9A SYNCHRONOUS BUCK SWITCHING REGULATORWITH 1MHz OPERATION FREQUENCY

PRELIMINARY DATA SHEET

Pb Free Product

DESCRIPTION

The NX9511B is synchronous buck switching converter in multi chip module designed for step down DC to DC converter applications. They are optimized to convert bus voltages from 2V to 25V to as low as 0.8V output voltage. The output current can be up to 9A. The NX9511B offer an Enable pin that can be used to program the converter's start up. NX9511B operates at fixed internal frequency of 1MHz and employ loss-less current limiting protection by sensing the Rdson of synchronous MOSFET followed by latch out feature. Feedback under voltage triggers Hiccup.

Other features are: Internal digital soft start; Vcc undervoltage lock out and shutdown capability via the enable pin or comp pin. NX9511B is available in 5x5 MCM package.

FEATURES

- Switching Controller and MOSFETs in one package
- Bus voltage operation from 2V to 25V
- Fixed 1MHz
- Internal Digital Soft Start Function
- Output current up to 9A
- Enable pin to program BUS UVLO
- Programmable current limit triggers latch out by sensing Rdson of Synchronous MOSFET
- No negative spike at Vout during startup and shutdown
- Pb-free and RoHS compliant

APPLICATIONS

- Low Profile On board DC to DC Application
- Graphic Card on board converters
- Memory Vddq Supply
- ADSL Modem

TYPICAL APPLICATION

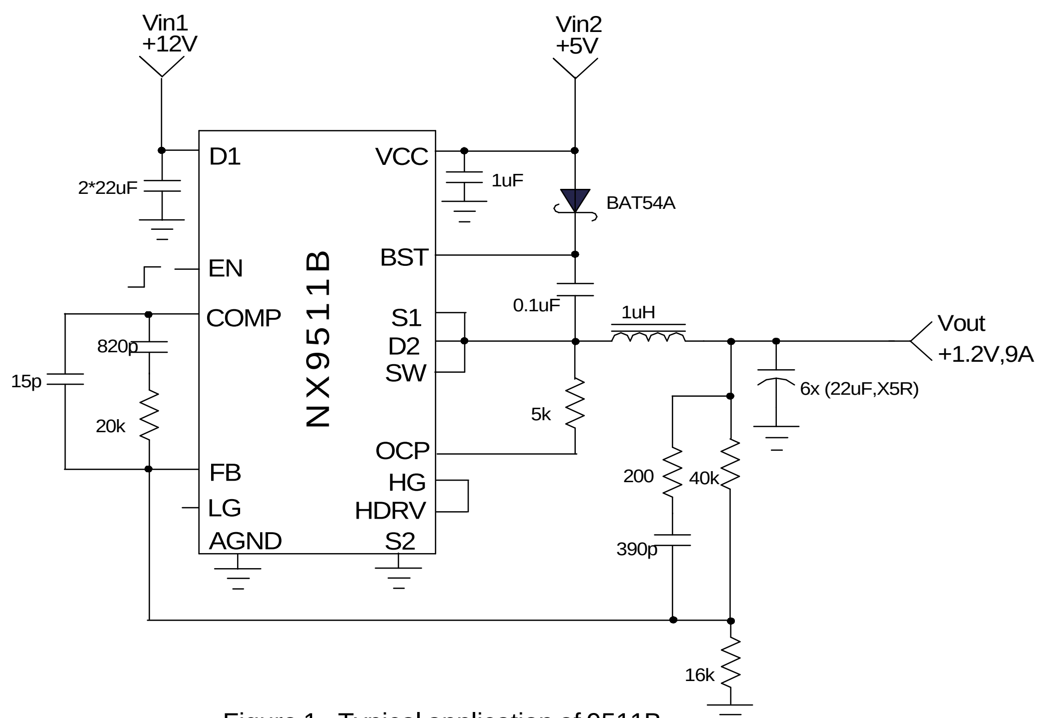


Figure 1 - Typical application of 9511B

ORDERING INFORMATION

Device	Temperature	Package	Frequency	Pb-Free
NX9511BCMTR	0 to 70°C	5X5 MCM-32L	1MHz	Yes

Microsemi
Analog Mixed Signal Group
11861 Western Avenue, Garden Grove, CA. 92841, 800-877-6458, 714-898-8121, Fax: 714-893-2570

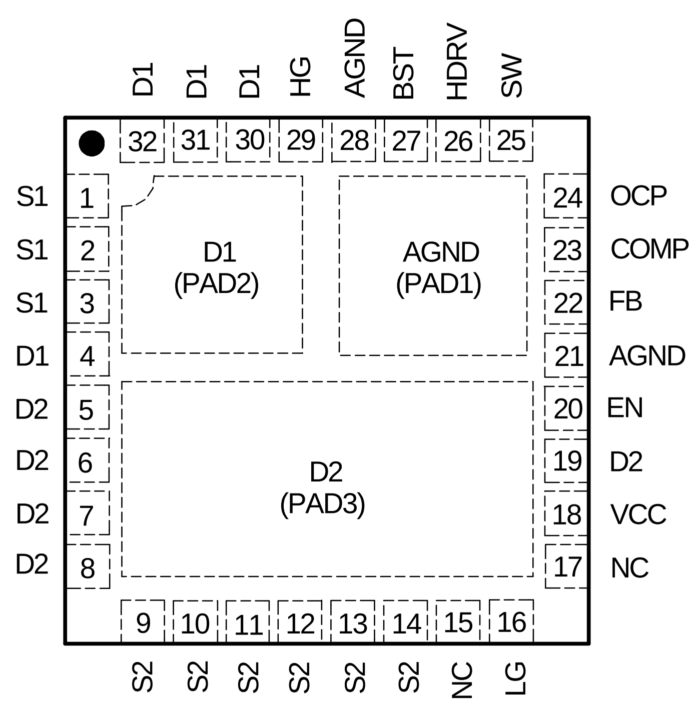
ABSOLUTE MAXIMUM RATINGS

VCC to GND & BST to SW voltage .... -0.3V to 6.5V
D1 to GND 25V
BST to GND Voltage .... -0.3V to 35V
D2,S1 to GND .... -2V to 35V
All other pins .... -0.3V to VCC+0.3V or 6.5V
Storage Temperature Range .... -65°C to 150°C
Operating Junction Temperature Range .... -40°C to 125°C
ESD Susceptibility 2kV
Power Dissipation .... TBD
Output Current ....TBD

CAUTION: Stresses above those listed in "ABSOLUTE MAXIMUM RATINGS", may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

PACKAGE INFORMATION

32-LEAD PLASTIC MCM 5 x 5



ELECTRICAL SPECIFICATIONS

Unless otherwise specified, these specifications apply over Vcc = 5V, V_{IN} = 12V and T_A= 0 to 70°C. Typical values refer to T_A = 25°C. Low duty cycle pulse testing is used which keeps junction and case temperatures equal to the ambient temperature.

PARAMETER	SYM	Test Condition	Min	TYP	MAX	Units
Reference Voltage						
Ref Voltage	V_{REF}			0.8		V
Ref Voltage line regulation				0.2		%
Supply Voltage(Vcc)						
V_{CC} Voltage Range	V_{CC}		4.5	5	5.5	V
V_{CC} Supply Current (Static)	I_{CC} (Static)	Outputs not switching		3		mA
Supply Voltage(V_{BST})						
V_{BST} Supply Current (Static)	I_{BST} (Static)	Outputs not switching		0.2		mA
VCC, V_{BST} Supply Current (Dynamic)	I(Dynamic)			15		mA
Under Voltage Lockout						
V_{CC}-Threshold	V_{CC}_UVLO	V_{CC} Rising		4		V
V_{CC}-Hysteresis	V_{CC}_Hyst	V_{CC} Falling		0.2		V
Oscillator						
Frequency	F_S			1		MHz
Ramp-Amplitude Voltage	V_{RAMP}			1.5		V
Max Duty Cycle				75		%
Min Duty Cycle					0	%
Error Amplifiers						
Transconductance				2000		umho
Input Bias Current	Ib			10		nA
EN & SS						
Soft Start time	Tss			2		mS
Enable HI Threshold				1.25		V
Enable Hysterises				150		mV
Ouput Stage						
High Side MOSFET R_{DSON}				17		ohm
Low Side MOSFET R_{DSON}				17		ohm
Output Current				9		A
OCP Adjust						
OCP current				40		uA
FB Under Voltage Protection						
FB Under Voltage Threshold				0.48		V

PIN DESCRIPTIONS

PIN #	PIN SYMBOL	PIN DESCRIPTION
1-3	S1	Bus input which is connected to high side MOSFET's drain.
5-8,19	D2	Drain of low side MOSFET.
9-14	S2	Source of low side MOSFET and need to be connected to power ground.
15,17	NC	
16	LG	Low side gate driver output for monitoring.
18	VCC	Power supply voltage. A high freq 1uF ceramic capacitor is placed as close as possible to and connected to this pin and ground pin. The maximum rating of this pin is 5V.
20	EN	External enable signal input for the controller.
22	FB	This pin is the error amplifier inverting input. It is connected via resistor divider to the output of the switching regulator to set the output DC voltage. When FB pin voltage is lower than 0.6V, hiccup circuit starts to recycle the soft start circuit after 2048 switching cycles.
23	COMP	This pin is the output of error amplifier and is used to compensate the voltage control feedback loop. This pin can also be used to perform a shutdown if pulled lower than 0.3V.
24	OCP	This pin is connected to the drain of the external low side MOSFET via resistor and is the input of the over current protection(OCP) comparator. An internal current source 40uA is flown to the external resistor which sets the OCP voltage across the Rdson of the low side MOSFET. Current limit point is this voltage divided by the Rds-on. Once this threshold is reached the Hdrv and Ldrv pins are latched out. Ground pin.
25	SW	SW is the controller pin out which needs to be connected to S1and D2 and provides return path for the high side driver.
26	HDRV	High side gate driver output which needs to be connected high side MOSFET gate HG.
27	BST	This pin supplies voltage to high side FET driver. A high freq 0.1uF ceramic capacitor is placed as close as possible to and connected to these pins and respected SW pins.
21,28	AGND	Analog ground.
29	HG	High side MOSFET gate which needs to be connected to high side gate driver output HDRV.
30-32,4	D1	Drain of High side MOSFET.

BLOCK DIAGRAM

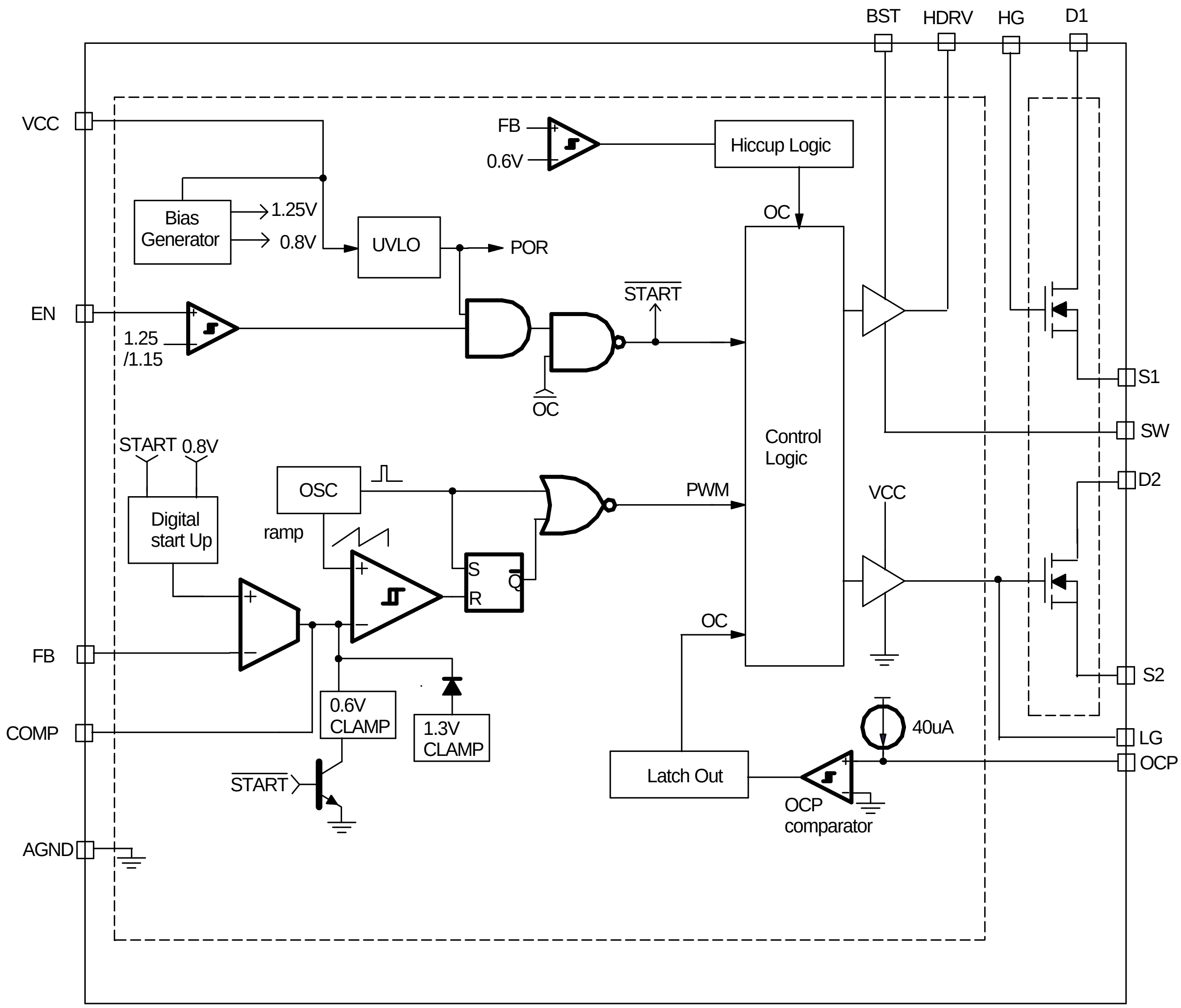


Figure 2 - Simplified block diagram of the NX9511B

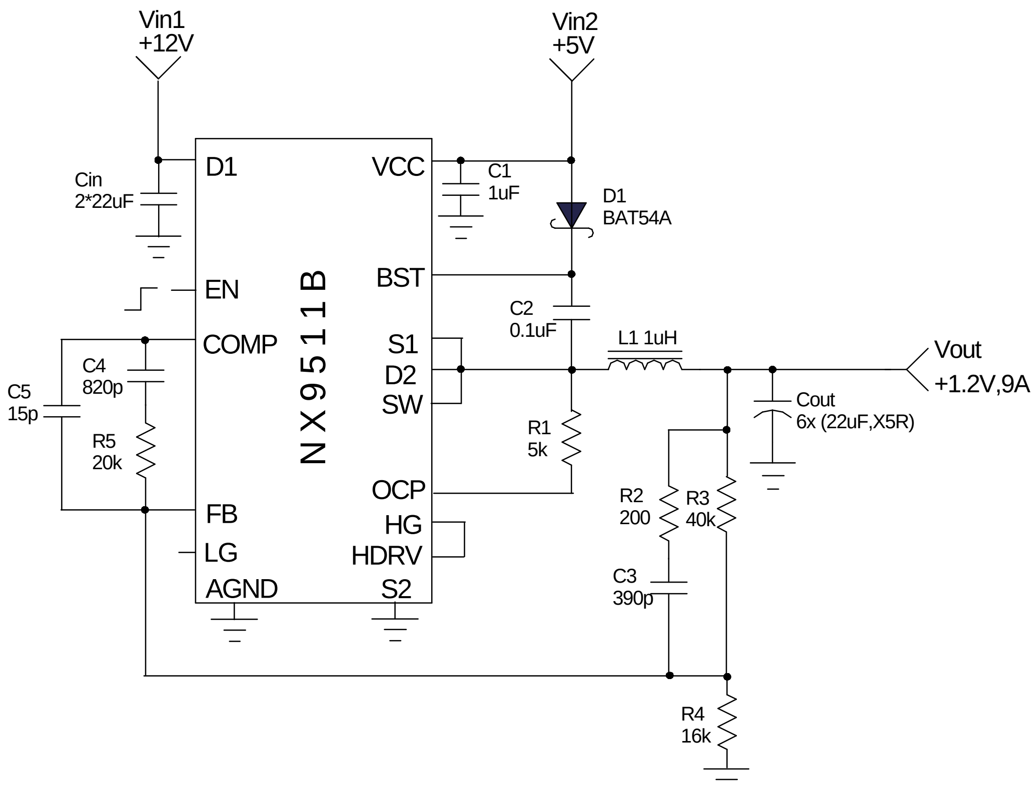


Figure 3- Demo board schematic

Bill of Materials

Item	Quantity	Reference	Value	Manufacture
1	1	C1	1u	
2	1	C2	0.1u	
3	1	C5	15p	
4	8	Cin,Cout	22u	
5	1	C4	820p	
6	1	C3	390p	
7	1	D1	BAT54A	
8	1	L2	DO3316P-102HC	Coilcraft
9	1	R5	20k	
10	1	R3	40k	
11	1	R2	200	
12	1	R4	16k	
13	1	U1	NX9511B/MLPQ32	
14	1	U2	L78L05AB/sot89	NEXSEM INC.

Demoboard waveforms

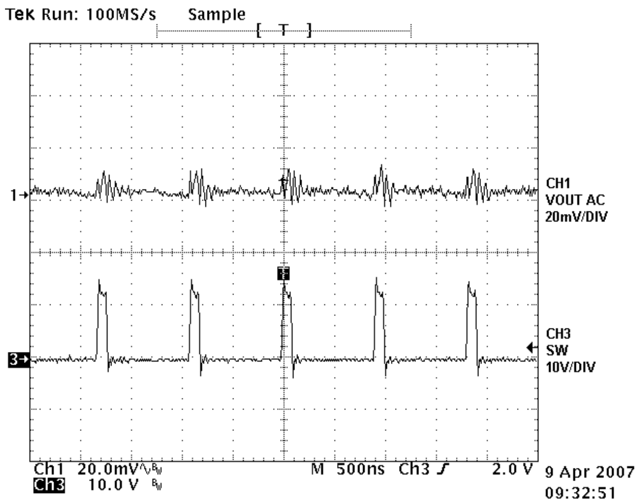


Figure 4 - Output ripple (VIN=12V,VOUT=1.2V)

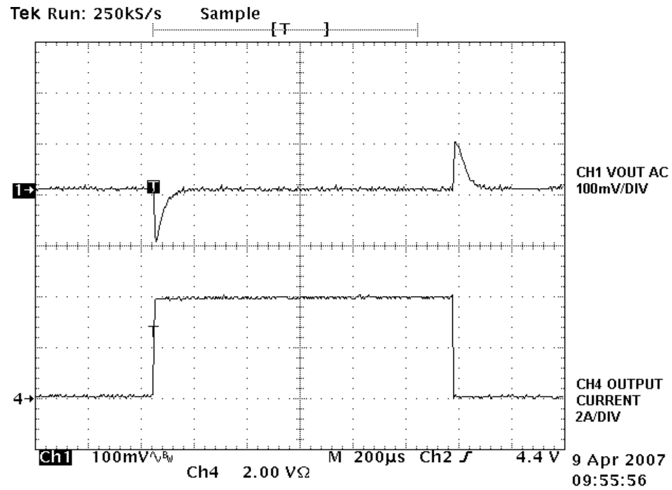


Figure 5 - Output voltage transient response (VIN=12V, VOUT=1.2V, IOUT=4A)

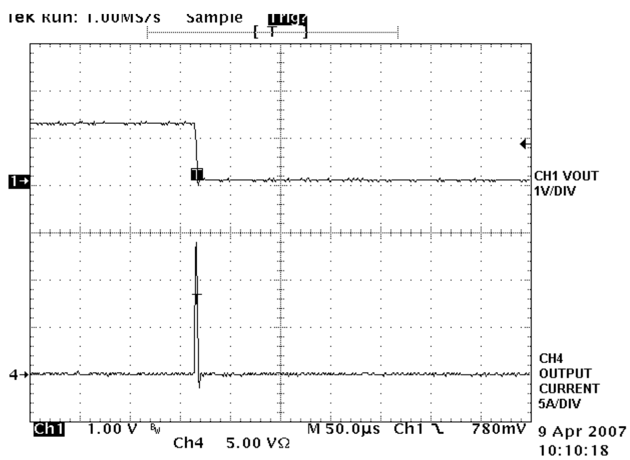


Figure 6 - Over current protection

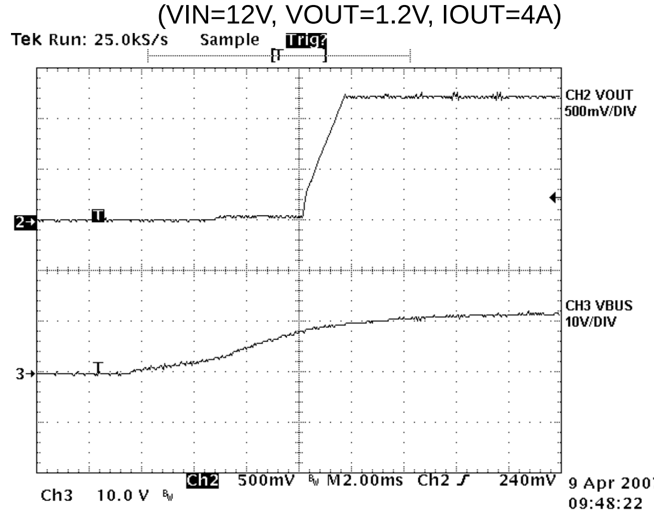


Figure 7 - Startup

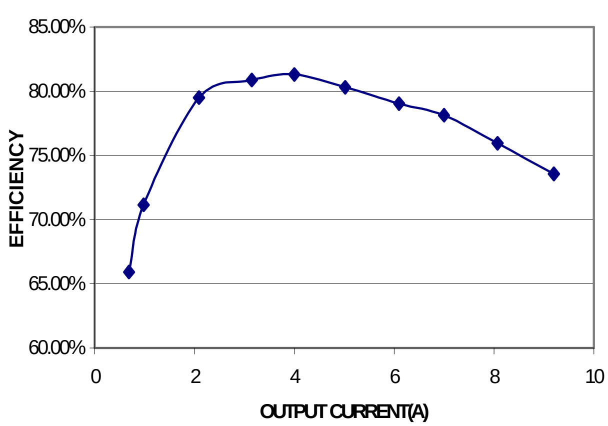


Figure 8 - Output Efficiency @VOUT=1.2V,VIN=12V

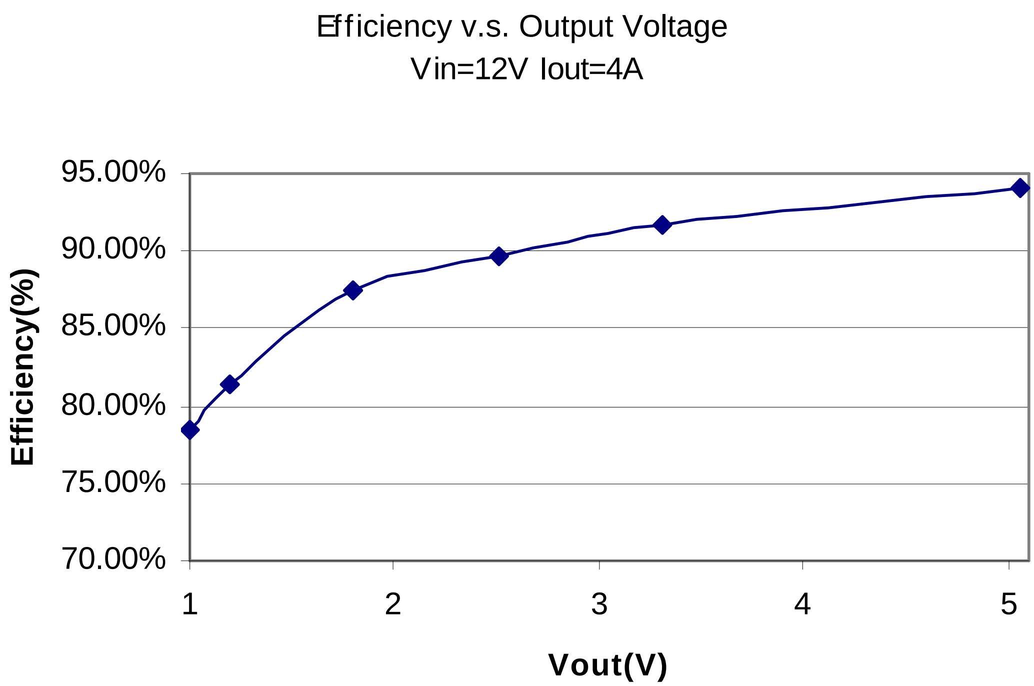


Figure 9 - Output Efficiency

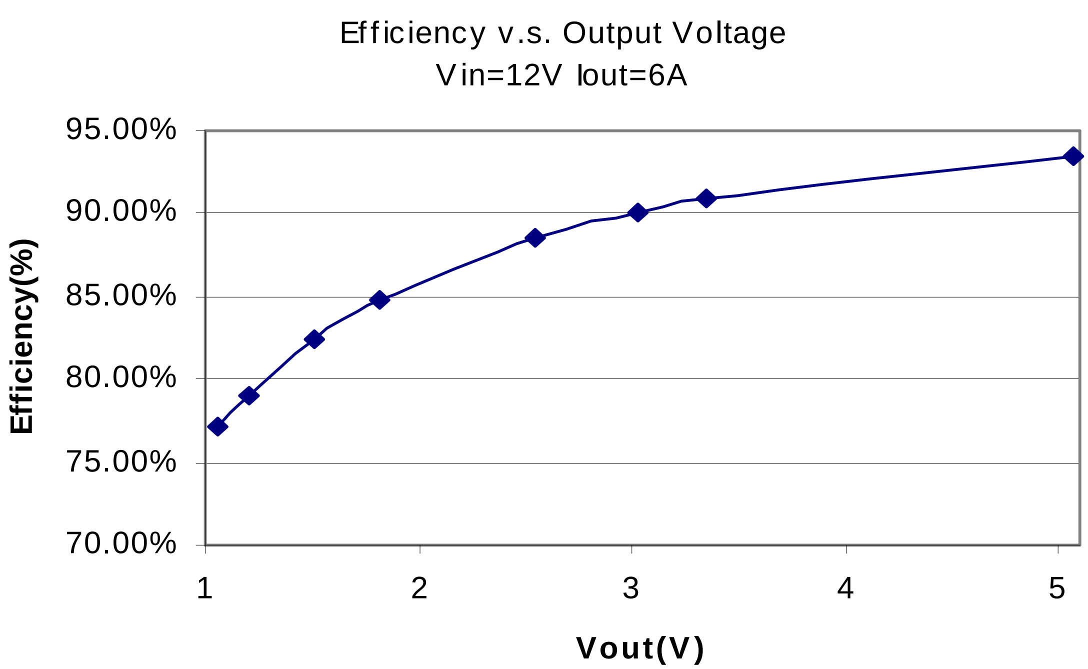


Figure 10 - Output Efficiency

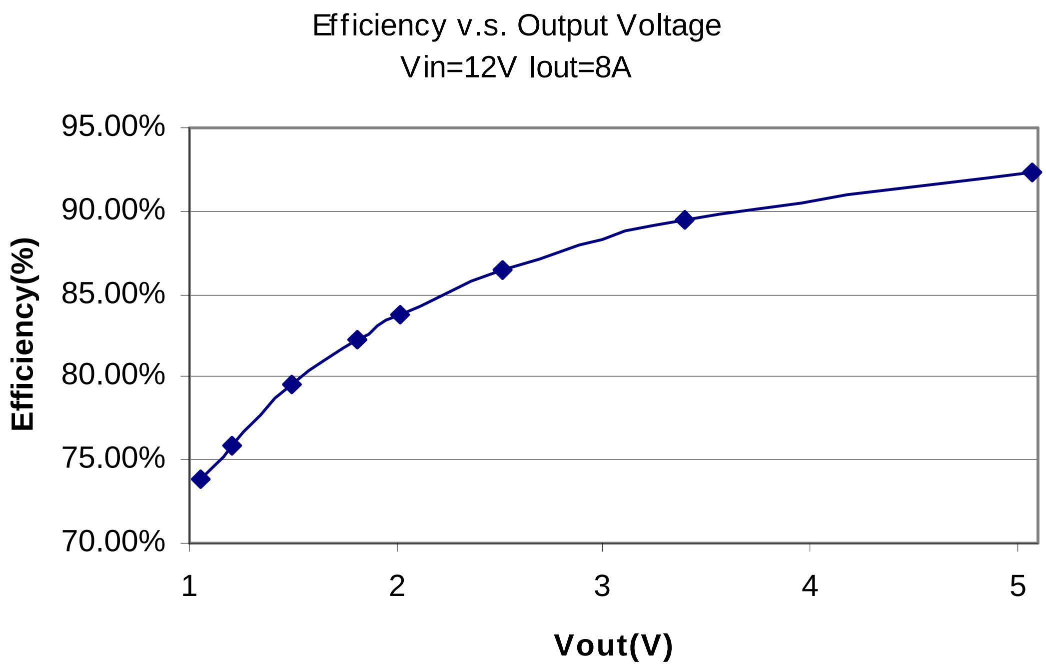


Figure 11 - Output Efficiency

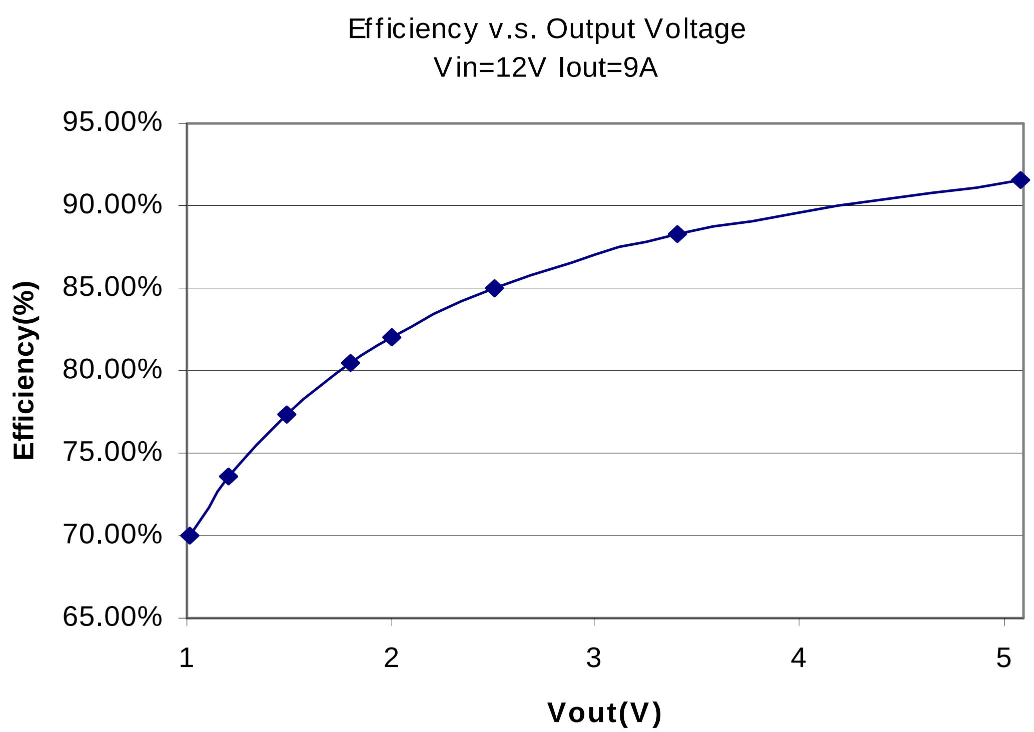


Figure 12 - Output Efficiency

Typical application

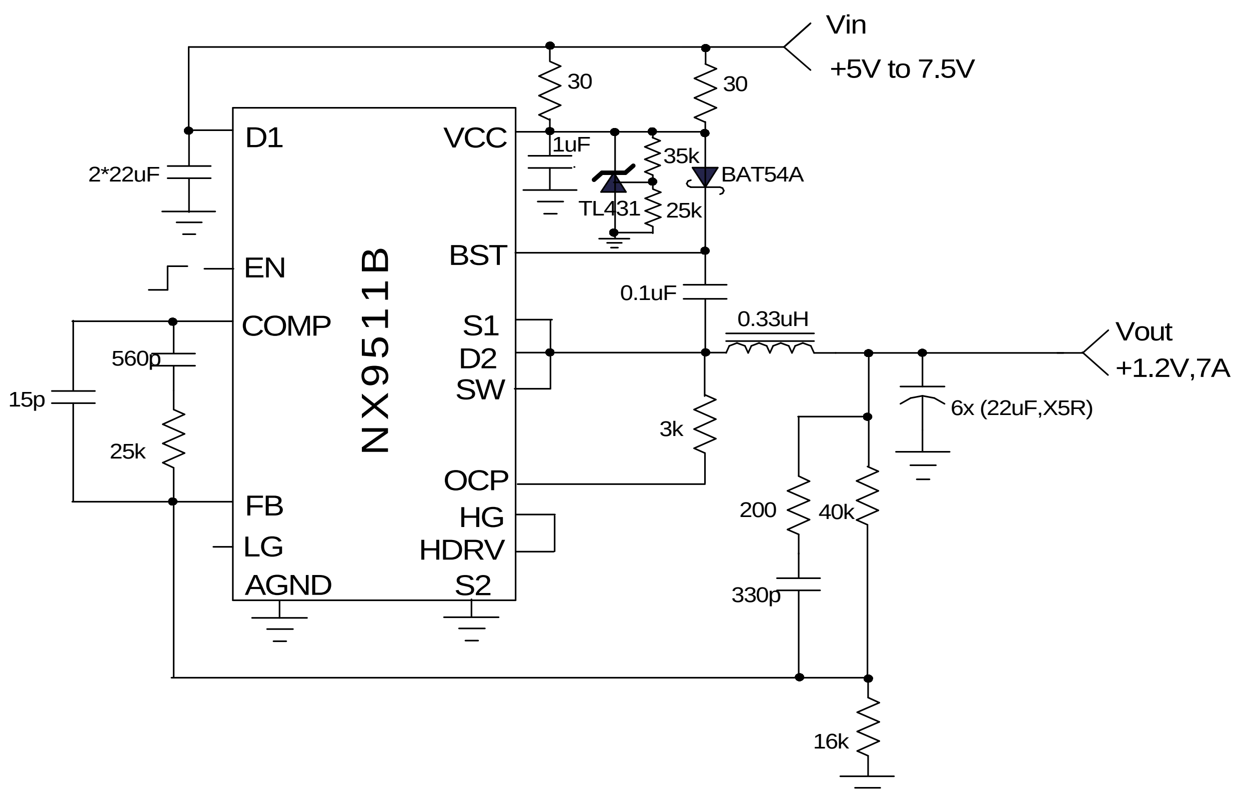


Figure 13 - Typical application of 9511B

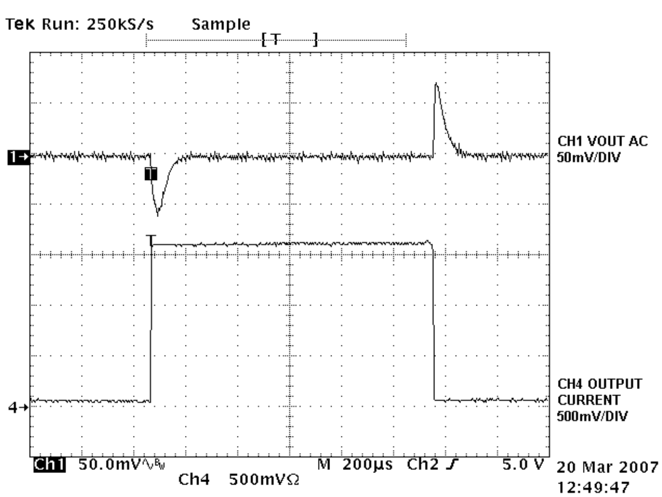


Figure 14 - Output voltage transient response
(VIN=5V, VOUT=1.2V, IOUT=1.5A)

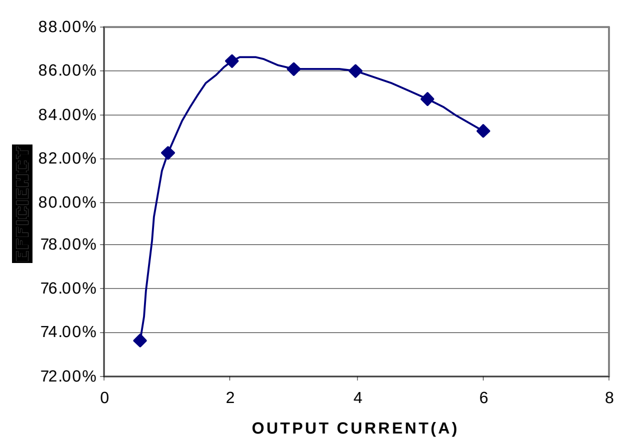


Figure 15 - Output Efficiency @VOUT=1.2V,VIN=5V

APPLICATION INFORMATION

Symbol Used In Application Information:

V_{IN} - Input voltage
V_{OUT} - Output voltage
I_{OUT} - Output current
ΔV_{RIPPLE} - Output voltage ripple
F_S - Working frequency
ΔI_{RIPPLE} - Inductor current ripple

Design Example

The following is typical application for NX9511B:
V_{IN} = 12V
V_{OUT}=1.8V
F_S=1000kHz
I_{OUT}=9A
ΔV_{RIPPLE}<=20mV
ΔV_{DROOP}<=100mV @ 9A step

Output Inductor Selection

The selection of inductor value is based on inductor ripple current, power rating, working frequency and efficiency. Larger inductor value normally means smaller ripple current. However if the inductance is chosen too large, it brings slow response and lower efficiency. Usually the ripple current ranges from 20% to 40% of the output current. This is a design freedom which can be decided by design engineer according to various application requirements. The inductor value can be calculated by using the following equations:

$$L_{OUT}=\frac{V_{IN}-V_{OUT}}{\Delta I_{RIPPLE}}\times\frac{V_{OUT}}{V_{IN}}\times\frac{1}{F_S} \qquad ...(1)$$
$$I_{RIPPLE}=k\times I_{OUTPUT}$$

where k is between 0.2 to 0.4.
Select k=0.3, then

$$L_{OUT}=\frac{12V-1.8V}{0.4\times 9A}\times\frac{1.8V}{12V}\times\frac{1}{1000kHz}$$
$$L_{OUT}=0.42uH$$

Choose inductor from COILCRAFT DO3316H-681MLD with L=0.68uH is a good choice.

Current Ripple is recalculated as

$$\Delta I_{RIPPLE}=\frac{V_{IN}-V_{OUT}}{L_{OUT}}\times\frac{V_{OUT}}{V_{IN}}\times\frac{1}{F_S}$$
$$=\frac{12V-1.8V}{0.68uH}\times\frac{1.8V}{12V}\times\frac{1}{1000kHz}=2.25A \qquad ...(2)$$

Output Capacitor Selection

Output capacitor is basically decided by the amount of the output voltage ripple allowed during steady state(DC) load condition as well as specification for the load transient. The optimum design may require a couple of iterations to satisfy both condition.

The amount of voltage ripple during the DC load condition is determined by equation(3).

$$\Delta V_{RIPPLE}=ESR\times\Delta I_{RIPPLE}+\frac{\Delta I_{RIPPLE}}{8\times F_S\times C_{OUT}} \qquad ...(3)$$

Where ESR is the output capacitors' equivalent series resistance,C_{OUT} is the value of output capacitors.

Typically ceramic capacitors are selected as output capacitors in NX9811B applications. DC ripple spec is easy to be met, usually mutiple ceramic capacitors are required at the output to meet transient requirement. In this example, two 47uF,X5R are used.

Compensator Design

Due to the double pole generated by LC filter of the power stage, the power system has 180^o phase shift , and therefore, is unstable by itself. In order to achieve accurate output voltage and fast transient response,compensator is employed to provide highest possible bandwidth and enough phase margin.Ideally,the Bode plot of the closed loop system has crossover frequency between1/10 and 1/5 of the switching frequency, phase margin greater than 50^o and the gain crossing 0dB with -20dB/decade. Power stage output capacitors usually decide the compensator type. If electrolytic capacitors are chosen as output capacitors, type II compensator can be used to compensate the system, because the zero caused by output capacitor ESR is lower than crossover frequency. Otherwise type III compensator should be chosen.

A. Type III compensator design

For low ESR output capacitors, typically such as Sanyo oscap and poscap, the frequency of ESR zero caused by output capacitors is higher than the cross-over frequency. In this case, it is necessary to compensate the system with type III compensator. The following figures and equations show how to realize the type III compensator by transconductance amplifier.

$$F_{Z1} = \frac{1}{2\times\pi\times R_4\times C_2} \quad ...(4)$$

$$F_{Z2} = \frac{1}{2\times\pi\times (R_2+R_3)\times C_3} \quad ...(5)$$

$$F_{P1} = \frac{1}{2\times\pi\times R_3\times C_3} \quad ...(6)$$

$$F_{P2} = \frac{1}{2\times\pi\times R_4\times \frac{C_1\times C_2}{C_1+C_2}} \quad ...(7)$$

where F_{Z1},F_{Z2},F_{P1} and F_{P2} are poles and zeros in the compensator. Their locations are shown in figure 4.

The transfer function of type III compensator for transconductance amplifier is given by:

$$\frac{V_e}{V_{OUT}} = \frac{1-g_m\times Z_f}{1+g_m\times Z_{in}+Z_{in}/R_1}$$

For the voltage amplifier, the transfer function of compensator is

$$\frac{V_e}{V_{OUT}} = \frac{-Z_f}{Z_{in}}$$

To achieve the same effect as voltage amplifier, the compensator of transconductance amplifier must satisfy this condition: R_4>>2/gm. And it would be desirable if $R_1||R_2||R_3$>>1/gm can be met at the same time.

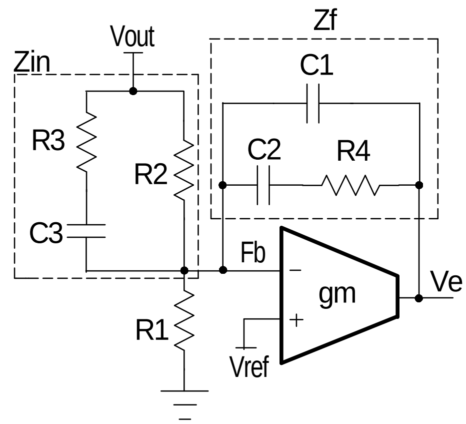


Figure 16 - Type III compensator using transconductance amplifier

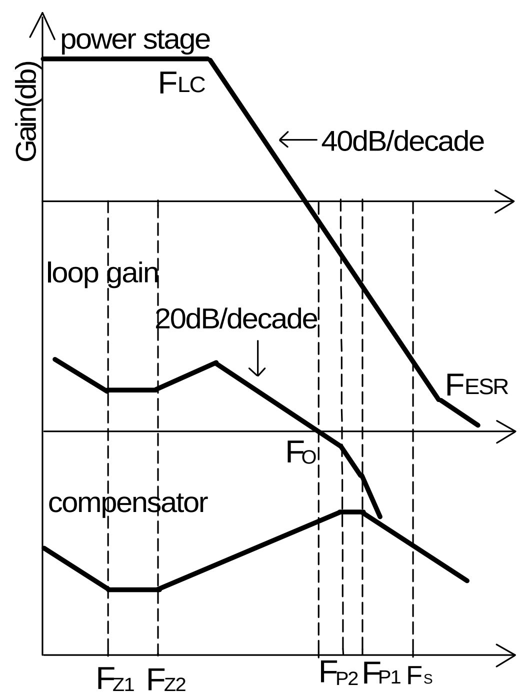


Figure 17 - Bode plot of Type III compensator

Design example for type III compensator are in order. The crossover frequency has to be selected as $F_{LC}<F_O<F_{ESR,}$ and $F_O<=1/10\sim1/5F_{s.}$

1.Calculate the location of LC double pole F_{LC} and ESR zero F_{ESR}.

$$F_{LC}=\frac{1}{2\times\pi\times\sqrt{L_{OUT}\times C_{OUT}}}=\frac{1}{2\times\pi\times\sqrt{0.68uH\times 94uF}}=20kHz$$

$$F_{ESR}=\frac{1}{2\times\pi\times ESR\times C_{OUT}}=\frac{1}{2\times\pi\times 0.5m\Omega\times 94uF}=3.4MHz$$

2. Set R_2 equal to 20kΩ.

$$R_1=\frac{R_2\times V_{REF}}{V_{OUT}-V_{REF}}=\frac{60k\Omega\times 0.8V}{1.8V-0.8V}=48k\Omega$$

Choose R_1=48kΩ.

3. Set zero $F_{Z2}=0.75F_{LC}$ and $F_{p1}=F_{ESR}$.

4. Calculate R_4 and C_3 with the crossover frequency at 1/10~ 1/5 of the switching frequency. Set F_O=100kHz.

$$C_3=\frac{1}{2\times\pi\times R_2}\times\left(\frac{1}{F_{z2}}-\frac{1}{F_{p1}}\right)=\frac{1}{2\times\pi\times 60k\Omega}\times\left(\frac{1}{15kHz}-\frac{1}{3.4MHz}\right)=180pF$$

$$R_4=\frac{V_{OSC}}{V_{in}}\times\frac{2\times\pi\times F_O\times L}{C_3}\times C_{out}=\frac{1.5V}{12V}\times\frac{2\times\pi\times 100kHz\times 0.68uH}{180pF}\times 94uF=28k\Omega$$

Choose C_3=180pF, R_4=30kΩ.

5. Calculate C_2 with zero F_{z1} at 50% of the LC double pole by equation (11).

$$C_2=\frac{1}{2\times\pi\times F_{Z1}\times R_4}=\frac{1}{2\times\pi\times 0.5\times 20kHz\times 30k\Omega}=533pF$$

Choose C_2=520pF.

6. Calculate C_1 by equation (14) with pole F_{p2} at half the switching frequency.

$$C_1=\frac{1}{2\times\pi\times R_4\times F_{P2}}=\frac{1}{2\times\pi\times 30k\Omega\times 500kHz}=10pF$$

Choose C_1=12pF

7. Calculate R_3 by equation (13).

$$R_3=\frac{1}{2\times\pi\times F_{P1}\times C_3}=\frac{1}{2\times\pi\times 3.4MHz\times 180pF}=261\Omega$$

Choose R_3=300Ω.

Output Voltage Calculation

Output voltage is set by reference voltage and external voltage divider. The reference voltage is fixed at 0.8V. The divider consists of two ratioed resistors so that the output voltage applied at the Fb pin is 0.8V when the output voltage is at the desired value. The following equation and picture show the relationship between V_{OUT}, V_{REF} and voltage divider.

$$R_1=\frac{R_2\times V_{REF}}{V_{OUT}-V_{REF}} \qquad ...(8)$$

where R_2 is part of the compensator, and the value of R_1 value can be set by voltage divider.

See compensator design for R_1 and R_2 selection.

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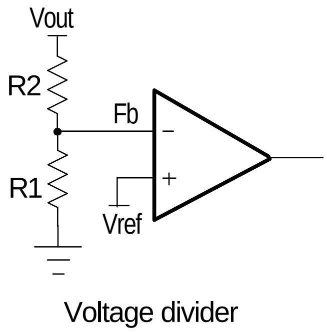


Figure 18 - Voltage divider

Soft Start and Enable

NX9511B has digital soft start for switching controller and has one enable pin for this start up. When the Power Ready (POR) signal is high and the voltage at enable pin is above 1.25V the internal digital counter starts to operate and the voltage at positive input of Error amplifier starts to increase, the feedback network will force the output voltage follows the reference and starts the output slowly. After 2048 cycles, the soft start is complete and the output voltage is regulated to the desired voltage decided by the feedback resistor divider.

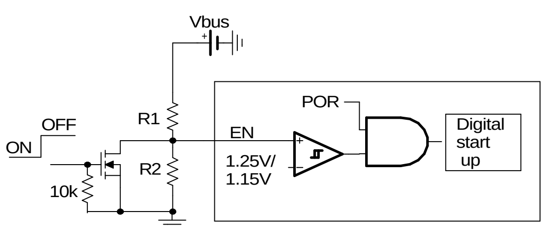


Figure 19 - Enable and Shut down the NX9511B with Enable pin.

The start up of NX9511B can be programmed through resistor divider at Enable pin. For example, if the input bus voltage is12V and we want NX9511B starts when Vbus is above 9V. We can select using the following equation.

$$R_1 = \frac{(9V - 1.25V) \times R_2}{1.25V}$$

The NX9511B can be turned off by pulling down the Enable pin by extra signal MOSFET as shown in the above Figure. When Enable pin is below 1.25V the digital soft start is reset to zero. In addition, all the high side and low side driver is off and no negative spike will be generated during the turn off.

Over Current Protection

Over current protection is achieved by sensing current through the low side MOSFET. An internal current source of 40uA flows through an external resistor connected from OCP pin to SW node sets the over current protection threshold. When synchronous FET is on, the voltage at node SW is given as

$$V_{SW} = -I_L \times R_{DSON}$$

The voltage at pin OCP is given as

$$I_{OCP} \times R_{OCP} + V_{SW}$$

When the voltage is below zero, the over current occurs.

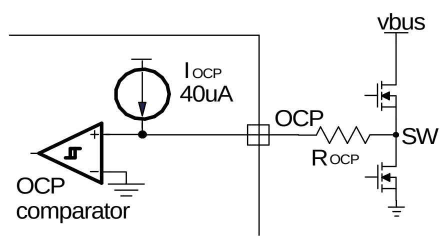


Figure 20 - Over current protection

The over current limit can be set by the following equation

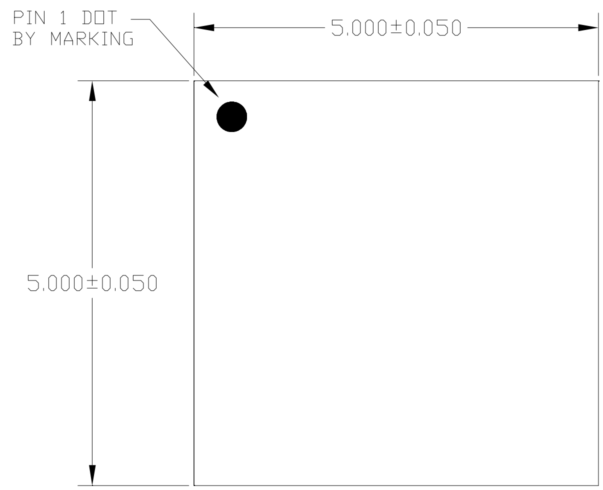
$$I_{SET} = \frac{I_{OCP} \times R_{OCP}}{K \times R_{DSON}}$$

The internal MOSFET R_{DSON}=17mΩ, the worst case thermal consideration K=1.3 and the current limit is set at 10A, then

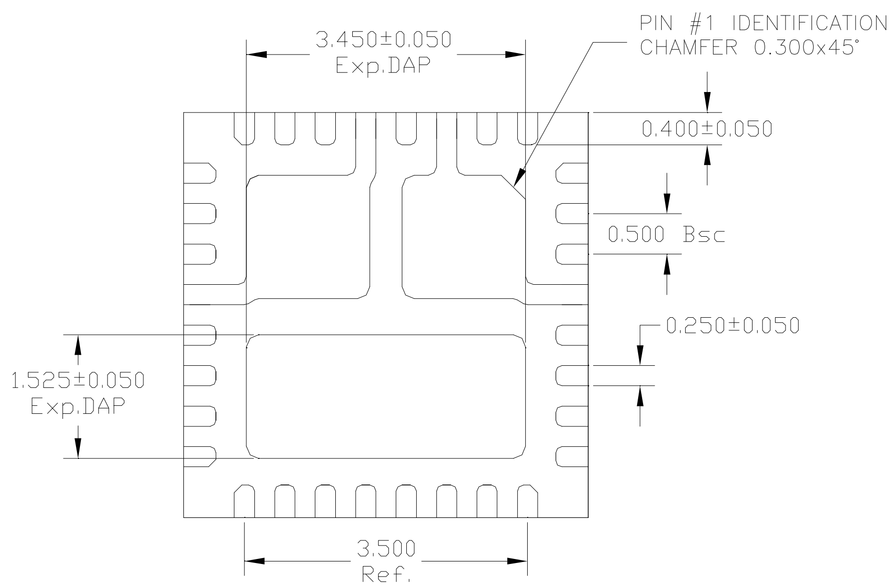
$$R_{OCP} = \frac{I_{SET} \times K \times R_{DSON}}{I_{OCP}} = \frac{10A \times 1.3 \times 17m\Omega}{40uA} = 5.5k\Omega$$

Choose R_{OCP}=5.5kΩ

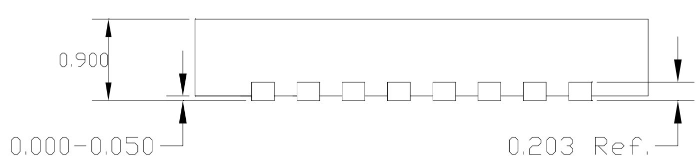
MLPQ 32 PIN 5 x 5 PACKAGE OUTLINE DIMENSIONS



TOP VIEW



BOTTOM VIEW



SIDE VIEW

NOTE: ALL DIMENSIONS ARE DISPLAYED IN MILLIMETERS.

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