

Channel Tuning Made Easy Using Linear Redrivers

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ABSTRACT

This report demonstrates the benefits of using Texas Instruments Linear Redrivers to simplify the process of channel tuning and improve system margins. Test results of the [DS125BR820](#) linear redriver operating in various pre-channel and post-channel conditions are presented and show improvements in channel conditions in terms of transmitter pre- and post-cursor error-free operating region. This allows link training to more easily find an optimal operating point that is more robust against system variations. These results are applicable to other Linear Redriver devices in TI's signal conditioning portfolio, including [DS125BR111](#), [DS125BR401A](#), and [DS80PCI810](#).

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1 Introduction

The testing carried out in this report involves the [DS125BR820](#) Low-Power 12.5 Gbps 8-Channel Linear Redriver, which is designed to support 40GbE (40G-CR4/KR4/SR4/LR4), 10GbE (10G-KR, SFF-8431), 12G SAS-3, PCIe Gen 3.0, and other applications up to 12.5Gbps. The linear nature of the [DS125BR820](#)'s equalization allows the [DS125BR820](#) to preserve the transmit signal characteristics of the host ASIC, thereby allowing the host and the link partner ASIC to negotiate transmit equalizer coefficients during Link Training. These results are applicable to other Linear Redriver devices in TI's signal conditioning portfolio, including [DS125BR111](#), [DS125BR401A](#), and [DS80PCI810](#).

2 Pre-Channel and Post-Channel Performance Test

This test was conducted by varying the length of channel segments at the input and output of the [DS125BR820](#), known as pre-channel and post-channel respectively. For each pre- and post-channel configuration, the transmitter pre- and post-cursor settings were swept, and the number of bit errors was recorded for 97 seconds (> 1E12 bits). In addition, baseline tests were conducted without the [DS125BR820](#) Linear Redriver for different lengths of channel. The goal of this test was to compare the system's region of error-free operation for a given total channel length with and without the [DS125BR820](#).

2.1 Test Setup – Hardware

The ASIC transmitter output is connected to a trace board (pre-channel) and then to the input of the [DS125BR820EVM](#). The output of the [DS125BR820EVM](#) is connected to another trace board (post-channel) followed by the ASIC receiver. In the no-redriver test case, the [DS125BR820EVM](#) is removed and replaced with two female-to-female SMA connectors, leaving only PCB trace between the transmitter and receiver. A diagram of the test setup with the redriver is shown in [Figure 1](#). A diagram of the equivalent no-redriver test case is shown in [Figure 2](#).

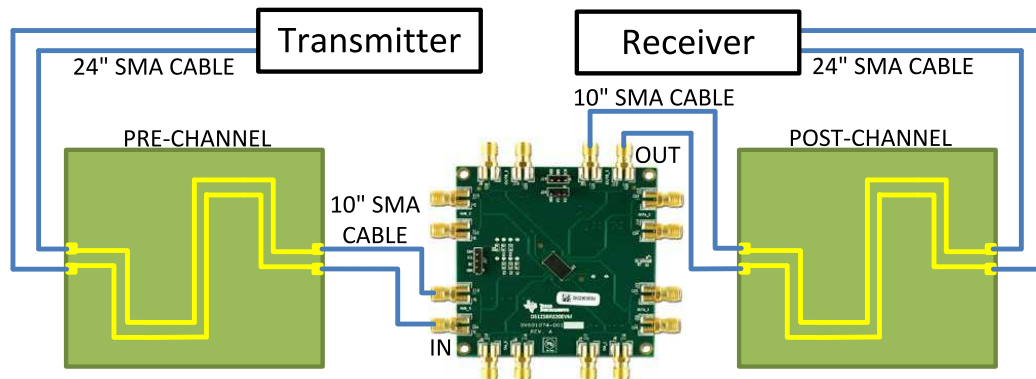


Figure 1. Test Setup with DS125BR820EVM

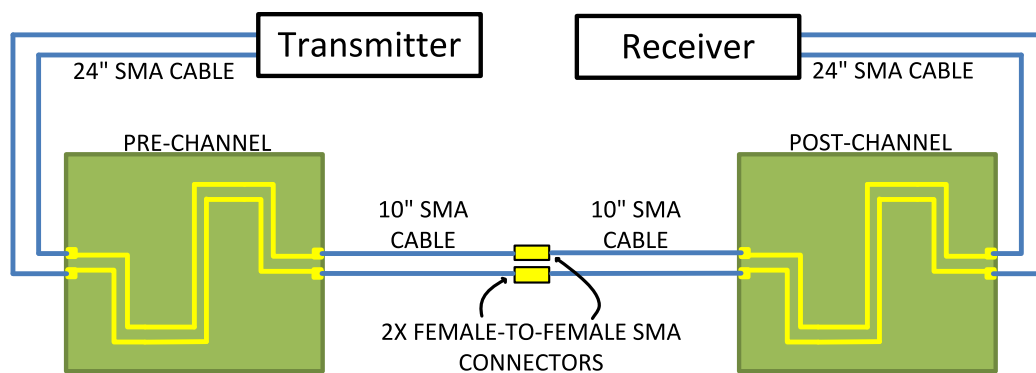


Figure 2. Test Setup without Redriver

2.1.1 DS125BR820EVM

The [DS125BR820EVM](#) SMA evaluation kit provides a complete platform to evaluate the signal conditioning features of the Texas Instruments [DS125BR820](#) redriver. The [DS125BR820EVM](#) can be used for standards compliance testing, performance evaluation, and system prototyping. The equalization settings (EQ) and output differential amplitude (VOD) can be adjusted by strapping control pins to the proper logic levels, or register programming through SMBus serial interface.

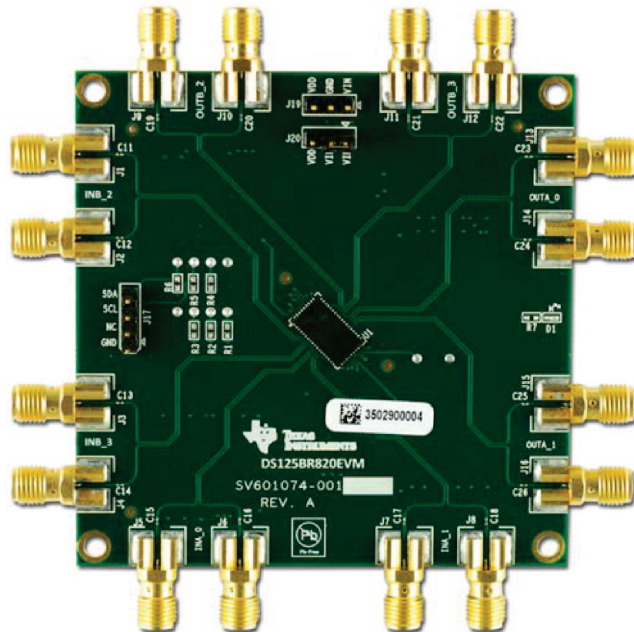


Figure 3. DS125BR820EVM Top Side

2.1.2 ASIC Transmitter

A generic, commercially-available transmitter was used as the source of the 10.3125 Gbps and 12.5 Gbps PRBS31 data in this test. The differential output amplitude was configured to be 780 mV peak-to-peak. A frequency offset of ~210 ppm was introduced between the transmitter and receiver. The transmitter sweeps pre-cursor values from -3.1 dB to 0 dB (-15% to 0%) and post-cursor from -10.5 dB to 0 dB (-35% to 0%).

2.1.3 ASIC Receiver

A generic, commercially-available receiver was used to check the PRBS31 data for bit errors. This receiver has a continuous-time linear equalizer (CTLE) with up to 14 dB of equalization capability as well as a five-tap decision feedback equalizer (DFE). Both the CTLE and DFE are automatically adapted in real time to optimize the post-equalized eye height.

2.1.4 FR4 Microstrip Trace Boards

Various FR4 differential microstrip trace boards are used to mimic pre- and post-channel conditions of a real system. These boards vary in length from 5 to 40 inches (4 mil trace width) in steps of 5 inches.

2.2 Test Setup – Device Configuration

The settings used for the [DS125BR820](#) Redriver in these tests are listed in Table 1. Lower EQ settings may be more suitable for shorter channel lengths.

Table 1. DS125BR820 Settings Used for Testing

EQ SETTING			VOD SETTING		
Value	Pin Strap	Equivalent Register Setting ⁽¹⁾	Value	Pin Strap	Equivalent Register Setting ⁽²⁾
Level 3	1 (1 kΩ to VIH ⁽³⁾)	Reg_0xF = 0x03	Level 6	VODA1 = VODB1 = 1 (1 kΩ to VIH ⁽³⁾) VODA1 = VODB1 = 0 (1 kΩ to GND)	Reg_0x10 = 0xAE

⁽¹⁾ Each channel has its own EQ control register. Reg_0x0F controls channel 0. Reg_0x16 controls channel 1, and so on.

⁽²⁾ Each channel has its own VOD control register. Reg_0x10 controls channel 0. Reg_0x17 controls channel 1, and so on.

⁽³⁾ VIH is nominally 2.5 V when the device is in 2.5-V Mode, or 3.3 V when the device is in 3.3-V Mode. For more details, see the electrical characteristics table of the device datasheet.

2.3 Results

The measurements are plotted in a matrix where the x-axis is the post-cursor value in decibels and the y-axis is the pre-cursor value in decibels applied by the ASIC TX. The total error count during the 97 second test is shown in each point and is color coded to represent the total error range. Green means there were zero errors, and red represents the maximum number of the error counter, 4,095. Some examples can be seen in [Figure 6](#) through [Figure 11](#). For all of the data with various channel configurations, see [Appendix A](#) and [Appendix B](#).

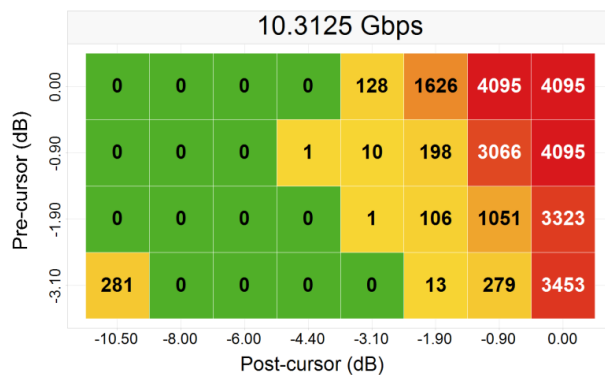


Figure 4. 40" (-33.9 dB) Channel No-Redriver

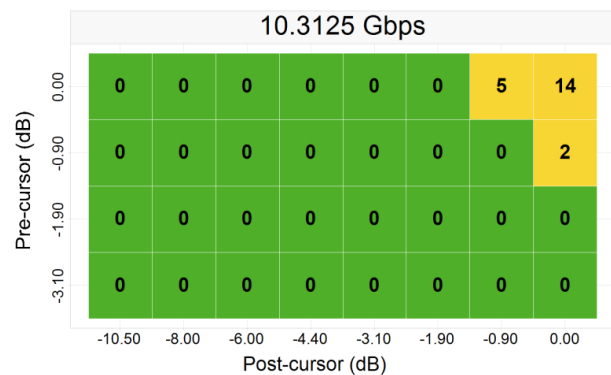


Figure 5. 5" (-5.7 dB) Pre- and 35" (-31.9 dB) Post-channel with Redriver

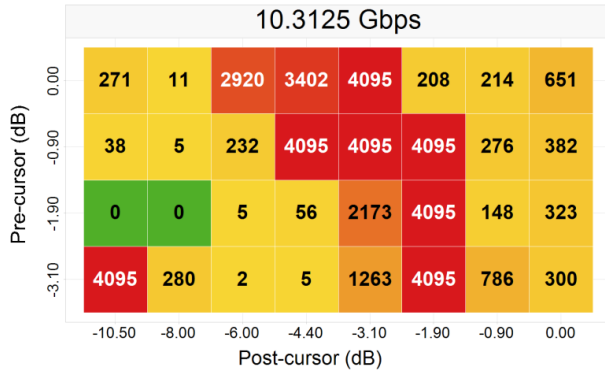


Figure 6. 45" (-38.2 dB) Channel No-Redriver

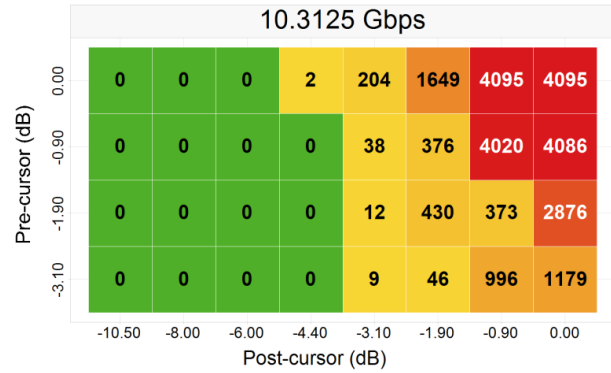


Figure 7. 5" (-5.7 dB) Pre- and 40" (-35.3 dB) Post-channel with Redriver

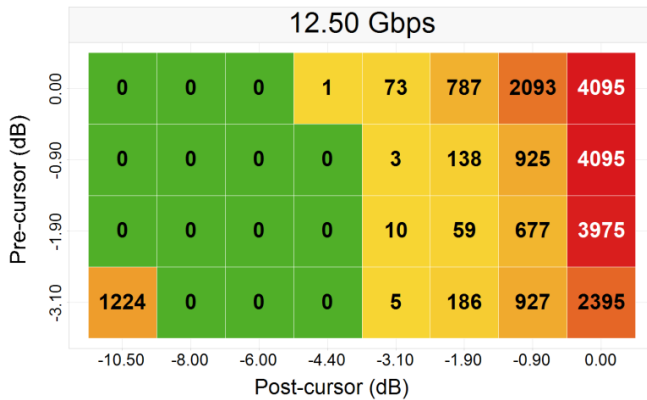


Figure 8. 30" (-31.2 dB) Channel No-Redriver

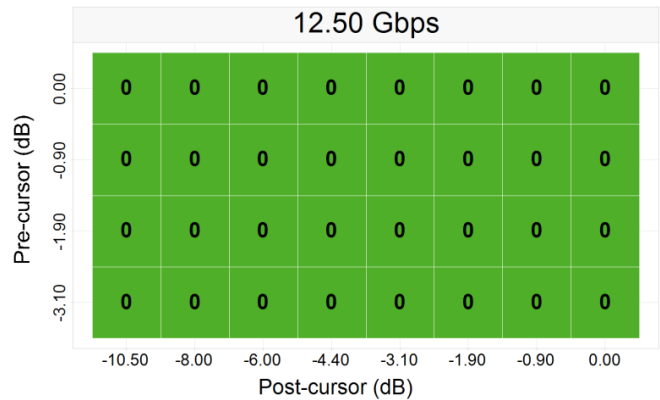


Figure 9. 5" (-6.8 dB) Pre- and 25" (-27 dB) Post-channel with Redriver

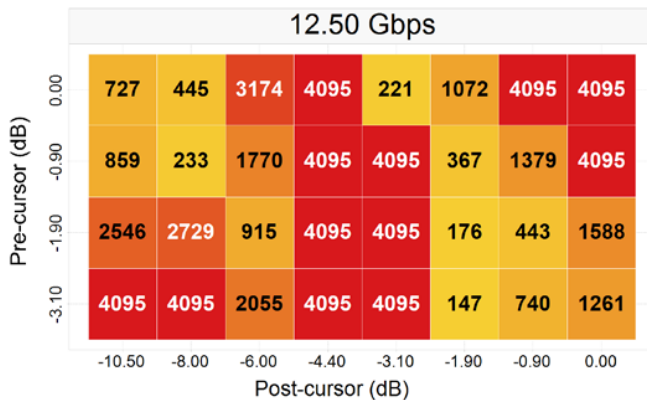


Figure 10. 35" (-36 dB) Channel No-Redriver

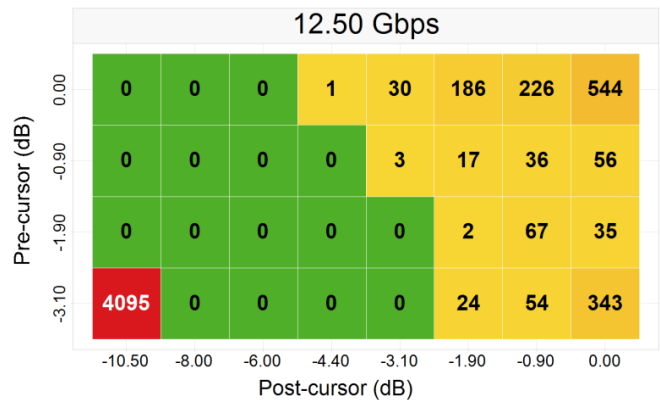


Figure 11. 10" (-11.9 dB) Pre- and 25" (-27 dB) Post-channel with Redriver

NOTE: In addition to comparing the performance of with-redriver and no-redriver cases for similar total channel lengths, no-redriver tests with a given channel length were compared to with-redriver tests with a longer channel length for the purposes of demonstrating channel reach extension. This is shown in [Figure 12](#) and [Figure 13](#) (35" against 45" at 10.3125 Gbps), and [Figure 14](#) and [Figure 15](#) (30" against 35" at 12.5 Gbps).

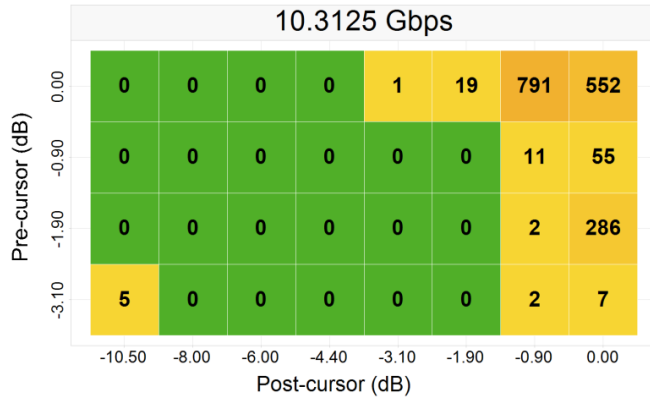


Figure 12. 35" (-30.5 dB) Channel No-Redriver

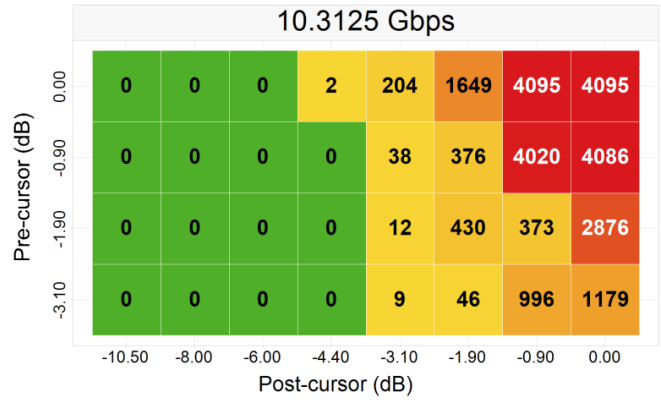


Figure 13. 5" (-5.7 dB) Pre- and 40" (-35.3 dB) Post-channel with Redriver

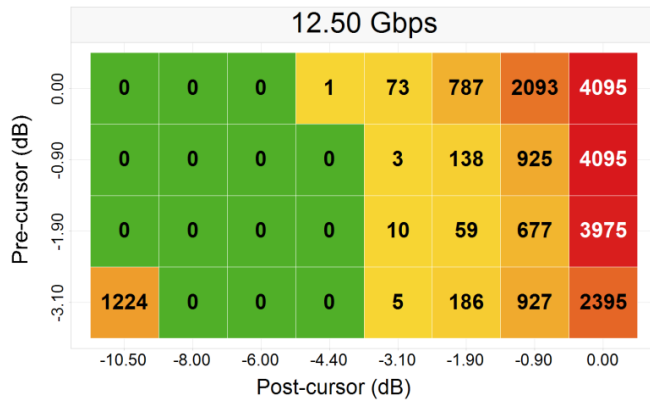


Figure 14. 30" (-31.2 dB) Channel No-Redriver

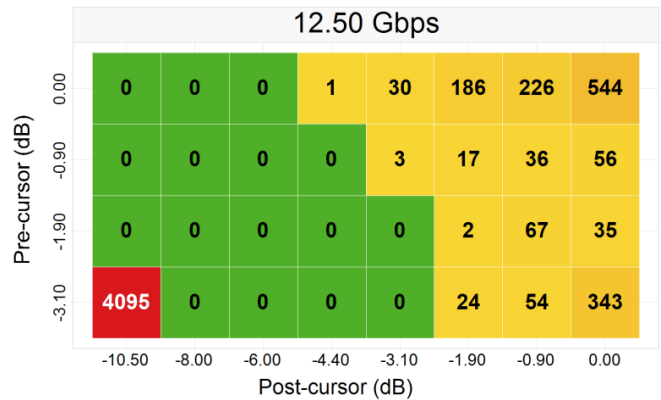


Figure 15. 10" (-11.9 dB) Pre- and 25" (-27 dB) Post-channel with Redriver

3 Conclusions

The [DS125BR820](#) Linear Redriver shows a clear improvement in the size of the error-free region for a given channel length, as shown in [Figure 4](#) through [Figure 11](#). This increase in system margin is a great advantage because link training happens very quickly and the resulting operating point may not be optimal due to normal run-to-run variations. Having a larger error-free operating region is helpful to ensure best chances of link training finding an error-free operating point. Having a larger error-free region is also beneficial because the system characteristics may change over time due to ambient temperature changes or voltage supply fluctuations.

Furthermore, [Figure 12](#) through [Figure 15](#) shows it is possible to extend the overall channel reach of the system by utilizing TI's linear redrivers. At both 10.3125 Gbps and 12.5 Gbps, similar system margins were obtained with up to 10 dB additional insertion loss as a result of using the [DS125BR820](#) Linear Redriver.

TI's Linear Redrivers add system flexibility thereby relaxing the requirements for the ASIC and simplifying the process of channel tuning. This can provide advantages in overall system cost, power consumption, and time to market.

10.3125 Gbps Error Count Matrices

The following figures show a comparison between the error count matrices for the with and without redriver cases for 10.3125 Gbps. Note that 4,095 is the maximum number of errors and the loss in decibels includes the trace losses of the EVM and all other parts of the test fixture.

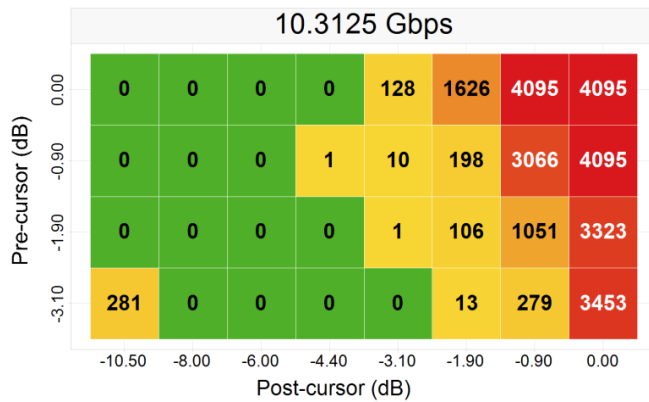


Figure 16. 40" (-33.9 dB) Channel No-Redriver

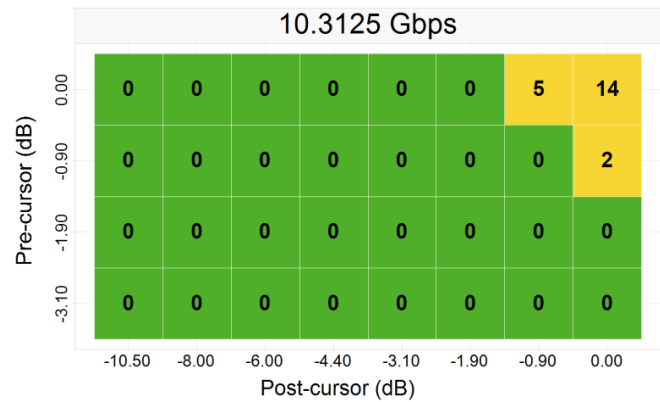


Figure 17. 5" (-5.7 dB) Pre- and 35" (-31.9 dB) Post-channel with Redriver

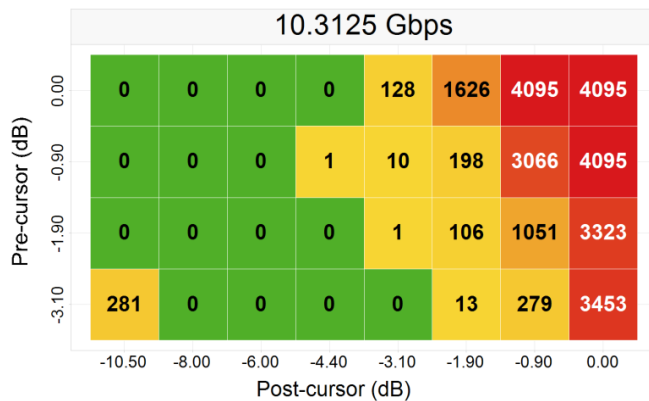


Figure 18. 40" (-33.9 dB) Channel No-Redriver

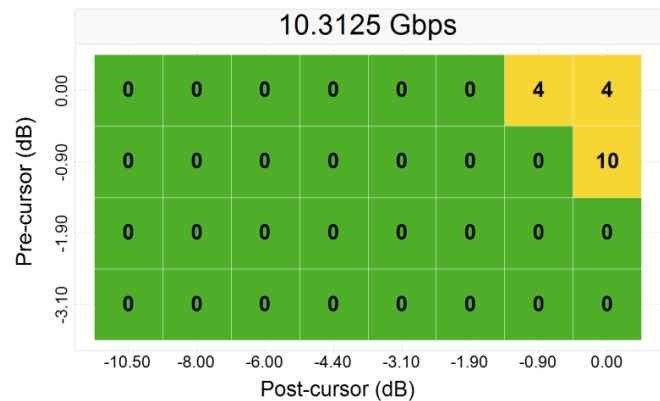


Figure 19. 15" (-14.5 dB) Pre- and 25" (-22.9 dB) Post-channel with Redriver

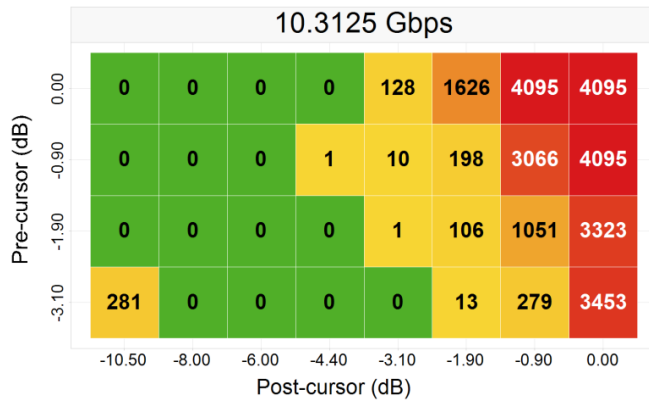


Figure 20. 40" (-33.9 dB) Channel No-Redriver

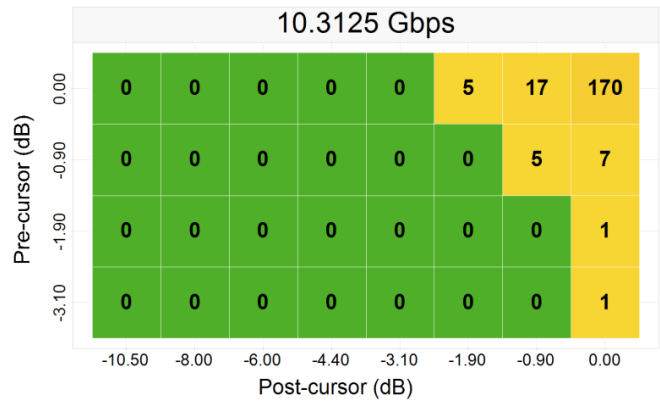


Figure 21. 25" (-22.9 dB) Pre- and 15" (-14.5 dB) Post-channel with Redriver

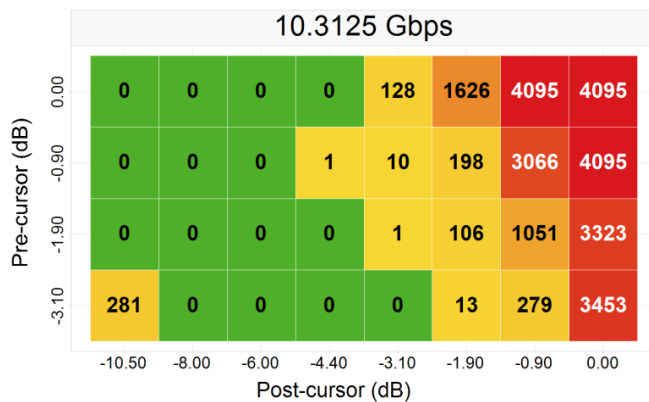


Figure 22. 40" (-33.9 dB) Channel No-Redriver

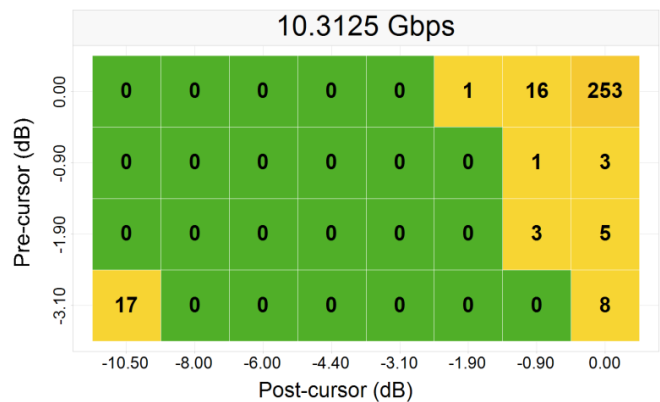


Figure 23. 35" (-31.9 dB) Pre- and 5" (-5.7 dB) Post-channel with Redriver

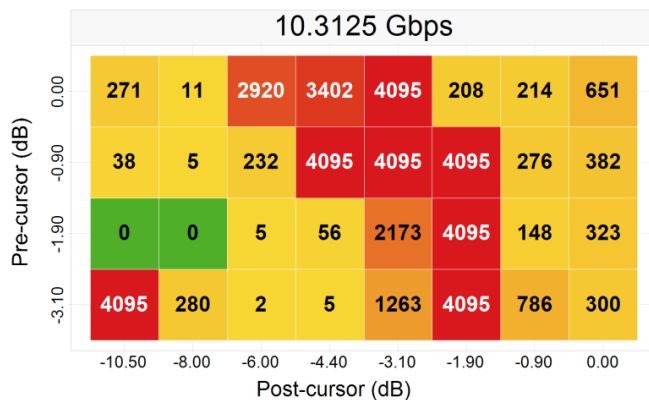


Figure 24. 45" (-38.2 dB) Channel No-Redriver

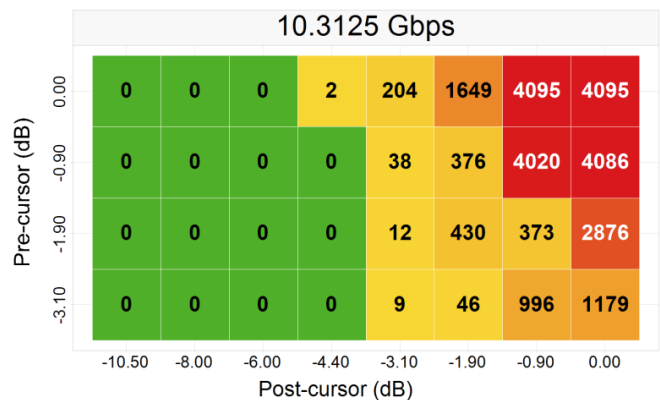


Figure 25. 5" (-5.7 dB) Pre- and 40" (-35.3 dB) Post-channel with Redriver

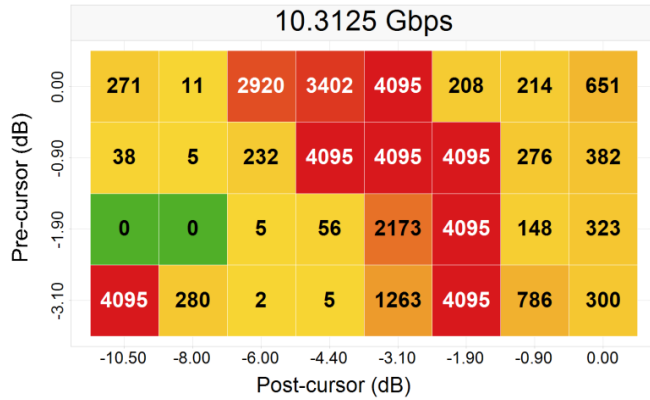


Figure 26. 45" (-38.2 dB) Channel No-Redriver

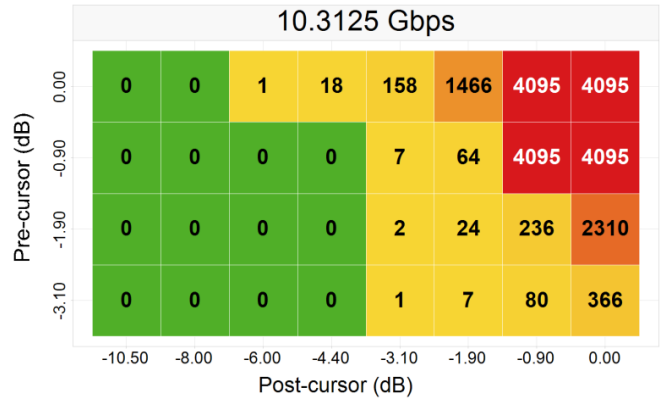


Figure 27. 15" (-14.5 dB) Pre- and 30" (-27.9 dB) Post-channel with Redriver

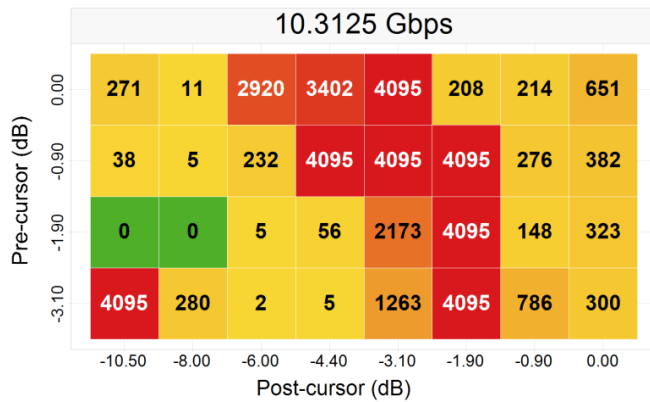


Figure 28. 45" (-38.2 dB) Channel No-Redriver

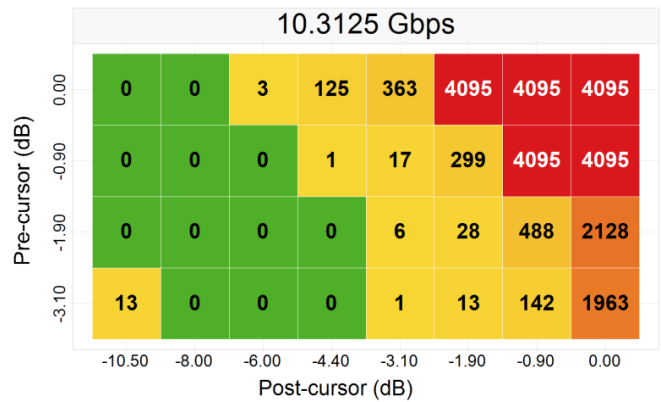


Figure 29. 30" (-27.9 dB) Pre- and 15" (-14.5 dB) Post-channel with Redriver

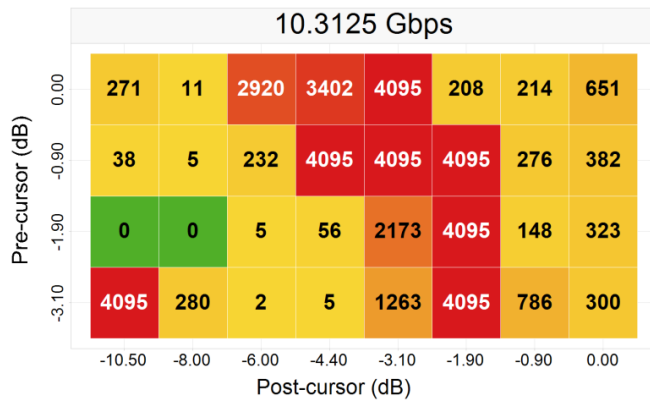


Figure 30. 45" (-38.2 dB) Channel No-Redriver

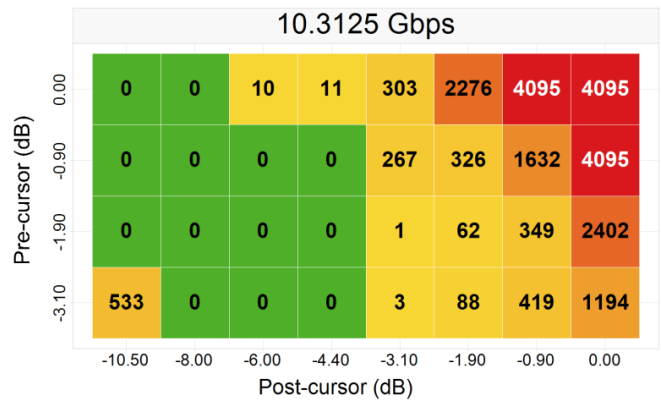


Figure 31. 40" (-35.3 dB) Pre- and 5" (-5.7 dB) Post-channel with Redriver

12.5 Gbps Error Count Matrices

The following figures show a comparison between the error count matrices for the with and without redriver cases for 12.5 Gbps. Note that 4,095 is the maximum number of errors and the loss in decibels includes the trace losses of the EVM and all other parts of the test fixture.

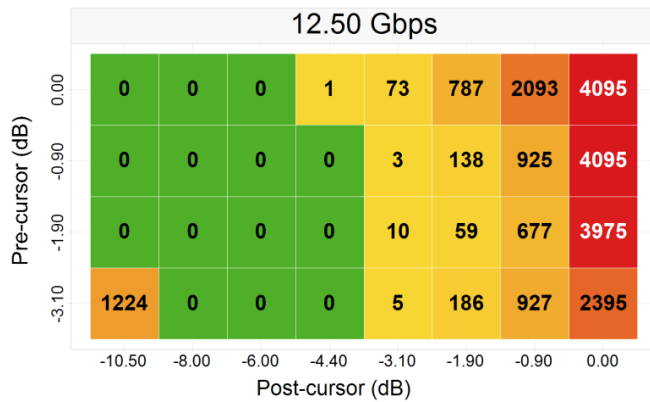


Figure 32. 30" (-31.2 dB) Channel No-Redriver

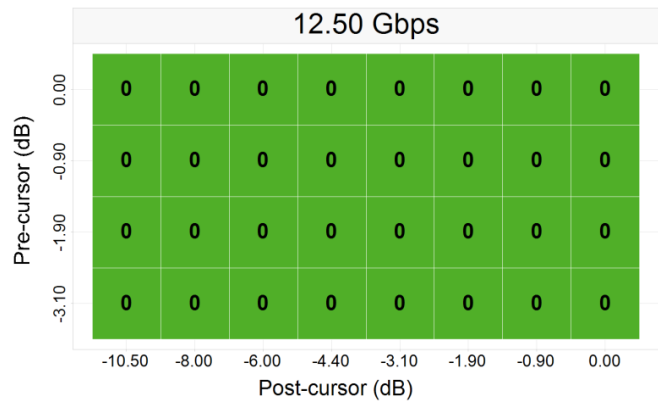


Figure 33. 5" (-6.8 dB) Pre- and 25" (-27 dB) Post-channel with Redriver

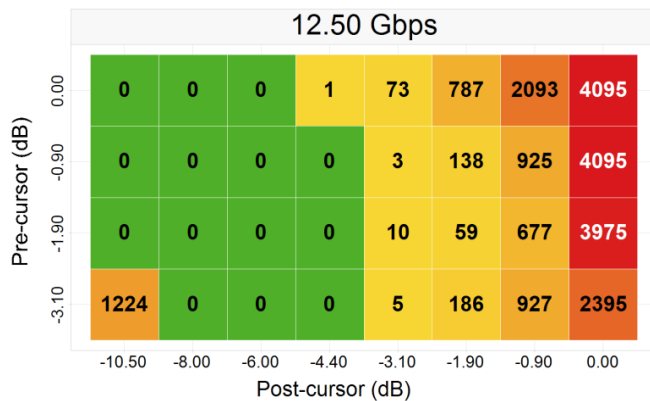


Figure 34. 30" (-31.2 dB) Channel No-Redriver

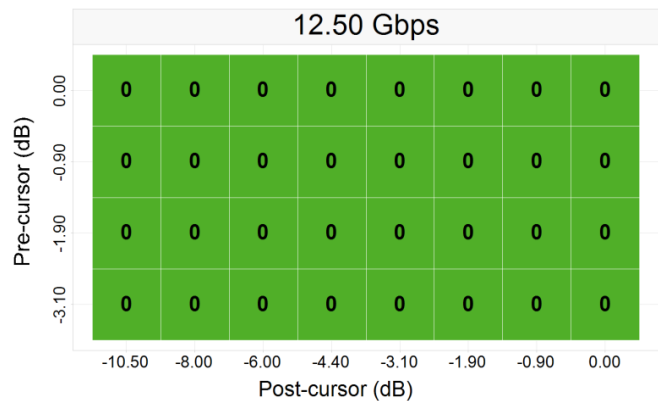


Figure 35. 10" (-11.9 dB) Pre- and 20" (-22.1 dB) Post-channel with Redriver

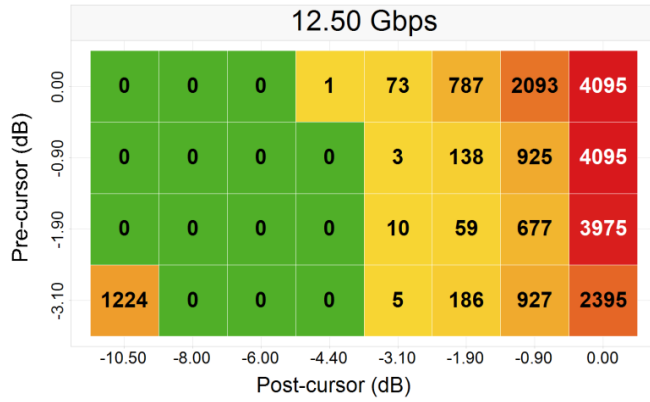


Figure 36. 30" (-31.2 dB) Channel No-Redriver

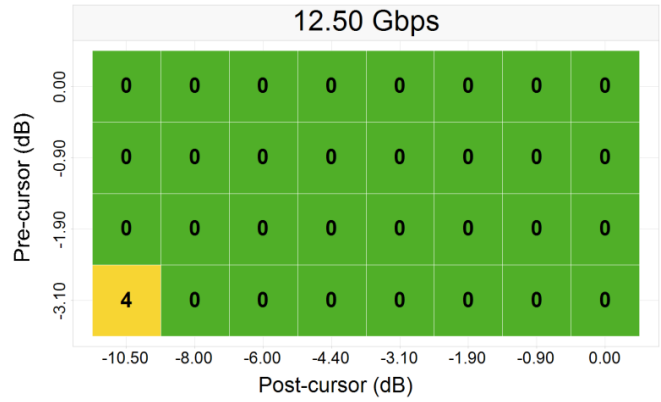


Figure 37. 20" (-22.1 dB) Pre- and 10" (-11.9 dB) Post-channel with Redriver

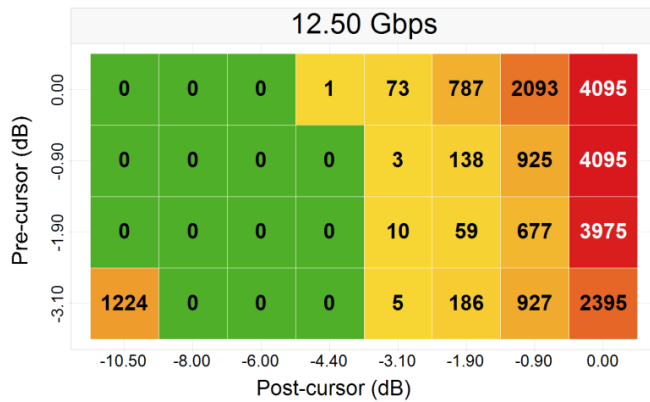


Figure 38. 30" (-31.2 dB) Channel No-Redriver

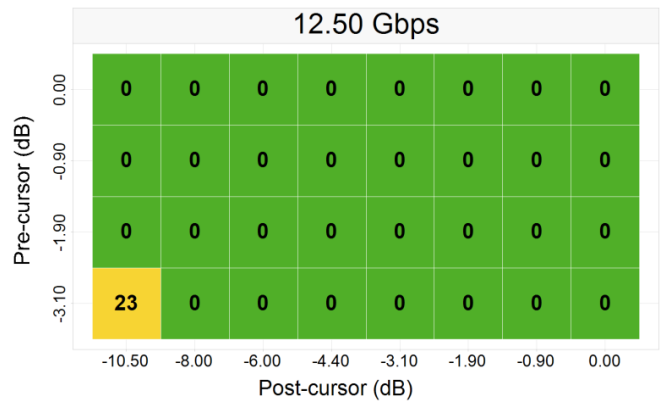


Figure 39. 25" (-27 dB) Pre- and 5" (-6.8 dB) Post-channel with Redriver

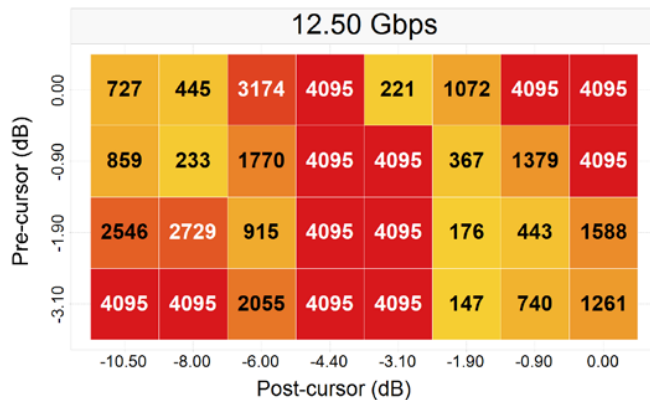


Figure 40. 35" (-36 dB) Channel No-Redriver

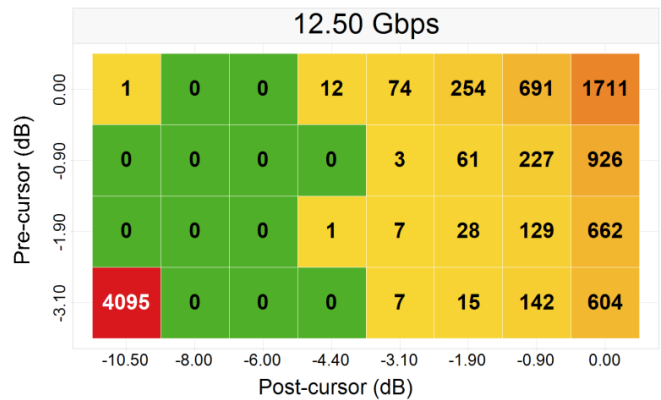


Figure 41. 5" (-6.8 dB) Pre- and 30" (-32.9 dB) Post-channel with Redriver

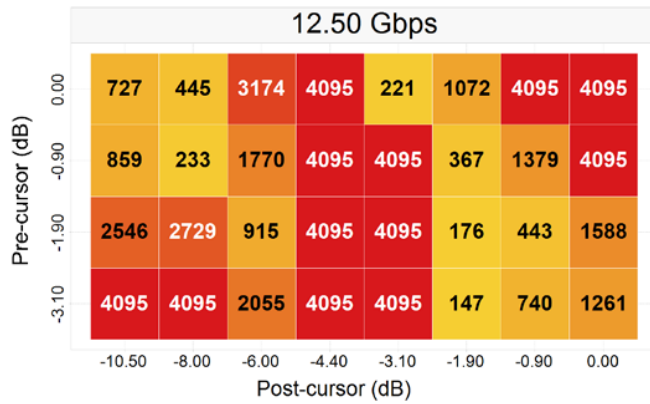


Figure 42. 35" (-36 dB) Channel No-Redriver

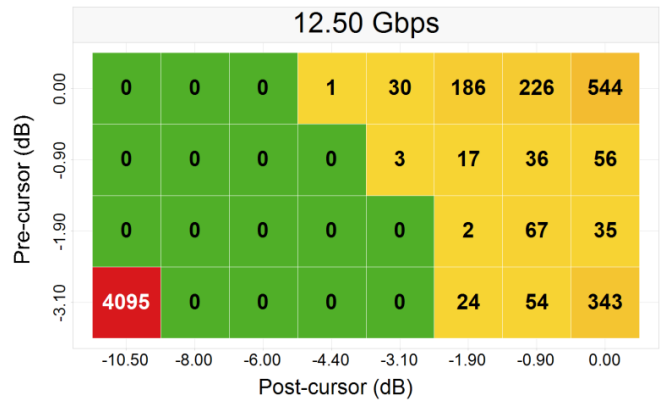


Figure 43. 10" (-11.9 dB) Pre- and 25" (-27 dB) Post-channel with Redriver

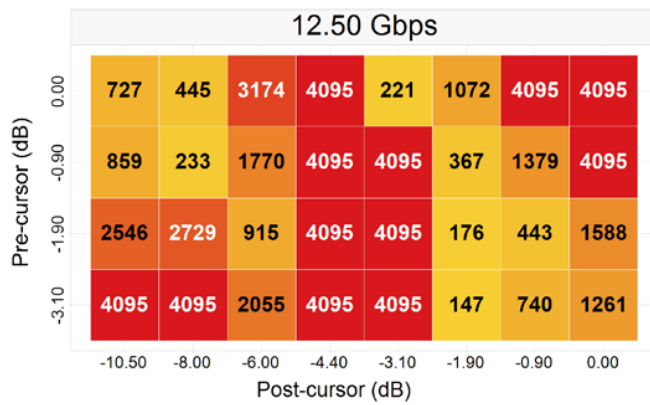


Figure 44. 35" (-36 dB) Channel No-Redriver

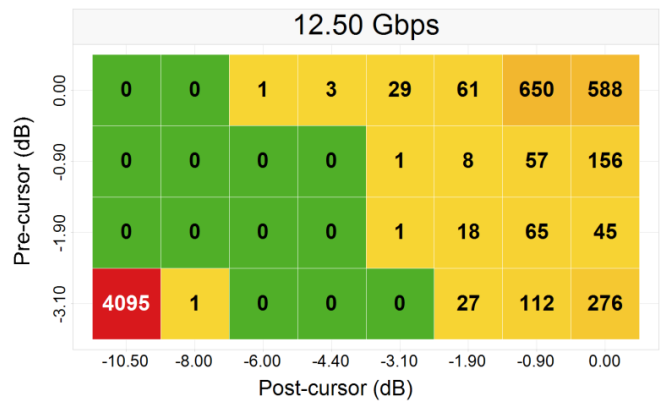


Figure 45. 25" (-27 dB) Pre- and 10" (-11.9 dB) Post-channel with Redriver

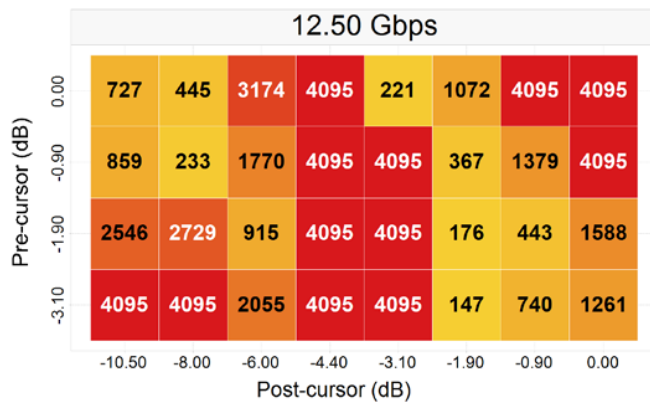


Figure 46. 35" (-36 dB) Channel No-Redriver

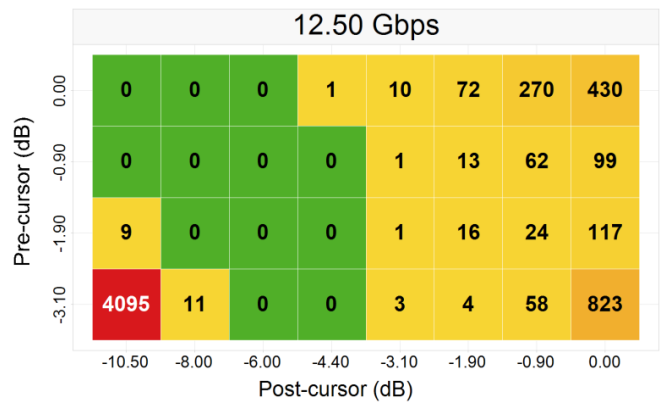


Figure 47. 30" (-32.9 dB) Pre- and 5" (-6.8 dB) Post-channel with Redriver

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 - 2.3 If any EVM fails to conform to the warranty set forth above, TI's sole liability shall be at its option to repair or replace such EVM, or credit User's account for such EVM. TI's liability under this warranty shall be limited to EVMs that are returned during the warranty period to the address designated by TI and that are determined by TI not to conform to such warranty. If TI elects to repair or replace such EVM, TI shall have a reasonable time to repair such EVM or provide replacements. Repaired EVMs shall be warranted for the remainder of the original warranty period. Replaced EVMs shall be warranted for a new full ninety (90) day warranty period.
3. *Regulatory Notices:*
 - 3.1 *United States*
 - 3.1.1 *Notice applicable to EVMs not FCC-Approved:*

This kit is designed to allow product developers to evaluate electronic components, circuitry, or software associated with the kit to determine whether to incorporate such items in a finished product and software developers to write software applications for use with the end product. This kit is not a finished product and when assembled may not be resold or otherwise marketed unless all required FCC equipment authorizations are first obtained. Operation is subject to the condition that this product not cause harmful interference to licensed radio stations and that this product accept harmful interference. Unless the assembled kit is designed to operate under part 15, part 18 or part 95 of this chapter, the operator of the kit must operate under the authority of an FCC license holder or must secure an experimental authorization under part 5 of this chapter.
 - 3.1.2 *For EVMs annotated as FCC – FEDERAL COMMUNICATIONS COMMISSION Part 15 Compliant:*

CAUTION

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

FCC Interference Statement for Class A EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

FCC Interference Statement for Class B EVM devices

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

3.2 Canada

3.2.1 For EVMs issued with an Industry Canada Certificate of Conformance to RSS-210

Concerning EVMs Including Radio Transmitters:

This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Concernant les EVMs avec appareils radio:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Concerning EVMs Including Detachable Antennas:

Under Industry Canada regulations, this radio transmitter may only operate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication. This radio transmitter has been approved by Industry Canada to operate with the antenna types listed in the user guide with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

Concernant les EVMs avec antennes détachables

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée équivalente (p.i.r.e.) ne dépasse pas l'intensité nécessaire à l'établissement d'une communication satisfaisante. Le présent émetteur radio a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés dans le manuel d'usage et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

3.3 Japan

3.3.1 *Notice for EVMs delivered in Japan:* Please see http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_01.page 日本国内に輸入される評価用キット、ボードについては、次のところをご覧ください。
http://www.tij.co.jp/lstds/ti_ja/general/eStore/notice_01.page

3.3.2 *Notice for Users of EVMs Considered "Radio Frequency Products" in Japan:* EVMs entering Japan may not be certified by TI as conforming to Technical Regulations of Radio Law of Japan.

If User uses EVMs in Japan, not certified to Technical Regulations of Radio Law of Japan, User is required by Radio Law of Japan to follow the instructions below with respect to EVMs:

1. Use EVMs in a shielded room or any other test facility as defined in the notification #173 issued by Ministry of Internal Affairs and Communications on March 28, 2006, based on Sub-section 1.1 of Article 6 of the Ministry's Rule for Enforcement of Radio Law of Japan,
2. Use EVMs only after User obtains the license of Test Radio Station as provided in Radio Law of Japan with respect to EVMs, or
3. Use of EVMs only after User obtains the Technical Regulations Conformity Certification as provided in Radio Law of Japan with respect to EVMs. Also, do not transfer EVMs, unless User gives the same notice above to the transferee. Please note that if User does not follow the instructions above, User will be subject to penalties of Radio Law of Japan.

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4 *EVM Use Restrictions and Warnings:*

4.1 EVMS ARE NOT FOR USE IN FUNCTIONAL SAFETY AND/OR SAFETY CRITICAL EVALUATIONS, INCLUDING BUT NOT LIMITED TO EVALUATIONS OF LIFE SUPPORT APPLICATIONS.

4.2 User must read and apply the user guide and other available documentation provided by TI regarding the EVM prior to handling or using the EVM, including without limitation any warning or restriction notices. The notices contain important safety information related to, for example, temperatures and voltages.

4.3 *Safety-Related Warnings and Restrictions:*

4.3.1 User shall operate the EVM within TI's recommended specifications and environmental considerations stated in the user guide, other available documentation provided by TI, and any other applicable requirements and employ reasonable and customary safeguards. Exceeding the specified performance ratings and specifications (including but not limited to input and output voltage, current, power, and environmental ranges) for the EVM may cause personal injury or death, or property damage. If there are questions concerning performance ratings and specifications, User should contact a TI field representative prior to connecting interface electronics including input power and intended loads. Any loads applied outside of the specified output range may also result in unintended and/or inaccurate operation and/or possible permanent damage to the EVM and/or interface electronics. Please consult the EVM user guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative. During normal operation, even with the inputs and outputs kept within the specified allowable ranges, some circuit components may have elevated case temperatures. These components include but are not limited to linear regulators, switching transistors, pass transistors, current sense resistors, and heat sinks, which can be identified using the information in the associated documentation. When working with the EVM, please be aware that the EVM may become very warm.

4.3.2 EVMs are intended solely for use by technically qualified, professional electronics experts who are familiar with the dangers and application risks associated with handling electrical mechanical components, systems, and subsystems. User assumes all responsibility and liability for proper and safe handling and use of the EVM by User or its employees, affiliates, contractors or designees. User assumes all responsibility and liability to ensure that any interfaces (electronic and/or mechanical) between the EVM and any human body are designed with suitable isolation and means to safely limit accessible leakage currents to minimize the risk of electrical shock hazard. User assumes all responsibility and liability for any improper or unsafe handling or use of the EVM by User or its employees, affiliates, contractors or designees.

4.4 User assumes all responsibility and liability to determine whether the EVM is subject to any applicable international, federal, state, or local laws and regulations related to User's handling and use of the EVM and, if applicable, User assumes all responsibility and liability for compliance in all respects with such laws and regulations. User assumes all responsibility and liability for proper disposal and recycling of the EVM consistent with all applicable international, federal, state, and local requirements.

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