





**AMC23C14** SBAS945A - FEBRUARY 2022 - REVISED JULY 2022

# AMC23C14 Dual, Fast Response, Reinforced Isolated Window Comparator With Adjustable Threshold

#### 1 Features

- Wide high-side supply range: 3 V to 27 V
- Low-side supply range: 2.7 V to 5.5 V
- **Dual window comparator:** 
  - Window comparator 1: ±20-mV to ±300-mV adjustable threshold
  - Window comparator 2: ±300-mV fixed threshold
- Supports positive-comparator mode:
  - Cmp0: 600-mV to 2.7-V adjustable threshold
  - Cmp2: 300-mV fixed threshold
  - Cmp1 and Cmp3: Disabled
- Reference for threshold adjustment: 100 µA, ±2%
- Trip threshold error: ±1% (max) at 250 mV
- Open-drain outputs
- Propagation delay: 280 ns (typ)
- High CMTI: 15 V/ns (min)
- Safety-related certifications:
  - 7000-V<sub>PK</sub> reinforced isolation per DIN EN IEC 60747-17 (VDE 0884-17)
  - 5000-V<sub>RMS</sub> isolation for 1 minute per UL1577
- · Fully specified over the extended industrial temperature range: -40°C to +125°C

## 2 Applications

- Overcurrent or overvoltage detection in:
  - Motor drives
  - Frequency inverters
  - Solar inverters
  - DC/DC converters

## 3 Description

The AMC23C14 is a dual. isolated window comparator with a short response time. The opendrain outputs are separated from the input circuitry by an isolation barrier that is highly resistant to magnetic interference. This barrier is certified to provide reinforced galvanic isolation of up to 5 kV<sub>RMS</sub> according to VDE 0884-17 and UL1577, and supports a working voltage of up to 1 kV<sub>PK</sub>.

Both comparators have windows that are centered around 0 V, meaning that the comparators trip if the input exceeds the thresholds in a positive or negative direction. One comparator has fixed thresholds of ±300 mV. The second comparator has adjustable thresholds from ±20 mV to ±300 mV through a single external resistor.

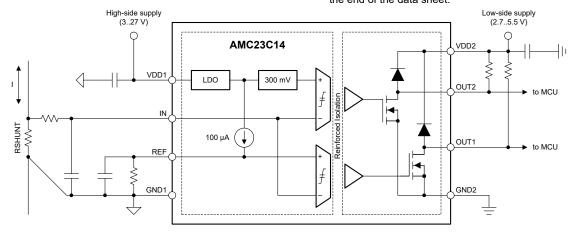
The AMC23C14 also supports a positive-comparator only mode. When the voltage on the REF pin is greater than 550 mV, the negative comparators are disabled and only the positive comparators are functional. The reference voltage in this mode can be as high as 2.7 V. This mode is particularly useful for monitoring positive voltage supplies.

The AMC23C14 is available in an 8-pin, wide-body SOIC package and is specified over the extended industrial temperature range of -40°C to +125°C.

#### Package Information<sup>(1)</sup>

|             |          | •                 |
|-------------|----------|-------------------|
| PART NUMBER | PACKAGE  | BODY SIZE (NOM)   |
| AMC23C14    | SOIC (8) | 5.85 mm × 7.50 mm |

For all available packages, see the orderable addendum at the end of the data sheet.



Typical Application



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## **4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

# Changes from Revision \* (February 2022) to Revision A (July 2022)Page• Changed document status from advance information to production data1



# **5 Pin Configuration and Functions**

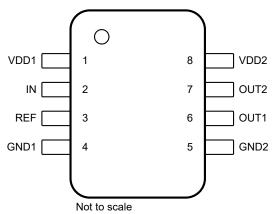


Figure 5-1. DWV Package, 8-Pin SOIC (Top View)

Table 5-1. Pin Functions

| NO. NAME |      | TYPE             | DESCRIPTION   |
|----------|------|------------------|---|
|          |      | ITPE             | DESCRIPTION   |
| 1        | VDD1 | High-side power  | High-side power supply. <sup>(1)</sup>  |
| 2        | IN   | Analog input     | Common analog input pin for window comparator 1 and 2.  |
| 3        | REF  | Analog input     | Reference pin that defines the trip threshold for window comparator 1. The voltage on this pin also affects the hysteresis of comparator Cmp0 as explained in the <i>Reference Input</i> section. This pin is internally connected to a 100-µA current source. Connect a resistor from REF to GND1 to define the trip threshold, and a capacitor from REF to GND1 to filter the reference voltage. For best transient noise immunity, place the capacitor as closely to the pin as possible. This pin can also be driven by an external voltage source. |
| 4        | GND1 | High-side ground | High-side ground.   |
| 5        | GND2 | Low-side ground  | Low-side ground.  |
| 6        | OUT1 | Digital output   | Open-drain output of window comparator 1. Connect to an external pullup resistor or leave unconnected (floating) when not used.   |
| 7        | OUT2 | Digital output   | Open-drain output of window comparator 2. Connect to an external pullup resistor or leave unconnected (floating) when not used.   |
| 8        | VDD2 | Low-side power   | Low-side power supply. <sup>(1)</sup>   |

<sup>(1)</sup> See the *Layout* section for power-supply decoupling recommendations.



## **6 Specifications**

# **6.1 Absolute Maximum Ratings**

see(1)

|                        |  | MIN  | MAX        | UNIT |
|------------------------|--|------|------------|------|
| Power-supply voltage   | VDD1 to GND1                                 | -0.3 | 30         | V    |
| Fower-supply voltage   | VDD2 to GND2                                 | -0.3 | 6.5        | v    |
| Analog input voltage   | REF to GND1                                  | -0.5 | 6.5        | V    |
| Analog input voltage   | IN to GND1                                   | -6   | 5.5        | v    |
| Digital output voltage | OUT1, OUT2 to GND2                           | -0.5 | VDD2 + 0.5 | V    |
| Input current          | Continuous, any pin except power-supply pins | -10  | 10         | mA   |
| Tomporatura            | Junction, T <sub>J</sub>                     |      | 150        | °C   |
| Temperature            | Storage, T <sub>stg</sub>                    | -65  | 150        | C    |

<sup>(1)</sup> Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

## 6.2 ESD Ratings

|                    |                         |   | VALUE | UNIT |
|--------------------|-------------------------|---|-------|------|
| V                  | Electrostatic discharge | Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>     | ±2000 | V    |
| V <sub>(ESD)</sub> | Electrostatic discharge | Charged-device model (CDM), per ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup> | ±1000 | V    |

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

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## **6.3 Recommended Operating Conditions**

over operating ambient temperature range (unless otherwise noted)

|  |   | ·                        | MIN   | NOM  | MAX      | UNIT |
|--|---|--------------------------|---|------|----------|------|
| POWER SUPPLY         VVDD1         High-side power-supply voltage         VDD1 to GND1         3.0         5         27           VVDD2         Low-side power supply voltage         VDD2 to GND2         2.7         3.3         5.5           ANALOG INPUT           IN to GND1, VDD1 ≤ 4.3 V         −0.4         VDD1 − 0.3           In to GND1, VDD1 > 4.3 V         −0.4         4           Reference voltage, window comparator mode         REF to GND1         20         300           Low hysteresis mode         20         450           High hysteresis mode (Cmp0 only)         600         2700(¹¹)           Reference voltage headroom         VDD1 − VREF         1.4           Filter capacitance on REF pin         20         100           DIGITAL OUTPUTS           Digital output voltage         OUT1, OUT2 to GND2         GND2         VDD2           Sink current         OUT1, OUT2         0         4 |   |                          |   |      |          |      |
| V <sub>VDD1</sub>  | High-side power-supply voltage              | VDD1 to GND1             | 3.0   | 5    | 27       | V    |
| $V_{VDD2}$   | Low-side power supply voltage               | VDD2 to GND2             | 2.7   | 3.3  | 5.5      | V    |
| ANALO  | G INPUT                                     | -                        | 1   |      | •        |      |
| \/   | In most well a ma                           | IN to GND1, VDD1 ≤ 4.3 V | -0.4  | VDI  | D1 – 0.3 | .,   |
| V <sub>IN</sub>  | Input voltage                               | IN to GND1, VDD1 > 4.3 V | -0.4  |      | 4        | V    |
| Voce   | Reference voltage, window comparator mode   | REF to GND1              | 20  | 300  |          |      |
| Voce   |   | Low hysteresis mode      | 20  |      | 450      | mV   |
| * KEF  | Reference voltage, positive-comparator mode | 0 ,                      | 600   | 2700 | 2700(1)  | 1111 |
|  | Reference voltage headroom                  | VDD1 – V <sub>REF</sub>  | 3.0 5 2.7 3.3  -0.4 VDD1 -0.4 20 20 600 27 1.4 20 100 |      | V        |      |
|  | Filter capacitance on REF pin               |                          | 20  | 100  |          | nF   |
| DIGITAI  | LOUTPUTS                                    |                          |   |      |          |      |
|  | Digital output voltage                      | OUT1, OUT2 to GND2       | GND2  |      | VDD2     | V    |
|  | Sink current                                | OUT1, OUT2               | 0   |      | 4        | mA   |
| TEMPE  | RATURE RANGE                                | <u>'</u>                 | l   |      |          |      |
| T <sub>A</sub>   | Specified ambient temperature               |                          | -40   | 25   | 125      | °C   |

<sup>(1)</sup> Reference voltages  $(V_{REF}) > 1.6 \text{ V}$  require  $V_{VDD1} > V_{VDD1,MIN}$  to maintain minimum headroom  $(V_{VDD1} - V_{REF})$  of 1.4 V.

#### **6.4 Thermal Information**

|                       | Junction-to-board thermal resistance  Junction-to-top characterization parameter  Junction-to-board characterization parameter | DWV (SOIC) | LINIT |
|-----------------------|--|------------|-------|
|                       |  | 8 PINS     | UNIT  |
| $R_{\theta JA}$       | Junction-to-ambient thermal resistance   | 102.8      | °C/W  |
| R <sub>θJC(top)</sub> | Junction-to-case (top) thermal resistance  | 45.1       | °C/W  |
| $R_{\theta JB}$       | Junction-to-board thermal resistance   | 63.0       | °C/W  |
| $\Psi_{JT}$           | Junction-to-top characterization parameter   | 14.3       | °C/W  |
| $\Psi_{JB}$           | Junction-to-board characterization parameter   | 61.1       | °C/W  |
| R <sub>0JC(bot)</sub> | Junction-to-case (bottom) thermal resistance   | n/a        | °C/W  |

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

## 6.5 Power Ratings

|                 | PARAMETER                              | TEST CONDITIONS           | VALUE | UNIT  |
|-----------------|--|---------------------------|-------|-------|
|                 |  | VDD1 = 25 V, VDD2 = 5.5 V | 110   |       |
| P <sub>D</sub>  | Maximum power dissipation (both sides) | VDD1 = VDD2 = 5.5 V       | 34    | mW    |
|                 |  | VDD1 = VDD2 = 3.6 V       | 22    |       |
|                 |  | VDD1 = 25 V               | 98    |       |
| P <sub>D1</sub> | Maximum power dissipation (high-side)  | VDD1 = 5.5 V              | 21    | mW    |
|                 |  | VDD1 = 3.6 V              | 14    |       |
| Р               | Maximum power dissipation (low-side)   | VDD2 = 5.5 V              | 12    | mW    |
| P <sub>D2</sub> | waxiinuin powei dissipation (low-side) | VDD2 = 3.6 V              | 8     | IIIVV |



#### **6.6 Insulation Specifications**

over operating ambient temperature range (unless otherwise noted)

|                   | PARAMETER   | TEST CONDITIONS  | VALUE              | UNIT             |
|-------------------|---|--|--------------------|------------------|
| GENER             | AL  |  |                    |                  |
| CLR               | External clearance <sup>(1)</sup>                     | Shortest pin-to-pin distance through air   | ≥ 8.5              | mm               |
| CPG               | External creepage <sup>(1)</sup>                      | Shortest pin-to-pin distance across the package surface  | ≥ 8.5              | mm               |
| DTI               | Distance through insulation                           | Minimum internal gap (internal clearance) of the double insulation   | ≥ 15.4             | μm               |
| СТІ               | Comparative tracking index                            | DIN EN 60112 (VDE 0303-11); IEC 60112  | ≥ 600              | V                |
|                   | Material group  | According to IEC 60664-1   | 1                  |                  |
|                   | Overvoltage category                                  | Rated mains voltage ≤ 600 V <sub>RMS</sub>   | 1-111              |                  |
|                   | per IEC 60664-1                                       | Rated mains voltage ≤ 1000 V <sub>RMS</sub>  | 1-11               |                  |
| DIN EN            | IEC 60747-17 (VDE 0884-17)(2)                         |  |                    | •                |
| V <sub>IORM</sub> | Maximum repetitive peak isolation voltage             | At AC voltage  | 1060               | V <sub>PK</sub>  |
| .,                | Maximum-rated isolation                               | At AC voltage (sine wave)  | 750                | V <sub>RMS</sub> |
| $V_{IOWM}$        | working voltage                                       | At DC voltage  | 1060               | V <sub>DC</sub>  |
| \ <u>'</u>        | Maximum transient                                     | V <sub>TEST</sub> = V <sub>IOTM</sub> , t = 60 s (qualification test)  | 7070               | V                |
| $V_{IOTM}$        | isolation voltage                                     | V <sub>TEST</sub> = 1.2 × V <sub>IOTM</sub> , t = 1 s (100% production test)   | 8500               | V <sub>PK</sub>  |
| V <sub>IMP</sub>  | Maximum impulse voltage(3)                            | Tested in air, 1.2/50-µs waveform per IEC 62368-1  | 8300               | V <sub>PK</sub>  |
| V <sub>IOSM</sub> | Maximum surge isolation voltage <sup>(4)</sup>        | Tested in oil (qualification test),<br>1.2/50-µs waveform per IEC 62368-1  | 10000              | V <sub>PK</sub>  |
|                   |   | Method a, after input/output safety test subgroups 2 and 3, $V_{ini} = V_{IOTM}, t_{ini} = 60 \text{ s}, V_{pd(m)} = 1.2 \times V_{IORM}, t_m = 10 \text{ s}$        | ≤ 5                |                  |
| q <sub>pd</sub>   | Apparent charge <sup>(5)</sup>                        | Method a, after environmental tests subgroup 1, $V_{ini} = V_{IOTM}$ , $t_{ini} = 60$ s, $V_{pd(m)} = 1.6 \times V_{IORM}$ , $t_m = 10$ s                            | ≤ 5                | рС               |
|                   |   | Method b1, at routine test (100% production) and preconditioning (type test), $V_{ini} = V_{IOTM}$ , $t_{ini} = 1$ s, $V_{pd(m)} = 1.875$ × $V_{IORM}$ , $t_m = 1$ s | ≤ 5                |                  |
| C <sub>IO</sub>   | Barrier capacitance, input to output <sup>(6)</sup>   | V <sub>IO</sub> = 0.5 V <sub>PP</sub> at 1 MHz   | ~1.5               | pF               |
|                   |   | V <sub>IO</sub> = 500 V at T <sub>A</sub> = 25°C   | > 10 <sup>12</sup> |                  |
| R <sub>IO</sub>   | Insulation resistance, input to output <sup>(6)</sup> | V <sub>IO</sub> = 500 V at 100°C ≤ T <sub>A</sub> ≤ 125°C  | > 10 <sup>11</sup> | Ω                |
|                   | input to output                                       | V <sub>IO</sub> = 500 V at T <sub>S</sub> = 150°C  | > 10 <sup>9</sup>  |                  |
|                   | Pollution degree                                      |  | 2                  |                  |
|                   | Climatic category                                     |  | 55/125/21          |                  |
| UL1577            |   |  |                    | '                |
| V <sub>ISO</sub>  | Withstand isolation voltage                           | $V_{TEST} = V_{ISO} = 5700 V_{RMS}$ , $t = 60 s$ (qualification),<br>$V_{TEST} = 1.2 \times V_{ISO} = 6840 V_{RMS}$ , $t = 1 s$ (100% production test)               | 5000               | V <sub>RMS</sub> |

- (1) Apply creepage and clearance requirements according to the specific equipment isolation standards of an application. Care must be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed circuit board (PCB) do not reduce this distance. Creepage and clearance on a PCB become equal in certain cases. Techniques such as inserting grooves, ribs, or both on a PCB are used to help increase these specifications.
- (2) This coupler is suitable for *safe electrical insulation* only within the safety ratings. Compliance with the safety ratings shall be ensured by means of suitable protective circuits.
- (3) Testing is carried out in air to determine the surge immunity of the package.
- (4) Testing is carried in oil to determine the intrinsic surge immunity of the isolation barrier.
- (5) Apparent charge is electrical discharge caused by a partial discharge (pd).
- (6) All pins on each side of the barrier are tied together, creating a two-pin device.



#### 6.7 Safety-Related Certifications

| VDE   | UL  |
|---|---|
| DIN EN IEC 60747-17 (VDE 0884-17),<br>EN IEC 60747-17,<br>DIN EN IEC 62368-1 (VDE 0868-1),<br>EN IEC 62368-1,<br>IEC 62368-1 Clause : 5.4.3 ; 5.4.4.4 ; 5.4.9 | Recognized under 1577 component recognition |
| Reinforced insulation   | Single protection                           |
| Certificate number: pending   | File number: E181974                        |

## 6.8 Safety Limiting Values

Safety limiting<sup>(1)</sup> intends to minimize potential damage to the isolation barrier upon failure of input or output circuitry. A failure of the I/O can allow low resistance to ground or the supply and, without current limiting, dissipate sufficient power to overheat the die and damage the isolation barrier potentially leading to secondary system failures.

|                | PARAMETER                               | TEST CONDITIONS   | MIN | TYP | MAX  | UNIT |
|----------------|---|---|-----|-----|------|------|
|                | Sofaty input output or aupply ourrent   | R <sub>θJA</sub> = 102.8°C/W,<br>VDD1 = VDD2 = 5.5 V,<br>T <sub>J</sub> = 150°C, T <sub>A</sub> = 25°C  |     |     | 220  | mΛ   |
| Is             | Safety input, output, or supply current | R <sub>θ,JA</sub> = 102.8°C/W,<br>VDD1 = VDD2 = 3.6 V,<br>T <sub>J</sub> = 150°C, T <sub>A</sub> = 25°C |     |     | 340  | mA   |
| Ps             | Safety input, output, or total power    | R <sub>θJA</sub> = 102.8°C/W,<br>T <sub>J</sub> = 150°C, T <sub>A</sub> = 25°C                          |     |     | 1220 | mW   |
| T <sub>S</sub> | Maximum safety temperature              |   |     |     | 150  | °C   |

The maximum safety temperature,  $T_S$ , has the same value as the maximum junction temperature,  $T_J$ , specified for the device. The  $I_S$ and P<sub>S</sub> parameters represent the safety current and safety power, respectively. Do not exceed the maximum limits of I<sub>S</sub> and P<sub>S</sub>. These limits vary with the ambient temperature, T<sub>A</sub>.

The junction-to-air thermal resistance,  $R_{\theta JA}$ , in the *Thermal Information* table is that of a device installed on a high-K test board for leaded surface-mount packages. Use these equations to calculate the value for each parameter:

 $T_J = T_A + R_{\theta JA} \times P$ , where P is the power dissipated in the device.

 $T_{J(max)} = T_S = T_A + R_{\theta JA} \times P_S, \text{ where } T_{J(max)} \text{ is the maximum junction temperature.}$   $P_S = I_S \times \text{AVDD}_{max} + I_S \times \text{DVDD}_{max}, \text{ where AVDD}_{max} \text{ is the maximum high-side voltage and DVDD}_{max} \text{ is the maximum controller-side}$ supply voltage.



## **6.9 Electrical Characteristics**

minimum and maximum specifications apply from  $T_A$  = -40°C to 125°C, VDD1 = 3.0 V to 27 V, VDD2 = 2.7 V to 5.5 V,  $V_{REF}$  = 20 mV to 2.7 V<sup>(1)</sup>, and  $V_{IN}$  = -400 mV to 4 V<sup>(3)</sup>; typical specifications are at  $T_A$  = 25°C, VDD1 = 5 V, VDD2 = 3.3 V, and  $V_{REF}$  = 250 mV (unless otherwise noted)

|                   | PARAMETER                               | TEST CONDITIONS   | MIN  | TYP                               | MAX | UNIT |
|-------------------|---|---|--|-----------------------------------|-----|------|
| ΔΝΔΙ Ο            | G INPUT                                 | 1201 201100110  |  |                                   |     |      |
| R <sub>IN</sub>   | Input resistance                        | IN pin, 0 ≤ V <sub>IN</sub> ≤ 4 V   |  | 1                                 |     | GΩ   |
| ' 'IN             | mput resistance                         | IN pin, $0 \le V_{IN} \le 4 V^{(4)}$  |  | 0.1                               | 25  | 012  |
| I <sub>BIAS</sub> | Input bias current                      | IN pin, $-400 \text{ mV} \le V_{\text{IN}} \le 0 \text{ V}^{(5)}$   | -310   | -0.5                              | 25  | nA   |
| C <sub>IN</sub>   | Input capacitance                       | IN pin  | -510   | 4                                 |     | pF   |
|                   | ENCE PIN                                | пу риг  |  |                                   |     | ρι   |
|                   | Reference current                       | DEE to CND4 20 mV cV  | 99   | 100                               | 101 |      |
| I <sub>REF</sub>  | Reference current                       | REF to GND1, 20 mV < V <sub>REF</sub> ≤ 2.7 V   |  |                                   |     | μA   |
| $V_{MSEL}$        | Mode selection threshold <sup>(2)</sup> | V <sub>REF</sub> rising   | 500<br>450   | 550<br>500                        | 550 | mV   |
|                   | Made coloction throughold by oteracio   | V <sub>REF</sub> falling  | 450  |                                   | 550 | \ /  |
| 200 1/            | Mode selection threshold hysteresis     | O AND CMPS)   |  | 50                                |     | mV   |
|                   | FIXED-THRESHOLD COMPARATORS (CMP        | •   |  | 004                               |     | .,,  |
| V <sub>IT+</sub>  | Positive-going trip threshold           | Cmp2  |  | 304                               | 0.5 | mV   |
| E <sub>IT+</sub>  | Positive-going trip threshold error     | Cmp2  | -3.5   | 000                               | 3.5 | mV   |
| V <sub>IT-</sub>  | Negative-going trip threshold           | Cmp2  |  | 300                               |     | mV   |
| E <sub>IT</sub>   | Negative-going trip threshold error     | Cmp2  | -3.5   |                                   | 3.5 | mV   |
| V <sub>IT</sub>   | Negative-going trip threshold           | Cmp3  |  | -304                              |     | mV   |
| E <sub>IT</sub>   | Negative-going trip threshold error     | Cmp3  | -4.5   |                                   | 4.5 | mV   |
| V <sub>IT+</sub>  | Positive-going trip threshold           | Cmp3  |  | -300                              |     | mV   |
| E <sub>IT+</sub>  | Positive-going trip threshold error     | Cmp3  | -4.5   |                                   | 4.5 | mV   |
| V <sub>HYS</sub>  | Trip threshold hysteresis               | Cmp2 and Cmp3, (V <sub>IT+</sub> – V <sub>IT-</sub> )   |  | 4                                 |     | mV   |
| VARIAB            | LE-THRESHOLD COMPARATORS (CMP0 AN       | ND CMP1)  |  |                                   |     |      |
| V <sub>IT+</sub>  | Positive-going trip threshold           | Cmp0  | V <sub>R</sub>   | EF + V <sub>HYS</sub>             |     | mV   |
|                   |   | $\begin{aligned} &\text{Cmp0, (V}_{\text{IT+}} - \text{V}_{\text{REF}} - \text{V}_{\text{HYS}}), \\ &\text{V}_{\text{REF}} = 20 \text{ mV, V}_{\text{HYS}} = 4 \text{ mV} \end{aligned}$                  | -2   |                                   | 2   |      |
| E <sub>IT+</sub>  | Positive-going trip threshold error     | $\begin{aligned} &\text{Cmp0, } (\text{V}_{\text{IT+}} - \text{V}_{\text{REF}} - \text{V}_{\text{HYS}}), \\ &\text{V}_{\text{REF}} = 250 \text{ mV, } \text{V}_{\text{HYS}} = 4 \text{ mV} \end{aligned}$ | -2   |                                   | 2   | mV   |
|                   |   | Cmp0, $(V_{IT+} - V_{REF} - V_{HYS})$ , $V_{REF} = 2 V$ , $V_{HYS} = 25 \text{ mV}$   | V <sub>REF</sub> + V <sub>HYS</sub> -2 2  -2 2  -2 - V <sub>REF</sub> - V <sub>HYS</sub> ), -2 2  -2 - V <sub>REF</sub> - V <sub>HYS</sub> ), -2 5  -2 5  -2 7  -2 8  -2 |                                   |     |      |
| $V_{IT-}$         | Negative-going trip threshold           | Cmp0  |  | $V_{REF}$                         |     | mV   |
|                   |   | Cmp0, $(V_{IT-} - V_{REF})$ , $V_{REF} = 20 \text{ mV}$   | -2.5   |                                   | 2.5 |      |
| E <sub>IT</sub> _ | Negative-going trip threshold error     | Cmp0, $(V_{IT-} - V_{REF})$ , $V_{REF} = 250 \text{ mV}$  | -2.5   |                                   | 2.5 | mV   |
|                   |   | Cmp0, $(V_{IT-} - V_{REF})$ , $V_{REF} = 2 V$   | -5   |                                   | 5   |      |
| $V_{IT-}$         | Negative-going trip threshold           | Cmp1  | $-V_{\rm F}$   | <sub>REF</sub> – V <sub>HYS</sub> |     | mV   |
| F                 | Negative-going trip threshold error     | Cmp1, $(V_{IT-} + V_{REF} + V_{HYS})$ , $V_{REF} = 20$ mV, $V_{HYS} = 4$ mV   | -3   |                                   | 3   | mV   |
| E <sub>IT</sub>   | regative-going tip tilleshold ellor     | Cmp1, $(V_{IT-} + V_{REF} + V_{HYS})$ ,<br>$V_{REF} = 250 \text{ mV}$ , $V_{HYS} = 4 \text{ mV}$  | -3   |                                   | 3   | IIIV |
| V <sub>IT+</sub>  | Positive-going trip threshold           | Cmp1  |  | -V <sub>REF</sub>                 |     | mV   |
| _                 | Desirius asias distributed and          | Cmp1, (V <sub>IT+</sub> + V <sub>REF</sub> ), V <sub>REF</sub> = 20 mV  | -3.5   |                                   | 3.5 | >/   |
| E <sub>IT+</sub>  | Positive-going trip threshold error     | Cmp1, $(V_{IT+} + V_{REF})$ , $V_{REF} = 250 \text{ mV}$  | -3.5   |                                   | 3.5 | mV   |
| .,                | Tri- the shall be sate of               | Cmp0 and Cmp1, (V <sub>IT+</sub> − V <sub>IT−</sub> ), V <sub>REF</sub> ≤ 450 mV  |  | 4                                 |     | - 17 |
| V <sub>HYS</sub>  | Trip threshold hysteresis               | Cmp0 only, $(V_{IT+} - V_{IT-})$ , $V_{REF} \ge 600 \text{ mV}$   |  | 25                                |     | mV   |
| DIGITAL           | OUTPUTS                                 |   |  |                                   | I   |      |
| V <sub>OL</sub>   | Low-level output voltage                | I <sub>SINK</sub> = 4 mA  |  | 80                                | 250 | mV   |
| I <sub>LKG</sub>  | Open-drain output leakage current       | VDD2 = 5 V, V <sub>OUT</sub> = 5 V  |  | 5                                 | 100 | nA   |
| CMTI              | Common-mode transient immunity          | $ V_{IN} - V_{REF}  \ge 4 \text{ mV}, R_{PULLUP} = 10 \text{ k}\Omega$  | 15   | 40                                |     | V/ns |

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## **6.9 Electrical Characteristics (continued)**

minimum and maximum specifications apply from  $T_A = -40^{\circ}\text{C}$  to 125°C, VDD1 = 3.0 V to 27 V, VDD2 = 2.7 V to 5.5 V,  $V_{REF} = 20$  mV to 2.7 V<sup>(1)</sup>, and  $V_{IN} = -400$  mV to 4 V<sup>(3)</sup>; typical specifications are at  $T_A = 25^{\circ}\text{C}$ , VDD1 = 5 V, VDD2 = 3.3 V, and  $V_{REF} = 250$  mV (unless otherwise noted)

|                     | PARAMETER                               | MIN          | TYP       | MAX | UNIT |    |
|---------------------|---|--------------|-----------|-----|------|----|
| POWER SI            | JPPLY                                   |              |           |     |      |    |
| VDD1                | VDD1 under reltered detection threehold | VDD1 rising  | 01 rising |     | 3    |    |
| VDD1 <sub>UV</sub>  | VDD1 undervoltage detection threshold   | VDD1 falling |           |     | 2.9  | V  |
| VDD1 <sub>POR</sub> | VDD1 power-on reset threshold           | VDD1 falling |           |     | 2.3  | V  |
| VDD2                | VDD2 undervoltage detection threshold   | VDD2 rising  |           | •   | 2.7  | \/ |
| VDD2 <sub>UV</sub>  | VDD2 undervoltage detection threshold   | VDD2 falling |           |     | 2.1  | V  |
| I <sub>DD1</sub>    | High-side supply current                |              |           | 3.2 | 4.3  | mA |
| I <sub>DD2</sub>    | Low-side supply current                 |              |           | 1.8 | 2.2  | mA |

- (1) Reference voltages >1.6 V require VDD1 > VDD1<sub>MIN</sub>. See the *Recommended Operating Conditions* table for details.
- (2) The voltage level V<sub>REF</sub> determines if the device operates as window-comparator with positive and negative thresholds or as simple comparator with positive thresholds only. See the *Reference Input* section for more details.
- (3) But not exceeding the maximum input voltage specified in the Recommended Operating Conditions table.
- (4) The typical value is measured at  $V_{IN} = 0.4 \text{ V}$ .
- (5) The typical value is measured at  $V_{IN} = -400 \text{ mV}$ .



## **6.10 Switching Characteristics**

over operating ambient temperature range (unless otherwise noted)

|                      | PARAMETER  | TEST CONDITIONS  | MIN      | TYP | MAX | UNIT |
|----------------------|--|--|----------|-----|-----|------|
| OPEN-D               | RAIN OUTPUTS                                       |  | <u> </u> |     |     |      |
| <b>+</b>             | Propagation delay time IV   I riging               | VDD2 = 3.3 V, V <sub>REF</sub> = 250 mV,<br>V <sub>OVERDRIVE</sub> = 10 mV, C <sub>L</sub> = 15 pF |          | 280 | 410 | no   |
| t <sub>pH</sub>      | Propagation delay time,  V <sub>IN</sub>   rising  | VDD2 = 3.3 V, V <sub>REF</sub> = 2 V,<br>V <sub>OVERDRIVE</sub> = 50 mV, C <sub>L</sub> = 15 pF    |          | 240 | 370 | ns   |
| •                    | Propagation delay time,  V <sub>IN</sub>   falling | VDD2 = 3.3 V, V <sub>REF</sub> = 250 mV,<br>V <sub>OVERDRIVE</sub> = 10 mV, C <sub>L</sub> = 15 pF | 280      |     | 410 | ns   |
| t <sub>pL</sub>      | Propagation delay time, [VIN] failing              | VDD2 = 3.3 V, V <sub>REF</sub> = 2 V,<br>V <sub>OVERDRIVE</sub> = 50 mV, C <sub>L</sub> = 15 pF    |          | 240 |     |      |
| t <sub>f</sub>       | Output signal fall time                            | $R_{PULLUP} = 4.7 \text{ k}\Omega, C_L = 15 \text{ pF}$  |          | 2   |     | ns   |
| MODE S               | ELECTION   |  |          |     |     |      |
| t <sub>HSEL</sub>    | Comparator hysteresis selection deglitch time      | Cmp0, V <sub>REF</sub> rising or falling   |          | 10  |     | μs   |
| t <sub>DIS13</sub>   | Comparator disable deglitch time                   | Cmp1 and Cmp3, V <sub>REF</sub> rising   |          | 10  |     | μs   |
| t <sub>EN13</sub>    | Comparator enable deglitch time                    | Cmp1 and Cmp3, V <sub>REF</sub> falling  |          | 100 |     | μs   |
| START-L              | JP TIMING  |  |          |     |     |      |
| t <sub>LS ,STA</sub> | Low-side start-up time                             | VDD2 step to 2.7 V, VDD1 ≥ 3.0 V   |          | 40  |     | μs   |
| t <sub>HS ,STA</sub> | High-side start-up time                            | VDD1 step to 3.0 V, VDD2 ≥ 2.7 V   |          | 45  |     | μs   |
| t <sub>HS,BLK</sub>  | High-side blanking time                            |  |          | 200 |     | μs   |
| t <sub>HS,FLT</sub>  | High-side-fault detection delay time               |  |          | 100 |     | μs   |

## **6.11 Timing Diagrams**

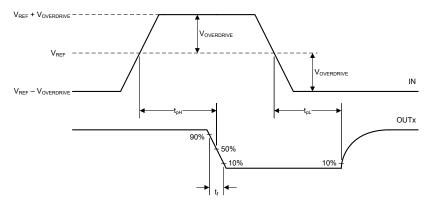


Figure 6-1. Rise, Fall, and Delay Time Definition

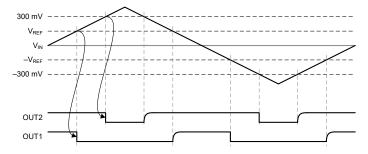
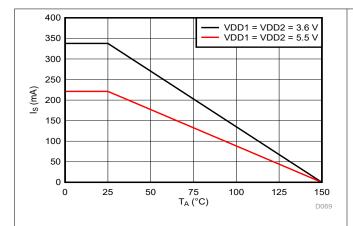


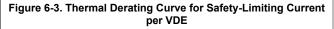
Figure 6-2. Functional Timing Diagram

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## **6.12 Insulation Characteristics Curves**





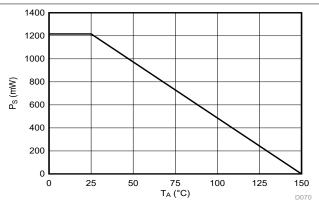
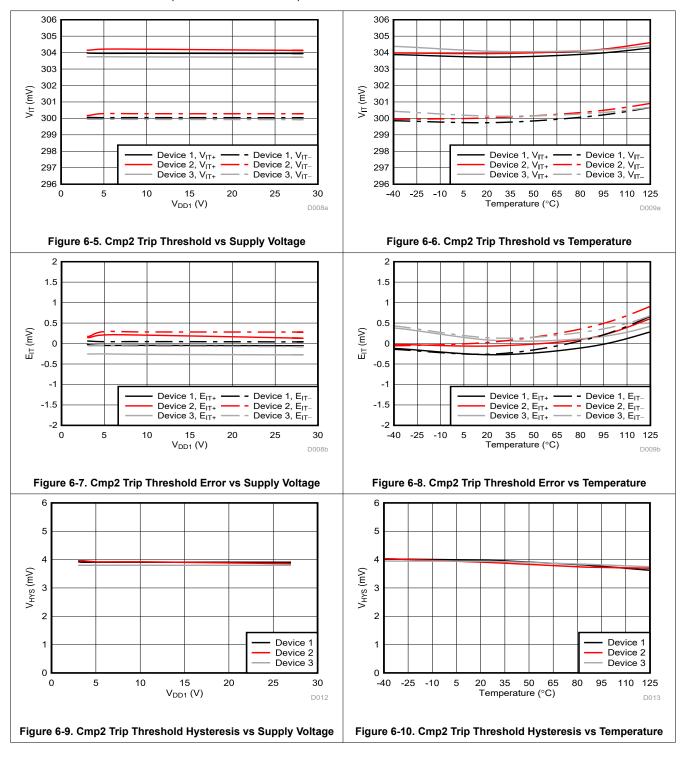
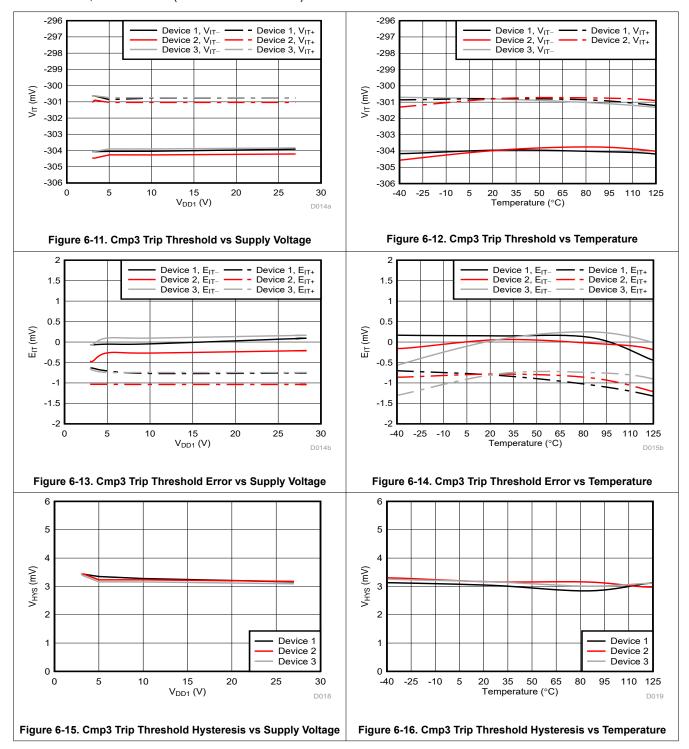


Figure 6-4. Thermal Derating Curve for Safety-Limiting Power per VDE

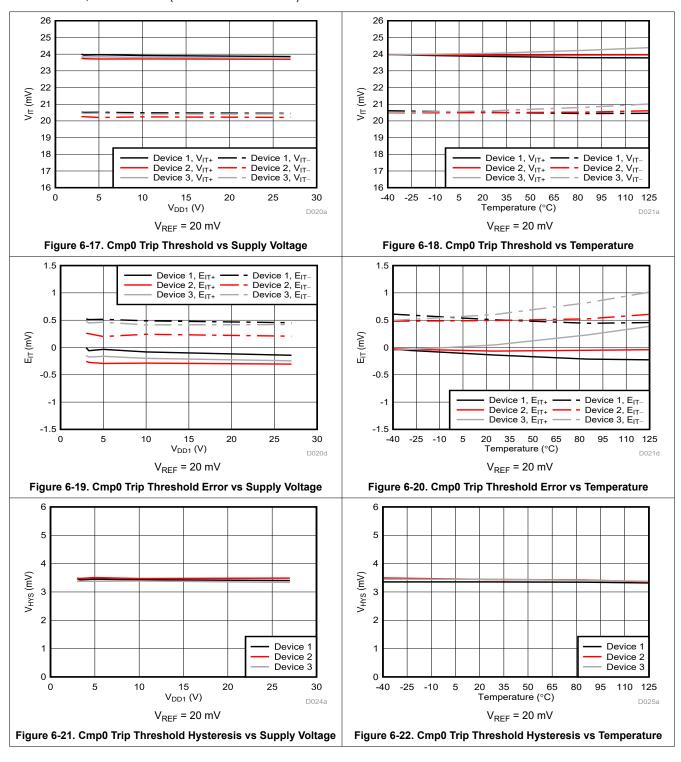


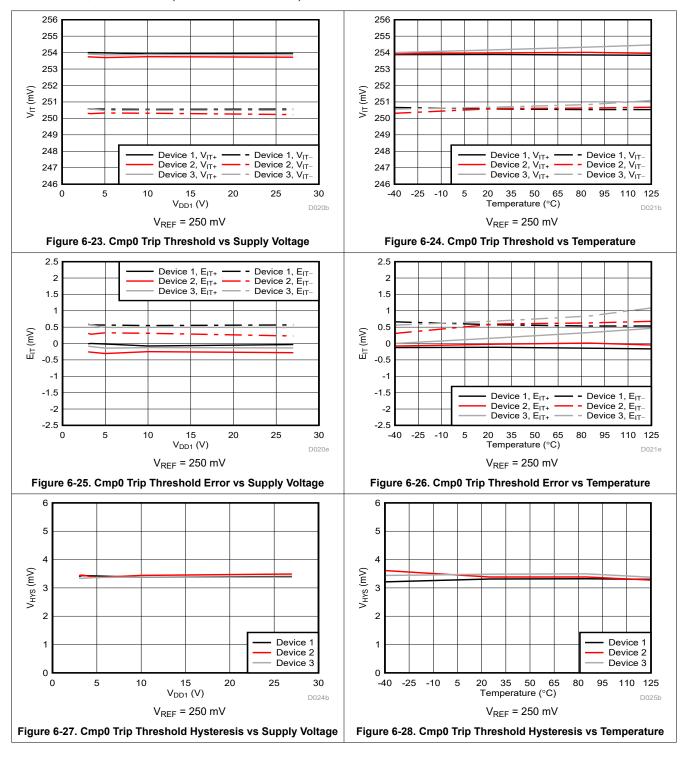
## **6.13 Typical Characteristics**



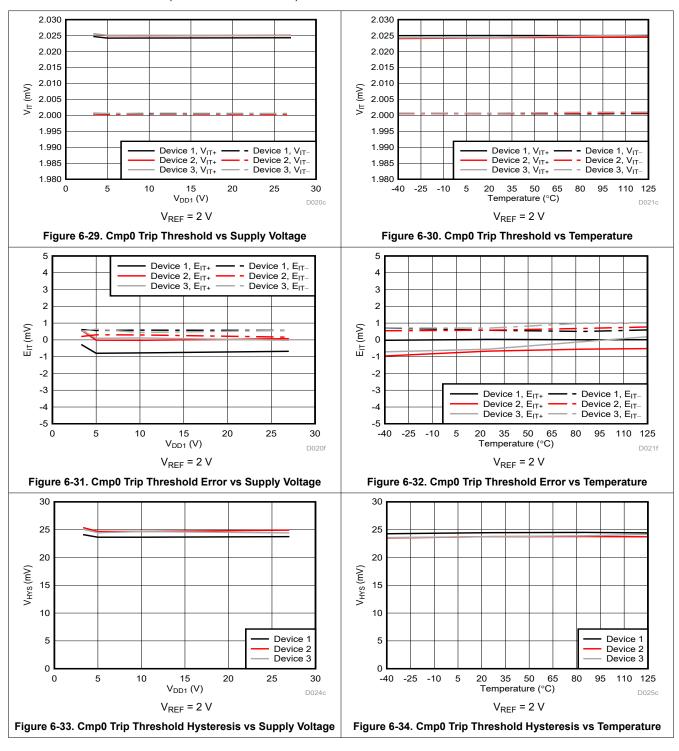


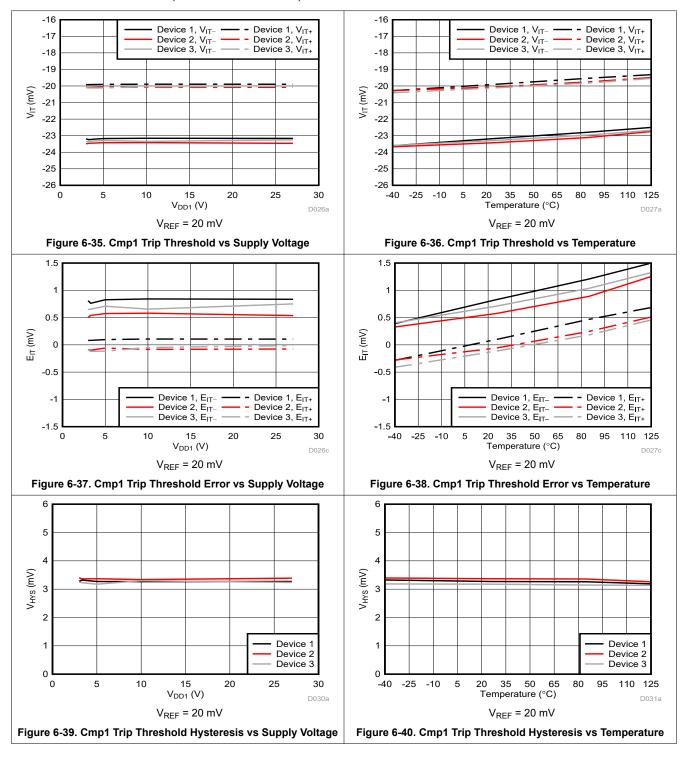




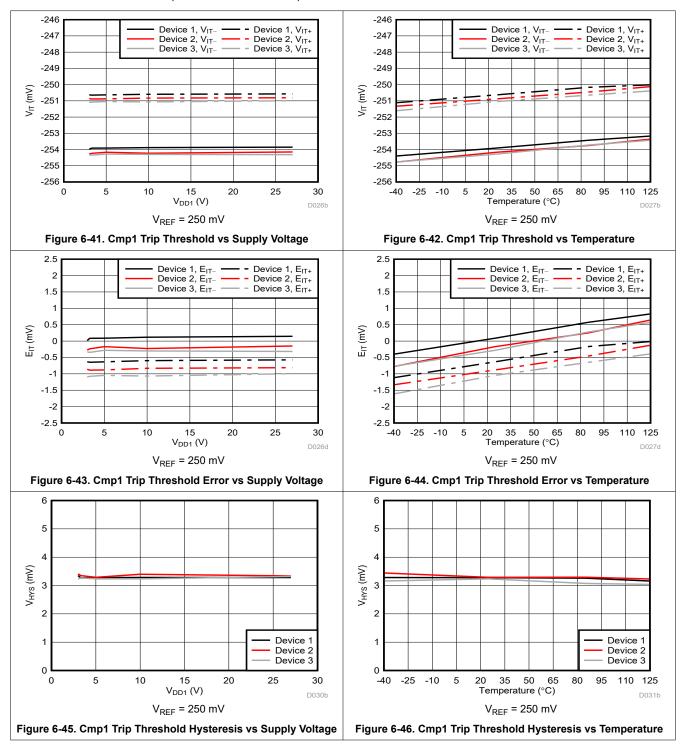


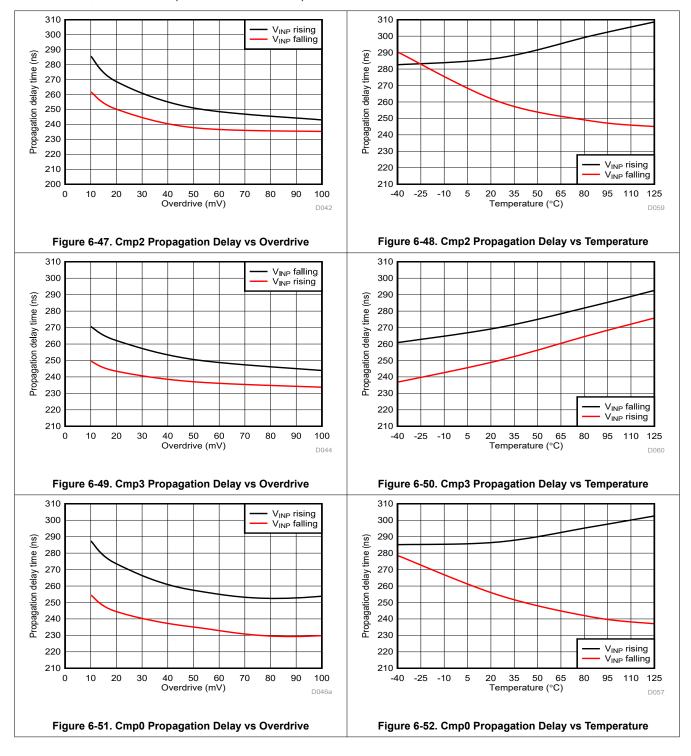




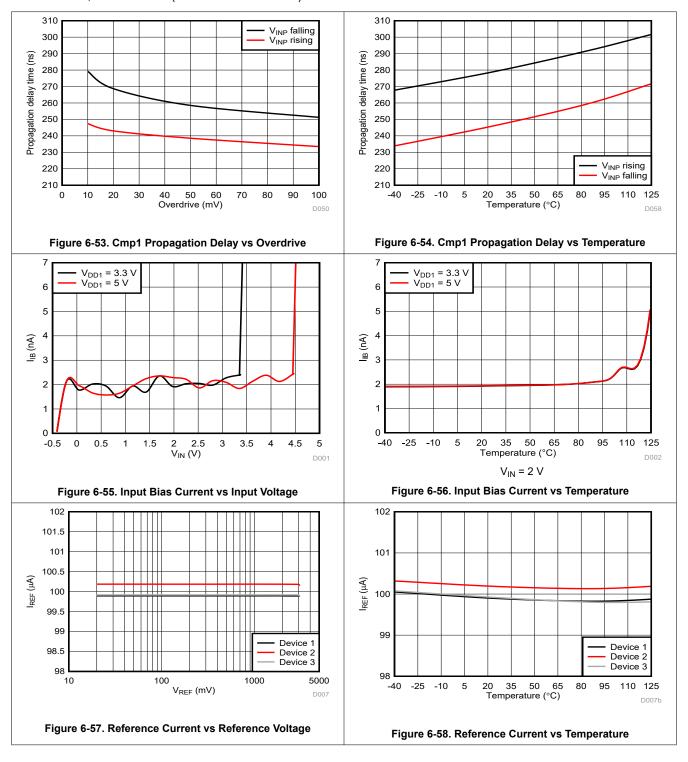


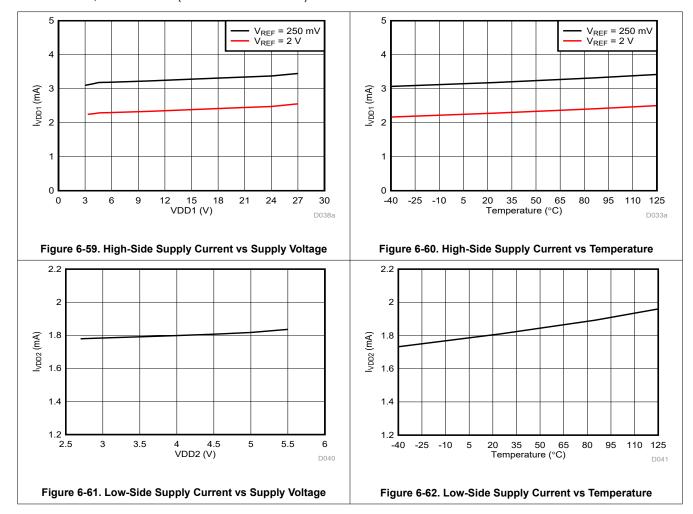












## 7 Detailed Description

#### 7.1 Overview

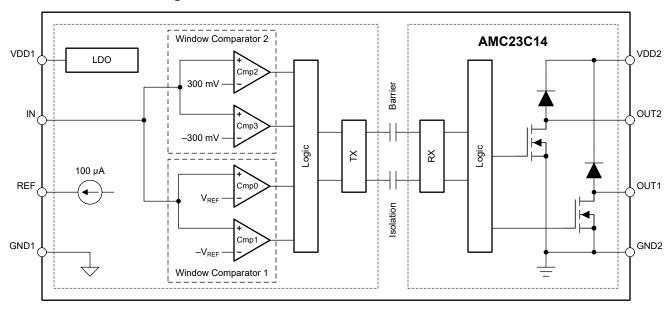
The AMC23C14 is a dual, isolated window comparator with open-drain outputs. Window comparator 1 is comprised of comparator Cmp0 and Cmp1 and window comparator 2 is comprised of Cmp2 and Cmp3. Cmp0 and Cmp2 compare the input voltage ( $V_{IN}$ ) against their respective positive thresholds ( $V_{IT+}$ ) and Cmp1 and Cmp3 compare the input voltage ( $V_{IN}$ ) against their respective negative thresholds ( $V_{IT-}$ ). The respective  $V_{IT+}$  and  $V_{IT-}$  thresholds are of equal magnitude but opposite signs, therefore both window comparators have windows that are centered around 0 V. Window comparator 2 has fixed thresholds of  $\pm 300$  mV. Window comparator 1 has adjustable thresholds from  $\pm 20$  mV to  $\pm 300$  mV through an internally generated 100- $\mu$ A reference current and a single external resistor.

The open-drain outputs are actively pulled low when the input voltage  $(V_{IN})$  is outside the respective comparison window, but are otherwise in a high-impedance state.

When the voltage on the REF pin is greater than  $V_{MSEL}$ , the device operates in positive-comparator mode. This mode is particularly useful for monitoring positive voltage supplies. Both negative comparators (Cmp1 and Cmp3) are disabled and only the positive comparators (Cmp0 and Cmp2) are functional. The reference voltage in this mode can be as high as 2.7 V.

Galvanic isolation between the high- and low-voltage side of the device is achieved by transmitting the comparator states across a SiO<sub>2</sub>-based, reinforced capacitive isolation barrier. This isolation barrier supports a high level of magnetic field immunity, as described in the ISO72x Digital Isolator Magnetic-Field Immunity application report. The digital modulation scheme used in the AMC23C14 to transmit data across the isolation barrier, and the isolation barrier characteristics itself, result in high reliability and common-mode transient immunity.

#### 7.2 Functional Block Diagram



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#### 7.3 Feature Description

#### 7.3.1 Analog Input

The AMC23C14 has a single input that drives both window comparators. Window comparator 1 has an adjustable threshold and window comparator 2 has a fixed threshold.

The positive comparators trip when the input voltage  $(V_{IN})$  rises above the respective  $V_{IT+}$  threshold that is defined as the reference value plus the internal hysteresis voltage (for example, 304 mV for the fixed-threshold comparator). The positive comparators release when  $V_{IN}$  drops below the respective  $V_{IT-}$  threshold that equals the reference value (for example, 300 mV for the fixed-threshold comparator). The negative comparators trip when  $V_{IN}$  drops below the respective  $V_{IT-}$  threshold that is defined as the negative reference value minus the internal hysteresis voltage (for example, -304 mV for the fixed-threshold comparator). The negative comparators release when  $V_{IN}$  rises above the respective  $V_{IT+}$  threshold that equals the negative reference value (for example -300 mV for the fixed-threshold comparator).

The difference between  $V_{\text{IT-}}$  and  $V_{\text{IT-}}$  is referred to as the *comparator hysteresis* and is 4 mV for reference voltages below 450 mV. The integrated hysteresis makes the AMC23C14 less sensitive to input noise and provides stable operation in noisy environments without having to add external positive feedback to create hysteresis. The hysteresis of Cmp0 increases to 25 mV for reference values ( $V_{\text{REF}}$ ) greater than 600 mV. See the *Reference Input* description for more details.

Figure 7-1 shows a timing diagram of the relationship between hysteresis and switching thresholds.

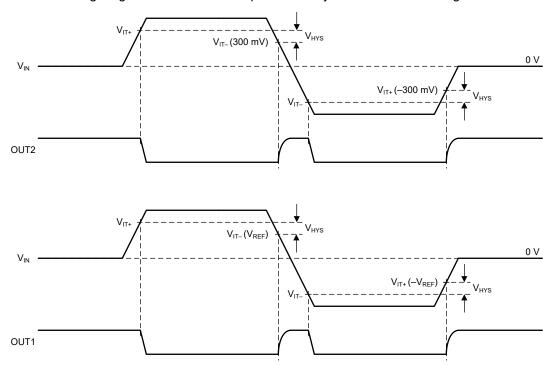


Figure 7-1. Switching Thresholds and Hysteresis

#### 7.3.2 Reference Input

The voltage on the REF pin determines the trip threshold of window comparator 1. The internal precision current source forces a 100- $\mu$ A current through an external resistor connected from the REF pin to GND1. The resulting voltage across the resistor ( $V_{REF}$ ) equals the magnitude of the positive and negative trip thresholds, see Figure 7-1. Place a 100- $\mu$ A current source during power-up and the charging time may exceed the high-side blanking time ( $t_{HS,BLK}$ ). In this case, as shown in Figure 7-2, window comparator 1 may output an incorrect state after the high-side blanking time has expired until  $V_{REF}$  reaches its final value. See the *Power-Up and Power-Down Behavior* section for more details on power-up behavior.

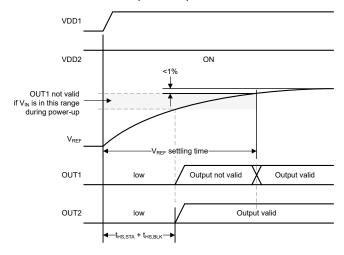


Figure 7-2. Output Behavior for Long Settling Times of the Reference Voltage

The voltage on the REF pin also determines the functionality of the negative comparators (Cmp1, Cmp3) and the hysteresis of the positive comparator (Cmp0) shown in the *Functional Block Diagram*. If  $V_{REF}$  exceeds the  $V_{MSEL}$  threshold defined in the *Electrical Characteristics* table, both negative comparators (Cmp1 and Cmp3) are disabled and the hysteresis of Cmp0 is increased from 4 mV (typical) to 25 mV. Positive-comparator mode is intended for voltage-monitoring applications that require higher input voltages and higher noise immunity.

The reference pin can be driven by an external voltage source to change the comparator thresholds during operation. However, do not drive  $V_{REF}$  dynamically across the  $V_{MSEL}$  threshold during normal operation because doing so changes the hysteresis of the Cmp0 comparator and can lead to unintentional switching of the OUT1 output.

Figure 7-3 shows a mode selection timing diagram.

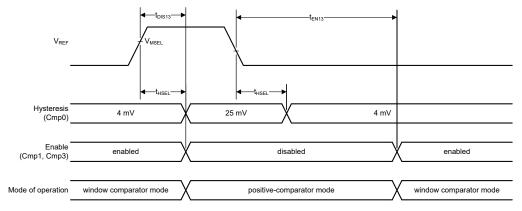


Figure 7-3. Mode Selection

#### 7.3.3 Isolation Channel Signal Transmission

The AMC23C14 uses an on-off keying (OOK) modulation scheme, as shown in Figure 7-4, to transmit the comparator output states across the  $SiO_2$ -based isolation barrier. The transmit driver (TX) shown in the *Functional Block Diagram* transmits an internally-generated, high-frequency carrier across the isolation barrier to represent a digital *one* and does not send a signal to represent a digital *zero*.

The receiver (RX) on the other side of the isolation barrier recovers and demodulates the signal and provides the data for the logic that drives the open-drain output buffers. The AMC23C14 transmission channel is optimized to achieve the highest level of common-mode transient immunity (CMTI) and lowest level of radiated emissions caused by the high-frequency carrier and RX/TX buffer switching.

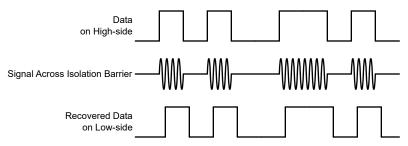


Figure 7-4. OOK-Based Modulation Scheme

#### 7.3.4 Open-Drain Digital Outputs

The AMC23C14 has two open-drain outputs, one for each window comparator. As illustrated in Figure 7-1, OUT1 is actively pulled low when  $|V_{IN}|$  exceeds the threshold values defined by the voltage on the REF pin. OUT2 is actively pulled low when  $|V_{IN}|$  exceeds the threshold values defined by the internal 300-mV reference.

The open-drain outputs are diode-connected to the VDD2 supply, see the *Functional Block Diagram*, which means the outputs cannot be pulled more than 500 mV above the VDD2 supply before significant current begins to flow into the OUTx pins. In particular, the open-drain outputs are clamped to one diode voltage above ground if VDD2 is at the GND2 level. This behavior is indicated by the gray shadings in Figure 7-5 through Figure 7-10.

On a system level, the CMTI performance of an open-drain signal line depends on the value of the pullup resistor. During a common-mode transient event with a high slew rate (high dV/dt), the open-drain signal line may be pulled low due to parasitic capacitive coupling between the high-side and the low-side of the printed circuit board (PCB). The effect of the parasitic coupling on the signal level is a function of the pullup strength and a lower value pullup resistor results in better CMTI performance. The AMC23C14 has been characterized with a relatively weak pullup resistor value of 10 k $\Omega$  to ensure that the specified CMTI performance is met in a typical application with a 4.7 k $\Omega$  or lower pullup resistor.

#### 7.3.5 Power-Up and Power-Down Behavior

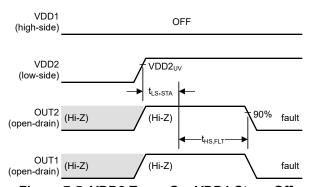
Both open-drain outputs power up in a high-impedance (Hi-Z) state when the low-side supply (VDD2) turns on. After power-up, if the high-side is not functional yet, both outputs are actively pulled low. This condition happens after the low-side start-up time plus the high-side fault detection delay time ( $t_{LS,STA} + t_{HS,FLT}$ ), as shown in Figure 7-5. Similarly, if the high-side supply drops below its undervoltage threshold (VDD1<sub>UV</sub>) for more than the high-side fault detection delay time during normal operation, both outputs are pulled low, as shown in Figure 7-8. This delay allows the system to shut down reliably when the high-side supply is missing.

Communication starts between the high-side and low-side of the comparator is delayed by the high-side blanking time (t<sub>HS,BLK</sub>, a time constant implemented on the high-voltage side) to allow the internal 300-mV reference and the voltage on the REF pin to settle, and to avoid unintentional switching of the comparator outputs during power-up.

Figure 7-5 through Figure 7-10 depict typical power-up and power-down scenarios.

In Figure 7-5, the low-side supply (VDD2) turns on but the high-side supply (VDD1) remains off. Both outputs power up in the default Hi-Z state. After  $t_{HS,FLT}$ , both outputs are pulled low indicating a no-power fault on the high-side.

In Figure 7-6, the high-side supply (VDD1) turns on long after the low-side supply (VDD2) turns on. Both outputs are initially in an active-low state, see case (1). After the high-side supply is enabled, there is a duration of  $t_{HS, STA} + t_{HS,BLK}$  before the device assumes normal operation and both outputs reflect the current state of the window comparators.



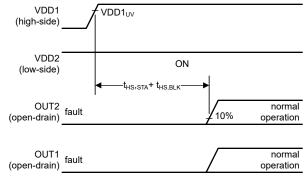


Figure 7-5. VDD2 Turns On, VDD1 Stays Off

Figure 7-6. VDD2 is On; VDD1 Turns On (Long Delay)

In Figure 7-7, the low-side supply (VDD2) turns on, followed by the high-side supply (VDD1) with only a short delay. Both outputs are initially in a Hi-Z state. The high-side fault detection delay ( $t_{HS,FLT}$ ) is shorter than the high-side blanking time ( $t_{HS,BLK}$ ), and therefore both outputs are pulled low after  $t_{HS,FLT}$ , indicating that the high-side is not operational yet. After the high-side blanking time ( $t_{HS,BLK}$ ) elapses, the device assumes normal operation and both outputs reflect the current state of the window comparators.

In Figure 7-8, the high-side supply (VDD1) turns off, followed by the low-side supply (VDD2). After the high-side fault detection delay time ( $t_{HS,FLT}$ ), both outputs are actively pulled low. As soon as VDD2 drops below the VDD2<sub>UV</sub> threshold, both outputs enter a Hi-Z state.

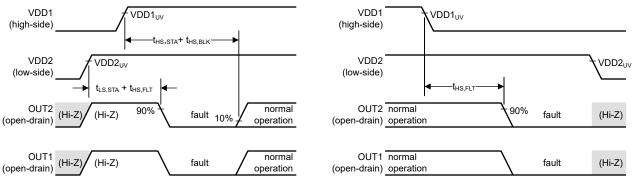


Figure 7-7. VDD2 Turns On, Followed by VDD1 (Short Delay)

Figure 7-8. VDD1 Turns Off, Followed by VDD2

In Figure 7-9, the low-side supply (VDD2) turns on after the high-side is fully powered up (the delay between VDD1 and VDD2 is greater than  $(t_{HS,STA} + t_{HS,BLK})$ ). Both outputs start in a Hi-Z state. After the low-side start-up time  $(t_{LS,STA})$ , the device enters normal operation.

In Figure 7-10, the low-side supply (VDD2) turns off, followed by the high-side supply (VDD1). As soon as VDD2 drops below the VDD2 $_{UV}$  threshold, both outputs enter a Hi-Z state.

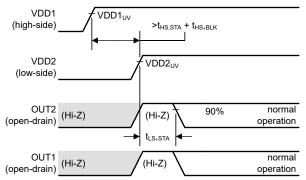


Figure 7-9. VDD1 Turns On, Followed by VDD2 (Long Delay)

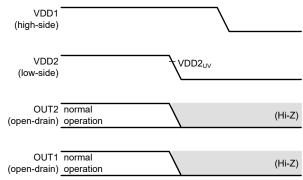


Figure 7-10. VDD2 Turns Off, Followed by VDD1

#### 7.3.6 VDD1 Brownout and Power-Loss Behavior

Brownout is a condition where the VDD1 supply droops below the specified operating voltage range but the device remains functional. Power-loss is a condition where the VDD1 supply drops below a level where the device stops being functional. Depending on the duration and the voltage level, a brownout condition may or may not be noticeable at the output of the device. A power-loss condition is always signaled on the output of the isolated comparator.

Figure 7-11 through Figure 7-13 show typical brownout and power-loss scenarios.

In Figure 7-11, VDD1 droops below the undervoltage detection threshold (VDD1 $_{UV}$ ) but recovers before the high-side-fault detection delay time ( $t_{HS,FLT}$ ) expires. The brownout event has no effect on the comparator outputs.

In Figure 7-12, VDD1 droops below the undervoltage detection threshold (VDD1 $_{UV}$ ) for more than the high-side-fault detection delay time ( $t_{HS,FLT}$ ). The brownout condition is detected as a fault and both outputs are pulled low after a delay equal to  $t_{HS,FLT}$ . The device resumes normal operation as soon as VDD1 recovers above the VDD1 $_{UV}$  threshold.

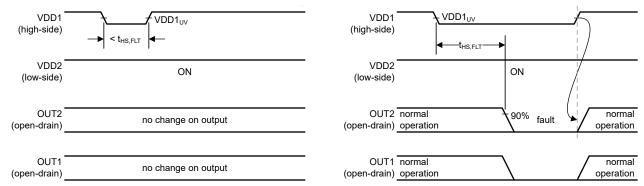


Figure 7-11. Output Response to a Short Brownout Figure 7-12. Output Response to a Long Brownout Event on VDD1 Event on VDD1

In Figure 7-13, VDD1 droops below the power-on-reset (POR) threshold (VDD1 $_{POR}$ ). The power-loss condition is detected as a fault and both outputs are pulled low after a delay equal to  $t_{HS,FLT}$ . The device resumes normal operation after a delay equal to  $t_{HS,STA} + t_{HS,BLK}$  after VDD1 recovers above the VDD1 $_{UV}$  threshold.

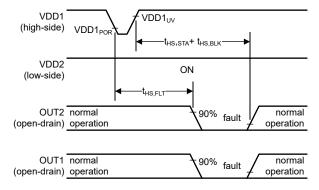


Figure 7-13. Output Response to a Power-Loss Event on VDD1

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#### 7.4 Device Functional Modes

The AMC23C14 is operational when the power supplies VDD1 and VDD2 are applied, as specified in the *Recommended Operating Conditions* table.

The four comparators on the high-side (Cmp0 to Cmp3) function as two independent window comparators when the voltage on the REF pin is below the  $V_{MSEL}$  threshold. If the voltage on the REF pin exceeds the  $V_{MSEL}$  threshold, the negative comparators (Cmp1 and Cmp3) are disabled, and Cmp0 and Cmp2 function as two independent positive comparators, as described in the *Reference Input* section.

## 8 Application and Implementation

#### **Note**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

#### 8.1 Application Information

With its low response time, high common-mode transient immunity (CMTI) and reinforced isolation barrier, the AMC23C14 is designed to provide fast and reliable overcurrent and overvoltage detection for high-voltage applications in harsh and noisy environments.

#### 8.2 Typical Applications

#### 8.2.1 Overcurrent and Short-Circuit Current Detection

Fast overcurrent and short-circuit current detection is a common requirement in DC/DC converter and motor-control applications, and can be implemented with an AMC23C14 isolated window comparator as shown in Figure 8-1.

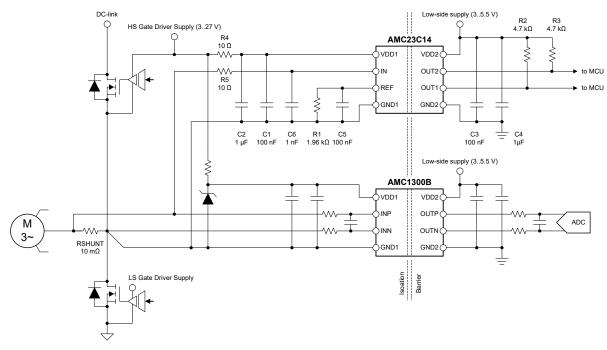


Figure 8-1. Using the AMC23C14 for Overcurrent and Short-Circuit Detection

The load current flowing through an external shunt resistor RSHUNT produces a voltage drop that is sensed by the AMC1300B for control purposes. The same voltage is monitored by the AMC23C14 that is connected in parallel to the current-sensing amplifier and provides a fast sensing path for positive and negative fault-current detection. The trip threshold for overcurrent detection is set by the external resistor R1. The trip threshold for short-circuit detection is fixed by the internal 300-mV reference. Overcurrent conditions are signaled on OUT1, and short-circuit conditions are signaled on OUT2.

As depicted in Figure 8-1, the integrated low-dropout (LDO) regulator on the high-side allows direct connection of the VDD1 input to a commonly used floating gate-driver supply. Alternatively, the AMC23C14 can share a regulated supply with the AMC1300B. In that case, the VDD1 pin of the AMC23C14 connects directly to the VDD1 pin of the AMC1300B and R4 is not needed. The fast response time and high common-mode transient immunity (CMTI) of the AMC23C14 ensure reliable and accurate operation even in high-noise environments.

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#### 8.2.1.1 Design Requirements

Table 8-1 lists the parameters for the application example in Figure 8-1.

Table 8-1. Design Requirements

| PARAMETER                                  | VALUE          |
|--|----------------|
| High-side supply voltage                   | 3 V to 27 V    |
| Low-side supply voltage                    | 2.7 V to 5.5 V |
| Shunt-resistor value                       | 10 mΩ          |
| Linear input voltage range of the AMC1300B | ±250 mV        |
| Maximum peak motor current                 | ±25 A          |
| Overcurrent detection threshold            | ±20 A          |
| Short-circuit current detection threshold  | ±30 A          |

#### 8.2.1.2 Detailed Design Procedure

The value of the shunt resistor in this example is 10 m $\Omega$ , determined by the linear input voltage range of the AMC1300B current-sensing amplifier ( $\pm 250$  mV) and the full-scale current of  $\pm 25$  A. The short-circuit current detection threshold of the AMC23C14 is a fixed 300-mV value and places the short-circuit current threshold at 30 A.

At the desired 20-A overcurrent detection level, the voltage drop across the shunt resistor is 10 m $\Omega$  × 20 A = 200 mV. The positive-going trip threshold of window comparator 1 is  $V_{REF}$  +  $V_{HYS}$ , where  $V_{HYS}$  is 4 mV as specified in the *Electrical Characteristics* table and  $V_{REF}$  is the voltage across R1 that is connected between the REF and GND1 pins. R1 is calculated as  $(V_{TRIP} - V_{HYS}) / I_{REF} = (200 \text{ mV} - 4 \text{ mV}) / 100 \text{ }\mu\text{A} = 1.96 \text{ }k\Omega$  and matches a value from the E96 series (1% accuracy).

A  $10-\Omega$ , 1-nF RC filter (R5, C6) is placed at the input of the comparator to filter the input signal and reduce noise sensitivity. This filter adds  $10~\Omega \times 1~nF = 10~ns$  of propagation delay that must be considered when calculating the overall response time of the protection circuit. Larger filter constants are preferable to increase noise immunity if the system can tolerate the additional delay.

Table 8-2 summarizes the key parameters of the design.

Table 8-2. Overcurrent and Short-Circuit Detection Design Example

| PARAMETER   | VALUE           |
|---|-----------------|
| Reference resistor value (R1)                           | 1.96 kΩ         |
| Reference capacitor value (C5)                          | 100 nF          |
| Reference voltage                                       | 196 mV          |
| Reference voltage settling time (to 90% of final value) | 470 μs          |
| Overcurrent trip threshold (rising)                     | 200 mV / 20.0 A |
| Overcurrent trip threshold (falling)                    | 196 mV / 19.6 A |
| Short-circuit current trip threshold (rising)           | 304 mV / 30.4 A |
| Short-circuit current trip threshold (falling)          | 300 mV / 30.0 A |

#### 8.2.2 Overvoltage and Undervoltage Detection

Industrial I/O modules are frequently powered by external field supplies with a nominal voltage of 24 V and a tolerance of -15% to +20%. In safety-critical applications, the controller-side may need to know whether the voltage is in the valid range for correct operation or not. Figure 8-2 shows the AMC23C14 in an application that monitors a 24-V supply on the high-side and signals undervoltage and overvoltage conditions to the programmable logic controller (PLC) on the low-side.

The voltage divider R5 and R6 is sized to trip the fixed internal 300-mV threshold when the power supply exceeds the minimum valid operating voltage of 20.4 V (24 V - 15%). In a second step, R1 (connected to the REF pin) is sized to trip the adjustable-threshold comparator when the power supply exceeds 28.8 V (24 V + 20%). The AMC23C14 is powered from the field supply and is protected against voltages greater than 30 V by a Zener diode (Z1) and shunt resistor R4.

When the power supply is below 20.4 V, both outputs of the AMC23C14 are in a Hi-Z state. Between 20.4 V and 28.8 V, OUT1 is in a Hi-Z state and OUT2 is actively pulled low. Both outputs are pulled low, as shown in Figure 8-3, when the power supply is above 28.8 V.

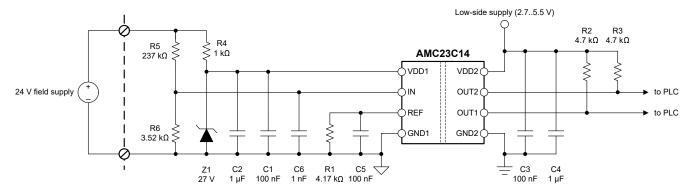


Figure 8-2. Using the AMC23C14 for Overvoltage and Undervoltage Detection

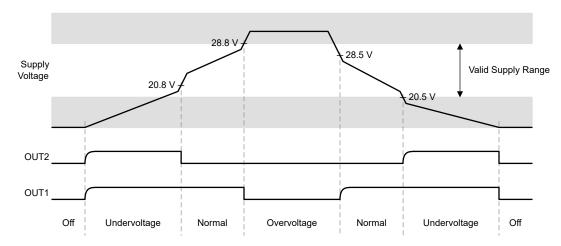


Figure 8-3. Output of the AMC23C14 in Supply Voltage Supervisor Application

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#### 8.2.2.1 Design Requirements

Table 8-1 lists the parameters for the application example in Figure 8-2.

Table 8-3. Design Requirements

| PARAMETER                                  | VALUE               |
|--|---------------------|
| High-side supply voltage                   | 3 V to 27 V         |
| Low-side supply voltage                    | 2.7 V to 5.5 V      |
| Field supply range                         | 24 V, -15 % to +20% |
| Undervoltage detection threshold           | 20.4 V              |
| Overvoltage detection threshold            | 28.8 V              |
| Cross-current in resistor divider (R5, R6) | 100 μΑ              |

#### 8.2.2.2 Detailed Design Procedure

The 100- $\mu$ A, cross-current requirement at nominal field-supply voltage (24 V) determines that the total impedance of the resistor divider comprised of R5 and R6 is 240 k $\Omega$ . The impedance of the voltage divider is dominated by R5, and therefore R5 is chosen as 237 k $\Omega$ .

At a field-supply voltage of 20.4 V, the voltage across R6 must equal the fixed-comparator threshold of 300 mV. This value determines the voltage divider ratio and the ideal value of R6 is calculated as R6 = R5 × 300 mV / ( $V_{TRIP} - 300 \text{ mV}$ ), where  $V_{TRIP}$  equals 20.4 V. The calculated value for R6 is 3.54 k $\Omega$  and the closest lower value from the E192 series is 3.52 k $\Omega$ .

With R6 and R5 known, the voltage can be calculated that is present at the input of the comparator when the field supply reaches 28.8 V, which is the upper limit of the valid operating range. This voltage is  $V_2$  = 28.8 V × (R6 / (R5 + R6) = 421.5 mV, and determines the value of R1. R1 is the resistor connected to the REF pin of the AMC23C14. R1 is calculated as  $(V_2 - V_{HYS})$  /  $I_{REF}$  = (421.5 mV - 4 mV) / 100  $\mu$ A = 4.17 k $\Omega$ . The value 4.17 k $\Omega$  matches a value in the E192 series. The comparator hysteresis voltage ( $V_{HYS}$ ) is subtracted from  $V_2$  because the comparator trips at  $V_{REF}$  +  $V_{HYS}$ , see Figure 7-1.

With R5 = 237 k $\Omega$ , R6 = 3.52 k $\Omega$ , and R1 = 4.17 k $\Omega$ , the resulting rising and falling thresholds are 20.8 V and 20.5 V for undervoltage detection and 28.8 V and 28.5 V for overvoltage detection, see Figure 8-3.

Table 8-4 summarizes the key parameters of the design.

Table 8-4. Overvoltage and Undervoltage Detection Design Example

| PARAMETER   | VALUE   |
|---|---------|
| Voltage divider, top resistor value (R5)                | 237 kΩ  |
| Voltage divider, bottom resistor value (R6)             | 3.52 kΩ |
| Reference resistor value (R1)                           | 4.17 kΩ |
| Reference capacitor value (C5)                          | 100 nF  |
| Reference voltage                                       | 417 mV  |
| Reference voltage settling time (to 90% of final value) | 960 μs  |
| Undervoltage trip threshold (rising)                    | 20.5 V  |
| Undervoltage trip threshold (falling)                   | 20.8 V  |
| Overvoltage trip threshold (rising)                     | 28.8 V  |
| Overvoltage trip threshold (rising)                     | 28.5 V  |

#### 8.2.3 Application Curves

Figure 8-4 shows the typical response of the AMC23C14 to a bipolar, triangular input waveform with an amplitude of 720 mV<sub>PP</sub>. OUT1 switches when VIN crosses the ±250-mV level determined by the REF pin voltage that is biased to 250 mV in this example. OUT2 switches when VIN crosses the ±300-mV level determined by the fixed internal reference value.

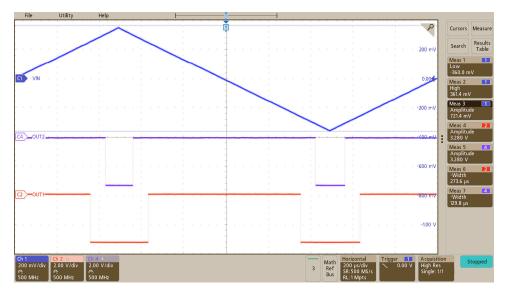


Figure 8-4. Output Response of the AMC23C14 to a Triangular Input Waveform

The integrated LDO of the AMC23C14 greatly relaxes the power-supply requirements on the high-voltage side and allows powering the device from non-regulated transformer, charge pump, and bootstrap supplies. As shown in Figure 8-5 through Figure 8-7, the internal LDO provides a stable operating voltage to the internal circuitry, allowing the trip thresholds to remain mostly undisturbed even at ripple voltages of  $2 V_{PP}$  and higher.

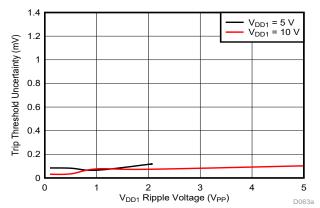


Figure 8-5. Trip Threshold Sensitivity to VDD1 Ripple Voltage (Cmp0, f<sub>RIPPLE</sub> = 10 kHz)

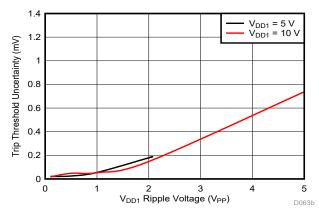
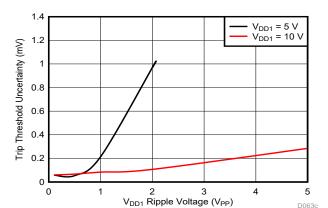


Figure 8-6. Trip Threshold Sensitivity to VDD1 Ripple Voltage (Cmp1, f<sub>RIPPLE</sub> = 10 kHz)



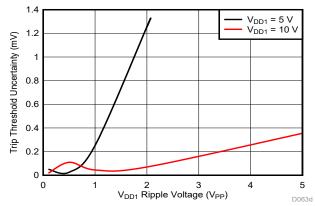


Figure 8-7. Trip Threshold Sensitivity to VDD1 Ripple Voltage (Cmp2, f<sub>RIPPLE</sub> = 10 kHz)

Figure 8-8. Trip Threshold Sensitivity to VDD1 Ripple Voltage (Cmp3, f<sub>RIPPLE</sub> = 10 kHz)

### 8.3 Best Design Practices

Keep the connection between the low-side of the sense resistor and the GND1 pin of the AMC23C14 short and low impedance. Any voltage drop in the ground line adds error to the voltage sensed at the input of the comparator and leads to inaccuracies in the trip thresholds.

For best common-mode transient immunity, place the filter capacitor C5 as closely to the REF pin as possible as illustrated in Figure 8-10. Use a low value pullup resistor (<10 k $\Omega$ ) on the open-drain output, as explained in the *Open-Drain Digital Outputs* section, to minimize the effect of capacitive coupling on the open-drain signal line during a common-mode transient event.

Do not exceed the 300-mV  $V_{REF}$  limit specified in the *Recommended Operating Conditions* table for bidirectional current-sensing applications. Do not operate the device with the REF pin biased close to the  $V_{MSEL}$  threshold (450-mV to 600-mV range) to avoid dynamic switching of the Cmp0 hysteresis as explained in the *Reference Input* section.

The AMC23C14 provides a limited 200- $\mu$ s blanking time ( $t_{HS,BLK}$ ) to allow the reference voltage ( $V_{REF}$ ) to settle during start up. For many applications, the reference voltage takes longer to settle than the 200- $\mu$ s blanking time and the output of the comparator can possibly glitch during system start up as described in Figure 7-2. Consider the reference voltage settling time in the overall system start- $\mu$ g design.

#### 8.4 Power Supply Recommendations

The AMC23C14 does not require any specific power-up sequencing. The high-side power supply (VDD1) is decoupled with a low-ESR, 100-nF capacitor (C1) parallel to a low-ESR, 1-µF capacitor (C2). The low-side power supply (VDD2) is equally decoupled with a low-ESR, 100-nF capacitor (C3) parallel to a low-ESR, 1-µF capacitor (C4). Place all four capacitors (C1, C2, C3, and C4) as close to the device as possible. Figure 8-9 shows a decoupling schematic for the AMC23C14.

For high VDD1 supply voltages (>5.5 V) place a  $10-\Omega$  resistor (R4) is series with the VDD1 power supply for additional filtering.

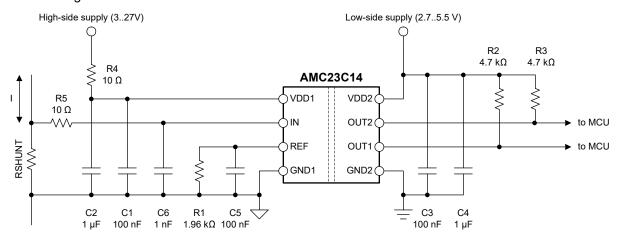


Figure 8-9. Decoupling of the AMC23C14

Capacitors must provide adequate effective capacitance under the applicable DC bias conditions they experience in the application. Multilayer ceramic capacitors (MLCCs) typically exhibit only a fraction of their nominal capacitance under real-world conditions and this factor must be taken into consideration when selecting these capacitors. This problem is especially acute in low-profile capacitors, in which the dielectric field strength is higher than in taller components. Reputable capacitor manufacturers provide capacitance versus DC bias curves that greatly simplify component selection.

#### 8.5 Layout

#### 8.5.1 Layout Guidelines

Figure 8-10 shows a layout recommendation with the critical placement of the decoupling capacitors (as close as possible to the AMC23C14 supply pins) and placement of the other components required by the device.

#### 8.5.2 Layout Example

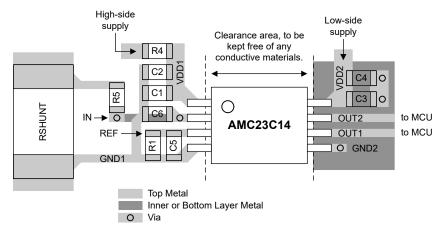


Figure 8-10. Recommended Layout of the AMC23C14

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## 9 Device and Documentation Support

## 9.1 Documentation Support

#### 9.1.1 Related Documentation

For related documentation, see the following:

- Texas Instruments, Isolation Glossary application report
- Texas Instruments, Semiconductor and IC Package Thermal Metrics application report
- Texas Instruments, ISO72x Digital Isolator Magnetic-Field Immunity application report
- Texas Instruments, AMC1300 Precision, ±250-mV Input, Reinforced Isolated Amplifier data sheet
- Texas Instruments, Isolated Amplifier Voltage Sensing Excel Calculator design tool

#### 9.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 9.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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## 9.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 9.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

## 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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#### PACKAGING INFORMATION

| Orderable Device | Status | Package Type | Package<br>Drawing | Pins | Package<br>Qty | Eco Plan     | Lead finish/<br>Ball material | MSL Peak Temp       | Op Temp (°C) | Device Marking<br>(4/5) | Samples |
|------------------|--------|--------------|--------------------|------|----------------|--------------|-------------------------------|---------------------|--------------|-------------------------|---------|
|                  |        |              |                    |      |                |              | (6)                           |                     |              |                         |         |
| AMC23C14DWV      | ACTIVE | SOIC         | DWV                | 8    | 64             | RoHS & Green | NIPDAU                        | Level-3-260C-168 HR | -40 to 125   | MC23C14                 | Samples |
| AMC23C14DWVR     | ACTIVE | SOIC         | DWV                | 8    | 1000           | RoHS & Green | NIPDAU                        | Level-3-260C-168 HR | -40 to 125   | MC23C14                 | Samples |
| PAMC23C14DWVR    | ACTIVE | SOIC         | DWV                | 8    | 1000           | TBD          | Call TI                       | Call TI             | -40 to 125   |                         | Samples |

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE OPTION ADDENDUM**

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# **PACKAGE MATERIALS INFORMATION**

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#### TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width     |
|----|---|
| В0 | Dimension designed to accommodate the component length    |
| K0 | Dimension designed to accommodate the component thickness |
| W  | Overall width of the carrier tape                         |
| P1 | Pitch between successive cavity centers                   |

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

| Device       | Package<br>Type | Package<br>Drawing |   | SPQ  | Reel<br>Diameter<br>(mm) | Reel<br>Width<br>W1 (mm) | A0<br>(mm) | B0<br>(mm) | K0<br>(mm) | P1<br>(mm) | W<br>(mm) | Pin1<br>Quadrant |
|--------------|-----------------|--------------------|---|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| AMC23C14DWVR | SOIC            | DWV                | 8 | 1000 | 330.0                    | 16.4                     | 12.05      | 6.15       | 3.3        | 16.0       | 16.0      | Q1               |

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#### \*All dimensions are nominal

|   | Device       | Package Type | Package Drawing | ckage Drawing Pins |      | Length (mm) | Width (mm) | Height (mm) |  |
|---|--------------|--------------|-----------------|--------------------|------|-------------|------------|-------------|--|
| ı | AMC23C14DWVR | SOIC         | DWV             | 8                  | 1000 | 350.0       | 350.0      | 43.0        |  |



SOIC



#### NOTES:

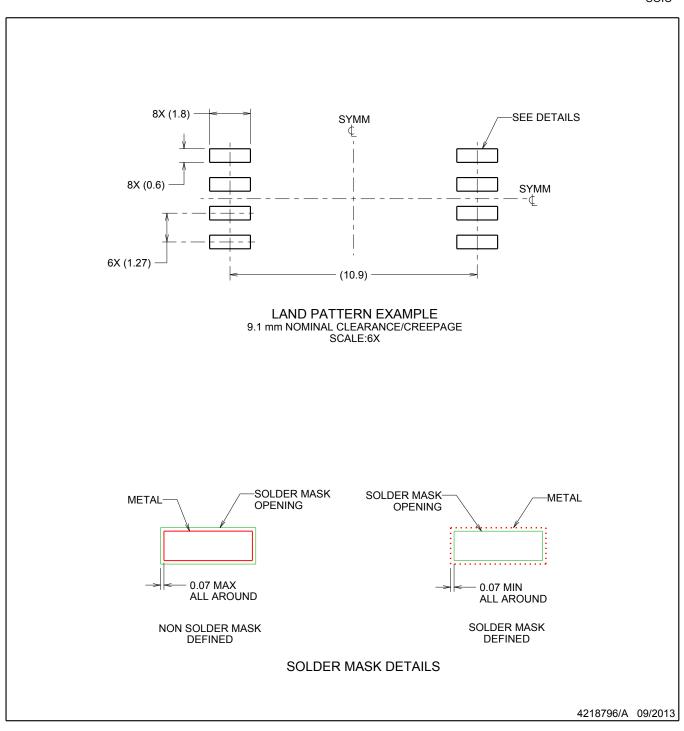
- 1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing
- per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm, per side.



SOIC

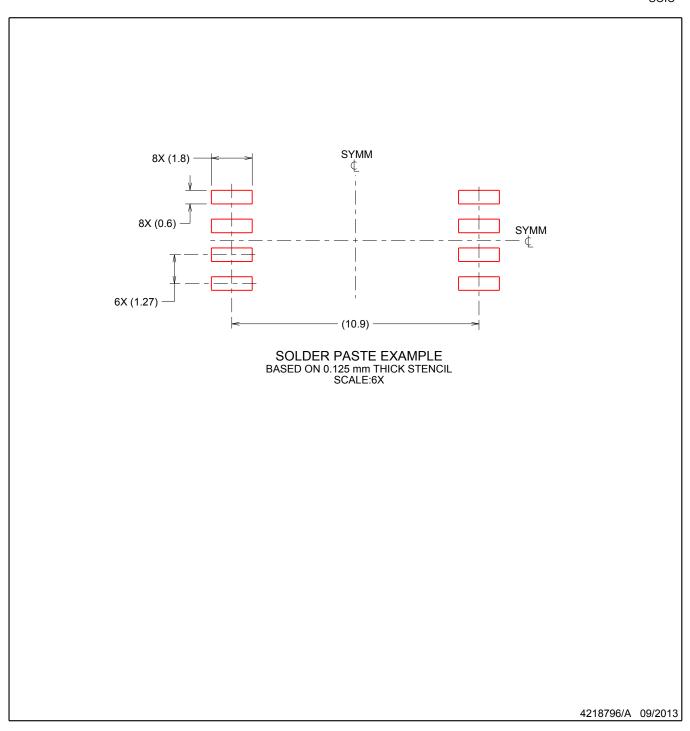


NOTES: (continued)

- 5. Publication IPC-7351 may have alternate designs.
- 6. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



SOIC



#### NOTES: (continued)

- 7. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 8. Board assembly site may have different recommendations for stencil design.



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