

Errata  
**MSP430F5254 Microcontroller**



**ABSTRACT**

This document describes the known exceptions to the functional specifications (advisories).

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## 1 Functional Advisories

Advisories that affect the device's operation, function, or parametrics.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
COMP10	✓
CPU47	✓
DMA4	✓
DMA7	✓
DMA10	✓
PMAP1	✓
PMM9	✓
PMM11	✓
PMM12	✓
PMM14	✓
PMM15	✓
PMM18	✓
PMM20	✓
PORT15	✓
PORT19	✓
RTC3	✓
RTC6	✓
SYS16	✓
TB25	✓
UCS7	✓
UCS9	✓
UCS11	✓
USCI26	✓
USCI34	✓
USCI35	✓
USCI39	✓
USCI40	✓

## 2 Preprogrammed Software Advisories

Advisories that affect factory-programmed software.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
BSL7	✓

## 3 Debug Only Advisories

Advisories that affect only debug operation.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
EEM17	✓

Errata Number	Rev B
<a href="#">EEM19</a>	✓
<a href="#">EEM21</a>	✓
<a href="#">EEM23</a>	✓
<a href="#">JTAG26</a>	✓
<a href="#">JTAG27</a>	✓

## 4 Fixed by Compiler Advisories

Advisories that are resolved by compiler workaround. Refer to each advisory for the IDE and compiler versions with a workaround.

✓ The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev B
<a href="#">CPU21</a>	✓
<a href="#">CPU22</a>	✓
<a href="#">CPU40</a>	✓

Refer to the following MSP430 compiler documentation for more details about the CPU bugs workarounds.

### TI MSP430 Compiler Tools (Code Composer Studio IDE)

- [MSP430 Optimizing C/C++ Compiler](#): Check the `--silicon_errata` option
- [MSP430 Assembly Language Tools](#)

### MSP430 GNU Compiler (MSP430-GCC)

- [MSP430 GCC Options](#): Check `-msilicon-errata=` and `-msilicon-errata-warn=` options
- [MSP430 GCC User's Guide](#)

### IAR Embedded Workbench

- [IAR workarounds for msp430 hardware issues](#)

## 5 Nomenclature, Package Symbolization, and Revision Identification

The revision of the device can be identified by the revision letter on the [Package Markings](#) or by the [HW\\_ID](#) located inside the TLV structure of the device.

### 5.1 Device Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all MSP MCU devices. Each MSP MCU commercial family member has one of two prefixes: MSP or XMS. These prefixes represent evolutionary stages of product development from engineering prototypes (XMS) through fully qualified production devices (MSP).

**XMS** – Experimental device that is not necessarily representative of the final device's electrical specifications

**MSP** – Fully qualified production device

Support tool naming prefixes:

**X**: Development-support product that has not yet completed Texas Instruments internal qualification testing.

**null**: Fully-qualified development-support product.

XMS devices and X development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

MSP devices have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

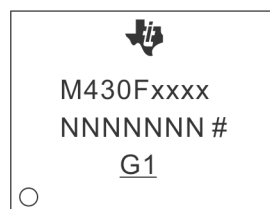
Predictions show that prototype devices (XMS) have a greater failure rate than the standard production devices. TI recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

TI device nomenclature also includes a suffix with the device family name. This suffix indicates the temperature range, package type, and distribution format.

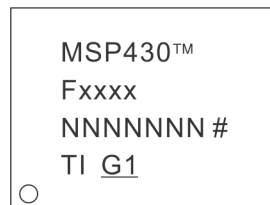
### 5.2 Package Markings

#### ZQE80

#### *BGA (ZQE), 80 pin*



# = Die revision  
○ = Pin 1 location  
N = Lot trace code

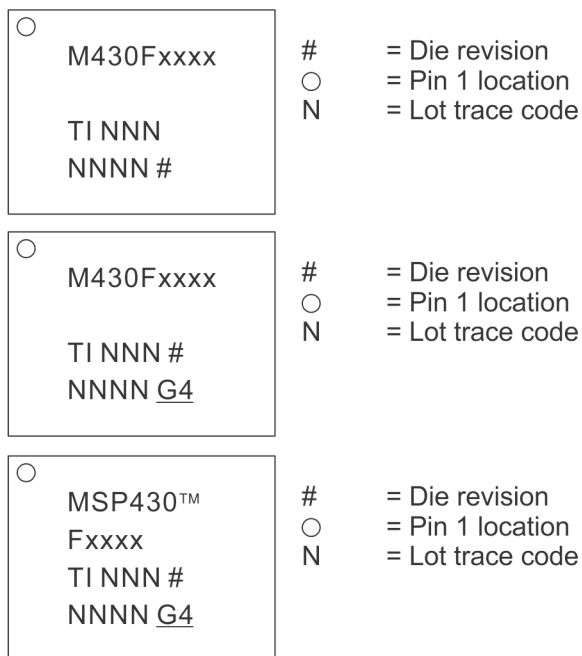


# = Die revision  
○ = Pin 1 location  
N = Lot trace code

NOTE: Package marking with "TM" applies only to devices released after 2011.

#### RGC64

#### *QFN (RGC), 64 pin*



NOTE: Package marking with "TM" applies only to devices released after 2011.

### 5.3 Memory-Mapped Hardware Revision (TLV Structure)

Die Revision	TLV Hardware Revision
Rev B	20h

Further guidance on how to locate the TLV structure and read out the HW\_ID can be found in the device User's Guide.

## 6 Advisory Descriptions

<b>BSL7</b>	<b><i>BSL Module</i></b>
<b>Category</b>	Software in ROM
<b>Function</b>	BSL does not start after waking up from LPMx.5
<b>Description</b>	When waking up from LPMx.5 mode, the BSL does not start as it does not clear the Lock I/O bit (LOCKLPM5 bit in PM5CTL0 register) on start-up.
<b>Workaround</b>	<ol style="list-style-type: none"> <li>1. Upgrade the device BSL to the latest version (see Creating a Custom Flash-Based Bootstrap Loader (BSL) Application Note - SLAA450 for more details)</li> </ol> OR <ol style="list-style-type: none"> <li>2. Do not use LOCKLPM5 bit (LPMx.5) if the BSL is used but cannot be upgraded.</li> </ol>
<b>COMP10</b>	<b><i>COMP Module</i></b>
<b>Category</b>	Functional
<b>Function</b>	Comparator port output toggles when entering or leaving LPM3/LPM4
<b>Description</b>	<p>The comparator port pin output (CECTL1.CEOUT) erroneously toggles when device enters or leaves LPM3/LPM4 modes under the following conditions:</p> <ol style="list-style-type: none"> <li>1) Comparator is disabled (CECTL1.CEON = 0)</li> </ol> AND <ol style="list-style-type: none"> <li>2) Output polarity is enabled (CECTL1.CEOUTPOL = 1)</li> </ol> AND <ol style="list-style-type: none"> <li>3) The port pin is configured to have CEOUT functionality.</li> </ol> <p>For example, if the CEOUT pin is high when the device is in Active Mode, CEOUT pin becomes low when the device enters LPM3/LPM4 modes.</p>
<b>Workaround</b>	<p>When the comparator is disabled, ensure at least one of the following:</p> <ol style="list-style-type: none"> <li>1) Output inversion is disabled (CECTL.CEOUTPOL = 0)</li> </ol> OR <ol style="list-style-type: none"> <li>2) Change pin configuration from CEOUT to GPIO with output low.</li> </ol>
<b>CPU21</b>	<b><i>CPU Module</i></b>
<b>Category</b>	Compiler-Fixed
<b>Function</b>	Using POPM instruction on Status register may result in device hang up
<b>Description</b>	When an active interrupt service request is pending and the POPM instruction is used to set the Status Register (SR) and initiate entry into a low power mode, the device may hang up.

**Workaround** None. It is recommended not to use POPM instruction on the Status Register.

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	Not affected	
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below. --silicon_errata=CPU21
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

**CPU22**

**CPU Module**

**Category**

Compiler-Fixed

**Function**

Indirect addressing mode with the Program Counter as the source register may produce unexpected results

**Description**

When using the indirect addressing mode in an instruction with the Program Counter (PC) as the source operand, the instruction that follows immediately does not get executed. For example in the code below, the ADD instruction does not get executed.

```
mov @PC, R7
add #1h, R4
```

**Workaround**

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	Not affected	
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below. --silicon_errata=CPU22
MSP430 GNU Compiler (MSP430-GCC)	MSP430-GCC 4.9 build 167 or later	

**CPU40**

**CPU Module**

**Category**

Compiler-Fixed

**Function**

PC is corrupted when executing jump/conditional jump instruction that is followed by instruction with PC as destination register or a data section

**Description**

If the value at the memory location immediately following a jump/conditional jump instruction is 0X40h or 0X50h (where X = don't care), which could either be an instruction opcode (for instructions like RRCM, RRAM, RLAM, RRUM) with PC as destination register or a data section (const data in flash memory or data variable in RAM), then the PC value is auto-incremented by 2 after the jump instruction is executed; therefore, branching to a wrong address location in code and leading to wrong program execution.

For example, a conditional jump instruction followed by data section (0140h).

```
@0x8012 Loop DEC.W R6
@0x8014 DEC.W R7
@0x8016 JNZ Loop
@0x8018 Value1 DW 0140h
```

**Workaround**

In assembly, insert a NOP between the jump/conditional jump instruction and program code with instruction that contains PC as destination register or the data section.

Refer to the table below for compiler-specific fix implementation information.

IDE/Compiler	Version Number	Notes
IAR Embedded Workbench	IAR EW430 v5.51 or later	For the command line version add the following information Compiler: --hw_workaround=CPU40 Assembler:-v1
TI MSP430 Compiler Tools (Code Composer Studio)	v4.0.x or later	User is required to add the compiler or assembler flag option below. --silicon_errata=CPU40
MSP430 GNU Compiler (MSP430-GCC)	Not affected	

**CPU47****CPU Module****Category**

Functional

**Function**

An unexpected Vacant Memory Access Flag (VMAIFG) can be triggered

**Description**

An unexpected Vacant Memory Access Flag (VMAIFG) can be triggered, if a PC-modifying instruction (e.g. - ret, push, call, pop, jmp, br) is fetched from the last addresses (last 4 or 8 byte) of a memory (e.g.- FLASH, RAM, FRAM) that is not contiguous to a higher, valid section on the memory map.  
In debug mode using breakpoints the last 8 bytes are affected.  
In free running mode the last 4 bytes are affected.

**Workaround**

Edit the linker command file to make the last 4 or 8 bytes of affected memory sections unavailable, to avoid PC-modifying instructions on these locations.  
Remaining instructions or data can still be stored on these locations.

**DMA4****DMA Module****Category**

Functional

**Function**

Corrupted write access to 20-bit DMA registers

**Description**

When a 20-bit wide write to a DMA address register (DMAxSA or DMAxDA) is interrupted by a DMA transfer, the register contents may be unpredictable.

**Workaround**

1. Design the application to guarantee that no DMA access interrupts 20-bit wide accesses to the DMA address registers.

OR

2. When accessing the DMA address registers, enable the Read Modify Write disable bit



(DMARMWDIS = 1) or temporarily disable all active DMA channels (DMAEN = 0).

OR

3. Use word access for accessing the DMA address registers. Note that this limits the values that can be written to the address registers to 16-bit values (lower 64K of Flash).

## **DMA7**

### ***DMA Module***

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#### **Category**

Functional

#### **Function**

DMA request may cause the loss of interrupts

#### **Description**

If a DMA request starts executing during the time when a module register containing an interrupt flags is accessed with a read-modify-write instruction, a newly arriving interrupt from the same module can get lost. An interrupt flag set prior to DMA execution would not be affected and remain set.

#### **Workaround**

1. Use a read of Interrupt Vector registers to clear interrupt flags and do not use read-modify-write instruction.

OR

2. Disable all DMA channels during read-modify-write instruction of specific module registers containing interrupts flags while these interrupts are activated.

## **DMA10**

### ***DMA Module***

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#### **Category**

Functional

#### **Function**

DMA access may cause invalid module operation

#### **Description**

The peripheral modules MPY, CRC, USB, RF1A and FRAM controller in manual mode can stall the CPU by issuing wait states while in operation. If a DMA access to the module occurs while that module is issuing a wait state, the module may exhibit undefined behavior.

#### **Workaround**

Ensure that DMA accesses to the affected modules occur only when the modules are not in operation. For example with the MPY module, ensure that the MPY operation is completed before triggering a DMA access to the MPY module.

## **EEM17**

### ***EEM Module***

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#### **Category**

Debug

#### **Function**

Wrong Breakpoint halt after executing Flash Erase/Write instructions

#### **Description**

Hardware breakpoints or Conditional Address triggered breakpoints on instructions that follow Flash Erase/Write instructions, stops the debugger at the actual Flash Erase/Write instruction even though the flash erase/write operation has already been executed. The hardware/conditional address triggered breakpoints that are placed on either the next two single opcode instructions OR the next double opcode instruction that follows the Flash Erase/Write instruction are affected by this erratum.

#### **Workaround**

None. Use other conditional/advanced triggered breakpoints to halt the debugger right after Flash erase/write instructions.

**Note**

This erratum affects debug mode only.

**EEM19*****EEM Module*****Category**

Debug

**Function**

DMA may corrupt data in debug mode

**Description**

When the DMA is enabled and the device is in debug mode, the data written by the DMA may be corrupted when a breakpoint is hit or when the debug session is halted.

**Workaround**

This erratum has been addressed in MSPDebugStack version 3.5.0.1. It is also available in released IDE EW430 IAR version 6.30.3 and CCS version 6.1.1 or newer. If using an earlier version of either IDE or MSPDebugStack, do not halt or use breakpoints during a DMA transfer.

**Note**

This erratum applies to debug mode only.

**EEM21*****EEM Module*****Category**

Debug

**Function**

LPMx.5 debug limitations

**Description**

Debugging the device in LPMx.5 mode might wake the device up from LPMx.5 mode inadvertently, and it is possible that the device enters a lock-up condition; that is, the device cannot be accessed by the debugger any more.

**Workaround**

Follow the debugging steps in Debugging MSP430 LPM4.5 [SLAA424](#) .

**EEM23*****EEM Module*****Category**

Debug

**Function**

EEM triggers incorrectly when modules using wait states are enabled

**Description**

When modules using wait states (USB, MPY, CRC and FRAM controller in manual mode) are enabled, the EEM may trigger incorrectly. This can lead to an incorrect profile counter value or cause issues with the EEMs data watch point, state storage, and breakpoint functionality.

**Workaround**

None.

**Note**

This erratum affects debug mode only.

**JTAG26*****JTAG Module*****Category**

Debug

**Function**

LPMx.5 Debug Support Limitations

**Description** The JTAG connection to the device might fail at device-dependent low or high supply voltage levels if the LPMx.5 debug support feature is enabled. To avoid a potentially unreliable debug session or general issues with JTAG device connectivity and the resulting bad customer experience Texas Instruments has chosen to remove the LPMx.5 debug support feature from common MSP430 IDEs including TIs Code Composer Studio 6.1.0 with msp430.emu updated to version 6.1.0.7 and IARs Embedded Workbench 6.30.2, which are based on the MSP430 debug stack MSP430.DLL 3.5.0.1 <http://www.ti.com/tool/MSPDS>

TI plans to re-introduce this feature in limited capacity in a future release of the debug stack by providing an IDE override option for customers to selectively re-activate LPMx.5 debug support if needed. Note that the limitations and supply voltage dependencies outlined in this erratum will continue to apply.

For additional information on how the LPMx.5 debug support is handled within the MSP430 IDEs including possible workarounds on how to debug applications using LPMx.5 without toolchain support refer to [Code Composer Studio User's Guide for MSP430 chapter F.4](#) and [IAR Embedded Workbench User's Guide for MSP430 chapter 2.2.5](#).

**Workaround**

1. If LPMx.5 debug support is deemed functional and required in a given scenario:
  - a) Do not update the IDE to continue using a previous version of the debug stack such as MSP430.DLL v3.4.3.4.

OR

  - b) Roll back the debug stack by either performing a clean re-installation of a previous version of the IDE or by manually replacing the debug stack with a prior version such as MSP430.DLL v3.4.3.4 that can be obtained from <http://www.ti.com/tool/MSPDS>.
2. In case JTAG connectivity fails during the LPMx.5 debug mode, the device supply voltage level needs to be raised or lowered until the connection is working.

Do not enable the LPMx.5 debug support feature during production programming.

## JTAG27

### **JTAG Module**

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**Category**

Debug

**Function**

Unintentional code execution after programming via JTAG/SBW

**Description**

The device can unintentionally start executing code from uninitialized RAM addresses 0x0006 or 0x0008 after being programming via the JTAG or SBW interface. This can result in unpredictable behavior depending on the contents of the address location.

**Workaround**

1. If using programming tools purchased from TI (MSP-FET, LaunchPad), update to CCS version 6.1.3 later or IAR version 6.30 or later to resolve the issue.
2. If using the MSP-GANG Production Programmer, use v1.2.3.0 or later.
3. For custom programming solutions refer to the specification on MSP430 Programming Via the JTAG Interface User's Guide (SLAU320) revision V or newer and use MSPDebugStack v3.7.0.12 or later.

For MSPDebugStack (MSP430.DLL) in CCS or IAR, download the latest version of the development environment or the latest version of the [MSPDebugStack](#)

NOTE: This only affects debug mode.'

## **PMAP1**

### ***PMAP Module***

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#### **Category**

Functional

#### **Function**

Port Mapping Controller does not clear unselected inputs to mapped module.

#### **Description**

The Port Mapping Controller provides the logical OR of all port mapped inputs to a module (Timer, USCI, etc). If the PSEL bit (PxSEL.y) of a port mapped input is cleared, then the logic level of that port mapped input is latched to the current logic level of the input. If the input is in a logical high state, then this high state is latched into the input of the logical OR. In this case, the input to the module is always a logical 1 regardless of the state of the selected input.

#### **Workaround**

1. Drive input to the low state before clearing the PSEL bit of that input and switching to another input source.

or

2. Use the Port Mapping Controller reconfiguration feature, PMAPRECFG, to select inputs to a module and map only one input at a time.

## **PMM9**

### ***PMM Module***

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#### **Category**

Functional

#### **Function**

False SVSxIFG events

#### **Description**

The comparators of the SVS require a certain amount of time to stabilize and output a correct result once re-enabled; this time is different for the Full Performance versus the Normal mode. The time to stabilize the SVS comparators is intended to be accounted for by a built-in event-masking delay of 2 us when Full Performance mode is enabled. However, the comparators of the SVS in Full Performance mode take longer than 2 us to stabilize so the possibility exists that a false positive will be triggered on the SVSH or SVSL. This results in the SVSxIFG flags being set and depending on the configuration of SVSxPE bit a POR can also be triggered. Additionally when the SVSxIFGs are set, all GPIOs are tri-stated i.e. floating until the SVSx comparators are settled.

The SVS IFG's are falsely set under the following conditions:

1. Wakeup from LPM2/3/4 when SVSxMD = 0 (default setting) && SVSxFP=1. The SVSx comparators are disabled automatically in LPM2/3/4 and are then re-enabled on return to active mode.
2. SVSx is turned on in full performance mode (SVSxFP=1).
3. A PUC/POR occurs after SVSx is disabled. After a PUC or POR the SVSx are enabled automatically but the settling delay does not get triggered. Based on SVSxPE bit this may lead to POR events until the SVS comparator is fully settled.

#### **Workaround**

For each of the above listed conditions the following workarounds apply:

1. If the Full Performance mode is to be enabled for either the high- or low-side SVS comparators, the respective SVSxMD bits must be set (SVSxMD = 1) such that the SVS comparators are not temporarily shut off in LPM2/3/4. Note that this is equivalent to a 2 uA

(typical) adder to the low power mode current, per the device-specific datasheet, for each SVSx that remains enabled.

2. The SVSx must be turned on in normal mode (SVSxFP=0). It can be reconfigured to use full performance mode once the SVSx/SVMx delay has expired.

3. Ensure that SVSH and SVSL are always enabled.

## **PMM11**

### ***PMM Module***

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#### **Category**

Functional

#### **Function**

MCLK comes up fast on exit from LPM3 and LPM4

#### **Description**

The DCO exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. This behavior is masked from affecting code execution by default: SVSL and SVML run in normal-performance mode and mask CPU execution for 150 us on wakeup from LPM3 and LPM4. However, when the low-side SVS and the SVM are disabled or are operating in full-performance mode (SVMLE= 0 and SVSLE= 0, or SVMLFP= 1 and SVSLFP= 1) AND MCLK is sourced from the internal DCO running over 4 MHz, 7 MHz, 11 MHz, or 14 MHz at core voltage levels 0, 1, 2, and 3, respectively, the mask lasts only 2 us. MCLK is, therefore, susceptible to run out of spec for 4 us.

#### **Workaround**

Set the MCLK divide bits in the Unified Clock System Control 5 Register (UCSCTL5) to divide MCLK by two prior to entering LPM3 or LPM4 (set DIVMx= 001). This prevents MCLK from running out of spec when the CPU wakes from the low-power mode. Following the wakeup from the low-power mode, wait 32, 48, 80, or 100 cycles for core voltage levels 0, 1, 2, and 3, respectively, before resetting DIVMx to zero and running MCLK at full speed [for example, `__delay_cycles(100)`]

## **PMM12**

### ***PMM Module***

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#### **Category**

Functional

#### **Function**

SMCLK comes up fast on exit from LPM3 and LPM4

#### **Description**

The DCO exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. When SMCLK is sourced by the DCO, it is not masked on exit from LPM3 or LPM4. Therefore, SMCLK exceeds the programmed frequency of operation on exit from LPM3 and LPM4 for up to 6 us. The increased frequency has the potential to change the expected timing behavior of peripherals that select SMCLK as the clock source.

#### **Workaround**

- Use XT2 as the SMCLK oscillator source instead of the DCO

or

- Do not disable the clock request bit for SMCLKREQEN in the Unified Clock System Control 8 Register (UCSCTL8). This means that all modules that depend on SMCLK to operate successfully should be halted or disabled before entering LPM3 or LPM4. If the increased frequency prevents the proper function of an affected module, wait 32, 48, 80 or 100 cycles for core voltage levels 0, 1, 2, or 3, respectively, before re-enabling the module. (for example, `__delay_cycles(100)`)

## **PMM14**

### ***PMM Module***

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#### **Category**

Functional

- Function** Increasing the core level when SVS/SVM low side is configured in full-performance mode causes device reset
- Description** When the SVS/SVM low side is configured in full performance mode (SVSMLCTL.SVSLFP = 1), the setting time delay for the SVS comparators is ~2us. When increasing the core level in full-performance mode; the core voltage does not settle to the new level before the settling time delay of the SVS/SVM comparator expires. This results in a device reset.
- Workaround** When increasing the core level; enable the SVS/SVM low side in normal mode (SVSMLCTL.SVSLFP=0). This provides a settling time delay of approximately 150us allowing the core sufficient time to increase to the expected voltage before the delay expires.

**PMM15****PMM Module****Category**

Functional

**Function**

Device may not wake up from LPM2, LPM3, or LPM4

**Description**

Device may not wake up from LPM2, LPM3 or LPM4 if an interrupt occurs within 1 us after the entry to the specified LPMx; entry can be caused either by user code or automatically (for example, after a previous ISR is completed). Device can be recovered with an external reset or a power cycle. Additionally, a PUC can also be used to reset the failing condition and bring the device back to normal operation (for example, a PUC caused by the WDT).

This effect is seen when:

- A write to the SVSMHCTL and SVSMLCTL registers is immediately followed by an LPM2, LPM3, LPM4 entry without waiting the requisite settling time ((PMMIFG.SVSMHDLYIFG = 0 and PMMIFG.SVSMHDLYIFG = 0)).

or

The following two conditions are met:

- The SVSL module is configured for a fast wake-up or when the SVSL/SVML module is turned off. The affected SVSMLCTL register settings are shaded in the following table.

	SVSLE	SVSLMD	SVSLFP	AM, LPM0/1 SVSL state	Manual	Automatic	Wakeup Time LPM2/3/4
					SVSMLACE = 0 LPM2/3/4 SVSL State	SVSMLACE = 1 LPM2/3/4 SVSL State	
SVSL	0	x	x	OFF	OFF	OFF	t <sub>WAKE-UP FAST</sub>
	1	0	0	Normal	OFF	OFF	t <sub>WAKE-UP SLOW</sub>
	1	0	1	Full Performance	OFF	OFF	t <sub>WAKE-UP FAST</sub>
	1	1	0	Normal	Normal	OFF	t <sub>WAKE-UP SLOW</sub>
	1	1	1	Full Performance	Full Performance	Normal	t <sub>WAKE-UP FAST</sub>
SVML	SVMLE	SVMLFP		AM, LPM0/1 SVML state	Manual	Automatic	Wakeup Time LPM2/3/4
					SVSMLACE = 0 LPM2/3/4 SVML State	SVSMLACE = 1 LPM2/3/4 SVML State	
	0	x	OFF	OFF	OFF	t <sub>WAKE-UP FAST</sub>	
	1	0	Normal	Normal	OFF	t <sub>WAKE-UP SLOW</sub>	
1	1	Full Performance	Full Performance	Normal	t <sub>WAKE-UP FAST</sub>		

and

-The SVSH/SVMH module is configured to transition from Normal mode to an OFF state when moving from Active/LPM0/LPM1 into LPM2/LPM3/LPM4 modes. The affected SVSMHCTL register settings are shaded in the following table.

	SVSHE	SVSHMD	SVSHFP	AM, LPM0/1 SVSH state	Manual SVSMHACE = 0	Automatic SVSMHACE = 1
					LPM2/3/4 SVSH State	LPM2/3/4 SVSH State
SVSH	0	x	x	OFF	OFF	OFF
	1	0	0	Normal	OFF	OFF
	1	0	1	Full Performance	OFF	OFF
	1	1	0	Normal	Normal	OFF
	1	1	1	Full Performance	Full Performance	Normal
SVMH	SVMHE	SVMHFP		AM, LPM0/1 SVMH state	Manual SVSMHACE = 0	Automatic SVSMHACE = 1
					LPM2/3/4 SVMH State	LPM2/3/4 SVMH State
	0	x	OFF	OFF	OFF	
	1	0	Normal	Normal	OFF	
1	1	Full Performance	Full Performance	Normal		

## Workaround

Any write to the SVSMxCTL register must be followed by a settling delay (PMMIFG.SVSMLDLYIFG = 0 and PMMIFG.SVSMHDLYIFG = 0) before entering LPM2, LPM3, LPM4.

and

1. Ensure the SVSx, SVMx are configured to prevent the issue from occurring by the following:

- Configure the SVSL module for slow wake up (SVSLFP = 0). Note that this will increase the wake up time from LPM2/3/4 to twakeupslow (~150 us).

or

- Do not configure the SVSH/SVMH such that the modules transition from Normal mode to an OFF state on LPM entry and ensure SVSH/SVMH is in manual mode. Instead force the modules to remain ON even in LPMx. Note that this will cause increased power consumption when in LPMx.

Refer to the MSP430 Driver Library([MSPDRIVERLIB](#)) for proper PMM configuration functions.

Use the following function, PMM15Check (void), to determine whether or not the existing PMM configuration is affected by the erratum. The return value of the function is 1 if the configuration is affected, and 0 if the configuration is not affected.

```

unsigned char PMM15Check (void)
{
// First check if SVSL/SVML is configured for fast wake-up
if ( (!(SVSMLCTL & SVSLE)) || ((SVSMLCTL & SVSLE) && (SVSMLCTL & SVSLFP)) ||
!(SVSMLCTL & SVMLE) || ((SVSMLCTL & SVMLE) && (SVSMLCTL & SVMLEFP)) )
{ // Next Check SVSH/SVMH settings to see if settings are affected by PMM15
if ((SVSMHCTL & SVSHE) && !(SVSMHCTL & SVSHFP))
{
if ( (!(SVSMHCTL & SVSHMD)) || ((SVSMHCTL & SVSHMD) &&
(SVSMHCTL & SVSMHACE)) )
return 1; // SVSH affected configurations
}
if ((SVSMHCTL & SVMHE) && !(SVSMHCTL & SVMHFP) && (SVSMHCTL &
SVSMHACE))
return 1; // SVMH affected configurations
}
}

```

```
return 0; // SVS/M settings not affected by PMM15
}
}
```

2. If fast servicing of interrupts is required, add a 150us delay either in the interrupt service routine or before entry into LPM3/LPM4.

**PMM18*****PMM Module*****Category**

Functional

**Function**

PMM supply overvoltage protection falsely triggers POR

**Description**

The PMM Supply Voltage Monitor (SVM) high side can be configured as overvoltage protection (OVP) using the SVMHOVPE bit of SVSMHCTL register. In this mode a POR should typically be triggered when DVCC reaches ~3.75V. If the OVP feature of SVM high side is enabled going into LPM234, the SVM might trigger at DVCC voltages below 3.6V (~3.5V) within a few ns after wake-up. This can falsely cause an OVP-triggered POR. The OVP level is temperature sensitive during fail scenario and decreases with higher temperature (85 degC ~3.2V).

**Workaround**

Use automatic control mode for high-side SVS & SVM (SVSMHCTL.SVSMHACE=1). The SVM high side is inactive in LPM2, LPM3, and LPM4.

**PMM20*****PMM Module*****Category**

Functional

**Function**

Unexpected SVSL/SVML event during wakeup from LPM2/3/4 in fast wakeup mode

**Description**

If PMM low side is configured to operate in fast wakeup mode, during wakeup from LPM2/3/4 the internal Vcore voltage can experience voltage drop below the corresponding SVSL and SVML threshold (recommendation according to User's Guide) leading to an unexpected SVSL/SVML event. Depending on PMM configuration, this event triggers a POR or an interrupt.

**Note**

As soon the SVSL or the SVML is enabled in Normal performance mode the device is in slow wakeup mode and this erratum does not apply. In addition, this erratum has sporadic characteristic due to an internal asynchronous circuit. The drop of Vcore does not have an impact on specified device performance.

**Workaround**

If SVSL or SVML is required for application (to observe external disruptive events at Vcore pin) the slow wakeup mode has to be used to avoid unexpected SVSL/SVML events. This is achieved if the SVSL or the SVML is configured in "Normal" performance mode (not disabled and not in "Full" Performance Mode).

**PORT15*****PORT Module*****Category**

Functional

**Function**

In-system debugging causes the PMALOCKED bit to be always set

**Description**

The port mapping controller registers cannot be modified when single-stepping or halting at break points between a valid password write to the PMAPWD register and the expected lock of the port mapping (PMAP) registers. This causes the PMAPLOCKED bit to remain



set and not clear as expected.

Note: This erratum only applies to in-system debugging and is not applicable when operating in free-running mode.

**Workaround** Do not single step through or place break points in the port mapping configuration section of code.

**PORT19** ***PORT Module***

---

**Category** Functional

**Function** Port interrupt may be missed on entry to LPMx.5

**Description** If a port interrupt occurs within a small timing window (~1MCLK cycle) of the device entry into LPM3.5 or LPM4.5, it is possible that the interrupt is lost. Hence this interrupt will not trigger a wakeup from LPMx.5.

**Workaround** None

**RTC3** ***RTC Module***

---

**Category** Functional

**Function** Unreliable write to RTC register

**Description** A write access to the RTC registers (SEC, MIN, HOUR, DATE, MON, YEAR, DOW) may result in unexpected results. As a consequence the addressed register might not contain the written data, or some data can be accidentally written to other RTC registers.

**Workaround** Use the RTC library routines, available as F541x/F543x code examples on the MSP430 Code Examples page ([www.ti.com/msp430](http://www.ti.com/msp430) > Software > Code Examples), which use carefully aligned MOV instructions. Library is listed as RTC\_Workaround.zip and includes both CCE and IAR example projects that show proper usage. Using this library, full access to RTC registers is possible.

**RTC6** ***RTC Module***

---

**Category** Functional

**Function** the step size of the RTC frequency adjustment is twice the specified size.

**Description** In BCD mode of operation, the step size of the RTC frequency adjustment is =+8ppm/-4ppm. This is twice the size specified in the User's Guide. In BCD mode, for up calibration this results in a step size per step of 8ppm (1024 cycles) instead of 4ppm (512 cycles). For down calibration this results in a step size per step of 4ppm (512 cycles) instead of 2ppm (256 cycles). In Binary mode, the step size = +4ppm/-2ppm as per the spec.

**Workaround** In BCD mode of operation, half the calibration value could be written into RTCCAL register to compensate the doubled step size.

**SYS16** ***SYS Module***

---

**Category** Functional

**Function** Fast Vcc ramp after device power up may cause a reset

**Description** At initial power-up, after Vcc crosses the brownout threshold and reaches a constant level, an abrupt ramp of Vcc at a rate  $dV/dT > 1V/100\mu s$  can cause a brownout condition to be incorrectly detected even though Vcc does not fall below the brownout threshold. This causes the device to undergo a reset.

**Workaround** Use a controlled Vcc ramp to power up the device.

## TB25 *TB Module*

---

**Category** Functional

**Function** In up mode, TBxCCRn value is immediately transferred to TBxCLn when TBxCCTLn.CLLD bits are set or 0x01 or 0x10

**Description** IF Timer B is configured for Up mode,  
AND  
the compare latch load event (TBxCCTLn.CLLD bits) setting is configured to update TBxCCRn when TBxR reaches 0,  
THEN  
TBxCCRn will update immediately instead of the described condition.

This is contrary to the user guide description of TBxCCTLn.CLLD = 0x01 or 0x10 modes.

**Workaround** If user needs to update TBxCCRn value when TBxR counts to 0 in Timer B up mode:

1. Set TBxCCTLn.CLLD = 0x00
2. Enable the Timer B interrupt (TBIE) in TBxCTL
3. Update TBxCCRn value within interrupt routine.

Timer B Interrupt would need to be serviced in a timely manner to mitigate disruption or unintended timer output if an output mode is used.

## UCS7 *UCS Module*

---

**Category** Functional

**Function** DCO drifts when servicing short ISRs when in LPM0 or exiting active from ISRs for short periods of time

**Description** The FLL uses two rising edges of the reference clock to compare against the DCO frequency and decide on the required modifications to the DCOx and MODx bits. If the device is in a low power mode with FLL disabled (LPM0 with DCO not sourcing ACLK/SMCLK or LPM2, LPM3, LPM4 where SCG1 bit is set) and enters a state which enables FLL (enter ISR from LPM0/LPM2 or exit active from ISRs) for a period less than 3x reference clock cycles, then the FLL will cause the DCO to drift. This occurs because the FLL immediately begins comparing an active DCO with its reference clock and making the respective modifications to the DCOx and MODx bits. If the FLL is not given sufficient time to capture a full reference clock cycle (2 x reference clock periods) and adjust accordingly (1 x reference clock period), then the DCO will keep drifting each time the FLL is enabled.

**Workaround** (1) If DCO is not sourcing ACLK or SMCLK in the application, use LPM1 instead of LPM0 to make sure FLL is disabled when interrupt service routine is serviced.  
(2) When exiting active from ISRs, insert a delay of at least 3 x reference clock periods. To save on power budget, the 3 x reference clock periods could also be spent in LPM0 with TimerA or TimerB using ACLK/SMCLK sourced from DCO. This way, the FLL and DCO are still active in LPM0.

<b>UCS9</b>	<b>UCS Module</b>
<b>Category</b>	Functional
<b>Function</b>	Digital Bypass mode prevents entry into LPM4
<b>Description</b>	When entering LPM4, if an external digital input applied to XT1 in HF mode or XT2 is not turned off, the PMM does not switch to low-current mode causing higher than expected power consumption.
<b>Workaround</b>	Before entering LPM4: (1) Switch to a clock source other than external bypass digital input. OR (2) Turn off external bypass mode (UCSCTL6.XT1BYPASS = 0).
<b>UCS11</b>	<b>UCS Module</b>
<b>Category</b>	Functional
<b>Function</b>	Modifying UCSCTL4 clock control register triggers an additional erroneous clock request
<b>Description</b>	Changing the SELM/SELS/SELA bits in the UCSCTL4 register will correctly configure the respective clock to use the intended clock source but might also erroneously set XT1/XT2 fault flag if the crystals are not present at XT1/XT2 or not configured in the application firmware. If the NMI interrupt for the OFIFG is enabled, an unintentional NMI interrupt will be triggered and needs to be handled.
	<b>Note</b> The XT1/XT2 fault flag can be set regardless of which SELM/SELS/SELA bit combinations are being changed.
<b>Workaround</b>	Clear all the fault flags in UCSCTL7 register once after changing any of the SELM/SELS/SELA bits in the UCSCTL4 register. If OFIFG-NMI is enabled during clock switching, disable OFIFG-NMI interrupt during changing the SELM/SELS/SELA bits in the UCSCTL4 register to prevent unintended NMI. Alternatively it can be handled accordingly (clear falsely set fault flags) in the Interrupt Service Routine to ensure proper OFIFG clearing.
<b>USCI26</b>	<b>USCI Module</b>
<b>Category</b>	Functional
<b>Function</b>	Tbuf parameter violation in I2C multi-master mode
<b>Description</b>	In multi-master I2C systems the timing parameter Tbuf (bus free time between a stop condition and the following start) is not guaranteed to match the I2C specification of 4.7us in standard mode and 1.3us in fast mode. If the UCTXSTT bit is set during a running I2C transaction, the USCI module waits and issues the start condition on bus release causing the violation to occur. Note: It is recommended to check if UCBBUSY bit is cleared before setting UCTXSTT=1.
<b>Workaround</b>	None
<b>USCI34</b>	<b>USCI Module</b>
<b>Category</b>	Functional

<b>Function</b>	I2C multi-master transmit may lose first few bytes.
<b>Description</b>	<p>In an I2C multi-master system (UCMM =1), under the following conditions:</p> <p>(1)the master is configured as a transmitter (UCTR =1)</p> <p>AND</p> <p>(2)the start bit is set (UCTXSTT =1);</p> <p>if the I2C bus is unavailable, then the USCI module enters an idle state where it waits and checks for bus release. While in the idle state it is possible that the USCI master updates its TXIFG based on clock line activity due to other master/slave communication on the bus. The data byte(s) loaded in TXBUF while in idle state are lost and transmit pointers initialized by the user in the transmit ISR are updated incorrectly.</p>
<b>Workaround</b>	<p>Verify that the START condition has been sent (UCTXSTT =0) before loading TXBUF with data.</p>

Example:

```
#pragma vector = USCIAB0TX_VECTOR
__interrupt void USCIAB0TX_ISR(void)
{
// Workaround for USCI34
if(UCB0CTL1&UCTXSTT)
{
// TXData = pointer to the transmit buffer start
// PTxData = pointer to transmit in the ISR
PTxData = TXData; // restore the transmit buffer pointer if the Start bit is set
}
//
if(IFG2&UCB0TXIFG)
{
if (PTxData <= PTxDataEnd) // Check TX byte counter
{
UCB0TXBUF = *PTxData++; // Load TX buffer
}
else
{
UCB0CTL1 |= UCTXSTP; // I2C stop condition
IFG2 &= ~UCB0TXIFG; // Clear USCI_B0 TX int flag
__bic_SR_register_on_exit(CPUOFF); // Exit LPM0
}
}
}
```

<b>USCI35</b>	<b><i>USCI Module</i></b>
<b>Category</b>	Functional
<b>Function</b>	Violation of setup and hold times for (repeated) start in I2C master mode
<b>Description</b>	<p>In I2C master mode, the setup and hold times for a (repeated) START, <math>t_{SU,STA}</math> and <math>t_{HD,STA}</math> respectively, can be violated if SCL clock frequency is greater than 50kHz in standard mode (100kbps). As a result, a slave can receive incorrect data or the I2C bus can be stalled due to clock stretching by the slave.</p>

**Workaround** If using repeated start, ensure SCL clock frequencies is < 50kHz in I2C standard mode (100 kbps).

**USCI39** ***USCI Module***

---

**Category** Functional

**Function** USCI I2C IFGs UCSTTIFG, UCSTPIFG, UCNACKIFG

**Description** Unpredictable code execution can occur if one of the hardware-clear-able IFGs UCSTTIFG, UCSTPIFG or UCNACKIFG is set while the global interrupt enable is set by software (GIE=1). This erratum is triggered if ALL of the following events occur in following order:

1. Pending Interrupt: One of the UCxIFG=1 AND UCxIE=1 while GIE=0
2. The GIE is set by software (e.g. EINT)
3. The pending interrupt is cleared by hardware (external I2C event) in a time window of 1 MCLK clock cycle after the "EINT" instruction is executed.

**Workaround** Disable the UCSTTIE, UCSTPIE and UCNACKIE before the GIE is set. After GIE is set, the local interrupt enable flags can be set again.

Assembly example:

```
bic #UCNACKIE+UCSTPIE+UCSTTIE, UCxBIE ; disable all self-clearing interrupts
NOP
EINT
bis #UCNACKIE+UCSTPIE+UCSTTIE, UCxBIE ; enable all self-clearing interrupts
```

**USCI40** ***USCI Module***

---

**Category** Functional

**Function** SPI Slave Transmit with clock phase select = 1

**Description** In SPI slave mode with clock phase select set to 1 (UCAxCTLW0.UCCKPH=1), after the first TX byte, all following bytes are shifted by one bit with shift direction dependent on UCMSB. This is due to the internal shift register getting pre-loaded asynchronously when writing to the USCIA TXBUF register. TX data in the internal buffer is shifted by one bit after the RX data is received.

**Workaround** Reinitialize TXBUF before using SPI and after each transmission. If transmit data needs to be repeated with the next transmission, then write back previously read value:

```
UCAxTXBUF = UCAxTXBUF;
```

## 7 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

### Changes from July 14, 2021 to August 27, 2021

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• TB25 was added to the errata documentation.....	6
• TB25 Description was updated.....	18
• TB25 Workaround was updated.....	18

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Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265  
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