

# Instruction Manual



## TMS 241 68HC12 Microcontroller Support 071-0145-01

### **Warning**

The servicing instructions are for use by qualified personnel only. To avoid personal injury, do not perform any servicing unless you are qualified to do so. Refer to all safety summaries prior to performing service.

Copyright © Tektronix, Inc. All rights reserved. Licensed software products are owned by Tektronix or its suppliers and are protected by United States copyright laws and international treaty provisions.

Use, duplication, or disclosure by the Government is subject to restrictions as set forth in subparagraph (c)(1)(ii) of the Rights in Technical Data and Computer Software clause at DFARS 252.227-7013, or subparagraphs (c)(1) and (2) of the Commercial Computer Software – Restricted Rights clause at FAR 52.227-19, as applicable.

Tektronix products are covered by U.S. and foreign patents, issued and pending. Information in this publication supercedes that in all previously published material. Specifications and price change privileges reserved.

Printed in the U.S.A.

Tektronix, Inc., P.O. Box 1000, Wilsonville, OR 97070-1000

TEKTRONIX and TEK are registered trademarks of Tektronix, Inc.

## SOFTWARE WARRANTY

Tektronix warrants that the media on which this software product is furnished and the encoding of the programs on the media will be free from defects in materials and workmanship for a period of three (3) months from the date of shipment. If a medium or encoding proves defective during the warranty period, Tektronix will provide a replacement in exchange for the defective medium. Except as to the media on which this software product is furnished, this software product is provided "as is" without warranty of any kind, either express or implied. Tektronix does not warrant that the functions contained in this software product will meet Customer's requirements or that the operation of the programs will be uninterrupted or error-free.

In order to obtain service under this warranty, Customer must notify Tektronix of the defect before the expiration of the warranty period. If Tektronix is unable to provide a replacement that is free from defects in materials and workmanship within a reasonable time thereafter, Customer may terminate the license for this software product and return this software product and any associated materials for credit or refund.

**THIS WARRANTY IS GIVEN BY TEKTRONIX IN LIEU OF ANY OTHER WARRANTIES, EXPRESS OR IMPLIED. TEKTRONIX AND ITS VENDORS DISCLAIM ANY IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. TEKTRONIX' RESPONSIBILITY TO REPLACE DEFECTIVE MEDIA OR REFUND CUSTOMER'S PAYMENT IS THE SOLE AND EXCLUSIVE REMEDY PROVIDED TO THE CUSTOMER FOR BREACH OF THIS WARRANTY. TEKTRONIX AND ITS VENDORS WILL NOT BE LIABLE FOR ANY INDIRECT, SPECIAL, INCIDENTAL, OR CONSEQUENTIAL DAMAGES IRRESPECTIVE OF WHETHER TEKTRONIX OR THE VENDOR HAS ADVANCE NOTICE OF THE POSSIBILITY OF SUCH DAMAGES.**



# Table of Contents

<b>General Safety Summary</b> .....	<b>iii</b>
<b>Service Safety Summary</b> .....	<b>v</b>
<b>Preface</b> .....	<b>vii</b>
Manual Conventions .....	vii
Logic Analyzer Documentation .....	viii
Contacting Tektronix .....	viii

## Getting Started

Support Package Description .....	1-1
Logic Analyzer Software Compatibility .....	1-1
Logic Analyzer Configuration .....	1-1
Requirements and Restrictions .....	1-2
Labeling P6434 Probes .....	1-2
DAS Mass Termination Interface (MTIF) Probes .....	1-2
Channel Assignments .....	1-2
CPU To Mictor Connections .....	1-6

## Operating Basics

<b>Setting Up the Support</b> .....	<b>2-1</b>
Channel Group Definitions .....	2-1
Show Cycles .....	2-1
Clocking .....	2-1
Custom Clocking .....	2-1
Clocking Options .....	2-1
Symbols .....	2-3
<b>Acquiring and Viewing Disassembled Data</b> .....	<b>2-5</b>
Acquiring Data .....	2-5
Viewing Disassembled Data .....	2-5
Hardware Display Format .....	2-6
Displaying Exception Vectors .....	2-6
Software Display Format .....	2-7
Control Flow Display Format .....	2-7
Subroutine Display Format .....	2-8
Changing How Data is Displayed .....	2-8
Optional Display Selections For the TLA 700 .....	2-8
Optional Display Selections For the DAS 9200 .....	2-9
Marking Cycles .....	2-9
Microprocessor Specific Disassembly Restrictions .....	2-10

## Specifications

Specification Tables .....	3-1
----------------------------	-----

## Replaceable Parts

Parts Ordering Information .....	4-1
----------------------------------	-----

## Index

## List of Tables

<b>Table 1-1: Address group channel assignments .....</b>	<b>1-3</b>
<b>Table 1-2: Data group channel assignments .....</b>	<b>1-4</b>
<b>Table 1-3: Control group channel assignments .....</b>	<b>1-4</b>
<b>Table 1-4: Ctrl2 group channel assignments .....</b>	<b>1-5</b>
<b>Table 1-5: Chip_Sel group channel assignments .....</b>	<b>1-5</b>
<b>Table 1-6: Addr_Hi group channel assignments .....</b>	<b>1-5</b>
<b>Table 1-7: Clock channel assignments .....</b>	<b>1-6</b>
<b>Table 1-8: CPU to Mictor connections for Mictor A pins .....</b>	<b>1-7</b>
<b>Table 1-9: CPU to Mictor connections for Mictor C pins .....</b>	<b>1-8</b>
<b>Table 1-10: CPU to Mictor connections for Mictor D pins .....</b>	<b>1-10</b>
<b>Table 2-1: Chip_Sel group symbol table definitions .....</b>	<b>2-3</b>
<b>Table 2-2: Ctrl2 group symbol table definitions .....</b>	<b>2-3</b>
<b>Table 2-3: Control group symbol table definitions .....</b>	<b>2-4</b>
<b>Table 2-4: Description of special characters in the display .....</b>	<b>2-5</b>
<b>Table 3-1: Specifications .....</b>	<b>3-1</b>

# General Safety Summary

Review the following safety precautions to avoid injury and prevent damage to this product or any products connected to it. To avoid potential hazards, use this product only as specified.

*Only qualified personnel should perform service procedures.*

While using this product, you may need to access other parts of the system. Read the *General Safety Summary* in other system manuals for warnings and cautions related to operating the system.

## To Avoid Fire or Personal Injury

**Connect and Disconnect Properly.** Do not connect or disconnect probes or test leads while they are connected to a voltage source.

**Ground the Product.** This product is indirectly grounded through the grounding conductor of the mainframe power cord. To avoid electric shock, the grounding conductor must be connected to earth ground. Before making connections to the input or output terminals of the product, ensure that the product is properly grounded.

**Observe All Terminal Ratings.** To avoid fire or shock hazard, observe all ratings and marking on the product. Consult the product manual for further ratings information before making connections to the product.

The common terminal is at ground potential. Do not connect the common terminal to elevated voltages.

**Do Not Operate Without Covers.** Do not operate this product with covers or panels removed.

**Avoid Exposed Circuitry.** Do not touch exposed connections and components when power is present.

**Do Not Operate With Suspected Failures.** If you suspect there is damage to this product, have it inspected by qualified service personnel.

**Do Not Operate in Wet/Damp Conditions.**

**Do Not Operate in an Explosive Atmosphere.**

**Keep Product Surfaces Clean and Dry.**

## Symbols and Terms

**Terms in this Manual.** These terms may appear in this manual:



---

**WARNING.** *Warning statements identify conditions or practices that could result in injury or loss of life.*

---



---

**CAUTION.** *Caution statements identify conditions or practices that could result in damage to this product or other property.*

---

**Terms on the Product.** These terms may appear on the product:

**DANGER** indicates an injury hazard immediately accessible as you read the marking.

**WARNING** indicates an injury hazard not immediately accessible as you read the marking.

**CAUTION** indicates a hazard to property including the product.

**Symbols on the Product.** The following symbols may appear on the product:



WARNING  
High Voltage



Protective Ground  
(Earth) Terminal



CAUTION  
Refer to Manual



Double  
Insulated



# Service Safety Summary

Only qualified personnel should perform service procedures. Read this *Service Safety Summary* and the *General Safety Summary* before performing any service procedures.

**Do Not Service Alone.** Do not perform internal service or adjustments of this product unless another person capable of rendering first aid and resuscitation is present.

**Disconnect Power.** To avoid electric shock, disconnect the main power by means of the power cord or, if provided, the power switch.

**Use Care When Servicing With Power On.** Dangerous voltages or currents may exist in this product. Disconnect power, remove battery (if applicable), and disconnect test leads before removing protective panels, soldering, or replacing components.

To avoid electric shock, do not touch exposed connections.



# Preface

This instruction manual contains specific information about the TMS 241 68HC12 microcontroller support package and is part of a set of information on how to operate this product on compatible Tektronix logic analyzers.

If you are familiar with operating microcontroller support packages on the logic analyzer for which the TMS 241 68HC12 support was purchased, you will probably only need this instruction manual to set up and run the support.

If you are not familiar with operating microcontroller support packages, you will need to supplement this instruction manual with information on basic operations to set up and run the support.

Information on basic operations of microcontroller support packages is included with each product. Each logic analyzer has basic information that describes how to perform tasks common to support packages on that platform. This information can be in the form of online help, an installation manual, or a user manual.

This manual provides detailed information on the following topics:

- Connecting the logic analyzer to the system under test
- Setting up the logic analyzer to acquire data from the system under test
- Acquiring and viewing disassembled data

## Manual Conventions

This manual uses the following conventions:

The term “disassembler” refers to the software that disassembles bus cycles into instruction mnemonics and cycle types.

The phrase “information on basic operations” refers to online help, an installation manual, or a basic operations of microcontroller supports user manual.

In the information on basic operations, the term “XXX” or “P54C” used in field selections and file names must be replaced with 68HC12. This is the name of the microcontroller in field selections and file names you must use to operate the 68HC12 support.

The term “SUT” (system under test) refers to the microcontroller-based system from which data will be acquired.

The term “logic analyzer” refers to the Tektronix logic analyzer for which this product was purchased.

The term “HI module” refers to the module in the higher-numbered slot and the term “LO module” refers to the module in the lower-numbered slot.

68HC12 refers to all supported variations of the 68HC12 microcontroller, including the 68HC812 and 68HC912 unless otherwise noted.

A tilde (~) following a signal name indicates that the signal is active low.

## Logic Analyzer Documentation

A description of other documentation available for each type of Tektronix logic analyzer is located in the corresponding module user manual. The manual set provides the information necessary to install, operate, maintain, and service the logic analyzer and associated products.

## Contacting Tektronix

Product Support	<p>For questions about using Tektronix measurement products, call toll free in North America: 1-800-TEK-WIDE (1-800-835-9433 ext. 2400) 6:00 a.m. – 5:00 p.m. Pacific time</p> <p>Or contact us by e-mail: tm_app_supp@tek.com</p> <p>For product support outside of North America, contact your local Tektronix distributor or sales office.</p>
Service Support	<p>Tektronix offers extended warranty and calibration programs as options on many products. Contact your local Tektronix distributor or sales office.</p> <p>For a listing of worldwide service centers, visit our web site.</p>
For other information	<p>In North America: 1-800-TEK-WIDE (1-800-835-9433) An operator will direct your call.</p>
To write us	<p>Tektronix, Inc. P.O. Box 1000 Wilsonville, OR 97070-1000 USA</p>
Website	<p>Tektronix.com</p>



# Getting Started



# Getting Started

This chapter contains information on the TMS 241 microcontroller support, and information on connecting your logic analyzer to your system under test.

## Support Package Description

The TMS 241 microcontroller support package displays disassembled data from systems based on the Motorola 68HC12 family of microcontrollers.

To use this support efficiently, you need to have the items listed in the information on basic operations as well as the following reference material:

68HC12 CPU12 Reference Manual, Motorola, First Edition, 1996, CPU12RM/AD

MC68HC812A4 Technical Summary: 16-Bit Microcontroller, Motorola, 1997, MC68HC812A4TS/D

Technical Supplement: MC68HC812A4 Electrical Characteristics, Motorola, 16-JAN-97, no part number, this is an online manual

MC68HC912B32 Technical Summary: 16-Bit Microcontroller, Motorola, 1997, MC68HC912B32TS/D

Technical Supplement: MC68HC912B32 Electrical Characteristics, Motorola, 16-JAN-97, no part number, this is an online manual

## Logic Analyzer Software Compatibility

The label on the microcontroller support floppy disk states which version of logic analyzer software this support is compatible with.

## Logic Analyzer Configuration

For use with a TLA 700 Series, the TMS 241 support requires a minimum of one 102-channel module.

For use with a DAS 9200 Series, the TMS 241 support requires a minimum of one 96-channel module.

## Requirements and Restrictions

Review the *Specifications* chapter in this manual as they pertain to your system under test, as well as the following descriptions of other 68HC12 support requirements and restrictions.

**System Clock Rate.** The 68HC12 microcontroller support can acquire data from the 68HC12 microcontroller operating at speeds of up to 8 MHz. This specification is valid at the time this manual was printed. Please contact your Tektronix Sales Representative for current information on the fastest devices supported.

**Custom Clocking.** The TMS 241 microcontroller support disassembler requires Custom clocking in order to function correctly. Other clocking selections like Internal and External may cause incorrect disassembly.

**Hardware Reset.** If a hardware reset occurs in your 68HC12 system during an acquisition, the application disassembler may acquire an invalid sample.

**Marking Cycles.** The 68HC12 disassembler does not support the marking of cycles.

## Labeling P6434 Probes

The TMS 241 channel assignments follow the standard channel mapping and labeling scheme for P6434 probes. Apply labels using the standard method as described in the *P6434 Mass Termination Probe Instructions*.

## DAS Mass Termination Interface (MTIF) Probes

The MTIF probes are already labeled since the probe sections for each probe are permanent. The TMS 241 channel assignments follow the standard channel mapping.

## Channel Assignments

Channel assignments shown in Table 1–1 through Table 1–7 use the following conventions:

- Unless otherwise indicated, all signals are required by the support.
- Channels are shown starting with the most significant bit (MSB) descending to the least significant bit (LSB).



- Channel group assignments are for all modules unless otherwise noted.
- A tilde (~) following a signal name indicates an active low signal.
- The module in the higher-numbered slot is referred to as the HI module and the module in the lower-numbered slot is referred to as the LO module.

The TLA 704 has the lower numbered slots on the top and the TLA 711 has the lower numbered slots on the left.

By default the Address group channel assignments are displayed in hexadecimal.

**Table 1-1: Address group channel assignments**

Bit order	Section:channel	68HC12 signal name
15	A1:7	PA7/A15
14	A1:6	PA6/A14
13	A1:5	PA5/A13
12	A1:4	PA4/A12
11	A1:3	PA3/A11
10	A1:2	PA2/A10
9	A1:1	PA1/A9
8	A1:0	PA0/A8
7	A0:7	PB7/A7
6	A0:6	PB6/A6
5	A0:5	PB5/A5
4	A0:4	PB4/A4
3	A0:3	PB3/A3
2	A0:2	PB2/A2
1	A0:1	PB1/A1
0	A0:0	PB0/A0

By default the Data group channel assignments are displayed in hexadecimal.

**Table 1-2: Data group channel assignments**

Bit order	Section:channel	68HC12 signal name
15	D1:7	PC7/D15
14	D1:6	PC6/D14
13	D1:5	PC5/D13
12	D1:4	PC4/D12
11	D1:3	PC3/D11
10	D1:2	PC2/D10
9	D1:1	PC1/D9
8	D1:0	PC0/D8
7	D0:7	PD7/D7
6	D0:6	PD6/D6
5	D0:5	PD5/D5
4	D0:4	PD4/D4
3	D0:3	PD3/D3
2	D0:2	PD2/D2
1	D0:1	PD1/D1
0	D0:0	PD0/D0

By default the Control group channel assignments are not visible.

IPIPE1\_X and IPIPE0\_X refer to the execution information encoded on the IPIPE signals.

**Table 1-3: Control group channel assignments**

Bit order	Section:channel	68HC12 signal name
4	C2:0	RESET-
3	C0:6	IPIPE1_X
2	C0:2	IPIPE0_X
1	C0:3	PE3/LSTRB-
0	C0:5	PE2/R/W-

By default the Ctrl2 group channel assignments are not visible.

IPIPE1\_Q and IPIPE0\_Q refer to the queue information encoded on the IPIPE signals.

Do not probe with the C2:6 and C2:2 channels as they are demuxed from the C0:6 and C2:2 channels.

**Table 1-4: Ctrl2 group channel assignments**

Bit order	Section:channel	68HC12 signal name
1	C2:6	IPIPE1_Q (demuxed from C0:6)
0	C2:2	IPIPE0_Q (demuxed form C0:2)

By default the Chip\_Sel group channel assignments are displayed symbolically.

**Table 1-5: Chip\_Sel group channel assignments**

Bit order	Section:channel	68HC12 signal name
6	A3:6	PF6/CSP1~ †
5	A3:5	PF5/CSP0~ †
4	A3:4	PF4/CSD~ †
3	A3:3	PF3/CS3~ †
2	A3:2	PF2/CS2~ †
1	A3:1	PF1/CS1~ †
0	A3:0	PF0/CS0~ †

† Signal not required for disassembly

By default the Addr\_Hi group channel assignments are displayed in hexadecimal.

**Table 1-6: Addr\_Hi group channel assignments**

Bit order	Section:channel	68HC12 signal name
5	A2:5	PG5/A21 †
4	A2:4	PG4/A20 †
3	A2:3	PG3/A19 †
2	A2:2	PG2/A18 †
1	A2:1	PG1/A17 †
0	A2:0	PG0/A16 †

† Signal not required for disassembly.

The probe section and channel assignments for the clock probes are not part of any group.

**Table 1-7: Clock channel assignments**

Section:channel	68HC12 signal name
CLK:1	ECLK

## CPU To Mictor Connections

To probe the microprocessor you will need to make connections between the CPU and the Mictor pins of the P6434 Mass Termination Probe. Refer to the P6434 Mass Termination Probe manual, Tektronix part number 070-9793-xx, for more information on mechanical specifications. Table 1-8 through Table 1-10 show the CPU pin to Mictor pin connections.

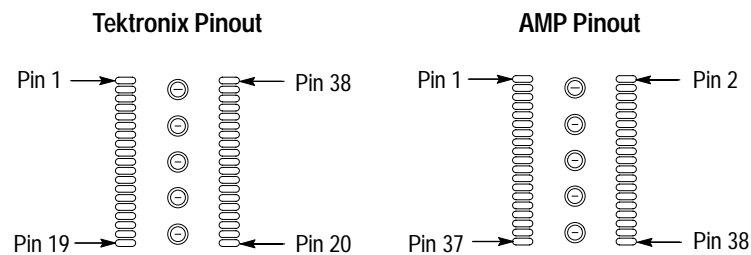
Tektronix uses a counter-clockwise pin assignment. Pin-1 is located at the top left, and pin-2 is located directly below it. Pin-20 is located on the bottom right, and pin-21 is located directly above it.

AMP uses an odd side-even side pin assignment. Pin-1 is located at the top left, and pin-3 is located directly below it. Pin-2 is located on the top right, and pin-4 is located directly below it.

---

**NOTE.** When designing Mictor connectors into your SUT, always follow the Tektronix pin assignment.

---



**Figure 1-1: Pin assignments for a Mictor connector (component side)**

Please pay close attention to the caution below.



**CAUTION.** To protect the CPU and the inputs of the module, it is recommended that a 180Ω resistor is connected in series between each ball pad of the CPU and each pin of the Mictor connector. The resistor must be no farther away from the ball pad of the CPU than 1/2-inch.

Table 1-8: CPU to Mictor connections for Mictor A pins

Tektronix Mictor A pin number	AMP Mictor A pin number	LA channel	68HC12 signal name	68HC812 pin number	68HC912 pin number
1	1		NC	NC	NC
2	3		NC	NC	NC
3	5	CLOCK:0	NC	NC	NC
4	7	A3:7	Not Used	Not Used	Not Used
5	9	A3:6	PF6/CSP1~	74	–
6	11	A3:5	PF5/CSP0~	73	–
7	13	A3:4	PF4/CSD~	72	–
8	15	A3:3	PF3/CS3~	71	–
9	17	A3:2	PF2/CS2~	70	–
10	19	A3:1	PF1/CS1~	69	–
11	21	A3:0	PF0/CS0~	68	–
12	23	A2:7	Not Used	Not Used	Not Used
13	25	A2:6	Not Used	Not Used	Not Used
14	27	A2:5	PG5/A21	18	–
15	29	A2:4	PG4/A20	17	–
16	31	A2:3	PG3/A19	16	–
17	33	A2:2	PG2/A18	13	–
18	35	A2:1	PG1/A17	12	–
19	37	A2:0	PG0/A16	11	–
20	38	A0:0	PB0/A0	52	18
21	36	A0:1	PB1/A1	53	19
22	34	A0:2	PB2/A2	54	20
23	32	A0:3	PB3/A3	55	21
24	30	A0:4	PB4/A4	56	22
25	28	A0:5	PB5/A5	57	23
26	26	A0:6	PB6/A6	58	24
27	24	A0:7	PB7/A7	59	25
28	22	A1:0	PA0/A8	60	39

Table 1-8: CPU to Mictor connections for Mictor A pins (cont.)

Tektronix Mictor A pin number	AMP Mictor A pin number	LA channel	68HC12 signal name	68HC812 pin number	68HC912 pin number
29	20	A1:1	PA1/A9	61	40
30	18	A1:2	PA2/A10	62	41
31	16	A1:3	PA3/A11	63	42
32	14	A1:4	PA4/A12	64	43
33	12	A1:5	PA5/A13	65	44
34	10	A1:6	PA6/A14	66	45
35	8	A1:7	PA7/A15	67	46
36	6	CLOCK:1	ECLK	48	29
37	4	NC	NC	NC	NC
38	2	NC	NC	NC	NC
39	39	GND	GND	GND	GND
40	40	GND	GND	GND	GND
41	41	GND	GND	GND	GND
42	42	GND	GND	GND	GND
43	43	GND	GND	GND	GND

Table 1-9: CPU to Mictor connections for Mictor C pins

Tektronix Mictor C pin number	AMP Mictor C pin number	LA channel	68HC12 signal name	68HC812 pin number	68HC912 pin number
1	1				
2	3				
3	5	CLOCK:3			
4	7	C3:7			
5	9	C3:6	Reserved		
6	11	C3:5			
7	13	C3:4			
8	15	C3:3			
9	17	C3:2	Reserved		
10	19	C3:1			
11	21	C3:0			
12	23	C2:7			
13	25	C2:6	IPIPE1_Q	§	§
14	27	C2:5			

Table 1-9: CPU to Mictor connections for Mictor C pins (cont.)

Tektronx Mictor C pin number	AMP Mictor C pin number	LA channel	68HC12 signal name	68HC812 pin number	68HC912 pin number
15	29	C2:4			
16	31	C2:3	PE3/LSTRB~	§	§
17	33	C2:2	IPIPE0_Q	49	28
18	35	C2:1			
19	37	C2:0	RESET~	40	32
20	38	C0:0			
21	36	C0:1			
22	34	C0:2	IPIPE0_X	49	28
23	32	C0:3	PE3/LSTRB2	39	35
24	30	C0:4			
25	28	C0:5	PE2/R/W~	38	36
26	26	C0:6	IPIPE1_X	50	27
27	24	C0:7			
28	22	C1:0			
29	20	C1:1			
30	18	C1:2	Reserved		
31	16	C1:3			
32	14	C1:4			
33	12	C1:5			
34	10	C1:6	Reserved		
35	8	C1:7			
36	6	NC			
37	4	NC			
38	2	NC			
39	39	GND			
40	40	GND			
41	41	GND			
42	42	GND			
43	43	GND			

§ Do not probe this signal. This signal is demultiplexed internally by the AMS program.

---

**NOTE.** When the microcontroller is in Byte mode, the data on the lower half of the data bus, Port D, will be suppressed. If you want to acquire data on Port D (the lower 8-bits of the data port) while operating in the 8-bit bus mode, you will have to probe those pins separately by using some unused channels.

---

Table 1–10: CPU to Mictor connections for Mictor D pins

Tektronix Mictor D pin number	AMP Mictor D pin number	LA channel	68HC12 signal name	68HC812 pin number	68HC912 pin number
1	1				
2	3				
3	5				
4	7	D3:7			
5	9	D3:6			
6	11	D3:5			
7	13	D3:4			
8	15	D3:3			
9	17	D3:2			
10	19	D3:1			
11	21	D3:0			
12	23	D2:7			
13	25	D2:6			
14	27	D2:5			
15	29	D2:4			
16	31	D2:3			
17	33	D2:2			
18	35	D2:1			
19	37	D2:0			
20	38	D0:0	PD0/D0	20	18
21	36	D0:1	PD1/D1	21	19
22	34	D0:2	PD2/D2	22	20
23	32	D0:3	PD3/D3	23	21
24	30	D0:4	PD4/D4	24	22
25	28	D0:5	PD5/D5	25	23
26	26	D0:6	PD6/D6	26	24
27	24	D0:7	PD7/D7	27	25
28	22	D1:0	PC0/D8	28	39
29	20	D1:1	PC1/D9	29	40
30	18	D1:2	PC2/D10	30	41



Table 1–10: CPU to Mictor connections for Mictor D pins (cont.)

Tektronix Mictor D pin number	AMP Mictor D pin number	LA channel	68HC12 signal name	68HC812 pin number	68HC912 pin number
31	16	D1:3	PC3/D11	31	42
32	14	D1:4	PC4/D12	32	43
33	12	D1:5	PC5/D13	33	44
34	10	D1:6	PC6/D14	34	45
35	8	D1:7	PC7/D15	35	46
36	6	CLOCK:2			
37	4	NC	NC	NC	NC
38	2	NC	NC	NC	NC
39	39	GND	GND	GND	GND
40	40	GND	GND	GND	GND
41	41	GND	GND	GND	GND
42	42	GND	GND	GND	GND
43	43	GND	GND	GND	GND





# Operating Basics



# Setting Up the Support

Information in this section is specific to the operations and functions of the TMS 241 68HC12 support on any Tektronix logic analyzer for which it can be purchased. Information on basic operations describes general tasks and functions.

Before you acquire and display disassembled data, you need to load the support and specify setups for clocking and triggering as described in the information on basic operations. The support provides default values for each of these setups, but you can change them as needed.

## Channel Group Definitions

The software automatically defines channel groups for the support. If you want to know which signal is in which group, refer to the channel assignment tables beginning on page 1–2.

**Show Cycles** A Show cycle is defined as any internal bus cycle made visible on the external bus. These types of cycles are acquired when you select Included.

## Clocking

**Custom Clocking** A special clocking program is loaded to the module every time you load the 68HC12 support. This special clocking is called Custom.

With Custom clocking, the module logs in signals from multiple groups of channels at different times as they become valid on the 68HC12 bus. The module then sends all the logged-in signals to the trigger machine and to the memory of the module for storage.

**Clocking Options** The only clocking option available is 68HC12.

**Timing Considerations** The data is clocked on both the rising and falling edge of the signal ECLK. The three stages for latching a complete data item follow:

1. The IPIPE Queue Movement information is clocked as the last stage of the previous data item. Simultaneously as the first part of the cycle information was latched, the address is latched and held on the rising edge of the clock.
2. The data and the other control signals are clocked in on the falling edge of the clock.

3. The last part of the cycle stores the IPIPE Execution information. The IPIPE Execution information is stored on the rising edge of the previous data item (that was already latched).

The next data cycle starts by latching the address for the next data item.

For a given data item the address is latched first, then the data, control, and IPIPE Execution information, and finally the IPIPE Queue movement.

In analyzing the data, the IPIPE\_X (IPIPE Execution) information is to be applied before the IPIPE\_Q (IPIPE Queue) information.

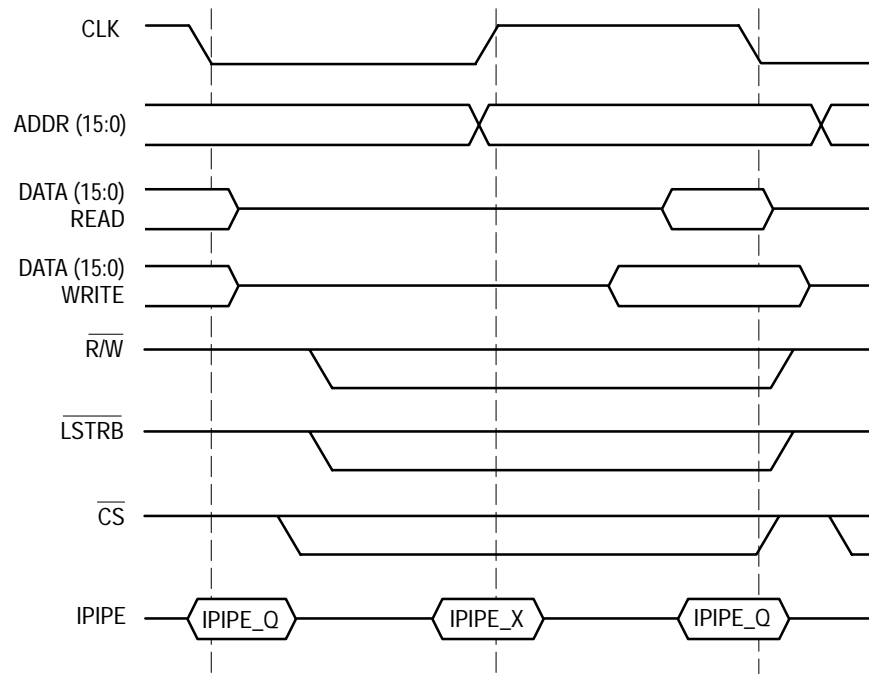


Figure 2-1: 68HC12 bus timing

## Symbols

The TMS 241 support supplies three symbol table files. The 68HC12\_CS symbol file may be used for triggering or display. The 68HC12Ctl2 symbol file may be used for triggering or display. The 68HC12Ctrl symbol file may be used for triggering or display.

Table 2–1 lists the name, bit pattern, and description for the symbols in the file 68HC12\_CS, the Chip\_Sel channel group symbol table.

**Table 2–1: Chip\_Sel group symbol table definitions**

Symbol	Chip_Sel group value						Description
	PF6/CSP1- PF5/CSP0- PF4/CSD-			PF3/CS3- PF2/CS2- PF1/CS1- PF0/CS0-			
CSP1-	0	1	1	1	1	1	Chip select program space 1
CSP0-	1	0	1	1	1	1	Chip select program space 0
CSD-	1	1	0	1	1	1	Chip select data space
CS3-	1	1	1	0	1	1	Chip select 3
CS2-	1	1	1	1	0	1	Chip select 2
CS1-	1	1	1	1	1	0	Chip select 1
CS0-	1	1	1	1	1	0	Chip select 0

Table 2–2 lists the name, bit pattern, and description for the symbols in the 68HC12Ctl2 channel group symbol table.

**Table 2–2: Ctrl2 group symbol table definitions**

Symbol	Ctrl2 group value		Description
	IPIPE1_Q IPIPE0_Q		
NoQueueMv	0	0	No queue movement
LtchBus	0	1	Latch the previous data to the buffer
AdvLdBus	1	0	Advance the queue and load from the bus
AdvLdLtch	1	1	Advance the queue and load from the latch

Table 2–3 lists the name, bit pattern, and description for the symbols in the 68HC12Ctrl channel group symbol table.

**Table 2–3: Control group symbol table definitions**

Symbol	Control group value	Description
	RESET- PE6/PIPE1 PE5/PIPE0 PE3/LSTRB- PE2/R/W-	
RESET~	0 X X X X	RESET
NoStart	1 0 0 X X	No start execution
StrtInt	1 0 1 X X	Start the interrupt sequence
StrtEven	1 1 0 X X	Start execution with the even byte
StrtOdd	1 1 1 X X	Start execution with the odd byte
LSTRB~	1 X X 0 X	Low byte strobe
WORD READ	1 X X X 1	Read cycle
WORD WRITE	1 X X X 0	Write cycle



# Acquiring and Viewing Disassembled Data

## Acquiring Data

Once you load the 68HC12 support and specify the trigger, you are ready to acquire and disassemble data.

If you have any problems acquiring data, refer to information on basic operations in your online help or *Appendix A: Error Messages and Disassembly Problems* in the basic operations user manual.

## Viewing Disassembled Data

You can view disassembled data in four display formats: Hardware, Software, Control Flow, and Subroutine. The information on basic operations describes how to select the disassembly display formats.

---

**NOTE.** *Selections in the Disassembly property page (the Disassembly Format Definition overlay) must be set correctly for your acquired data to be disassembled correctly. Refer to Changing How Data is Displayed on page 2–8.*

---

The default display format shows the Address, Data, and Control channel group values for each sample of acquired data.

If a channel group is not visible, you must use the Disassembly property page to make the group visible.

The disassembler displays special characters and strings in the instruction mnemonics to indicate significant events. Table 2–4 lists these special characters and strings, and gives a definition of what they represent.

**Table 2–4: Description of special characters in the display**

Character or string displayed	Description
>> on the TLA 700 m on the DAS 9200	The interpretation of the instruction was manually changed using the Mark Cycle function
****	Indicates there is insufficient data available for complete disassembly of the instruction. The number of asterisks indicates the width of the data that is unavailable. Each two asterisks represent one byte.
#	Indicates an immediate value
t	Indicates the number shown is in decimal, such as #12t

### Hardware Display Format

In Hardware display format, the disassembler displays certain cycle type labels in parentheses. Reads to interrupt and exception vectors will be labeled with the vector name. The following is a list of cycle type labels.

- ( BYTE READ )
- ( BYTE WRITE )
- ( WORD READ )
- ( WORD WRITE )
- ( RESET )
- ( INTERRUPT SEQUENCE )
- ( INTERNAL )
- ( FLUSH )
- ( EXTENSION )

Sample	68HC12 Address	68HC12 Data	68HC12 Mnemonics	Addr Hi	Chip Sel	Timestamp
187	FSH_PUL_PGM+2E	333A	PULB	3F	CSD~	-2.374,500 us
188	INTERNAL_MEMORY+6	B3--	( Byte Read )	3F	---	-2.249,500 us
189	INTERNAL_MEMORY+6	BB--	( Byte Read )	3F	---	-2.124,500 us
190	INTERNAL_MEMORY+6	BB--	( Byte Read )	3F	---	-1.999,500 us
191	INTERNAL_MEMORY+7	6587	( Word Read )	3F	---	-1.874,500 us
192	INTERNAL_MEMORY+7	6587	( Word Read )	3F	---	-1.750,000 us
193	FSH_PUL_PGM+30	3220	( FLUSH )	3F	CSD~	-1.499,500 us
194	INTERNAL_MEMORY+9	--AA	( Byte Read )	3F	---	-1.374,500 us
195	INTERNAL_MEMORY+9	--AA	( Byte Read )	3F	---	-1.249,500 us
196	INTERNAL_MEMORY+9	--AA	( Byte Read )	3F	---	-1.124,500 us
197	INTERNAL_MEMORY+A	1234	( Word Read )	3F	---	-999,500 ns
198	INTERNAL_MEMORY+A	1234	( Word Read )	3F	---	-875,000 ns
199	FSH_PUL_PGM+32	CDA7	( EXTENSION )	3F	CSD~	-624,500 ns
200	INTERNAL_MEMORY+C	BB--	( Byte Read )	3F	---	-499,500 ns
201	INTERNAL_MEMORY+C	BB--	( Byte Read )	3F	---	-374,500 ns
202	INTERNAL_MEMORY+C	BBA7	( INTERRUPT SEQUENCE )	3F	---	-249,500 ns
203	FFFA	EF3A	( VECTOR: XIRQ )	3F	CSP0-	0 ps
204	INTERNAL_MEMORY+B	2F40	( Word Write )	3F	---	125,000 ns
205	EF3A	F70A	FSH_QADB	3F	CSP0-	375,000 ns
206	INTERNAL_MEMORY+9	6587	( Word Write )	3F	---	500,500 ns
207	INTERNAL_MEMORY+7	3412	( Word Write )	3F	---	625,500 ns
208	EF3D	DB27	SEQ_EF46	3F	CSP0-	875,000 ns
209	INTERNAL_MEMORY+5	AABE	( Word Write )	3F	---	1,000,500 us
210	INTERNAL_MEMORY+4	9E--	( Byte Write )	3F	---	1,125,500 us
211	EF3E	07A6	( EXTENSION )	3F	CSP0-	1,375,000 us
212	QADB	--00	( Byte Read )	3F	---	1,500,500 us
213	QADB	--00	( Byte Read )	3F	---	1,625,500 us
214	EF40	808A	( FLUSH )	3F	CSP0-	1,875,500 us
215	EF46	CD00	LDY #0002	3F	CSP0-	2,125,500 us
216	EF49	02CC	LDD #FFFA	3F	CSP0-	2,376,000 us
217	EF4A	FFFA	( EXTENSION )	3F	CSP0-	2,625,500 us

Figure 2-2: Example of the hardware display

### Displaying Exception Vectors

When a vector read caused by an execution is detected, it will be labeled with the vector name. The following are the Interrupt/Exception labels:

- ( VECTOR:SYSTEM RESET )
- ( VECTOR:COP RESET )
- ( VECTOR:IRQ )
- ( VECTOR:TIMER CHANNEL 0 )
- ( VECTOR:TIMER CHANNEL 1 )
- ( VECTOR:TIMER CHANNEL 2 )
- ( VECTOR:TIMER CHANNEL 3 )
- ( VECTOR:TIMER CHANNEL 4 )
- ( VECTOR:TIMER CHANNEL 5 )
- ( VECTOR:TIMER CHANNEL 6 )

( VECTOR:TIMER CHANNEL 7 )  
 ( VECTOR:TIMER OVERFLOW )  
 ( VECTOR: PULSE ACC OVERFLOW )  
 ( VECTOR: PULSE ACC INP EDGE )  
 ( VECTOR:SCI 0 )  
 ( VECTOR:SCI 1 )  
 ( VECTOR:ATD )  
 ( VECTOR:KEY WAKEUP J )  
 ( VECTOR:KEY WAKEUP H )  
 ( VECTOR:RESERVED )

**Software Display Format**

The Software display format shows only the first fetch of executed instructions. Flushed cycles and extensions are not shown, even though they are part of the executed instruction. Read extensions will be used to disassemble the instruction, but will not be displayed as a separate cycle in the Software display format. Data reads and writes are not displayed.

**Control Flow Display Format**

In the Control Flow display format, only the first fetch of instructions that change the flow of control, or cause a branch in the addressing will be displayed.

If a conditional branch branches to an address that is reached sequentially, it might be impossible to determine if the branch was taken. If this happens the branch will not be displayed in the Control Flow display, and no flushing will be done by the software. Unconditional branches are always displayed whether or not the destination address is seen on the bus.

Instructions that unconditionally generate a change in the flow of control in the 68HC12 microcontroller are as follows:

BRA	LBRA	BSR	CALL	JMP
JSR	RTC	RTS	WAI	RTI
SWI	TRAP			

Instructions that conditionally generate a change in the flow of control in the 68HC12 microcontroller are as follows:

BCC	BCS	BEQ	BGND	BMI
BNE	BPL	BVC	BVS	BHI
BHS	BLO	BLS	BGE	BGT
BLE	BLT	BRCLR	BRSET	LBCC
LBCS	LBEQ	LBMI	LBNE	LBPL
LBVC	LBVS	LBHI	LBHS	LBLO
LBSL	LBGE	LBGT	LBLLE	LBLT
DBEQ	DBNE	IBEQ	IBNE	STOP
TBEQ	TBNE			

**Subroutine Display Format**

The Subroutine display format shows only the first fetch of subroutine call and return instructions. It will display conditional subroutine calls if they are considered to be taken.

Instructions that unconditionally generate a subroutine call or a return in the 68HC12 microcontroller are as follows:

BSR	CALL	JMP	JSR
RTC	RTS	WAI	RTI
SWI	TRAP		

Instructions that conditionally generate a subroutine call or a return in the 68HC12 microcontroller are as follows:

There are no conditional subroutine calls.

## Changing How Data is Displayed

There are common fields and features that allow you to further modify displayed data to suit your needs. You can make common and optional display selections in the Disassembly property page (the Disassembly Format Definition overlay).

You can make selections unique to the 68HC12 support to do the following tasks.

**Optional Display Selections For the TLA 700**

You can make optional selections for acquired disassembled data. In addition to the common selections that is described in the information on basic operations, you can change the displayed data in the following ways:

Show:	Hardware	(default setting)
	Software	
	Control Flow	
	Subroutine	

Highlight:	Software	(default setting)
	Control Flow	
	Subroutine	
	None	

Disassemble Across Gaps:	Yes	(default setting)
	No	

### Optional Display Selections For the DAS 9200

You can make optional selections for acquired disassembled data. In addition to the common selections that is described in the information on basic operations, you can change the displayed data in the following ways:

Display Mode:	Hardware Software Control Flow Subroutine	(default setting)
Timestamp:	Relative Delta Absolute Off	(default setting)
Highlight:	All Instructions Control Flow Subroutines	(default setting)
Highlight gaps:	Yes No	(default setting)
Disasm Across Gaps:	Yes No	(default setting)

### Optional Display Selections

The TMS 241 will add a field to the Define Format overlay (F5) to allow you to select between a 16- and 8-bit bus. The field name is Bus Width.

The disassembler needs this information to know where to find the data for correct disassembly. You must select either Byte Mode or Word Mode. The the default selection is Word Mode.

### Marking Cycles

The TMS 241 will only allow marking of instruction fetch cycles (which include read extensions and flush cycles). If the cursor is placed on any other cycle type, no cycle marks will be available.

**TLA 700 Series.** Marks are placed by using the Mark Opcode button. The Mark Opcode button is always be available. If the sample being marked is not an instruction fetch cycle, the Mark Opcode selections will be replaced by a note indicating that “An Opcode Mark cannot be placed at the selected data sample.”

When a cycle is marked, the character “>>” is displayed immediately to the left of the Mnemonics column. Cycles can be unmarked by using the “Undo Mark” selection, which will remove the character “>>”.

**DAS 9200 Series.** Marks are placed by using the F4 key: Mark Data function key. The Mark Data function key is always be available. If the cursor is not on an instruction fetch cycle, then no microprocessor cycle marks will be available when the key is pressed.

When a cycle is marked, the letter “m” is displayed immediately to the left of the Sequence column. Cycles can be unmarked by using the “Undo Mark” selection, which will remove the letter “m”.

### Cycle Marking

The TMS 241 supports cycle marks. In Byte Mode the following marks are available:

- Opcode
- Extension
- Flush
- Data
- Internal
- Undo Mark

In Word Mode the following marks are available:

- Even/Odd Opcode/Opcode
- Even/Odd Opcode/Extension
- Even/Odd Extension/Opcode
- Even/Odd Extension/Extension
- Even/Odd Flush/Opcode
- Even/Odd Opcode/Flush
- Even/Odd Extension/Flush
- Even/Odd Flush/Flush
- Even/Odd Data
- Even/Odd Internal
- Undo Mark

## Microprocessor Specific Disassembly Restrictions

The 68HC12 can function as a single chip microcomputer with all of the pins set up as I/O to control hardware. When the 68HC12 is operating in this mode the TMS 241 software cannot acquire program execution correctly. In order for the TMS 241 software to acquire useful disassembly, the 68HC12 must be configured so that the support can acquire bus activity.

In order for the TMS 241 to successfully acquire data the 68HC12 must be configured so that the acquisition software has access to the following:

- ECLK (PE4) must be configured to stretch instead of free running in the Mode Register.
- The 16-bits of the address: Port A and Port B
- The data: either as an 8- or 16-bit data bus depending on the configuration; Port C and Port D
- The Pipe Status signals (PE[6-5])

The following signals are used, and have a small effect on the disassembler:

- The R/W signal (PE2) that distinguishes the read cycles from the write cycles
- LSTRB (PE3) is used to distinguish the byte and word cycles; and which byte is valid.
- The mode register can be set to allow internal cycles from the internal EEPROM and RAM to be visible on the external bus, which can also be controlled by the mode select signals at reset time.
- The reset line is monitored and used in the clocking algorithm of the support.

The TMS 241 can provide support for:

- Either an 8- or 16-bit bus. The system bus width can be selected in the disassembly properties window, and defaults to a 16-bit bus.
- High address bits A16 through A21, Port G
- Symbolic support for the chip select bits, Port F

Figure 2–3 shows a sample acquisition after power up reset. After power up reset, and until the ports are initialized, the Pipe Status signals are not set correctly and therefore disassembly is not reliable.

In Figure 2–3 the Data group is indicated to be in byte mode. The raw data group is not normally enabled, but it can be when you want to know what is on the entire bus when the control signals are correct.

You can use the Mark Opcode feature to force the disassembler to show mnemonics. In Figure 2–3 Sequence numbers 9 through 13 have been marked, and have the marking symbol >> preceding the mnemonic, and force the ( Byte Read ) to show the mnemonic.

Sample	68HC12 Address	68HC12 Data	Data	68HC12 Mnemonics	Addr_Hi	Chip_Sel	Timestamp
0	0000	0000	0000	( RESET )	00	0000000	0 ps
1	0000	FFFF	FFFF	( RESET )	3F	CSPO-	37,783,500 ns
2	0000	FFFF	FFFF	( RESET )	3F	CSPO-	56,688,000 ns
3	0000	FFFF	FFFF	( RESET )	3F	CSPO-	56,759,500 ns
4	0000	FFFF	FFFF	( RESET )	3F	CSPO-	57,282,000 ns
5	0000	FFFF	FFFF	( RESET )	3F	CSPO-	75,575,500 ns
6	0000	FFFF	FFFF	( RESET )	3F	CSPO-	10,228,228,000 ns
7	FFFE	FD--	FD80	( Byte Read )	3F	CSPO-	10,228,727,500 ns
8	FFFE	FD90	FD90	( VECTOR: SYSTEM RESET )	3F	CSPO-	10,229,352,500 ns
9	FD80	4C09	4C09	RESET 0009, \$R0	3F	CSPO-	10,229,852,500 ns
10	FD83	804C	804C	RESET 0008, \$R0	3F	CSPO-	10,230,353,000 ns
11	FD84	0880	0880	( EXTENSION )	3F	CSPO-	10,230,978,000 ns
12	FD86	CF0C	CF0C	LDS #0C00	3F	CSPO-	10,231,853,000 ns
13	FD88	004F	004F	( EXTENSION )	3F	CSPO-	10,232,353,000 ns
14	FD8A	6F--	6F01	( Byte Read )	3F	CSPO-	10,233,103,500 ns
15	FD8C	03--	0306	( Byte Read )	3F	CSPO-	10,233,728,500 ns
16	FD90	CE--	CE0A	( Byte Read )	3F	CSPO-	10,234,228,000 ns
17	FD92	00--	0069	( Byte Read )	3F	CSPO-	10,234,728,500 ns
18	FD94	30--	308E	( Byte Read )	3F	CSPO-	10,235,353,500 ns
19	FD96	0C--	0C00	( Byte Read )	3F	CSPO-	10,235,853,500 ns
20	FD98	26--	26F9	( Byte Read )	3F	CSPO-	10,236,478,500 ns
21	FD9A	86--	862C	( Byte Read )	3F	CSPO-	10,236,978,000 ns
22	FD9C	5A--	5A0A	( Byte Read )	3F	CSPO-	10,237,478,500 ns
23	FD92	00--	0069	( Byte Read )	3F	CSPO-	10,237,978,000 ns
24	FD94	30--	308E	( Byte Read )	3F	CSPO-	10,238,478,500 ns
25	FD96	0C--	0C00	( Byte Read )	3F	CSPO-	10,238,978,000 ns
26	FD98	26--	26F9	( Byte Read )	3F	CSPO-	10,239,603,000 ns
27	FD9A	86--	862C	( Byte Read )	3F	CSPO-	10,240,103,500 ns
28	FD9C	5A--	5A0A	( Byte Read )	3F	CSPO-	10,240,603,500 ns

Figure 2-3: Sample disassembly after a power up reset





# Specifications



# Specifications

This chapter contains information regarding the specifications of the support.

## Specification Tables

Table 3–1 lists specifications the system under test must produce for the support to correctly acquire data.

**Table 3–1: Specifications**

Characteristics	Requirements
system under test clock rate	
Clock rate	Maximum      8 MHz
Minimum setup time required	
TLA 700	2.5 ns
DAS 9200	5 ns
Minimum hold time required	
TLA 700	0 ns
DAS 9200	0 ns





# Replaceable Parts



# Replaceable Parts

This section contains a list of the replaceable parts for the TMS 241 68HC12 microcontroller support product.

## Parts Ordering Information

Replacement parts are available through your local Tektronix field office or representative.

Changes to Tektronix products are sometimes made to accommodate improved components as they become available and to give you the benefit of the latest improvements. Therefore, when ordering parts, it is important to include the following information in your order.

- Part number
- Instrument type or model number
- Instrument serial number
- Instrument modification number, if applicable

If you order a part that has been replaced with a different or improved part, your local Tektronix field office or representative will contact you concerning any change in part number.

**Abbreviations**      Abbreviations conform to American National Standard ANSI Y1.1–1972.

**Mfr. Code to Manufacturer Cross Index**      The table titled Manufacturers Cross Index shows codes, names, and addresses of manufacturers or vendors of components listed in the parts list.

## Replaceable Parts

---

### Manufacturers cross index

---

<b>Mfr. code</b>	<b>Manufacturer</b>	<b>Address</b>	<b>City, state, zip code</b>
80009	TEKTRONIX INC	14150 SW KARL BRAUN DR PO BOX 500	BEAVERTON, OR 97077-0001

---

### Replaceable parts list

---

<b>Fig. &amp; index number</b>	<b>Tektronix part number</b>	<b>Serial no. effective</b>	<b>Serial no. discount'd</b>	<b>Qty</b>	<b>Name &amp; description</b>	<b>Mfr. code</b>	<b>Mfr. part number</b>
	071-0145-00			1	MANUAL, TECH: INSTRUCTIONS, 68HC12, TMS241,	80009	071-0145-00
	070-9803-00			1	MANUAL, TECH: INSTRUCTION, MICROPROCESSOR SUPPORT, PKG INSTALLATION, TLA700 SERIES, LOGIC ANALYZER	80009	070-9803-00
					<b>OPTIONAL ACCESSORIES</b>		
	070-9802-00			1	MANUAL, TECH: BASIC OPS MICRO SUP ON DAS/TLA 500 SERIES LOGIC ANALYZERS	80009	070-9802-00





# Index



# Index

## A

about this manual set, vii  
acquiring data, 2–5  
Address group, channel assignments, 1–3  
application, logic analyzer configuration, 1–1

## B

basic operations, where to find information, vii  
bus cycles, displayed cycle types, 2–6

## C

channel assignments  
  Address group, 1–3  
  Chip\_Sel, 1–5  
  clocks, 1–6  
  Control group, 1–4  
  Ctrl2, 1–5  
  Data group, 1–4  
  Misc group, 1–5  
channel group definitions, 2–1  
channel groups, visibility, 2–5  
Chip\_Sel, channel assignments, 1–5  
Chip\_Sel group, symbol table, 2–3  
clock channel assignments, 1–6  
clock rate, 1–2  
  maximum, 3–1  
clocking  
  clocking options, 2–1  
  custom clocking, 2–1  
  timing considerations, 2–1  
clocking options, 2–1  
  Show Cycles, 2–1  
connections, CPU to Mictor, 1–6  
contacting Tektronix, viii  
Control Flow display format, 2–7  
Control group  
  channel assignments, 1–4  
  symbol table, 2–4  
CPU to Mictor connections, 1–6  
Ctrl2, channel assignments, 1–5  
Ctrl2 group, symbol table, 2–3  
Custom clocking, Show Cycles, 2–1  
custom clocking, restrictions, 1–2  
cycle types, 2–6

## D

data  
  acquiring, 2–5  
  disassembly formats  
    Control Flow, 2–7  
    Software, 2–7  
    subroutine, 2–8  
data display, changing, 2–8  
Data group, channel assignments, 1–4  
definitions  
  disassembler, vii  
  HI module, viii  
  information on basic operations, vii  
  LO module, viii  
  logic analyzer, viii  
  P54C, vii  
  SUT, vii  
  XXX, vii  
disassembled data  
  cycle type definitions, 2–6  
  viewing, 2–5  
disassembler  
  definition, vii  
  logic analyzer configuration, 1–1  
  setup, 2–1  
Disassembly Format Definition overlay, 2–8, 2–9  
Disassembly property page, 2–8, 2–9  
display formats  
  Control Flow, 2–7  
  Software, 2–7  
  special characters, 2–5  
  subroutine, 2–8

## E

exception vectors, 2–6

## F

flow of control  
  conditional, 2–7  
  unconditional, 2–7

## H

Hardware display format, cycle type definitions, 2–6  
HI module, definition, viii  
hold time, minimum, 3–1

## I

IPIPE Execution information, 2–2  
IPIPE Queue Movement information, 2–1  
IPIPE\_Q, 2–2  
IPIPE\_X, 2–2

## L

LO module, definition, viii  
logic analyzer  
    configuration for disassembler, 1–1  
    configuration for the application, 1–1  
        with a DAS 9200 series, 1–1  
        with a TLA 700 series, 1–1  
    definition, viii  
    software compatibility, 1–1

## M

manual  
    conventions, vii  
    how to use the set, vii  
manufacturers cross reference, 4–2  
Mark Cycle function, 1–2  
Mark Opcode function, 1–2  
marking cycles, 2–9  
    unavailable, 1–2  
Mictor to CPU connections, 1–6  
Misc group, channel assignments, 1–5  
MTIF probes, 1–2

## P

P54C, definition, vii  
P6434 probes, labeling, 1–2  
parts ordering information, 4–1

## R

replaceable parts list, 4–2

Reset, SUT hardware, 1–2  
restrictions, 1–2  
    clock rate, 1–2  
    custom clocking, 1–2

## S

setup time, minimum, 3–1  
setups  
    disassembler, 2–1  
    support, 2–1  
Show Cycles, clocking option, 2–1  
signals, active low sign, viii  
Software display format, 2–7  
special characters displayed, 2–5  
specification tables, 3–1  
specifications, 3–1  
    channel assignments, 1–2  
subroutine display format, 2–8  
support, setup, 2–1  
support setup, 2–1  
SUT, definition, vii  
SUT hardware Reset, 1–2  
symbol table  
    Chip\_Sel channel group, 2–3  
    Control channel group, 2–4  
    Ctrl2 channel group, 2–3  
system clock rate, 1–2

## T

Tektronix, how to contact, viii  
terminology, vii  
timing considerations, 2–1

## V

viewing disassembled data, 2–5

## X

XXX, definition, vii