the tree structure, the following tree has been provided. Each level of indentation presents a branch. The command to execute can then be found by following the tree from the root or farthest left node all the way down to the leaf node.

For example, to do the analog isolated programming command, start at the [:]CALibration root node, go through the :OUTPut node and then move down past the [:VOLTage] and :CURRent nodes which appear at that level to the :ANALog node and then move through the optional [:VOLTage] node to the :ISOLated node.

Thus, the command would then be
[:]CALibration:OUTPut:ANALog[:VOLTage]:ISOLated

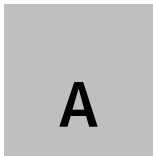
All commands can be formed by looking at this tree and taking the unique path from the root node to the leaf node. Table A-1 on page A-14 shows all the commands fully formed with parameters.

[:]CALibration

```

:PARAmeter
    :APROgram
    :INPut
    [ :OUTPut ]
:INPut
    :ANALog
        [ :VOLTage ]
        :CURRent
:OUTPut
    [ :VOLTage ]
    :CURRent
:MONitor
    [ :VOLTage ]
        :ISOLated
    :CURRent
        :ISOLated
:ANALog
    [ :VOLTage ]

```

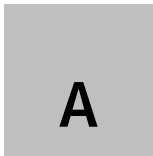



```

        :ISOLated
        :RESistive
            :ISOLated
        :CURRent
            :ISOLated
            :RESistive
                :ISOLated
    [ :VOLTage]
        :PROTection
            [ :OVER]
    :REStore
[ : ]INITiate
    [ :IMMediate]
[ : ]MEASure
    :AProgram
        [ :VOLTage]
            [ :DC]
                :ISOLated
                    [ :DC]
        :CURRent
            [ :DC]
                :ISOLated
                    [ :DC]
    [ :SCALar]
        [ :VOLTage]
            [ :DC]?
        :CURRent
            [ :DC]?
[ : ]OUTPut
    :PROTection
        :CLEar
        :FOLDback
            [ :MODE]
        :DELay
        :LATCh
    
```

SCPI Command Reference

```
:POLarity
[:POWER]
  [:STATe]
  :PowerON
    [:STATe]
:AUXilliary
  [:STATe]
  :PowerON
    [:STATe]
[:]PROGRAM
:READback
:STATe
[:RECORD]
  :START
  :STOP
:DElete
  [:ALL]
:REPeat
[:STEP]
  :DWELl
[[:]SOURCE]
:COMBine
  :CSHare
    [:MODE]
:VOLTage
  [:LEVEl]
    [:IMMediate]
      [:AMPLitude]
:PROTection
  [:OVERvoltage]
    [:LEVEl]
  :UNDer
    [:LEVEl]
:CURRent
  [:LEVEl]
```



```

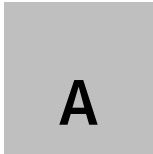
    [ :IMMEDIATE]
        [ :AMPLITUDE]

[ :]SENSE:
    :PROTECTION
        :INTERLOCK
            [ :STATE]
        :TEMPERATURE
            [ :LATCH]

[ :]STATUS
    :PRESET
    :QUESTIONABLE
        [ :EVENT]?
        :ENABLE
        :CONDITION
        :PTRANSITION
        :NTRANSITION
        :VOLTAGE
            [ :EVENT]?
            :ENABLE
            :CONDITION?
            :PTRANSITION
            :NTRANSITION
        :CURRENT
            [ :EVENT]?
            :ENABLE
            :CONDITION?
            :PTRANSITION
            :NTRANSITION
        :TEMPERATURE
            [ :EVENT]?
            :ENABLE
            :CONDITION?
            :PTRANSITION
            :NTRANSITION
    
```

SCPI Command Reference

```
:OPERation
  [:EVENT]?
  :ENABle
  :CONDition?
  :PTRansition
  :NTRansition
  :CSHare
    [:EVENT]?
    :ENABle
    :CONDition?
    :PTRansition
    :NTRansition
:SHUTdown
  [:EVENT]?
  :ENABle
  :CONDition
  :PTRansition
  :NTRansition
  :PROTection
    [:EVENT]?
    :ENABle
    :CONDition?
    :PTRansition
    :NTRansition
:STANdard
  [:EVENT]?
  :ENABle
:CLEar
:SBYTe
  [:EVENT]?
:SREQuest
  [:ENABle]
[:]SYSTEM
  :FPANel
  [:TIMEout]
```



```

:PROTection
    :LATCh
    [ :MAsK ]
:RESet
:WAIT
:TEST?
:RESet
:IDENtify?
:REMOte
    :STATe
    :SOURce
        [ :VOLTagE ]
        :CURRent
:COMMUnicate
    :APROgram
        :LEVel
            [ :VOLTagE ]
            [ :ISOLated ]
        :CURRent
            [ :ISOLated ]
    [ :MCHannel ]
        :ADDRESS
:SAVE
:RECall
:VERSIon?
:ERRor
    [ :NEXT ]?
    :CODE
        [ :NEXT ]?
    :COUNT?
:HELP
    [ :HEADers ]?
    :SYNTax?

```

SCPI Command Summary

The SCPI commands supported by this programmable power supply are described in the tables in the remainder of this section. These tables use the following column headings:

- **Function** The commonly used name for the function.
- **SCPI Command** The full command in long form.
- **Description** Explains what the command does or what is affected by it.
- **Query?** Indicates whether the unit supports a query version of the listed command. **N/A** indicates Not applicable. (The command has no query form and will respond with an error if queried.)

Table A-1 IEEE 488.2 Commands

Function	SCPI Command	Description	Parameter and Range	Query
Select Address	*ADR	Select the power supply unit to communicate with.	? <Address (1–30)>	Yes
Clear Status	*CLS [:]STATUS[<channel>]:CLEAR	Clears all the status data structures.		N/A
Query the Error Queue	*ERR	Query the Error Queue for the oldest error event.		
Standard Event Status Enable Query	*ESE? [:]STATUS[<channel>]:STANDARD:ENABLE	Query the Standard Event Status Enable register settings.		Yes
Standard Event Status Enable	*ESE [:]STATUS[<channel>]:STANDARD:ENABLE <ESE-word>	Set the Standard Event Status Enable Register bits.	<Enable Flags(0–255)>	N/A
Standard Event Status Register Query	*ESR? [:]STATUS[<channel>]:STANDARD[:EVENT]?	Query the Standard Event Status Register (SERS).		Yes

Table A-1 IEEE 488.2 Commands (Continued)

Display All SCPI Command Headers	*HELP?	Display all the SCPI command headers available on this device.		Yes
Identification Query	*IDN? [:]SYSTem[<channel>]:IDENtify?	Query device identification string.		Yes
Operation Complete Command	*OPC	Operation Complete Command		N/A
Query Operation Complete Command	*OPC?	Operation Complete Query		Yes
Recall	*RCL OR [:]SYSTem[<channel>]:RECall <setting_location>	Recall a User Memory Setting. See *SAV below.	<Setting Index (1–5)>	N/A
Reset	*RST [:]SYSTem[<channel>]:RESet	Resets all values to default state (excluding calibration data).		N/A
Save User Settings	*SAV [:]SYSTem[<channel>]:SAVE <setting_location>	Save a User Memory Setting.		N/A
Query Service Request Enable	*SRE? [:]STATus[<channel>]:SREQuest:ENABle?	Service Request Enable Query		Yes
Service Request Enable	*SRE [:]STATus[<channel>]:SREQuest:ENABle <status-enable>	Service Request Enable Command	<Enable Flags(0–255)>	N/A
Read Status Byte	*STB? [:]STATus[<channel>]:SBYTe[EVENT]?	Read the status byte.		Yes

Table A-1 IEEE 488.2 Commands (Continued)

Trigger	*TRG	Trigger system		N/A
Self-Test Query	*TST? [:]SYSTem[<channel>]:TEST?	Perform unit Self Test (Pass=0).		Yes
Wait To Continue	*WAI [:]SYSTem[<channel>]:WAIT	Wait to continue command.		N/A

Table A-2 Readback Commands

Function	SCPI Command	Description	Parameter and Range	Query
Read Output Current	[:]MEASure[<channel>][:SCALar]:CURRent[:DC]?	Measure and readback output current at the output terminals.		Yes
Read Output Voltage	[:]MEASure[<channel>][:SCALar][:VOLTage[:DC]?	Measure and readback output voltage at the output terminals.		Yes
Read APG Input Voltage	[:]MEASurement[:SCALar]:APROgram[:VOLTage[:DC]?	Measure and readback the voltage being input to the non isolated voltage analog programming input pin.		Yes
Read Isolated APG Input Voltage	[:]MEASurement[:SCALar]:APROgram[:VOLTage]:ISOLated[:DC]?	Measure and readback the voltage being input to the isolated voltage analog programming input pin.		Yes
Read APG Input Voltage	[:]MEASurement[:SCALar]:APROgram:CURRent[:DC]?	Measure and readback the voltage being input to the non isolated current analog programming input pin.		Yes
Read APG Input Voltage	[:]MEASurement[:SCALar]:APROgram:CURRent:ISOLated[:DC]?	Measure and readback the voltage being input to the isolated current analog programming input pin.		Yes

Table A-3 SCPI Commands for Output Control

Function	SCPI Command	Description	Parameter and Range	Query
Set Current Sharing Mode	[[[:]]SOURCE[<channel>]]:COMBine:CSHare[:MODE]	Set the XTR to operate in the current share master or slave mode. If only a single unit is being used it should be set to master.	? MASTER SLAVE	Yes
Set Output latches for the alarms	[[[:]]SOURCE[<channel>]]:COMBine:CSHare[:MODE]	Sets the output latches for the alarms.	? <alarm sum of latch flags>	Yes
Set (Immediate) Current Set point	[[[:]]SOURCE[<channel>]]:CURRent[:LEVEl][:IMMEdiate][:AMPLitude]	Set current set point (immediate)	? <Current Set Point> MAXimum MINimum	Yes
Set (Immediate) Voltage Set point	[[[:]]SOURCE[<channel>]]:VOLTage[:LEVEl][:IMMEdiate][:AMPLitude]	Change voltage set point (immediate)	? <Voltage Set Point> MAXimum MINimum	Yes
Set Over Voltage Protection Level	[[[:]]SOURCE[<channel>]]:VOLTage:PROTEction[:OVERvoltage][:LEVEl]	Set the over voltage protection level.	? <OVP Set Point> MAXimum MINimum	Yes
Set Under Voltage Protection Level	[[[:]]SOURCE[<channel>]]:VOLTage:PROTEction:UNDer[:LEVEl]	Set the under voltage protection level.	? <UVP Set Point> MAXimum MINimum	Yes

Table A-4 SCPI Commands for Calibration

Function	SCPI Command	Description	Parameter and Range	Query
Restore Factory Calibration	[:]CALibration[<channel>]:RESTore	Restores the calibration to the factory defaults.	N/A	N/A
Calibrate OVP protection.	[:]CALibration[<channel>][:VOLTage]:PROTection[:OVER]	Calibrate the over voltage protection.	<OVP Voltage Set in Volts>	No
Enter Output Voltage Data	[:]CALibration[<channel>]:OUTPut:VOLTage	Sets the voltage output calibration level.	<Voltage set in volts>	No
Enter Output Current Data	[:]CALibration[<channel>]:OUTPut:CURRent	Sets the current output calibration level	<Current set in amps>	No
Calibrate the Voltage controlled Non Isolated Voltage APG feature	[:]CALibration[<channel>]:MONitor[:VOLTage]	Calibrate the voltage monitor signal system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Voltage controlled Isolated Voltage APG feature	[:]CALibration[<channel>]:MONitor[:VOLTage]:ISOLated	Calibrate the isolated voltage monitor signal system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Voltage controlled Non Isolated Current APG feature	[:]CALibration[<channel>]:MONitor:CURRent	Calibrate the current monitor signal system.	? <NR1> <nothing for interactive mode>	Yes

Table A-4 SCPI Commands for Calibration (Continued)

Calibrate the Voltage controlled Isolated Current APG feature	[:]CALibration[<channel>]:MONitor :CURRent :ISOLated	Calibrate the isolated current monitor signal system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Voltage APG Input	[:]CALibration:INPut :ANALog[:VOLTage]	Calibrates the isolated and non-isolated VAP measurement commands.	<? NR1>	Yes
Calibrate the Current APG Input	[:]CALibration:INPut :ANALog:CURRent	Calibrates the isolated and non-isolated CAP measurement commands.	<? NR1>	Yes
Calibrate the Voltage controlled Non Isolated Voltage APG feature	[:]CALibration[<channel>]:OUTPut :ANALog[:VOLTage]	Calibrate the voltage analog programming system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Voltage controlled Isolated Voltage APG feature	[:]CALibration[<channel>]:OUTPut :ANALog[:VOLTage]:ISOLated	Calibrates the voltage analog programming system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Voltage controlled Non Isolated Current APG feature	[:]CALibration[<channel>]:OUTPut :ANALog:CURRent	Calibrate the current analog programming system.	? <NR1> <nothing for interactive mode>	Yes

Table A-4 SCPI Commands for Calibration (Continued)

Calibrate the Voltage controlled Isolated Current APG feature	[:]CALibration[<channel>]:OUTPut :ANALog:CURRent:ISOLated	Calibrates the current analog programming system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Resistive controlled Non Isolated Voltage APG feature	[:]CALibration[<channel>]:OUTPut :ANALog[:VOLTagE]:RESistive	Calibrate the Resistive controlled voltage analog programming system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Resistive controlled Isolated Voltage APG feature	[:]CALibration[<channel>]:OUTPut :ANALog[:VOLTagE] :RESistive:ISOLated	Calibrates the Resistive controlled voltage analog programming system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Resistive controlled Non Isolated Current APG feature	[:]CALibration[<channel>]:OUTPut :ANALog:CURRent:RESistive	Calibrate the Resistive controlled current analog programming system.	? <NR1> <nothing for interactive mode>	Yes
Calibrate the Resistive controlled Isolated Current APG feature	[:]CALibration[<channel>]:OUTPut :ANALog:CURRent:RESistive:ISOLated	Calibrates the Resistive controlled current analog programming system.	? <NR1> <nothing for interactive mode>	Yes

Table A-4 SCPI Commands for Calibration (Continued)

Get Output Calibration Parameters	[:]CALibration[<channel>]:PARAmeter [:OUTPut]	Queries and loads the output calibration parameters in arbitrary program block data format.	? <arbitrary program block data>	Yes
Get Analog Programming Calibration Parameters	[:]CALibration[<channel>]:PARAmeter :APROgram	Queries and loads the APG calibration parameters in arbitrary program block data format.	? <arbitrary program block data>	Yes

Table A-5 SCPI Commands to Clear All Protection Mechanisms

Function	SCPI Command	Description	Parameter and Range	Query
Clear Output Protection	[:]OUTPut[<channel>]:PROTection:CLEAr	Clears the currently set alarms.		N/A

Table A-6 SCPI Commands for Foldback Protection

Function	SCPI Command	Description	Parameter and Range	Query
Set Output Foldback Delay	[:]OUTPut[<channel>]:PROTection :FOLDback:DELAy	Set the delay time (seconds) before foldback protection is triggered.	? <Delay - (0.5-50)>	Yes
Set Output Foldback Mode	[:]OUTPut[<channel>]:PROTection :FOLDback[:MODE]	Select condition for foldback.	? CV CC NONE	Yes

Table A-7 SCPI Commands for Power

Function	SCPI Command	Description	Parameter and Range	Query
Shutdown Logic Control	[:]OUTPut:POLarity	Sets the TTL level that will trigger an External Shutdown.	? HIGH LOW	Yes
Main Output Control	[:]OUTPut[:POWER][:STATE]	Control Main Output State (Enable/Disable)	? ON OFF	Yes
Power On Main Output Control	[:]OUTPut[:POWER]:PON[:STATE]	Control Main Output Autostart State (Enable/Disable)	? ON OFF	Yes
Aux Output Control	[:]OUTPut:AUXilliary[:STATE]	Control Aux Output State (Enable/Disable)	? ON OFF	Yes
Power Auxiliary Output Control	[:]OUTPut:AUXilliary:PON[:STATE]	Control Aux Output Autostart State (Enable/Disable)	? ON OFF	Yes

Table A-8 SCPI Commands for Triggering

Function	SCPI Command	Description	Parameter and Range	Query
Set Immediate Initiation of Trigger System	[:]INITiate[<channel>][:IMMEDIATE]	Triggers the Autosequence Program.		N/A

Table A-9 System Commands

Function	SCPI Command	Description	Parameter and Range	Query
Set the menu system timeout	[:]SYSTem:FPANel [:TIMEout]	Sets the menu system timeout.	<1–20 to one decimal place seconds>	Yes
Resets the Instrument to default values.	[:]SYSTem[<channel>]:RESet	Resets all values to default state (excluding calibration data).		N/A
Wait to Continue	[:]SYSTem[<channel>]:WAIT	Wait to continue command.		N/A
Self Test	[:]SYSTem[<channel>]:TEST?	Perform unit Self test, returns 0 if pass, non zero value for failure.		Yes
ID Query	[:]SYSTem[<channel>]:IDENTify	Query device ID string.		Yes
Save User Preset	[:]SYSTem[<channel>]:SAVE	Save the user preset values. Select any slot from 1-5.	<Setting Index (1–5)>	No
Recall User Preset (previously saved)	[:]SYSTem[<channel>]:RECall	Load the user preset values. Select any slot from 1-5.	<Setting Index (1–5)>	No
Query System Error	[:]SYSTem[<channel>]:ERRor [:NEXT]?	Returns the next error in the instrument's error queue		Yes
Query System Error Code	[:]SYSTem[<channel>]:ERRor:CODE [:NEXT]?	Returns the error code only for the next error in the instrument's error queue.		Yes

Table A-9 System Commands (Continued)

Query the Error Queue for the number of entries.	[:]SYSTem[<channel>]:ERRor:COUNT?	Returns the number of errors currently in the error queue.		Yes
Select Voltage Analog Programming Input Voltage Input Level/ Range	[:]SYSTem[<channel>]:COMMunicate :APROgram:LEVel[:VOLTage][:ISOLated]	Select level for Voltage APG. Level can be between 2 -10 volts.	? <Level (2-10)> MAXimum MINimum	Yes
Select Current Analog Programming Input Voltage Input Level/ Range	[:]SYSTem[<channel>]:COMMunicate :APROgram:LEVel:CURRent[:ISOLated]	Select level for Current APG. Level can be between 2 -10 volts.	? <Level(2-10)> MAXimum MINimum	Yes
Select the address to communicate with.	[:]SYSTem[<channel>]:COMMunicate [:MCHannel]:ADDRESS	Select the current device to receive the commands. The parameter for this command is the address set on the front panel under the remote		Yes
Select Address	[:]SYSTem:COMMunicate[:SELF]:ADDRESS	Select the power supply unit to communicate with.	? <Address (1-30)	Yes
Setup the Voltage control APG source	[:]SYSTem[<channel>]:REMote:SOURce [:VOLTage]	Alter or query the state of the remote programming voltage APG source.	? LOCAL AVOLtag e IAVoltage AResistive IAResistive	Yes

Table A-9 System Commands (Continued)

Setup the Current control APG source	[:]SYSTem[<channel>]:REMOte:SOURce:CURRent	Alter or query the state of the remote programming current APG source.	? LOCal AVOLtag e IAVoltage ARE Sistive IAREsis tive	Yes
Set Front Panel lock state.	[:]SYSTem[<channel>]:REMOte:STATE	Change front panel control mode	? LOCal REMote	Yes
Query SCPI Version	[:]SYSTem[<channel>]:VERSion?	Returns the SCPI version to which the instrument complies. Format is YYYY.V		Yes
SCPI Help	[:]SYSTem[<channel>]:HELP[:HEADers]?	Query system for all supported SCPI command headers.		Yes
Legacy Help	[:]SYSTem[<channel>]:HELP:LEGacy?	Query the system for all supported legacy commands.		Yes
Command Syntax Help	[:]SYSTem[<channel>]:HELP:SYNTax?	Query the system for the syntax of a command. The command should be input after the query as a string parameter. To enter a command you should do this by typing the command as you would on the command line without parameters. To find all command headers see [:]SYSTem:HELP[:HEADers]?	<COMMAND>	Yes
Alarm Masking	[:]SYSTem[<channel>]:PROTEction[:MASK]	Enable/disable alarms/protection.	? <Alarm Mask - (0–255)	Yes

Table A-9 System Commands (Continued)

Set Alarm Output Latches	[:]SYSTem:PROTection:LATCh	Sets the Alarm Output Latches. See Table 3-6 on page 3-22.	? <Sum of output latch flags>	Yes
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Table A-10 Status Commands

Function	SCPI Command	Description	Parameter and Range	Query
Query Operation Status Condition Register	[:]STATus[<channel>]:OPERation:CONDition?	Query the Operations Condition Register. See Table 5-11 on page 5-36.		Yes
Set Operation Status Enable Register	[:]STATus[<channel>]:OPERation:ENABLE	Access the Operations Enable Register. See Table 5-11 on page 5-36.	? <Enable Flags - (0-65535)>	Yes
Query Operation Status Event Register	[:]STATus[<channel>]:OPERation[:EVENT]?	Query the Operations Event Register. See Table 5-11 on page 5-36.		Yes
Set Operation Status Negative Transition Register	[:]STATus[<channel>]:OPERation:NTRansition	Access the Operation Negative Trans Filter Register. See Table 5-11 on page 5-36.	? <Transition Flags - (0-65535)>	Yes
Set Operation Status Positive Transition Register	[:]STATus[<channel>]:OPERation:PTRansition	Access the Operation Positive Trans Filter Register. See Table 5-11 on page 5-36.	? <Transition Flags - (0-65535)>	Yes

Table A-10 Status Commands (Continued)

Query Operation Status Shutdown Condition Register	[:]STaTus[<channel>]:OPERation :SHUTdown:CONDition?	See Table 5-12 on page 5– 37.	Query the Operation Shutdown Condition Register	Yes
Set Operation Status Shutdown Enable Register	[:]STaTus[<channel>]:OPERation :SHUTdown:ENABle	Access the Operation Shutdown Enable Register. See Table 5-12 on page 5– 37.	? <Enable Flags - (0–65535)>	Yes
Query Operation Status Shutdown Event Register	[:]STaTus[<channel>]:OPERation :SHUTdown[:EVENT]?	See Table 5-12 on page 5– 37.	Query the Operation Shutdown Event Register	Yes
Set Operation Status Shutdown Negative Transition Register	[:]STaTus[<channel>]:OPERation :SHUTdown:NTRansition	See Table 5-12 on page 5– 37.	? <Transition Flags - (0–65535)>	Yes
Set Operation Status Shutdown Positive Transition Register	[:]STaTus[<channel>]:OPERation :SHUTdown:PTRansition	Access the Operation Shutdown Positive Trans Filter Register. See Table 5-12 on page 5– 37.	? <Transition Flags - (0–65535)>	Yes

Table A-10 Status Commands (Continued)

Query Operation Status Shutdown Protection Condition Register	[:]STATUS[<channel>]:OPERATION:SHUTDOWN:PROTECTION:CONDITION?	Query the Operation Shutdown Protection Condition Register. See Table 5-12 on page 5-37.		Yes
Set Operation Status Shutdown Protection Enable Register	[:]STATUS[<channel>]:OPERATION:SHUTDOWN:PROTECTION:ENABLE	Access the Operation Shutdown Protection Enable Register. See Table 5-12 on page 5-37.	? <Enable Flags - (0-65535)>	Yes
Query Operation Status Shutdown Protection Event Register	[:]STATUS[<channel>]:OPERATION:SHUTDOWN:PROTECTION[:EVENT]?	Query the Operation Shutdown Protection Event Register. See Table 5-12 on page 5-37.		Yes
Set Operation Status Shutdown Protection Negative Transition Register	[:]STATUS[<channel>]:OPERATION:SHUTDOWN:PROTECTION:NTRANSITION	Register. See Table 5-12 on page 5-37.	? <Transition Flags - (0-65535)>	Yes

Table A-10 Status Commands (Continued)

Set Operation Status Shutdown Protection Positive Transition Register	[:]STATUS[<channel>]:OPERation :SHUTdown:PROTEction:PTRansition	Access the Operation Shutdown Protection Positive Trans Filter Register. See Table 5-12 on page 5-37.	? <Transition Flags - (0-65535)>	Yes
Query Operation Status Event Register	[:]STATUS[<channel>]:OPERation :CSHare[:EVENT]?	Query the Operations Event Register. See Table 5-11 on page 5-36.		Yes
Set Operation Status Enable Register	[:]STATUS[<channel>]:OPERation :CSHare:ENABLE	Access the Operations Enable Register. See Table 5-11 on page 5-36.	? <Transition Flags - (0-65535)>	Yes
Query Operation Status Condition Register	[:]STATUS[<channel>]:OPERation :CSHare:CONDition?	Query the Operations Condition Register. See Table 5-11 on page 5-36.		Yes
Set Operation Status Positive Transition Register	[:]STATUS[<channel>]:OPERation :CSHare:PTRansition	Access the Operation Positive Trans Filter Register. See Table 5-11 on page 5-36.	? <Transition Flags - (0-65535)>	Yes
Set Operation Status Negative Transition Register	[:]STATUS[<channel>]:OPERation :CSHare:NTRansition	Access the Operation Negative Trans Filter Register. See Table 5-11 on page 5-36.	? <Transition Flags - (0-65535)>	Yes

Table A-10 Status Commands (Continued)

Preset Enable, Positive Transition and Negative Transition Status Registers	[:]STATUS[<channel>]:PRESet	Restores the configuration of the SCPI status registers to known reporting conditions, IE Transition registers and enable register. See “Status Reporting in SCPI” on page 5–25 for more details.		Yes
Query Questionable Status Condition Register	[:]STATUS[<channel>]:QUESTionable :CONDition?	Query the Questionable Condition Register. See Table 5-15 on page 5–45.		Yes
Set Questionable Status Enable Register	[:]STATUS[<channel>]:QUESTionable :ENABle	Access the Questionable Enable Register. See Table 5-15 on page 5–45.	? <Enable Flags - (0–65535)>	Yes
Query Questionable Status Event Register	[:]STATUS[<channel>]:QUESTionable [:EVENT]?	Query the Questionable Event Register. See Table 5-15 on page 5–45.		N/A
Set Questionable Status Negative Transition Register	[:]STATUS[<channel>]:QUESTionable :NTRansition	Access the Questionable Negative Trans Filter Register. See Table 5-15 on page 5–45.	? <Transition Flags - (0–65535)>	Yes
Set Questionable Status Positive Transition Register	[:]STATUS[<channel>]:QUESTionable :PTRansition	Access the Questionable Positive Trans Filter Register. See Table 5-15 on page 5–45.	? <Transition Flags - (0–65535)>	

Table A-10 Status Commands (Continued)

Query Questionable Status Current Condition Register	[:]STATUS[<channel>]:QUESTIONABLE :CURRENT:CONDITION?	See Table 5-15 on page 5-45.		Yes
Set Questionable Status Current Enable Register	[:]STATUS[<channel>]:QUESTIONABLE :CURRENT:ENABLE	See Table 5-15 on page 5-45.	? <Enable Flags-(0-65535)>	Yes
Query Questionable Status Current Event Register	[:]STATUS[<channel>]:QUESTIONABLE :CURRENT[:EVENT]?	See Table 5-15 on page 5-45.		Yes
Query Questionable Status Temperature Condition Register	[:]STATUS[<channel>]:QUESTIONABLE :TEMPERATURE:CONDITION?	Query the Questionable Temp Conditions Register. See Table 5-15 on page 5-45.		Yes
Set Questionable Status Temperature Enable Register	[:]STATUS[<channel>]:QUESTIONABLE :TEMPERATURE:ENABLE	Access the Questionable Temp Enable Register. See Table 5-15 on page 5-45.	? <Enable Flags - (0-65535)>	Yes
Query Questionable Status Temperature Event Register	[:]STATUS[<channel>]:QUESTIONABLE :TEMPERATURE[:EVENT]?	Query the Questionable Temp Event Register. See Table 5-15 on page 5-45.		Yes

Table A-10 Status Commands (Continued)

Set Questionable Status Temperature Negative Transition Register	[:]STATUS[<channel>]:QUESTIONABLE:TEMPERATURE:NTRANSITION	Access the Questionable Temp Negative Trans Filter Register. See Table 5-15 on page 5-45.	? <Transition Flags - (0-65535)>	Yes
Set Questionable Status Temperature Positive Transition Register	[:]STATUS[<channel>]:QUESTIONABLE:TEMPERATURE:PTRANSITION	Access the Questionable Temp Positive Trans Filter Register. See Table 5-15 on page 5-45.	? <Transition Flags - (0-65535)>	Yes
Query Questionable Status Voltage Condition Register	[:]STATUS[<channel>]:QUESTIONABLE:VOLTAGE:CONDITION?	See Table 5-15 on page 5-45.	Query the Questionable Voltage Condition Register	Yes
Set Questionable Status Voltage Enable Register	[:]STATUS[<channel>]:QUESTIONABLE:VOLTAGE:ENABLE	Access the Questionable Volt Enable Register. See Table 5-15 on page 5-45.	? <Enable Flags - (0-65535)>	Yes
Query Questionable Status Voltage Event Register	[:]STATUS[<channel>]:QUESTIONABLE:VOLTAGE[:EVENT]?	Query the Questionable Volt Event Register. See Table 5-15 on page 5-45.		Yes

Table A-10 Status Commands (Continued)

Set Questionable Status Voltage Negative Transition Register	[:]STATUS[<channel>]:QUESTionable :VOLTagE:NTRansition	Access the Questionable Voltage Negative Trans Filter Register. See Table 5-15 on page 5-45.	? <Transition Flags - (0-65535)>	Yes
Set Questionable Status Voltage Positive Transition Register	[:]STATUS[<channel>]:QUESTionable :VOLTagE:PTRansition	Access the Questionable Voltage Positive Trans Filter Register. See Table 5-15 on page 5-45.	? <Transition Flags - (0-65535)>	Yes
Query the Standard Event register (ESR?)	[:]STATUS[<channel>]:STANdard[:EVENT]?	See Table 5-10 on page 5-32. Same as *ESR.	Query the Standard Event Status Register (SERS).	Yes
Enable the Standard Event register (*ESE,*ESE?)	[:]STATUS[<channel>]:STANdard:ENABle	Access the Standard Event Status Register (SERS) Enable Flags. See Table 5-10 on page 5-32. Same as *ESE.	? <Enable Flags - (0-255)>	Yes
Query the Status Byte (*STB)	[:]STATUS[<channel>]:SBYTe[:EVENT]?	Query the Status Byte. See Table 5-10 on page 5-32.		Yes
Service Request Enable (*SRE,*SRE?)	[:]STATUS[<channel>]:SREQuest:ENABle	Access Service Request Enable Command.	? <Enable Flags - (0-255)>	Yes
	[:]STATUS[<channel>]:CLEar	Clears all the Status Data Structures.		

Table A-11 Protection Commands

Function	SCPI Command	Description	Parameter and Range	Query
Enable the interlock functionality.	[:]SENSe[<channel>]:PROTection :INTeRlock[:STATe]	Control the Enable/Disable state of the Interlock System.	? ON OFF	Yes

Table A-12 Auto Sequence Commands

Function	SCPI Command	Description	Parameter and Range	Query
Delete all sequences.	[:]PROGAm[<channel>]:DELeTe:ALL	Erases the sequence currently in memory.		N/A
Change Auto Sequence operating state.	[:]PROGAm[<channel>]:STATe	Access to the run state of the Sequence.	? RUN STOP PAUSE	Yes
Program selected sequence end action.	[:]PROGAm[<channel>]:REPeAT	Sets the number of times to repeat the sequence.	? <Repeat count (1–65534) INFinity	Yes
Begin Recording Auto Sequence Program	[:]PROGAm[<channel>][:RECOrd]:START	Start recording new sequence (overwrites old sequence).		N/A
Stop Recording Auto Sequence Program	[:]PROGAm[<channel>][:RECOrd]:STOP	Stop recording the auto sequence program. (Sequence ready to run.)		N/A

Table A-12 Auto Sequence Commands (Continued)

Function	SCPI Command	Description	Parameter and Range	Query
Set the Program Command Execution Delay Time	[:]PROGram[<channel>] [: STEP] : DWEL1	Sets the amount of time to delay between commands in a Sequence.	? <Dwell time in seconds>	Yes
Read the current contents of the Autosequence programming buffer.	[:]PROGram[<channel>] : READback?	Read the current contents of the Autosequence programming buffer.	?	Yes

B

Error Messages

Appendix B, Error Messages, provides information on the error messages which may appear. Errors are placed in a queue as they are detected.

Error Messages

Errors are placed in a queue as they are detected. The queue works on a first in, first out (FIFO) basis. If the queue overflows, the last error in the queue is replaced with error -350, "Queue Overflow". When all errors have been read from the queue, further error queries return 0, "No error".

The error queue is cleared when any of the following occur (IEEE 488.2, section 11.4.3.4):

- Upon receipt of a *CLS command
- Upon reading the last item from the queue

Command Error List

An error in the range [-199, -100] indicates that an IEEE 488.2 syntax error has been detected by the instrument's parser. The occurrence of any error in this class causes the command error bit (bit 5) in the Event Status Register to be set.

Table B-1 Command Error List

Error Code	Error Message Description
-100	Command error This is the generic syntax error
-102	Syntax Error An unrecognized command or data type was encountered; for example, a string was received when the device does not accept strings.
-108	Parameter not Allowed More parameters were received than expected for the header; for example, the *SRE common command only accepts one parameter, so receiving *SRE 0,1 is not allowed.
-109	Missing Parameter Fewer parameters were received than required for the header; for example, the *SAV common command requires one parameter, so receiving *SAV is not allowed.
-110	Command header error An error was detected in the header.
-113	Undefined header The header is syntactically correct, but it is undefined for this specific device; for example, *XYZ is not defined for any device.
-121	Invalid character in number An invalid character for the data type being parsed was encountered; for example, an alpha in a decimal numeric or a "9" in octal data.
-140	Character data error This error is generated when parsing a character data element.
-150	String data error This error is generated when parsing a string data element fails.
-151	Invalid string data A string data element was expected, but was invalid for some reason (see <i>IEEE 488.2, 7.7.5.2</i>); for example, an END message was received before the terminal quote character.

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Execution Error List

An error in the range [-299, -200] indicates that an error has been detected by the instrument's execution control block. The occurrence of any error in the class causes the execution error bit (bit 4) in the Event Status Register to be set.

Execution errors are reported by the device after rounding and expression evaluation operations have taken place.

Table B-2 Execution Error List

Error Code	Error Message Description
-200	<p>Execution Error</p> <p>This is the generic syntax error for devices that cannot detect more specific errors. This code indicates only that an Execution Error as defined in <i>IEEE 488.2</i>, 11.5.1.1.5 has occurred.</p>
-203	<p>Command protected</p> <p>Indicates that a legal password-protected program command or query could not be executed because the command was disabled. Check the calibration state.</p>
-220	<p>Parameter error</p> <p>Indicates that a program data element related error has occurred</p>
-221	<p>Setting conflict</p> <p>Indicates that a legal program data element was parsed, but could not be executed due to the current power supply state.</p> <p>The following list is not exhaustive but does cover some of the more common conditions that may contribute to this error:</p> <ul style="list-style-type: none"> • OVP/UVS Set Points —The OVP and UVP limit the setting of the voltage set point so that you cannot accidentally trigger these alarms by changing the set point outside of their range. Conversely, setting the OVP set point to be less than the voltage set point will also trigger this error. • Changing the Set Point while in APG mode —The user will be unable to change the set point while APG is being used to control that parameter: voltage or current. • Autosequence Programming —Various conflicts can occur while using Autosequence programming; for example, using the trigger command while the program is running will result in this error. • Calibration mode —When in calibration mode, certain settings will cause an error.

Table B-2 Execution Error List

Error Code	Error Message Description
-222	Data out of range Indicates that a legal program data element was parsed but could not be executed because the interpreted value was outside the legal range as defined by the device (see <i>IEEE 488.2</i> , 11.5.1.1.5)
-224	Illegal parameter value Used where the exact value, from a list of possible values, was expected.
-291	Out of memory Used when the Autosequence programming buffer is full.

B

Device-Specific Error List

An error in the range [-399, 300] or [1, 32767] indicates that the instrument has detected an error which is not a command error, a query error, or an execution error; some device operations did not properly complete, possibly due to an abnormal hardware or firmware condition. These codes are also used for self-test response errors. The occurrence of any error in the class causes the device-specific error bit (bit 3) in the Event Status Register to be set.

Table B-3 Device-Specific Error List

Error Code	Error Message Description
-300	Device-specific error. Indicates that the power supply could not complete the operation due to some condition of the power supply.
-350	Queue Overflow A specific code entered into the queue in lieu of the code that caused the error. This code indicates that there is no room in the queue and an error occurred but was not recorded.
-360	Communication error This is the generic communication error for devices.
-363	Input buffer overrun Software or hardware input buffer on serial port overflows with data caused by improper or nonexistent pacing.
-365	Time out error This is a generic device-dependent error.

Query Error List

An error number in the range [-499, -400] indicates that the output queue control of the instrument has detected a problem with the message exchange protocol described in IEEE 488.2, chapter 6. The occurrence of any error in this class causes the query error bit (bit 2) in the Event Status Register to be set.

Table B-4 Query Error List

Error Code	Error Message Description
-400	Query Error This is the generic query error for the power supply, used only when the other types of errors do not apply.

B

Error Messages

Appendix B, Error Messages, provides information on the error messages which may appear. Errors are placed in a queue as they are detected.

Error Messages

Errors are placed in a queue as they are detected. The queue works on a first in, first out (FIFO) basis. If the queue overflows, the last error in the queue is replaced with error -350, "Queue Overflow". When all errors have been read from the queue, further error queries return 0, "No error".

The error queue is cleared when any of the following occur (IEEE 488.2, section 11.4.3.4):

- Upon receipt of a *CLS command
- Upon reading the last item from the queue

Command Error List

An error in the range [-199, -100] indicates that an IEEE 488.2 syntax error has been detected by the instrument's parser. The occurrence of any error in this class causes the command error bit (bit 5) in the Event Status Register to be set.

Table B-1 Command Error List

Error Code	Error Message Description
-100	Command error This is the generic syntax error
-102	Syntax Error An unrecognized command or data type was encountered; for example, a string was received when the device does not accept strings.
-108	Parameter not Allowed More parameters were received than expected for the header; for example, the *SRE common command only accepts one parameter, so receiving *SRE 0,1 is not allowed.
-109	Missing Parameter Fewer parameters were received than required for the header; for example, the *SAV common command requires one parameter, so receiving *SAV is not allowed.
-110	Command header error An error was detected in the header.
-113	Undefined header The header is syntactically correct, but it is undefined for this specific device; for example, *XYZ is not defined for any device.
-121	Invalid character in number An invalid character for the data type being parsed was encountered; for example, an alpha in a decimal numeric or a "9" in octal data.
-140	Character data error This error is generated when parsing a character data element.
-150	String data error This error is generated when parsing a string data element fails.
-151	Invalid string data A string data element was expected, but was invalid for some reason (see <i>IEEE 488.2, 7.7.5.2</i>); for example, an END message was received before the terminal quote character.

B

Execution Error List

An error in the range [-299, -200] indicates that an error has been detected by the instrument's execution control block. The occurrence of any error in the class causes the execution error bit (bit 4) in the Event Status Register to be set.

Execution errors are reported by the device after rounding and expression evaluation operations have taken place.

Table B-2 Execution Error List

Error Code	Error Message Description
-200	<p>Execution Error</p> <p>This is the generic syntax error for devices that cannot detect more specific errors. This code indicates only that an Execution Error as defined in <i>IEEE 488.2</i>, 11.5.1.1.5 has occurred.</p>
-203	<p>Command protected</p> <p>Indicates that a legal password-protected program command or query could not be executed because the command was disabled. Check the calibration state.</p>
-220	<p>Parameter error</p> <p>Indicates that a program data element related error has occurred</p>
-221	<p>Setting conflict</p> <p>Indicates that a legal program data element was parsed, but could not be executed due to the current power supply state.</p> <p>The following list is not exhaustive but does cover some of the more common conditions that may contribute to this error:</p> <ul style="list-style-type: none"> • OVP/UVS Set Points —The OVP and UVP limit the setting of the voltage set point so that you cannot accidentally trigger these alarms by changing the set point outside of their range. Conversely, setting the OVP set point to be less than the voltage set point will also trigger this error. • Changing the Set Point while in APG mode —The user will be unable to change the set point while APG is being used to control that parameter: voltage or current. • Autosequence Programming —Various conflicts can occur while using Autosequence programming; for example, using the trigger command while the program is running will result in this error. • Calibration mode —When in calibration mode, certain settings will cause an error.

Table B-2 Execution Error List

Error Code	Error Message Description
-222	Data out of range Indicates that a legal program data element was parsed but could not be executed because the interpreted value was outside the legal range as defined by the device (see <i>IEEE 488.2</i> , 11.5.1.1.5)
-224	Illegal parameter value Used where the exact value, from a list of possible values, was expected.
-291	Out of memory Used when the Autosequence programming buffer is full.

B

Device-Specific Error List

An error in the range [-399, 300] or [1, 32767] indicates that the instrument has detected an error which is not a command error, a query error, or an execution error; some device operations did not properly complete, possibly due to an abnormal hardware or firmware condition. These codes are also used for self-test response errors. The occurrence of any error in the class causes the device-specific error bit (bit 3) in the Event Status Register to be set.

Table B-3 Device-Specific Error List

Error Code	Error Message Description
-300	Device-specific error. Indicates that the power supply could not complete the operation due to some condition of the power supply.
-350	Queue Overflow A specific code entered into the queue in lieu of the code that caused the error. This code indicates that there is no room in the queue and an error occurred but was not recorded.
-360	Communication error This is the generic communication error for devices.
-363	Input buffer overrun Software or hardware input buffer on serial port overflows with data caused by improper or nonexistent pacing.
-365	Time out error This is a generic device-dependent error.

Query Error List

An error number in the range [-499, -400] indicates that the output queue control of the instrument has detected a problem with the message exchange protocol described in IEEE 488.2, chapter 6. The occurrence of any error in this class causes the query error bit (bit 2) in the Event Status Register to be set.

Table B-4 Query Error List

Error Code	Error Message Description
-400	Query Error This is the generic query error for the power supply, used only when the other types of errors do not apply.

C

Specifications

Appendix C, Specifications, provides the product specifications for the XTR 850 Watt Series Programmable DC Power Supply.

- These specifications are represented over the full operating temperature range.
- Nominal line input voltage should be assumed unless otherwise stated.
- All sense lines are configured for local operation by default.
- Except where otherwise noted, specifications apply to single unit operation only.
- Specifications are subject to change without notice.

Electrical Specifications for XTR 850 Watt

Specifications

Table C-1 XTR 850 Watt Electrical Specifications for 6 V to 600 V Models

Models	6-110	8-100	12-70	20-42	33-25	40-21	60-14	80-10.5	100-8.5	150-5.6	300-2.8	600-1.4
Output Ratings:												
Output Voltage ¹	6 V	8 V	12 V	20 V	33 V	40 V	60 V	80 V	100 V	150 V	300 V	600 V
Output Current ²	110 A	100 A	70 A	42 A	25 A	21 A	14 A	10.5 A	8.5 A	5.6 A	2.8 A	1.4 A
Output Power ³	670 W	810 W	850 W	850 W	835 W	850 W	850 W	850 W	860 W	850 W	850 W	850 W
Line Regulation:												
Voltage ⁴ (0.005% of rated output voltage +2 mV)	2.3 mV	2.4 mV	2.6 mV	3.0 mV	3.7 mV	4 mV	5 mV	6 mV	7 mV	9.5 mV	17 mV	32 mV
Current ⁵ (0.01% of rated output current +2 mA)	13 mA	12 mA	9 mA	6.2 mA	4.5 mA	4.1 mA	3.4 mA	3.1 mA	2.9 mA	2.6 mA	2.3 mA	2.1 mA
Load Regulation:												
Voltage ⁶ (0.005% of rated output voltage + 2 mV)	2.3 mV	2.4 mV	2.6 mV	3.0 mV	3.7 mV	4 mV	5 mV	6 mV	7 mV	9.5 mV	17 mV	32 mV
Current ⁷ (0.02% of rated output current +5 mA)	27 mA	25 mA	19 mA	13.4 mA	10 mA	9.2 mA	7.8 mA	7.1 mA	6.7 mA	6.1 mA	5.6 mA	5.3 mA
Output Noise (rms, 300 kHz):												
Voltage	8 mV	8 mV	8 mV	8 mV	8 mV	8 mV	8 mV	8 mV	8 mV	10 mV	25 mV	50 mV
Current ⁸	200 mA	180 mA	120 mA	75 mA	60 mA	45 mA	35 mA	25 mA	20 mA	16 mA	10 mA	6 mA
Output Noise (p-p, 20 MHz):												
Voltage	50 mV	50 mV	50 mV	50 mV	50 mV	50 mV	50 mV	80 mV	80 mV	100 mV	150 mV	250 mV
Maximum Recommended Remote Sense Line Drop Compensation per Line ⁹	1 V	1 V	1 V	1.5 V	2 V	2 V	3 V	5 V	5 V	5 V	5 V	5 V
Up-prog. Response Time, 0-Vmax ¹⁰	60 ms	60 ms	60 ms	60 ms	60 ms	60 ms	60 ms	100 ms	100 ms	100 ms	150 ms	250 ms
Down-prog. Response Time: Full Load	50 ms	50 ms	50 ms	50 ms	50 ms	50 ms	50 ms	80 ms	100 ms	150 ms	150 ms	250 ms
Down-prog. Response Time: No Load	300 ms	400 ms	500 ms	600 ms	700 ms	800 ms	900 ms	1000 ms	1200 ms	1800 ms	2200 ms	3500 ms
Over-Voltage Trip Point	0.5–7.5 V	0.5–10 V	1–15 V	1–24 V	2–39 V	2–44 V	3–66 V	3–95 V	3–125 V	3–180 V	5–330 V	5–660 V

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Table C-1 XTR 850 Watt Electrical Specifications for 6 V to 600 V Models

Models	6-110	8-100	12-70	20-42	33-25	40-21	60-14	80-10.5	100-8.5	150-5.6	300-2.8	600-1.4
Efficiency ¹¹	75/77%	77/80%	81/84%	82/85%	83/86%	83/87%	83/87%	83/87%	83/87%	83/87%	83/87%	83/87%

1. Maximum output voltage is guaranteed to be $\leq 0.1\%$ of the rated voltage at zero output setting, using the front panel or digital remote programming modes.
 2. Maximum output current is guaranteed to be $\leq 0.2\%$ of the rated current at zero output setting, using the front panel or digital remote programming modes, and when measured with rated load resistance.
 3. Total output power is also based on AUX1 Output Voltage (5 V) and AUX1 Output Current (0.5 A) and AUX2 Output Voltage (15 V) and AUX2 Output Current (0.5 A).
 4. From 85–132 Vac or 170–265 Vac, constant load.
 5. From 85–132 Vac or 170–265 Vac, constant load.
 6. From no load to full load, constant input voltage.
 7. For load voltage change, equal to the unit voltage rating, constant input voltage.
 8. For 6 V models the current ripple is measured at 2–6 V output voltage and full output current. For all other models, the current ripple is measured at 10–100% output voltage and full output current.
 9. When using remote sense, the total of the load voltage and the load line drops must not exceed the rated output of the power supply. For example, for an XTR 6-110 in an application with 1 V of load line loss (0.5 V/Line), the maximum available load voltage would be 6–1= 5 V. Note: The unit may operate at higher output voltages than this, but there is no guarantee that the power supply will meet performance specifications. Ultimately, the upper limit of the output voltage will be determined by internal circuitry of the power supply (non-adjustable.)
 10. With rated, resistive load.
 11. At 100/200 Vac input voltage and maximum output power.
- Applies to all footnotes: Programming and Readback: RS-232, RS-485, USB built in. GPIB, Ethernet optional.
Specifications are guaranteed from 1% to 100% of the rated output voltage, current, and power.

AC Line Input Specifications for XTR 850 Watt

The input to the power supply requires the following input specifications.

Rated AC Input Voltage/Frequency	100–240 Vac, 47–63 Hz
Operational AC Input Voltage/Frequency	85–265 Vac continuous, single phase, 47–63 Hz
Input Current (at 100/200 Vac)	11.5/6 A
Inrush Current (100/200 Vac)	Less than 25 A
Power Factor Correction	0.99@100/200 Vac, rated output power



C-4 Remote Operation

Table C-2 Remote Operation

Programming Mode	APG	ISOL	Digital
Voltage and Current Output Voltage Programming	0–100%. Voltage control range is 0.0 to 2.0-10.0V in 0.1V increments.		
Voltage and Current Output Resistive Programming	0-100%. Resistive control range is 0.0 to 2.0 - 10.0K in 0.1K increments.		
Output Voltage and Current Monitor	0-100%. Output voltage monitor range is 0.0 to 2.0 - 10.0V in 0.1V increments.		
Voltage Programming Accuracy ¹	± 0.5% of rated output voltage, max. (0 to 4.0V / 4K Ohm range) ± 0.5% of rated output voltage, typical in other ranges		±0.1% of rated output voltage
Current Programming Accuracy ¹	± 1.0% of rated output current, max. (0 to 4.0V / 4K Ohm range) ± 1.0% of rated output current, typical in other ranges		±0.2% of rated output current
Voltage Readback Accuracy	± 1% of rated output voltage		±0.1% of rated output voltage
Current Readback Accuracy	± 1% of rated output current		±0.2% of rated output current
Isolation (Prog and Readback Lines)	With respect to chassis potential: 500 V	With respect to: chassis potential: 500 V. negative or positive main output: 1500 V.	
Parallel Operation	Up to 4 units in master/slave mode		
Series Operation	Up to 2 units (with external diodes)		
Constant Voltage (CV)/Constant Current (CC) Indicator	CV: TTL High (4–5 V) CC: TTL Low (0–0.6 V)		
Shutdown Control ²		Logic low 0.0 - 1.4V Logic high 2.0 - 15V Dry contact compatible	
OUTPUT ENABLE Auxiliary Control		TTL level or dry contact compatible	
Power Supply Status Signal		TTL high: OK (4–5 V) TTL low: fail (0–0.6 V)	
Interlock Enable/Disable		Dry contact. Open/Short: On or Off, programmable	

1. Typical APG or isolated APG accuracy can be improved to max accuracy by user calibration at the specific range selected.

2. The shutdown input has user selectable negative logic operation via front panel or remote digital input/output.

Common Specifications for All Models

Output Performance Specifications

Aux output ¹	+5V: +0.4V, – 0.5V at 0.4A +15V: +1.2V, – 1.4V at 0.4A
Temperature Coefficient	100 PPM/° C from rated output voltage, after a 30-minute warm-up
Drift (8 hours)	0.05% of rated output (over an 8 hour interval with constant line, load and temperature, after a 30-minute warm-up)
Hold-up Time	Typical 20 ms at any rated input line.
Transient Response Time ²	Less than 1 ms for 6 V to 60 V models. Less than 2 ms for 80 V to 600 V models
Meter Accuracy	0.5% of actual output voltage or current \pm 1 count
Isolation	
AC Input to Output	1350 Vac
AC Input to Chassis	1350 Vac
Output to Chassis ³	500 Vac

1.Current: 0.51A minimum guaranteed, 0.72A typically available. Overcurrent protection (each output) is automatic, non-latching. When OCP is tripped the aux voltage folds back and will recover to nominal condition when the over current condition is removed (typ. < 0.2A).

To protect external circuits attached to the aux outputs it is recommended that customers use an appropriately rated fuse in series with the aux outputs being used.

2.Time for the output voltage to recover within 0.5% at its rated output for a load change 10–90% of rated output current. Output set point 10–100%.

3.For floating chassis ground applications, please contact applications engineering for system design assistance.



Environmental Specifications (Indoor use)

Operating Temperature Range	0 °C to 50 °C, 100% load
Storage Temperature Range	-20 °C to 70 °C
Operating Humidity Range	30-90% RH (no condensation)
Storage Humidity Range	10-95% RH (no condensation)
Operating Altitude	Up to 6,500 feet (2,000 m)
Installation Category	II (IEC 1010-1)
Pollution Degree	2 (IEC 1010-1)

Mechanical Specifications

XTR 850 Watt (W×H×D)	8.4 × 1.7 × 19.0 inch (214 × 43.6 × 483 mm)
Weight	11 lb (5kg)
Cooling	Forced air cooling by internal fans

Regulatory Approvals

Safety	CSA 22.2 No. 61010-1 and UL61010-1. Marked with c(UL)us CE EN61010-1
EMC	Complies with EN55022, Class A, FCC Part 15A for conducted emissions Complies with EN55022, Class A, FCC Part 15A for radiated emissions Complies with EN61000-4 series of standards for immunity

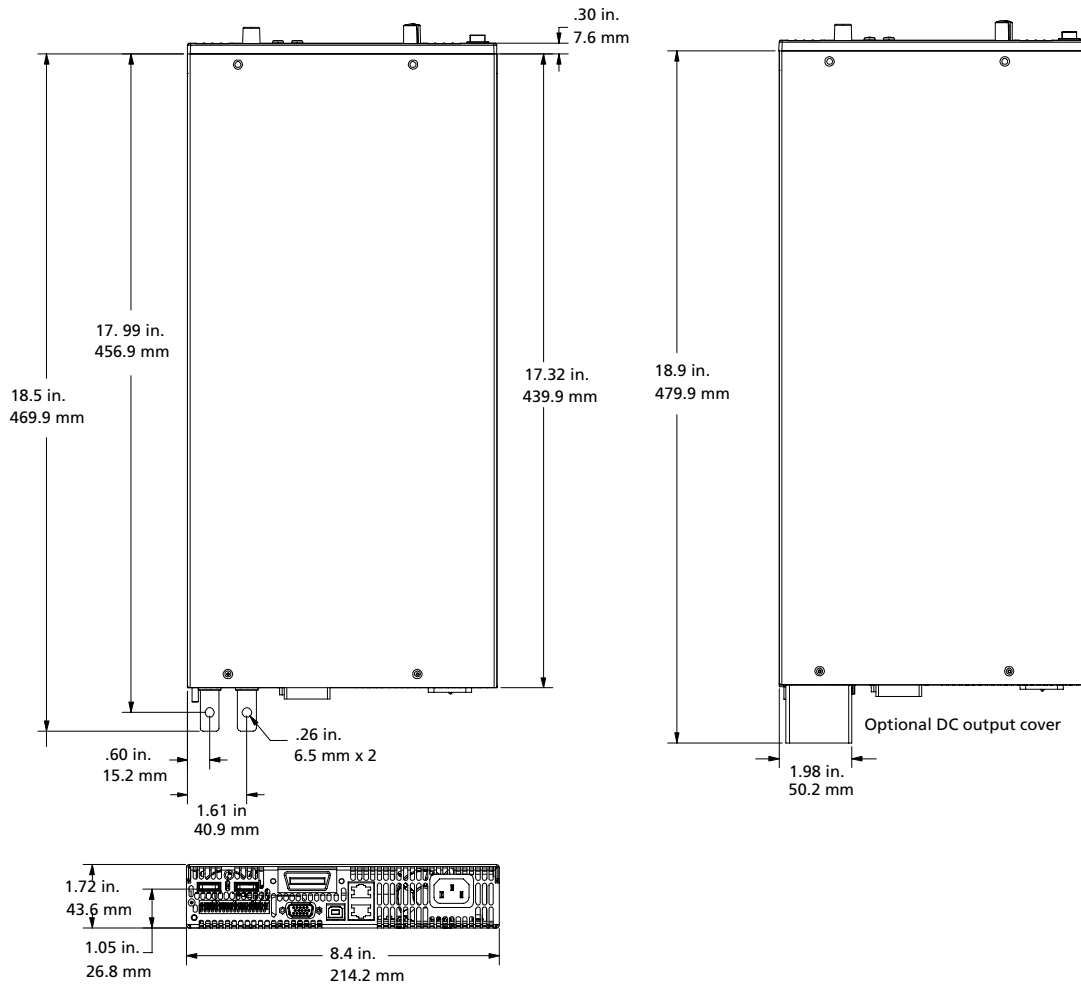


Figure C-1 XTR 850 Watt Mechanical Dimensions: 6 to 40 V Models

Specifications

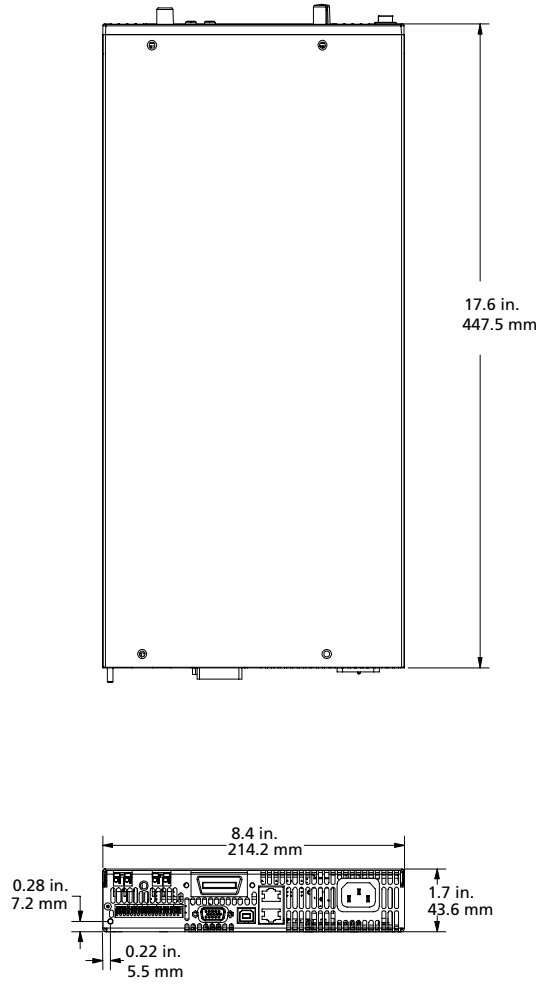


Figure C-2 XTR 850 Watt Mechanical Dimensions: 60 V to 600 V Models

Product Family: XTR 850 Watt Series Programmable DC Power Supply

Warranty Period: Five Years

WARRANTY TERMS

AMETEK Programmable Power, Inc. ("AMETEK"), provides this written warranty covering the Product stated above, and if the Buyer discovers and notifies AMETEK in writing of any defect in material or workmanship within the applicable warranty period stated above, then AMETEK may, at its option: repair or replace the Product; or issue a credit note for the defective Product; or provide the Buyer with replacement parts for the Product.

The Buyer will, at its expense, return the defective Product or parts thereof to AMETEK in accordance with the return procedure specified below. AMETEK will, at its expense, deliver the repaired or replaced Product or parts to the Buyer. Any warranty of AMETEK will not apply if the Buyer is in default under the Purchase Order Agreement or where the Product or any part thereof:

- is damaged by misuse, accident, negligence or failure to maintain the same as specified or required by AMETEK;
- is damaged by modifications, alterations or attachments thereto which are not authorized by AMETEK;
- is installed or operated contrary to the instructions of AMETEK;
- is opened, modified or disassembled in any way without AMETEK's consent; or
- is used in combination with items, articles or materials not authorized by AMETEK.

The Buyer may not assert any claim that the Products are not in conformity with any warranty until the Buyer has made all payments to AMETEK provided for in the Purchase Order Agreement.

PRODUCT RETURN PROCEDURE

1. Request a Return Material Authorization (RMA) number from the repair facility (**must be done in the country in which it was purchased**):
 - **In the USA**, contact the AMETEK Repair Department prior to the return of the product to AMETEK for repair:
Telephone: 800-733-5427, ext. 2295 or ext. 2463 (toll free North America)
858-450-0085, ext. 2295 or ext. 2463 (direct)
 - **Outside the United States**, contact the nearest Authorized Service Center (ASC). A full listing can be found either through your local distributor or our website, www.programmablepower.com, by clicking Support and going to the Service Centers tab.
2. When requesting an RMA, have the following information ready:
 - Model number
 - Serial number
 - Description of the problem

NOTE: Unauthorized returns will not be accepted and will be returned at the shipper's expense.

NOTE: A returned product found upon inspection by AMETEK, to be in specification is subject to an evaluation fee and applicable freight charges.

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