

## 600-kHz, Host-Controlled Multi-Cell Battery Charger With Input Overvoltage Protection

### **FEATURES**

- **NMOS-NMOS Synchronous Buck Converter** with 600 kHz Frequency and >95% Efficiency
- 30-ns Minimum Driver Dead-time and 99.5% Maximum Effective Duty Cycle
- **High-Accuracy Voltage and Current Regulation** 
  - ±0.5% Charge Voltage Accuracy
  - ±3% Charge Current Accuracy
  - ±3% Adapter Current Accuracy
  - ±2% Input Current Sense Amp Accuracy
- Integration
  - Internal Loop Compensation
  - Internal Soft-Start
- Safetv
  - Input Overvoltage Protection (OVP)
  - Dynamic Power Management (DPM) with **Status Indicator**
- Supports Two, Three, or Four Li+ Cells
- 5 24 V AC/DC-Adapter Operating Range
- Analog Inputs with Ratiometric Programming via Resistors or DAC/GPIO Host Control
  - Charge Voltage (4-4.512 V/cell)
  - Charge Current (up to 8 A, with 10-m $\Omega$ Sense Resistor)
  - Adapter Current Limit (DPM)
- **Status and Monitoring Outputs** 
  - AC/DC Adapter Present with Programmable Voltage Threshold
  - DPM Loop Active (DPMDET)
  - Current Drawn from Input Source
- Supports Any Battery Chemistry: Li+, NiCd, • NiMH, Lead Acid, etc.
- Charge Enable
- **10-µA Off-State Battery Current**
- 24-pin, 4x4-mm QFN Package

#### APPLICATIONS

- Notebook and Ultra-Mobile Computers •
- **Portable Data-Capture Terminals** •
- **Portable Printers**
- **Medical Diagnostics Equipment** .
- **Battery Bay Chargers** •
- **Battery Back-Up Systems**

### DESCRIPTION

The bq24705 is a high-efficiency, synchronous battery charger with integrated compensation, offering low component count for space-limited multi-chemistry battery charging applications. Charge current and voltage programming allows high regulation accuracies, and can be either hardwired with resistors, or programmed by the system power-management microcontroller using a DAC or GPIOs.

The bq24705 charges two, three, or four series Li+ cells, supporting up to 8 A of charge current, and is available in a 24-pin, 4x4-mm thin QFN package.

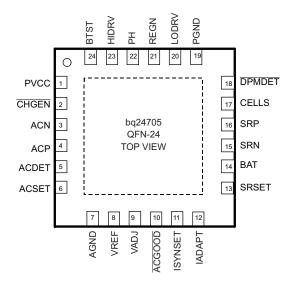


Figure 1. bg24705, 24 LD QFN, Top View



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet. PowerPad is a trademark of Texas Instruments.

## bq24705

SLUS779B-DECEMBER 2007-REVISED MARCH 2009



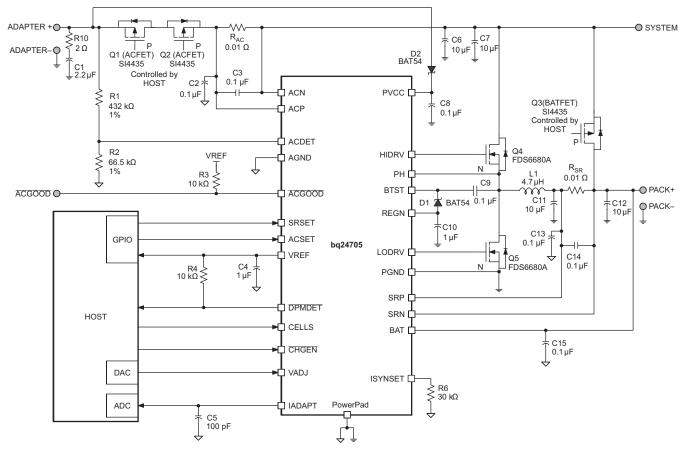
www.ti.com



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## **DESCRIPTION (CONTINUED)**

The bq24705 features Dynamic Power Management (DPM) and input power limiting. These features reduce battery charge current when the input power limit is reached to avoid overloading the AC adapter when supplying the load and the battery charger simultaneously. A highly-accurate current-sense amplifier enables precise measurement of input current from the AC adapter to monitor the overall system power.



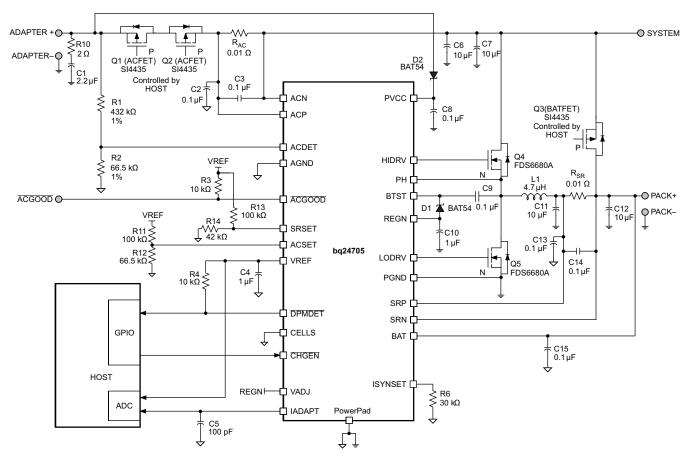
(1) Pull-up rail could be either VREF or other system rail.

(2) SRSET/ACSET could come from either DAC or resistor dividers.

(3)  $V_{IN} = 20 \text{ V}, V_{BAT} = 3$ -cell Li-Ion,  $I_{CHARGE} = 3 \text{ A}, I_{ADAPTER\_LIMIT} = 4 \text{ A}$ 

Figure 2. Typical System Schematic, Voltage and Current Programmed by DAC





- (1) Pull-up rail could be either VREF or other system rail.
- (2) SRSET/ACSET could come from either DAC or resistor dividers.
- (3)  $V_{IN} = 20 \text{ V}, V_{BAT} = 3$ -cell Li-Ion,  $I_{CHARGE} = 3 \text{ A}, I_{ADAPTER\_LIMIT} = 4 \text{ A}$

#### Figure 3. Typical System Schematic, Voltage and Current Programmed by Resistor

#### **ORDERING INFORMATION**

Part Number	Package	Ordering Number (Tape and Reel)	Quantity
h~24705		bq24705RGER	3000
bq24705	24-PIN 4 x 4 mm QFN	bq24705RGET	250

#### PACKAGE THERMAL DATA

PACKAGE	$\theta_{JA}$	T <sub>A</sub> =70°C POWER RATING	DERATING FACTOR ABOVE T <sub>A</sub> = 25°C
QFN – RGE <sup>(1)(2)</sup>	45°C/W	2.33 W	0.023 W/°C

 For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI Web site at www.ti.com.

(2) This data is based on using the JEDEC High-K board and the exposed die pad is connected to a Cu pad on the board. This is connected to the ground plane by a 2x3 via matrix.

#### TEXAS INSTRUMENTS

www.ti.com

#### Table 1. TERMINAL FUNCTIONS – 24-PIN QFN

TERMIN	IAL	DESCRIPTION	
NAME	NO.	DESCRIPTION	
PVCC	1	IC power positive supply. Place a $0.1-\mu F$ ceramic capacitor from PVCC to PGND pin close to the IC.	
CHGEN	2	Charge enable active-low logic input. LO enables charge. HI disables charge.	
ACN	3	Adapter current sense resistor, negative input. A 0.1-µF ceramic capacitor is placed from ACN to ACP to provide ACN 2 differential-mode filtering. An optional 0.1-µF ceramic capacitor is placed from ACN pin to AGND for common-mode filtering.	
ACP	4	Adapter current sense resistor, positive input. A 0.1-µF ceramic capacitor is placed from ACN to ACP to provide differential-mode filtering. A 0.1-µF ceramic capacitor is placed from ACP pin to AGND for common-mode filtering.	
ACDET	5	Adapter detected voltage set input. Program the adapter detect threshold by connecting a resistor divider from adapter input to ACDET pin to AGND pin. Adapter voltage is detected if ACDET-pin voltage is greater than 2.4 V.	
ACSET	6	Adapter current set input. The voltage ratio of ACSET voltage versus VREF voltage programs the input current regulation set-point during Dynamic Power Management (DPM). Program by connecting a resistor divider from VREF to ACSET to AGND; or by connecting the output of an external DAC to the ACSET pin.	
AGND	7	Analog ground. Ground connection for low-current sensitive analog and digital signals. On PCB layout, connect to the analog ground plane, and only connect to PGND through the PowerPad underneath the IC.	
VREF	8	3.3-V regulated voltage output. Place a 1- $\mu$ F ceramic capacitor from VREF to AGND pin close to the IC. This voltage could be used for ratiometric programming of voltage and current regulation. VREF is the source for the internal circuit.	
VADJ	9	Charge voltage set input. The voltage ratio of VADJ voltage versus VREF voltage programs the battery voltage regulation set-point. Program by connecting a resistor divider from VREF to VADJ, to AGND; or, by connecting the output of an external DAC to VADJ. VADJ connected to REGN programs the default of 4.2 V per cell.	
ACGOOD	10	Valid adapter active-low detect logic open-drain <u>output</u> . Pulled low when input voltage is above ACDET programmed threshold. Connect a 10-k $\Omega$ pullup resistor from ACGOOD pin to pullup supply rail.	
ISYNSET	11	Synchronous mode current set input. Place a resistor from ISYNSET to AGND to program the charge undercurrent threshold to force non-synchronous converter operation at low output current, and to prevent negative inductor current. Threshold should be set at greater than half of the maximum inductor ripple current (50% duty cycle).	
IADAPT	12	Adapter current sense amplifier output. IADAPT voltage is 20 times the differential voltage across ACP-ACN. Place a 100-pF or less ceramic decoupling capacitor from IADAPT to AGND.	
SRSET	13	Charge current set input. The voltage ratio of SRSET voltage versus VREF voltage programs the charge current regulation set-point. Program by connecting a resistor divider from VREF to SRSET to AGND; or by connecting the output of an external DAC to SRSET pin.	
BAT	14	Battery voltage remote sense. Directly connect a kelvin sense trace from the battery pack positive terminal to the BAT pin to accurately sense the battery pack voltage. Place a $0.1$ - $\mu$ F capacitor from BAT to AGND close to the IC to filter high-frequency noise.	
SRN	15	Charge current sense resistor, negative input. A 0.1-µF ceramic capacitor is placed from SRN to SRP to provide differential-mode filtering. An optional 0.1-µF ceramic capacitor is placed from SRN pin to AGND for common-mode filtering.	
SRP	16	Charge current sense resistor, positive input. A 0.1-μF ceramic capacitor is placed from SRN to SRP to provide differential-mode filtering. A 0.1-μF ceramic capacitor is placed from SRP pin to AGND for common-mode filtering.	
CELLS	17	2, 3 or 4 cells selection logic input. Logic low programs 3 cell. Logic high programs 4 cell. Floating programs 2 cell.	
DPMDET	18	Dynamic power management (DPM) input current loop active, open-drain output status. Logic low indicates input current is being limited by reducing the charge current. Connect $10-k\Omega$ pullup resistor from DPMDET to VREF or a different pullup-supply rail.	
PGND	19	Power ground. Ground connection for high-current power converter node. On PCB layout, connect directly to source of low-side power MOSFET, to ground connection of in put and output capacitors of the charger. Only connect to AGND through the PowerPad underneath the IC.	
LODRV	20	PWM low side driver output. Connect to the gate of the low-side power MOSFET with a short trace.	
REGN	21	PWM low side driver positive 6-V supply output. Connect a 1-µF ceramic capacitor from REGN to PGND, close to the IC. Use for high-side driver bootstrap voltage by connecting a small-signal Schottky diode from REGN to BTST.	
РН	22	PWM high side driver negative supply. Connect to the phase switching node (junction of the low-side power MOSFET drain, high-side power MOSFET source, and output inductor). Connect the 0.1-µF bootstrap capacitor from from PH to BTST.	
HIDRV	23	PWM high side driver output. Connect to the gate of the high-side power MOSFET with a short trace.	
BTST	24	PWM high side driver positive supply. Connect a 0.1-µF bootstrap ceramic capacitor from BTST to PH. Connect a small bootstrap Schottky diode from REGN to BTST.	

#### Table 1. TERMINAL FUNCTIONS – 24-PIN QFN (continued)

TERMINAL		DESCRIPTION	
NAME	NO.	DESCRIPTION	
PowerPad™		Exposed pad beneath the IC. AGND and PGND star-connected only at the PowerPad plane. Always solder PowerPad to the board, and have vias on the PowerPad plane connecting to AGND and PGND planes . It also serves as a thermal pad to dissipate the heat.	

#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)  $^{(1)}$   $^{(2)}$ 

		VALUE	UNIT
	PVCC, ACP, ACN, SRP, SRN, BAT	-0.3 to 30	
	PH	-1 to 30	
Voltage range	REGN, LODRV, VADJ, ACSET, SRSET, ACDET, ISYNSET, CHGEN, CELLS, ACGOOD, DPMDET, IADAPT	-0.3 to 7	V
	VREF	-0.3 to 3.6	
	BTST, HIDRV with respect to AGND and PGND	-0.3 to 36	
Maximum difference voltage	ACP-ACN, SRP-SRN, AGND-PGND	-0.5 to 0.5	V
Junction temperature range		-40 to 155	ŝ
Storage temperature range		-55 to 155	C

(1) Stresses beyond those listed under *absolute maximum ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *recommended operating conditions* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltages are with respect to GND if not specified. Currents are positive into, negative out of the specified terminal. Consult Packaging Section of the data book for thermal limitations and considerations of packages.

#### **RECOMMENDED OPERATING CONDITIONS**

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT	
	PH	-1		24		
	PVCC, ACP, ACN, SRP, SRN, BAT	0		24		
	REGN, LODRV, VADJ	0		6.5		
Voltage range	VREF	0		3.3 <sub>V</sub>		
	ACSET, SRSET, ACDET, ISYNSET, CHGEN, CELLS, ACGOOD, DPMDET, IADAPT	0		5.5	·	
	BTST, HIDRV with respect to AGND and PGND	0		30		
	AGND, PGND	-0.3		0.3		
Maximum differe	ence voltage: ACP-ACN, SRP-SRN	-0.3		0.3	V	
Junction temperature range		-40		125	°C	
Storage tempera	ature range	-55		150	50	

bq24705

SLUS779B-DECEMBER 2007-REVISED MARCH 2009



www.ti.com

### **ELECTRICAL CHARACTERISTICS**

7 V  $\leq$  V<sub>PVCC</sub>  $\leq$  24 V, 0°C < T<sub>J</sub> < +125°C, typical values are at T<sub>A</sub> = 25°C, with respect to AGND (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP MAX	UNI
OPERATING C	ONDITIONS				
V <sub>PVCC_OP</sub>	PVCC Input voltage operating range		5	24	V
CHARGE VOLT	AGE REGULATION				
V <sub>BAT REG RNG</sub>	BAT voltage regulation range	4V-4.512V per cell, times 2,3,4 cell	8	18	V
V <sub>ADJ_OP</sub>	VADJ voltage range		0	REGN	V
		8 V, 8.4 V, 9.024 V	-0.5%	0.5%	
	Charge voltage regulation accuracy	12 V, 12.6 V, 13.536 V	-0.5%	0.5%	
		16 V, 16.8 V, 18.048 V	-0.5%	0.5%	
	Charge voltage regulation set to default to 4.2 V per cell	VADJ connected to REGN, 8.4 V, 12.6 V, 16.8 V	-0.5%	0.5%	
CHARGE CURI	RENT REGULATION				
V <sub>IREG_CHG</sub>	Charge current regulation differential voltage range	$V_{IREG\_CHG} = V_{SRP} - V_{SRN}$	0	100	mV
V <sub>SRSET_OP</sub>	SRSET voltage range		0	VREF	V
· · ·		V <sub>IREG_CHG</sub> = 40–100 mV	-3%	3%	
		V <sub>IREG_CHG</sub> = 20 mV	-5%	5%	
	Charge current regulation accuracy	V <sub>IREG_CHG</sub> = 5 mV	-25%	25%	
		$V_{\text{IREG_CHG}} = 1.5 \text{ mV} (V_{\text{BAT}} \ge 4\text{V})$	-33%	33%	
INPUT CURREI	NT REGULATION				
V <sub>IREG_DPM</sub>	Adapter current regulation differential voltage range	$V_{IREG_{DPM}} = V_{ACP} - V_{ACN}$	0	100	mV
V <sub>ACSET_OP</sub>	ACSET voltage range		0	VREF	V
		V <sub>IREG_DPM</sub> = 40–100 mV	-3%	3%	
		V <sub>IREG_DPM</sub> = 20 mV	-5%	5%	
	Input current regulation accuracy	V <sub>IREG DPM</sub> = 5 mV	-25%	25%	
		V <sub>IREG DPM</sub> = 1.5 mV	-33%	33%	
VREF REGULA	TOR				
V <sub>VREF_REG</sub>	VREF regulator voltage	V <sub>ACDET</sub> > 0.6 V, 0-30 mA	3.267	3.3 3.333	V
IVREF LIM	VREF current limit	V <sub>VREF</sub> = 0 V, V <sub>ACDET</sub> > 0.6 V	35	75	mA
REGN REGULA	ATOR				
V <sub>REGN_REG</sub>	REGN regulator voltage	V <sub>ACDET</sub> > 0.6 V, 0-75 mA, PVCC > 10 V	5.6	5.9 6.2	V
I <sub>REGN_LIM</sub>	REGN current limit	$V_{REGN} = 0 V, V_{ACDET} > 0.6 V$	90	135	mA
	RENT SENSE AMPLIFIER				
V <sub>ACP/N_OP</sub>	Input common mode range	Voltage on ACP/ACN	0	24	V
VIADAPT	IADAPT output voltage range		0	2	V
IIADAPT	IADAPT output current		0	1	mA
A <sub>IADAPT</sub>	Current sense amplifier voltage gain	A <sub>IADAPT</sub> = V <sub>IADAPT</sub> / V <sub>IREG</sub> DPM		20	V/V
	· • •	$V_{\text{IREG}_{DPM}} = 40-100 \text{ mV}$	-2%	2%	
		$V_{\text{IREG DPM}} = 20 \text{ mV}$	-3%	3%	
	Adapter current sense accuracy	$V_{\text{IREG_DPM}} = 5 \text{ mV}$	-25%	25%	
		$V_{\text{IREG_DPM}} = 1.5 \text{ mV}$	-30%	30%	
	Output current limit		1		mA
_			•	100	pF
I <sub>IADAPT_LIM</sub> C <sub>IADAPT_MAX</sub>	Output current limit Maximum output load capacitance	$V_{IREG_{DPM}} = 1.5 \text{ mV}$ $V_{IADAPT} = 0 \text{ V}$ For stability with 0 mA to 1 mA load		100	



### **ELECTRICAL CHARACTERISTICS (continued)**

7 V  $\leq$  V<sub>PVCC</sub>  $\leq$  24 V, 0°C < T<sub>J</sub> < +125°C, typical values are at T<sub>A</sub> = 25°C, with respect to AGND (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
ACDET COMPA	RATOR						
V <sub>PVCC-BAT_OP</sub>	Differential Voltage from PVCC to BAT		-20		24	V	
V <sub>ACDET_CHG</sub>	ACDET adapter-detect rising threshold	Min voltage to enable charging, $V_{\text{ACDET}}$ rising	2.376	2.40	2.424	V	
V <sub>ACDET_CHG_HYS</sub>	ACDET falling hysteresis	V <sub>ACDET</sub> falling		40		mV	
	ACDET rising deglitch <sup>(1)</sup>	V <sub>ACDET</sub> rising	6.4	8	9.6	ms	
	ACDET falling deglitch	V <sub>ACDET</sub> falling		10		μs	
V <sub>ACDET_BIAS</sub>	ACDET enable-bias rising threshold	Min voltage to enable all bias, $V_{ACDET}$ rising	0.56	0.62	0.68	V	
V <sub>ACDET_BIAS_HYS</sub>	Adapter present falling hysteresis	V <sub>ACDET</sub> falling		20		mV	
	ACDET_BIAS rising deglitch <sup>(1)</sup>	V <sub>ACDET</sub> rising		10		μs	
	ACDET_BIAS falling deglitch	V <sub>ACDET</sub> falling		10		μο	
OPEN-DRAIN LO	OGIC OUTPUT PIN CHARACTERISTICS	ACGOOD)					
V <sub>O(LO)</sub>	Output low saturation voltage	Sink Current = 4 mA			0.5	V	
	ACGOOD falling delay	V <sub>ACDET</sub> rising	6.4	8	9.6	ms	
	ACGOOD rising delay	V <sub>ACDET</sub> falling		10		μs	
INPUT OVERVO	LTAGE COMPARATOR (ACOV)						
V <sub>ACOV</sub>	AC Overvoltage rising threshold on ACDET (See ACDET in <i>Terminal Functions</i> )		3.007	3.1	3.193	V	
V <sub>ACOV_HYS</sub>	AC Overvoltage rising deglitch			1.3			
1001_110	AC Overvoltage falling deglitch			1.3		ms	
PVCC / BAT CO							
V <sub>PVCC</sub> -BAT_FALL	PVCC to BAT falling threshold	V <sub>PVCC</sub> – V <sub>BAT</sub> falling to disable 140 185 Charger		240	mV		
V <sub>PVCC-BAT_HYS</sub>	PVCC to BAT hysteresis			50		mV	
	PVCC to BAT Rising Deglitch	$V_{PVCC} - V_{BAT} > V_{PVCC-BAT_RISE}$	7	9	11	ms	
	PVCC to BAT Falling Deglitch	$V_{PVCC} - V_{BAT} < V_{PVCC-BAT_FALL}$		10		μs	
INPUT UNDERV	OLTAGE LOCK-OUT COMPARATOR (UV	′L0)					
UVLO	AC Undervoltage rising threshold	Measure on PVCC	3.5	4	4.5	V	
	AC Undervoltage hysteresis, falling			260		mV	
BAT OVERVOL	TAGE COMPARATOR						
Vo	Overvoltage rising threshold <sup>(1)</sup>	As percentage of V <sub>BAT REG</sub>		104%			
•0	Overvoltage falling threshold <sup>(1)</sup>	As percentage of VBAT_REG		102%			
CHARGE OVER	CURRENT COMPARATOR						
V <sub>OC</sub>	Charge overcurrent falling threshold	As percentage of I <sub>REG_CHG</sub>		145%			
	Minimum Current Limit (SRP-SRN)			50		mV	
THERMAL SHU	TDOWN COMPARATOR						
T <sub>SHUT</sub>	Thermal shutdown rising temperature	Temperature Increasing	155		°C		
T <sub>SHUT_HYS</sub>	Thermal shutdown hysteresis, falling			20		U	
PWM HIGH SIDE	E DRIVER (HIDRV)						
Bro( )	High side driver turn-on resistance	$V_{BTST} - V_{PH} = 5.5 V$ , tested at 100 mA		3	6	Ω	
R <sub>DS(on)</sub>	High side driver turn-off resistance	$V_{BTST} - V_{PH} = 5.5 V$ , tested at 100 mA	= 5.5 V, tested at 100 mA 0.7		1.4	12	
V <sub>BTST_REFRESH</sub>	Bootstrap refresh comparator threshold voltage	$V_{\text{BTST}} - V_{\text{PH}}$ when low side refresh pulse is requested	4	_		V	

(1) Specified by design.

Copyright © 2007–2009, Texas Instruments Incorporated

SLUS779B-DECEMBER 2007-REVISED MARCH 2009



**FEXAS** 

## **ELECTRICAL CHARACTERISTICS (continued)**

7 V  $\leq$  V<sub>PVCC</sub>  $\leq$  24 V, 0°C < T<sub>J</sub> < +125°C, typical values are at T<sub>A</sub> = 25°C, with respect to AGND (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
PWM LOW SI	DE DRIVER (LODRV)					
2	Low side driver turn-on resistance	REGN = 6 V, tested at 100 mA		3	6	0
R <sub>DS(on)</sub>	Low side driver turn-off resistance	REGN = 6 V, tested at 100 mA		0.6	1.2	Ω
PWM DRIVER	RS TIMING	·				
	Driver Dead Time — Dead time when switching between LODRV and HIDRV. No load at LODRV and HIDRV		30			ns
PWM OSCILL	ATOR					
F <sub>SW</sub>	PWM switching frequency		480	600	720	kHz
V <sub>RAMP_HEIGHT</sub>	PWM ramp height	As percentage of PVCC		6.6		%PVCC
QUIESCENT	CURRENT	·				
l	Total off-state battery current from SRP,	$V_{BAT} = 16.8 \text{ V}, V_{ACDET} < 0.6 \text{ V}, V_{PVCC} > 5 \text{ V}, T_J = 85^{\circ}\text{C}$		7	10	μA
OFF_STATE	SRN, BAT, VCC, BTST, PH, etc.	$V_{BAT} = 16.8 V, V_{ACDET} < 0.6 V, V_{PVCC} > 5 V, T_J = 125^{\circ}C$		7	11	μΑ
I <sub>AC</sub>	Adapter quiescent current	$V_{PVCC}$ = 20 V, charge disabled		2.8	4	mA
INTERNAL SO	OFT START (8 steps to regulation current)					
	Soft start steps			8		step
	Soft start step time			1.7		ms
CHARGER SE	ECTION POWER-UP SEQUENCING	·				
	Charge-enable delay after power-up	Delay from when adapter is detected to when the charger is allowed to turn on	518	700	908	ms
ISYNSET AM	PLIFIER AND COMPARATOR (SYNCHRONOL	JS TO NON-SYNCHRONOUS TRANSIT	ON)			
	I <sub>SYN</sub> Accuracy	V <sub>(SRP-SRN)</sub> = 5 mV	-20%		20%	
	ISYNSET pin voltage			1		V
VISYNSET	ISYNSET rising deglitch			20		μs
	ISYNSET falling deglitch			640		μs
LOGIC IO PIN	I CHARACTERISTICS (CHGEN)	I				
V <sub>IN(LO)</sub>	Input low threshold voltage				0.8	V
V <sub>IN(HI)</sub>	Input high threshold voltage		2.1			
I <sub>BIAS</sub>	Input bias current	$V_{\overline{CHGEN}} = 0$ to $V_{REGN}$			1	μA
	PIN CHARACTERISTICS (CELLS)					•
V <sub>IN(LO)</sub>	Input low threshold voltage, 3 cells	CELLS voltage falling edge			0.5	
V <sub>IN(MID)</sub>	Input mid threshold voltage, 2 cells	CELLS voltage rising for MIN, CELLS voltage falling for MAX	0.8		1.8	V
V <sub>IN(HI)</sub>	Input high threshold voltage, 4 cells	CELLS voltage rising	2.5			
I <sub>BIAS_FLOAT</sub>	Input bias float current for 2-cell selection	$V = 0$ to $V_{REGN}$	-1		1	μA
	LOGIC OUTPUT PIN CHARACTERISTICS (DF					•
V <sub>O(LO)</sub>	Output low saturation voltage	Sink Current = 5 mA			0.5	V
0(10)	Delay, rising/falling			10		ms

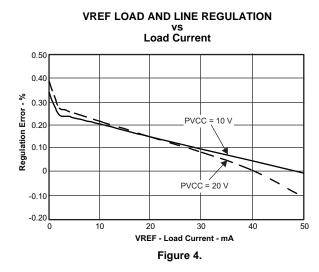


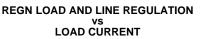
## **TYPICAL CHARACTERISTICS**

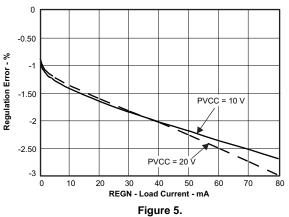
#### Table of Graphs<sup>(1)</sup>

Y	X	Figure
VREF Load and Line Regulation	vs Load Current	Figure 4
REGN Load and Line Regulation	vs Load Current	Figure 5
BAT Voltage	vs VADJ/VREF Ratio	Figure 6
Charge Current	vs SRSET/VREF Ratio	Figure 7
Input Current	vs ACSET/VREF Ratio	Figure 8
BAT Voltage Regulation Accuracy	vs Charge Current	Figure 9
BAT Voltage Regulation Accuracy		Figure 10
Charge Current Regulation Accuracy		Figure 11
Input Current Regulation (DPM) Accuracy		Figure 12
VIADAPT Input Current Sense Amplifier Accuracy		Figure 13
Input Regulation Current (DPM), and Charge Current	vs System Current	Figure 14
Transient System Load (DPM) Response		Figure 15
Charge Current Regulation	vs BAT Voltage	Figure 16
Efficiency	vs Battery Charge Current	Figure 17
Battery Removal (from Constant Current Mode)		Figure 18
REF and REGN Startup		Figure 19
Charger on Adapter Removal		Figure 20
Charge Enable / Disable and Current Soft-Start		Figure 21
Nonsynchronous to Synchronous Transition		Figure 22
Synchronous to Nonsynchronous Transition		Figure 23
Near 100% Duty Cycle Bootstrap Recharge Pulse	Figure 24	
Battery Shorted Charger Response, Over Current Prote	ection (OCP) and Charge Current Regulation	Figure 25
Continuous Conduction Mode (CCM) Switching Wavefor	orms	Figure 26
Discontinuous Conduction Mode (DCM) Switching Way	reforms	Figure 28
DPMDET Response with Transient System Load		Figure 27

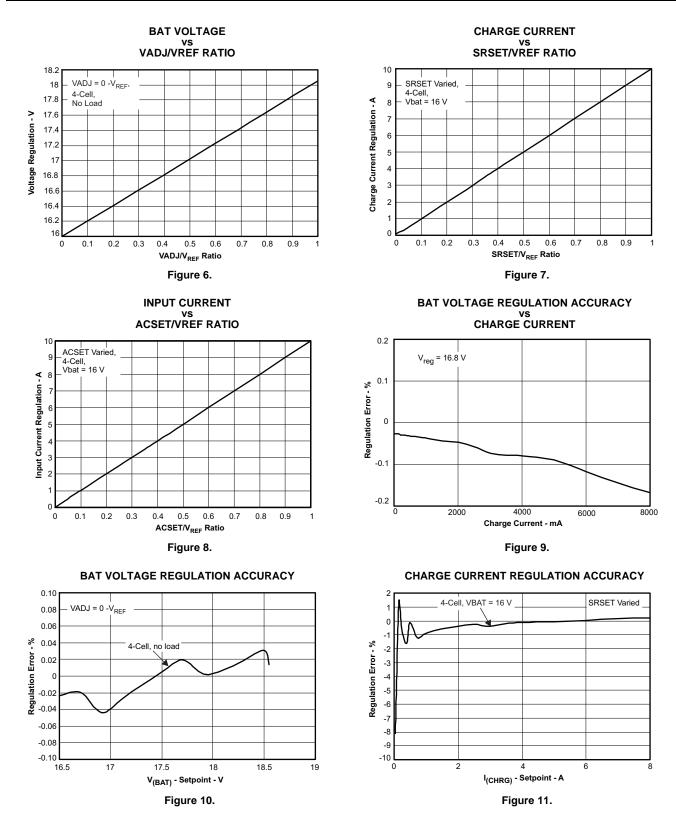
Test results based on Figure 3 application schematic. V<sub>IN</sub> = 20 V, V<sub>BAT</sub> = 3-cell Li-Ion, I<sub>CHG</sub> = 3 A, I<sub>ADAPTER\_LIMIT</sub> = 4 A, T<sub>A</sub> = 25°C, unless otherwise specified.





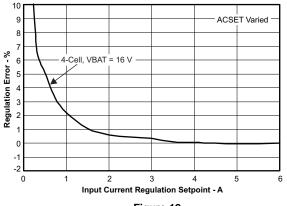








#### INPUT CURRENT REGULATION (DPM) ACCURACY







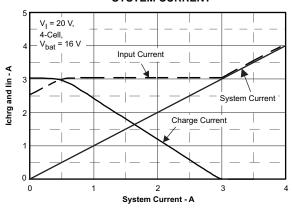
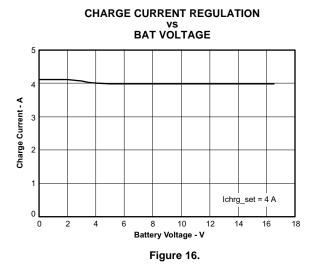
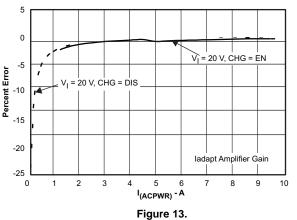
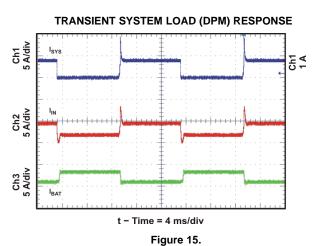


Figure 14.

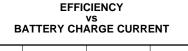


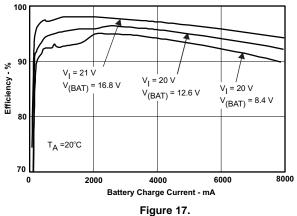
VIADAPT INPUT CURRENT SENSE AMPLIFIER ACCURACY



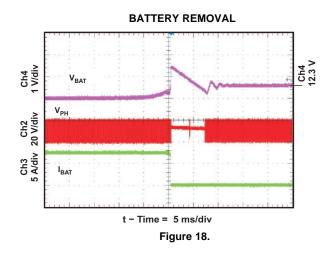


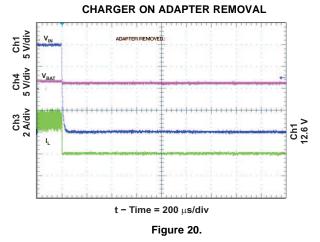












NONSYNCHRONOUS TO SYNCHRONOUS TRANSITION

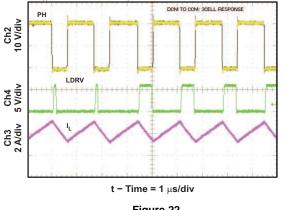


Figure 22.

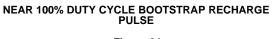
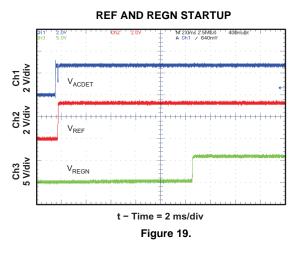
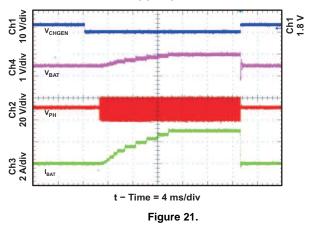


Figure 24.



CHARGE ENABLE / DISABLE AND CURRENT SOFT-START



SYNCHRONOUS TO NONSYNCHRONOUS TRANSITION

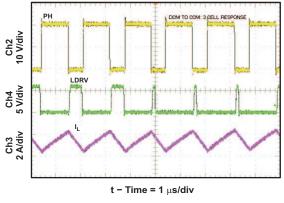
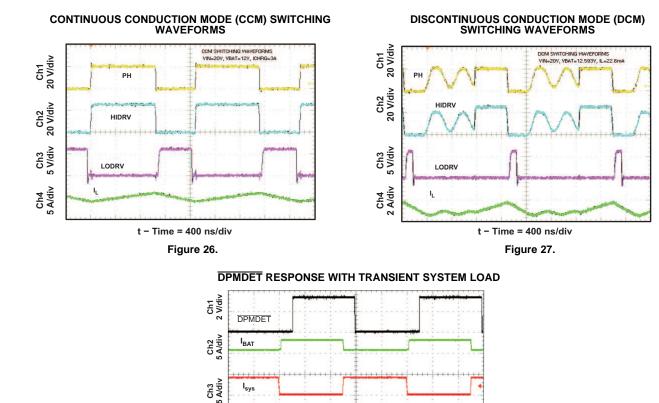


Figure 23.

BATTERY SHORTED CHARGER RESPONSE, OVERCURRENT PROTECTION (OCP) AND CHARGE CURRENT REGULATION

Figure 25.





t - Time = 20 ms/div Figure 28.

I<sub>sys</sub>

I<sub>IN</sub>

5 A/div

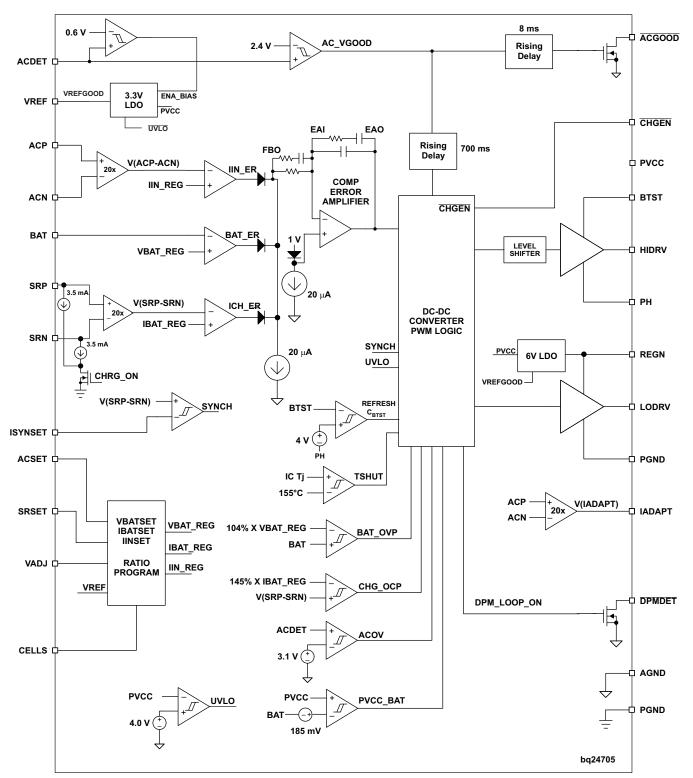
bq24705 SLUS779B-DECEMBER 2007-REVISED MARCH 2009

www.ti.com

INSTRUMENTS

Texas

#### FUNCTIONAL BLOCK DIAGRAM





### DETAILED DESCRIPTION

#### BATTERY VOLTAGE REGULATION

The bq24705 uses a high-accuracy voltage regulator for charging voltage. The internal default battery voltage setting  $V_{BATT}$ = 4.2 V × cell count. The regulation voltage is ratio-metric with respect to VREF. The ratio of VADJ and VREF provides extra 12.5% adjust range on  $V_{BATT}$  regulation voltage. By limiting the adjust range to 12.5% of the regulation voltage, the external resistor mismatch error is reduced from ±1% to ±0.1%. Therefore, an overall voltage accuracy as good as 0.5% is maintained, while using 1% mis-match resistors. Ratio-metric conversion also allows compatibility with D/As or microcontrollers ( $\mu$ C). The battery voltage is programmed through VADJ and VREF using Equation 1.

$V_{BAT}$ = cell count x	11/ +	0 512 v	V <sub>VADJ</sub>	
VBAT - Cell Count X		0.512 A	V <sub>REF</sub>	

(1)

VADJ is set between 0 and VREF. V<sub>BATT</sub> defaults to 4.2 V × cell count when VADJ is connected to REGN.

CELLS pin is the logic input for selecting cell count. Connect CELLS to charge 2,3, or 4 Li+ cells. When charging other cell chemistries, use CELLS to select an output voltage range for the charger.

CELLS	CELL COUNT
Float	2
AGND	3
VREF	4

The per-cell battery termination voltage is function of the battery chemistry. Consult the battery manufacturer to determine this voltage.

The BAT pin is used to sense the battery voltage for voltage regulation and should be connected as close to the battery as possible, or directly on the output capacitor. A  $0.1-\mu F$  ceramic capacitor from BAT to AGND is recommended to be as close to the BAT pin as possible to decouple high frequency noise.

#### BATTERY CURRENT REGULATION

The SRSET input sets the maximum charging current. Battery current is sensed by resistor  $R_{SR}$  connected between SRP and SRN. The full-scale differential voltage between SRP and SRN is 100 mV. Thus, for a 0.010  $\Omega$  sense resistor, the maximum charging current is 10 A. SRSET is ratio-metric with respect to VREF using Equation 2:

$$I_{CHARGE} = \frac{V_{SRSET}}{V_{REF}} \times \frac{0.10}{R_{SR}}$$

(2)

The input voltage range of SRSET is between 0 and VREF, up to 3.3 V.

The SRP and SRN pins are used to sense across  $R_{SR}$  with default value of 10 m $\Omega$ . However, resistors of other values can also be used. A larger the sense resistor, gives a larger sense voltage, and a higher regulation accuracy, but at the expense of higher conduction loss.

#### INPUT ADAPTER CURRENT REGULATION

The total input from an AC adapter or other DC sources is a function of the system supply current and the battery charging current. System current normally fluctuates as portions of the systems are powered up or down. Without Dynamic Power Management (DPM), the source must be able to supply the maximum system current and the maximum charger input current simultaneously. By using DPM, the input current regulator reduces the charging current when the input current exceeds the input current limit set by ACSET. The current capability of the AC adapter can be lowered, which may reduce the system cost.

Similar to setting battery regulation current, adapter current is sensed by resistor R<sub>AC</sub> connected between ACP and ACN. The maximum value is set by ACSET, which is a ratio-metric with respect to VREF, using Equation 3.

bq24705 SLUS779B-DECEMBER 2007-REVISED MARCH 2009

www.ti.com

(3)

$$I_{ADAPTER} = \frac{V_{ACSET}}{V_{REF}} \times \frac{0.10}{R_{AC}}$$

The input voltage range of ACSET is between 0 and VREF, up to 3.3 V.

The ACP and ACN pins are used to sense  $R_{AC}$  with default value of  $10m\Omega$ . However, resistors of other values can also be used. A larger the sense resistor, gives a larger sense voltage, and a higher regulation accuracy; but, at the expense of higher conduction loss.

### ADAPTER DETECT AND POWER UP

An external resistor voltage divider attenuates the adapter voltage before it goes to ACDET. The adapter detect threshold should typically be programmed to a value greater than the maximum battery voltage, and lower than the minimum allowed adapter voltage. The ACDET divider should be placed before the ACFET in order to sense the true adapter input voltage whether the ACFET is on or off.

If PVCC is below 4 V, the device is disabled.

If ACDET is below 0.6 V but PVCC is above 4 V, part of the bias is enabled, including a crude bandgap reference. IADAPT is disabled and pulled down to GND. The total quiescent current is less than 10  $\mu$ A.

Once ACDET rises above 0.6 V and PVCC is above 4 V, all the bias circuits are enabled. VREF goes to 3.3 V and REGN output goes to 6 V. IADAPT becomes valid to proportionally reflect the adapter current.

When ACDET rises and passes 2.4 V, a valid AC adapter is present. Then the following occurs:

- ACGOOD becomes high through external pull-up resistor to the host digital voltage rail;
- Charger turns on if all the conditions are satisfied (see *Enable and Disable Charging*).

### ENABLE AND DISABLE CHARGING

The following conditions must be valid before a charge is enabled:

- CHGEN is LOW;
- PVCC > UVLO;
- Adapter is detected;
- Adapter is higher than PVCC-BAT threshold;
- Adapter is not over voltage;
- 700 ms delay is complete after adapter detected;
- REGNGOOD and VREFGOOD are valid;
- Thermal Shut (TSHUT) is not valid;

One of the following conditions will stop on-going charging:

- CHGEN is HIGH;
- PVCC < UVLO;</li>
- Adapter is removed;
- Adapter is less than PVCC-BAT threshold;
- Adapter is over voltage;
- Adapter is over current;
- TSHUT IC temperature threshold is reached (155°C on rising-edge with 20°C hysteresis).

### AUTOMATIC INTERNAL SOFT-START CHARGER CURRENT

The charger automatically soft-starts the charger regulation current every time the charger is enabled to ensure there is no overshoot or stress on the output capacitors or the power converter. The soft-start consists of stepping-up the charge regulation current into 8 evenly divided steps up to the programmed charge current. Each step lasts around 1.7ms, for a typical rise time of 13.6ms. No external components are needed for this function.



#### **CONVERTER OPERATION**

The synchronous buck PWM converter uses a fixed frequency (600 kHz) voltage mode with feed-forward control scheme. A type III compensation network allows using ceramic capacitors at the output of the converter. The compensation input stage is connected internally between the feedback output (FBO) and the error amplifier input (EAI). The feedback compensation stage is connected between the error amplifier input (EAI) and error amplifier output (EAO). The LC output filter is selected to give a resonant frequency of 8–12.5 kHz nominal.

$$f_0 = \frac{1}{1}$$

Where resonant frequency,  $f_0$ , is given by:

 $\frac{1}{2\pi\sqrt{L_0C_0}}$  where (from Figure 2 schematic)

- $C_0 = C11 + C12$
- $L_0 = L1$

An internal saw-tooth ramp is compared to the internal EAO error control signal to vary the duty-cycle of the converter. The ramp height is one-fifteenth of the input adapter voltage making it always directly proportional to the input adapter voltage. This cancels out any loop gain variation due to a change in input voltage, and simplifies the loop compensation. The ramp is offset by 200 mV in order to allow zero percent duty-cycle, when the EAO signal is below the ramp. The EAO signal is also allowed to exceed the saw-tooth ramp signal in order to get a 100% duty-cycle PWM request. Internal gate drive logic allows achieving 99.98% duty-cycle while ensuring the N-channel upper device always has enough voltage to stay fully on. If the BTST pin to PH pin voltage falls below 4 V for more than 3 cycles, then the high-side n-channel power MOSFET is turned off and the low-side n-channel power MOSFET is turned on to pull the PH node down and recharge the BTST capacitor. Then the high-side driver returns to 100% duty-cycle operation until the (BTST-PH) voltage is detected to fall low again due to leakage current discharging the BTST capacitor below the 4 V, and the reset pulse is reissued.

The 600 kHz fixed frequency oscillator keeps tight control of the switching frequency under all conditions of input voltage, battery voltage, charge current, and temperature, simplifying output filter design and keeping it out of the audible noise region. The charge current sense resistor R<sub>SR</sub> should be placed with at least half or more of the total output capacitance placed before the sense resistor contacting both sense resistor and the output inductor; and the other half or remaining capacitance placed after the sense resistor. The output capacitance should be divided and placed onto both sides of the charge current sense resistor. A ratio of 50:50 percent gives the best performance; but the node in which the output inductor and sense resistor connect should have a minimum of 50% of the total capacitance. This capacitance provides sufficient filtering to remove the switching noise and give better current sense accuracy. The type III compensation provides phase boost near the cross-over frequency, giving sufficient phase margin.

### SYNCHRONOUS AND NON-SYNCHRONOUS OPERATION

The charger operates in non-synchronous mode when the sensed charge current is below the ISYNSET value. Otherwise, the charger operates in synchronous mode.

During synchronous mode, the low-side n-channel power MOSFET is on, when the high-side n-channel power MOSFET is off. The internal gate drive logic ensures there is break-before-make switching to prevent shoot-through currents. During the 30ns dead time where both FETs are off, the back-diode of the low-side power MOSFET conducts the inductor current. Having the low-side FET turn-on keeps the power dissipation low, and allows safely charging at high currents. During synchronous mode the inductor current is always flowing and operates in Continuous Conduction Mode (CCM), creating a fixed two-pole system.

During non-synchronous operation, after the high-side n-channel power MOSFET turns off, and after the break-before-make dead-time, the low-side n-channel power MOSFET will turn-on for around 80ns, then the low-side power MOSFET will turn-off and stay off until the beginning of the next cycle, where the high-side power MOSFET is turned on again. The 80ns low-side MOSFET on-time is required to ensure the bootstrap capacitor is always recharged and able to keep the high-side power MOSFET on during the next cycle. This is important for battery chargers, where unlike regular dc-dc converters, there is a battery load that maintains a voltage and can both source and sink current. The 80-ns low-side pulse pulls the PH node (connection between high and low-side MOSFET) down, allowing the bootstrap capacitor to recharge up to the REGN LDO value. After the 80 ns, the low-side MOSFET is kept off to prevent negative inductor current from occurring. The inductor current is blocked by the off low-side MOSFET, and the inductor current will become discontinuous. This mode is called Discontinuous Conduction Mode (DCM).

#### bq24705 SLUS779B-DECEMBER 2007-REVISED MARCH 2009



www.ti.com

(4)

During the DCM mode the loop response automatically changes and has a single pole system at which the pole is proportional to the load current, because the converter does not sink current, and only the load provides a current sink. This means at low currents the loop response is slower, as there is less sinking current available to discharge the output voltage. At low currents during non-synchronous operation, there may be a small amount of negative inductor current during the 80 ns recharge pulse. The charge should be low enough to be absorbed by the input capacitance.

When BTST – PH < 4 V, the 80-ns recharge pulse occurs on LODRV, the high-side MOSFET does not turn on. The low-side MOSFET does not turn on (only 80-ns recharge pulse).

### ISYNSET CONTROL (SYN AND NON-SYN MODE SETTING)

The ISYNSET pin is used to program the charge current threshold at which the charger changes from synchronous operation into non-synchronous operation. The low side driver turns on for only 80 ns to charge the boost capacitor. This is important to prevent negative inductor current, which may cause a boost effect in which the input voltage increases as power is transferred from the battery to the input capacitors. This boost effect can lead to an overvoltage on the PVCC node, and potentially cause some damage to the system. This programmable value allows setting the current threshold for any inductor current ripple, and avoiding negative inductor current. The minimum synchronous threshold should be set from 1/2 of the inductor current ripple to the full ripple current, where the inductor current ripple is given by:

$$\frac{I_{\text{RIPPLE}}MAX}{2} \leq I_{\text{SYN}} \leq I_{\text{RIPPLE}}MAX$$

and

$$\mathbf{I}_{\mathsf{RIPPLE}} = \frac{(\mathsf{V}_{\mathsf{IN}} - \mathsf{V}_{\mathsf{BAT}}) \times \frac{\mathsf{V}_{\mathsf{BAT}}}{\mathsf{V}_{\mathsf{IN}}} \times \frac{1}{\mathsf{f}_{\mathsf{S}}}}{\mathsf{L}} = \frac{\mathsf{V}_{\mathsf{IN}} \times (1 - \mathsf{D}) \times \mathsf{D} \times \frac{1}{\mathsf{f}_{\mathsf{S}}}}{\mathsf{L}}$$

where:

 $V_{IN} =$  adapter voltage  $V_{BAT} =$  BAT voltage  $f_{S} =$  switching frequency L = output inductor D = duty-cycle



(5)

I<sub>RIPPLE MAX</sub> happens when the duty-cycle, D is mostly near to 0.5 at given V<sub>in</sub>, f<sub>s</sub>,and L.

The ISYNSET comparator, or charge undercurrent comparator, compares the voltage between SRP-SRN, and the threshold set by an external resistor  $R_{ISYNSET}$ , which can be calculated by:

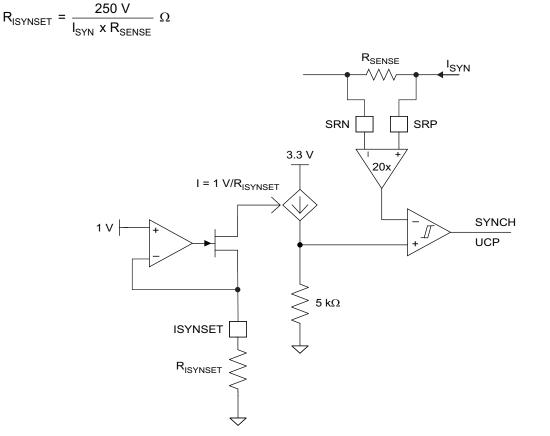


Figure 29. ISYNSET Comparator Block

### HIGH ACCURACY IADAPT USING CURRENT SENSE AMPLIFIER (CSA)

An industry standard, high accuracy current sense amplifier (CSA) is used to monitor the input current by the host or some discrete logic through the analog voltage output of the IADAPT pin. The CSA amplifies the input sensed voltage of ACP – ACN by 20x through the IADAPT pin. The IADAPT output is a voltage source 20 times the input differential voltage. Once PVCC is above 5 V and ACDET is above 0.6V, IADAPT no longer stays at ground, but becomes active. If the user wants to lower the voltage, they could use a resistor divider from IOUT to AGND, and still achieve accuracy over temperature as the resistors can be matched their thermal coefficients.

A 100-pF capacitor connected on the output is recommended for decoupling high-frequency noise. An additional RC filter is optional, after the 100-pF capacitor, if additional filtering is desired. Note that adding filtering also adds additional response delay.

### INPUT OVERVOLTAGE PROTECTION (ACOV)

ACOV provides protection to prevent system damage due to high input voltage. The controller enters ACOV when ACDET > 3.1 V and charge is disabled. ACOV is not latched—normal operation resumes when the ACDET voltage returns below 3.1 V. ACOV threshold is 130% of the adapter-detect threshold.

### INPUT UNDERVOLTAGE LOCK OUT (UVLO)

The system must have a minimum 4 V PVCC voltage to allow proper operation. This PVCC voltage could come from either input adapter or battery, using a diode-OR input. When the PVCC voltage is below 4 V the bias circuits REGN and VREF stay inactive, even with ACDET above 0.6 V.



### BATTERY OVERVOLTAGE PROTECTION

The converter stops switching when BAT voltage goes above 104% of the regulation voltage. The converter will not allow the high-side FET to turn on until the BAT voltage goes below 102% of the regulation voltage. This allows one-cycle response to an overvoltage condition, such as when the load is removed or the battery is disconnected. A 10-mA current sink from BAT to PGND is on only during charge, and allows discharging the stored output-inductor energy into the output capacitors.

#### CHARGE OVERCURRENT PROTECTION

The charger has a secondary overcurrent protection. It monitors the charge current, and prevents the current from exceeding 145% of regulated charge current. The high-side gate drive turns off when the overcurrent is detected, and automatically resumes when the current falls below the overcurrent threshold.

#### THERMAL SHUTDOWN PROTECTION

The QFN package has low thermal impedance, which provides good thermal conduction from the silicon to the ambient, to keep junctions temperatures low. As added level of protection, the charger converter turns off and self-protects whenever the junction temperature exceeds the TSHUT threshold of 155°C. The charger stays off until the junction temperature falls below 135°C.

#### Status Outputs (ACGOOD, DPMDET)

Two status outputs are available, and they require external pull up resistors to pull the pins to system digital rail for a high level.

ACGOOD open-drain output goes low if ACDET is above 2.4 V.

DPMDET open-drain output goes low when the DPM loop is active to reduce the battery charge current (after a 10-ms delay).



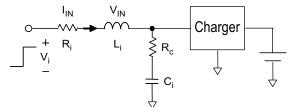
#### Table 2. Component List for Typical System Circuit of Figure 2

	OTV	DECODIDION					
PART DESIGNATOR	QTY	DESCRIPTION					
Q1, Q2, Q3	3	P-channel MOSFET, -30V,-6A, SO-8, Vishay-Siliconix, Si4435					
Q4, Q5	2	N-channel MOSFET, 30V, 12.5A, SO-8, Fairchild, FDS6680A					
D1, D2	2	Diode, Dual Schottky, 30V, 200mA, SOT23, Fairchild, BAT54C					
R <sub>AC</sub> , R <sub>SR</sub>	2	Sense Resistor, 10 m $\Omega$ , 1%, 1W, 2010, Vishay-Dale, WSL2010R0100F					
L1	1	Inductor, 4.7µH, Vishay-Dale, IHLP5050CE-01					
C6, C7, C11, C12	4	Capacitor, Ceramic, 10µF, 25V, 20%, X5R, 1206, Panasonic, ECJ-3YB1E106M					
C4, C10	2	Capacitor, Ceramic, 1µF, 25V, 10%, X7R, 2012, TDK, C2012X7R1E105K					
C2, C3, C8, C9, C13, C14, C15	7	Capacitor, Ceramic, 0.1µF, 50V, 10%, X7R, 0805, Kemet, C0805C104K5RACTU					
C5	1	Capacitor, Ceramic, 100pF, 25V, 10%, X7R, 0805, Kemet, C0805C101K5RACTU					
C1	1	Capacitor, Ceramic, 2.2µF, 25V, 10%, X7R, 2012, TDK, C2012X7R1E225K					
R3, R4	2	Resistor, Chip, 10 kΩ, 1/16W, 5%, 0402					
R1	1	Resistor, Chip, 432 kΩ, 1/16W, 1%, 0402					
R2	1	Resistor, Chip, 66.5 kΩ, 1/16W, 1%, 0402					
R10	1	Resistor, Chip, 2 Ω, 1W, 1%, 1210					
R6	1	Resistor, Chip, 30 kΩ, 1/16W, 1%, 0402					

#### **APPLICATION INFORMATION**

#### **Input Capacitance Calculation**

During the adapter hot plug-in, the ACFET has not been turned on. The AC switch is off and the simplified equivalent circuit of the input is shown in Figure 30.



- A. R<sub>i</sub>: Equivalent resistance of cable
- B. L<sub>i</sub>: Equivalent inductance of cable
- C. R<sub>C</sub> ESR of C<sub>i</sub>
- D. C<sub>i</sub>: Decoupling capacitor

#### Figure 30. Simplified Equivalent Circuit During Adapter Insertion

The voltage on the input capacitor(s) is given by:

$$V_{IN}(t) = I_{IN}(t) \times R_{C} + V_{Ci}(t) = V_{i} - V_{i}e^{\frac{R_{t}}{2L_{i}}t} \left[\frac{R_{i} - R_{C}}{\omega L_{i}} \sin\omega t + \cos\omega t\right]$$

$$V_{Ci}(t) = V_i - V_i e^{\frac{R_t}{2L_i}t} \left[\frac{R_t}{2\omega L_i} \sin\omega t + \cos\omega t\right]$$

$$R_{t} = R_{i} + R_{C} \quad \omega = \sqrt{\frac{I}{L_{i}C_{i}} - \left(\frac{R_{t}}{2L_{i}}\right)^{2}} \qquad \qquad I_{In}(t) = \frac{V_{i}}{\omega L_{i}} e^{\frac{R_{t}}{2L_{i}}t} \sin \omega t$$

(6)

SLUS779B-DECEMBER 2007-REVISED MARCH 2009

 $R_t = R_i + R_C > 2\sqrt{\frac{L_i}{C_i}}$ 

. Ci = 20 μF

bq24705

**Damping Conditions:** 

35



Copyright © 2007–2009, Texas Instruments Incorporated

Figure 31(a) demonstrates a highr C<sub>i</sub> which helps dampen the voltage spike. Figure 31(b) demonstrates the effect of the input stray inductance (L<sub>i</sub>) on the input voltage spike. The dashed curve in Figure 31(b) represents the worst case for C<sub>i</sub> = 40  $\mu$ F. Figure 31(c) shows how the resistance helps to suppress the input voltage spike.

35

Li = 5 μH

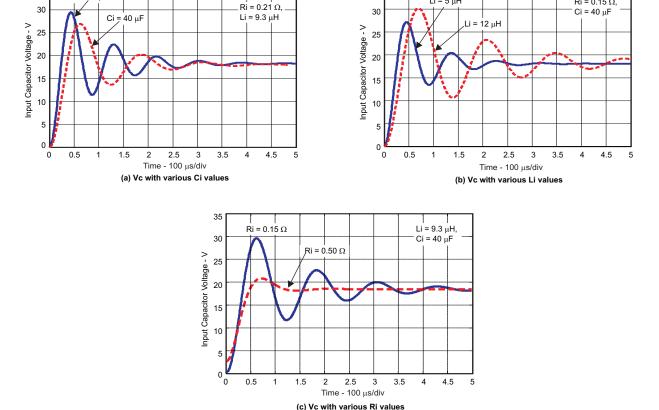


Figure 31. Parametric Study Of The Input Voltage

As shown in Figure 31, minimizing the input stray inductance, increasing the input capacitance, and adding resistance (including using higher ESR capacitors) helps supress the input voltage spike. However, a user often cannot control input srtay inductance, and increasing capacitance can increase costs. therefore, the most efficient and cost-effective approach is to add an external resistor.

Figure 32 depicts the recommended input filter design. The measured input voltage and current waveforms are shown in Figure 33. The input voltage spike has been well damped by adding a 2  $\Omega$  resistor, while keeping the capacitance low.

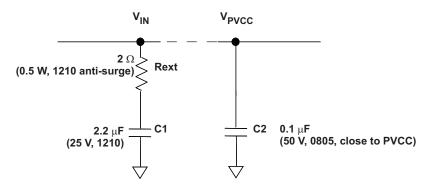


 $Ri = 0.15 \Omega$ ,

(7)

www.ti.com







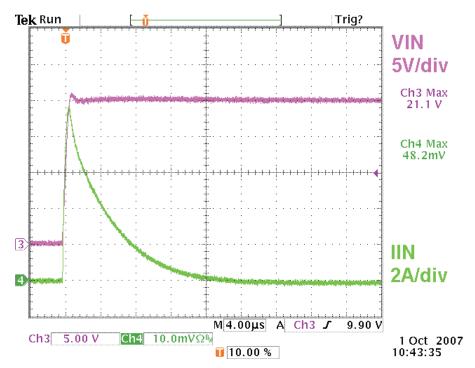


Figure 33. Adapter DC Side Hot Plug-In Test Waveforms

bq24705 SLUS779B-DECEMBER 2007-REVISED MARCH 2009

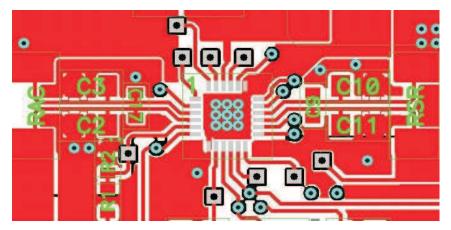


www.ti.com

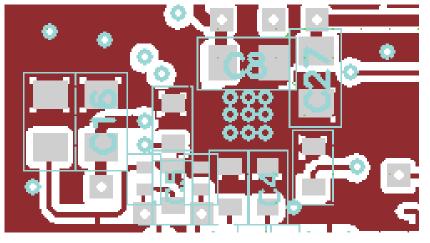
#### **PCB Layout Design Guideline**

- 1. It is critical that the exposed power pad on the backside of the IC package be soldered to the PCB ground. Ensure that there are sufficient thermal vias directly under the IC, connecting to the ground plane on the other layers.
- 2. The control stage and the power stage should be routed separately. At each layer, the signal ground and the power ground are connected only at the power pad.
- 3. The AC current-sense resistor must be connected to ACP (pin 4) and ACN (pin 3) with a Kelvin contact. The area of this loop must be minimized. An additional 0.1 μF decoupling capacitor for ACN is required to further reduce the noise. The decoupling capacitors for these pins should be placed as close to the IC as possible.
- 4. The charge-current sense resistor must be connected to SRP (pin 16), SRN (pin 15) with a Kelvin contact. The area of this loop must be minimized. An additional 0.1μF decoupling capacitor for SRN is required to further reduce the noise. The decoupling capacitors for these pins should be placed as close to the IC as possible.
- 5. Decoupling capacitors for PVCC (pin 1), VREF (pin 8), REGN (pin 21) should be placed underneath the IC (on the bottom layer) with the interconnections to the IC as short as possible.
- 6. Decoupling capacitors for BAT (pin 14), IADAPT (pin 12) must be placed close to the corresponding IC pins with the interconnections to the IC as short as possible.
- 7. Decoupling capacitor CX for the charger input must be placed close to the Q4 drain and Q5 source.

Figure 34 shows the recommended component placement with trace and via locations. For the QFN information, see the SCBA017 and SLUA271 documents.



(a) Top Layer



(b) Bottom Layer

Figure 34. Layout Example



### PACKAGING INFORMATION

Orderable Device	Status	Package Type	•	Pins	Package	Eco Plan	Lead finish/	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	Ball material	(3)		(4/5)	
							(6)				
BQ24705RGER	ACTIVE	VQFN	RGE	24	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	0 to 125	BQ	Samples
										24705	Samples
BQ24705RGERG4	ACTIVE	VQFN	RGE	24	3000	TBD	Call TI	Call TI	0 to 125		Samples
				_							Bumpies
BQ24705RGET	ACTIVE	VQFN	RGE	24	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	0 to 125	BQ	Samples
										24705	Samples
HPA00753RGER	ACTIVE	VQFN	RGE	24	3000	TBD	Call TI	Call TI	0 to 125		Samplas
											Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and



continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# PACKAGE MATERIALS INFORMATION

www.ti.com

Texas Instruments

### TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ24705RGER	VQFN	RGE	24	3000	330.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2
BQ24705RGET	VQFN	RGE	24	250	180.0	12.4	4.25	4.25	1.15	8.0	12.0	Q2

TEXAS INSTRUMENTS

www.ti.com

# PACKAGE MATERIALS INFORMATION

26-Jan-2013



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ24705RGER	VQFN	RGE	24	3000	367.0	367.0	35.0
BQ24705RGET	VQFN	RGE	24	250	210.0	185.0	35.0

## **GENERIC PACKAGE VIEW**

# VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



# **RGE0024B**



# **PACKAGE OUTLINE**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M. 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



# **RGE0024B**

# **EXAMPLE BOARD LAYOUT**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



 This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



# **RGE0024B**

# **EXAMPLE STENCIL DESIGN**

## VQFN - 1 mm max height

PLASTIC QUAD FLATPACK - NO LEAD



6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



### IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2022, Texas Instruments Incorporated